

Theo Übung ②

$$\boxed{1} (a) \psi_{n,l,m}(r, \theta, \phi) = \underbrace{-N_{nlm} (2\kappa r)^l e^{-\kappa r}}_{\text{Radialteil } R_{nl}(r)} \underbrace{L_{n+l}^{2l+1}(2\kappa r)}_{\text{Radialteil}} \underbrace{Y_{lm}(\phi, \theta)}_{\text{Winkelteil}}$$

$$\psi_{n,l,m}(r, \theta, \phi) = -N_{n,l,m} (2\kappa r)^l e^{-\kappa r} L_{n+l}^{2l+1}(2\kappa r) Y_{lm}(\phi, \theta)$$

$$N_{n,l,m} = \left(\frac{2}{a_b}\right)^{3/2} \cdot \frac{2}{n^2 (2n-l)!} \sqrt{\frac{(2l)!}{(2n-l)!}} \quad , \quad \kappa = \frac{Z}{a_b n}$$

$$L_{2n-l}^{2l+1}(2\kappa r) = \frac{(2n-l)!}{0!} e^{2\kappa r} \left(\frac{\partial}{\partial(2\kappa r)}\right)^{2n-l} \left((2\kappa r)^0 e^{-2\kappa r}\right)$$

$$= (2n-l)! \cdot e^{2\kappa r} \cdot (-1)^{2n-l} e^{-2\kappa r}$$

2n ist stets gerade, 2n-l
stets ungerade

$$Y_{l,m}(\phi, \theta) = \frac{(-1)^{m-l}}{2^{l-m} (l-m)!} \sqrt{\frac{(2l-l)!}{4\pi}} \cdot \frac{e^{i\phi(l-m)}}{\sin^{l-m}\theta} \left(\frac{\partial}{\partial(\cos\theta)}\right)^0 \sin^{2l}\theta$$

$$\psi_{n,l,m}(r, \theta, \phi) = \left(\frac{2}{a_b}\right)^{3/2} \cdot \frac{2}{n^2 (2n-l)!} \sqrt{\frac{(2l)!}{(2n-l)!}} (2\kappa r)^l e^{-\kappa r} \cdot (-1)^{m-l} \sqrt{\frac{(2l-l)!}{4\pi}} \cdot \frac{e^{i\phi(l-m)}}{\sin^{l-m}\theta} \cdot \sin^{2l}\theta$$

$$= (-1)^{m-l} \left(\frac{2}{a_b}\right)^{3/2} \frac{1}{n^2} (2\kappa r)^l e^{-\kappa r} \sqrt{\frac{(2l)!}{(2n-l)!}} \sqrt{\frac{(2l-l)!}{4\pi}} e^{i\phi(l-m)} \sin^{l-m}\theta$$

$$= \frac{1}{\sqrt{\pi}} \left(\frac{2}{a_b}\right)^{3/2} \frac{1}{n^2} (-\kappa r)^l e^{-\kappa r + i\phi(l-m)} \sin^{l-m}\theta$$

$$= \frac{1}{\sqrt{\pi}} \frac{1}{n^2} \kappa^{3/2} (-\kappa r)^l e^{-\kappa r + i\phi(l-m)} \sin^{l-m}\theta$$

$$d\Omega = dr d\Omega$$

Theo (5)

$$\langle r \rangle = \int \psi^* r \psi d\Omega$$

$$\psi = \frac{1}{\sqrt{a_0}} \left(\frac{r}{a_0} \right)^{2n} \frac{1}{n! (2n-1)!} \sqrt{\frac{1}{(2n-1)!}} (2nr)^{n-1} e^{-nr} (2n-1)! (-1)^{n-1} Y_{n-1, n-1}(\phi, \theta)$$

$$= \frac{n^{3/2}}{\sqrt{n}} 2^n (nr)^{n-1} \frac{1}{\sqrt{(2n-1)!}} e^{-nr} Y_{n-1, n-1}(\phi, \theta)$$

$$\psi^* = \frac{1}{\sqrt{n}} \frac{1}{\sqrt{(2n-1)!}} e^{-nr} Y_{n-1, n-1}^*(\phi, \theta)$$

$$\langle r \rangle = \int R Y \cdot R^* Y^* d\Omega = \int \int R R^* d\Omega Y Y^* d\Omega = \int R^2 d\Omega \int Y Y^* d\Omega$$

$\int R R^* d\Omega = 1$ (n.o.)

(r, θ bilden die Jacobian der Integration! $\Rightarrow f = r^2$, da in Kugel coord. Jac. $\Rightarrow f = r^2 \sin \theta$ ist)

weil Y normiert ist!

$$\langle r \rangle = \int_0^\infty dr \frac{n^3}{n} 2^n (nr)^{2n-2} \frac{1}{(2n-1)!} e^{-2nr} r^3$$

$$= \frac{n^3}{n} \frac{2^n}{(2n-1)!} \int_0^\infty r^{2n-2+3} e^{-2nr} dr$$

Setze $2nr =: t$

$$\Rightarrow \frac{dt}{dr} = 2n$$

$$= \frac{n^3}{n} \left(\frac{1}{2n} \right) \frac{1}{2n} \int_0^\infty t^{2n+1} e^{-t} dt$$

$$\Gamma(2n+2) = (2n+1)!$$

$$= \frac{1}{2n} \frac{2^n}{n} \cdot 2n (2n+1) \frac{1}{2^{2n+1}} = \frac{2n+1}{2n} = \frac{(2n+1/2) a_0^n}{2n}$$

$$= \frac{a_0^n}{2} (n + 1/2)$$

$$1.1) (c) \quad \Delta r = \sqrt{\langle r^2 \rangle - \langle r \rangle^2}$$

$$\langle r \rangle^2 = \left[\frac{a_b u}{z} (u + \frac{1}{2}) \right]^2$$

$$\langle r^2 \rangle = \int_0^\infty R^2 r^4 dr = \uparrow \text{siehe (b)}$$

$$\frac{2^{2u} K^{2u+1}}{u (2u-1)!} \int_0^\infty r^{2u+2} e^{-2Kr} dr$$

$$= \frac{2^{2u} K^{2u+1}}{u (2u-1)!} \cdot \frac{1}{2K} \left(\frac{1}{2K} \right)^{2u+2} (2u+2)!$$

$$= \frac{1}{448 u K^2} (2u)(2u+1)(2u+2) = \frac{4u^2 + 6u + 2}{4 K^2} = \frac{(4u^2 + 6u + 2) a_b^2 u^2}{4 z^2}$$

$$= \left(\frac{a_b u}{z} \right)^2 (u^2 + \frac{3}{2}u + \frac{1}{2}) = \left(\frac{a_b u}{z} \right)^2 (u+1)(u+\frac{1}{2})$$

$$\Delta r = \sqrt{\left(\frac{a_b u}{z} \right)^2 (u+\frac{1}{2}) \left\{ (u+1) - (u+\frac{1}{2}) \right\}}$$

$$= \left(\frac{a_b u}{z} \right) \cdot \sqrt{\frac{u+\frac{1}{2}}{2}}$$

$$2) \quad \frac{\Delta r}{\langle r \rangle} = \frac{\sqrt{\frac{u+\frac{1}{2}}{2}}}{(u+\frac{1}{2})} = \frac{1}{\sqrt{2u+1}}$$

(d): „Bahnkurve & orthogonal dazu“ bedeutet:
bzw. in ~~Polarkoordinaten~~ Zylinderkoordin. mit $\theta = \text{const. } \pi/2$.
(r, θ).

$$|Y|^2 = \frac{1}{\pi u} \left(\frac{1}{(u-1)!} \right)^2 K^3 (-Kr) e^{-2Kr} \sin^{2u-2} \theta$$

$$= \frac{1}{\pi u} \frac{1}{(u-1)!^2} \frac{K^3}{a_b^3} \left(\frac{z}{a_b} \right)^3 \frac{1}{u^3} \left(\frac{-zr}{a_b u} \right)^{2u-2} e^{-2zr/a_b u} \sin^{2u-2} \theta$$

↳ von ϕ unabhängig \rightarrow dreh-symmetrisch um z-Achse.