

1) a) $\frac{d}{dx} y(x) - a \frac{d^3}{dx^3} y(x) = x y(x)$

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$$\int_{-\infty}^{\infty} \frac{d}{dx} y(x) e^{-i\epsilon x} dx - \int_{-\infty}^{\infty} a \frac{d^3}{dx^3} y(x) e^{-i\epsilon x} dx = \int_{-\infty}^{\infty} x \cdot y(x) e^{-i\epsilon x} dx$$

$$+ i\epsilon \hat{y}(\epsilon) - (i\epsilon)^3 a \hat{y}(\epsilon) = i \frac{d}{d\epsilon} \hat{y}(\epsilon)$$

$$\frac{d}{d\epsilon} \hat{y}(\epsilon) = \epsilon \hat{y}(\epsilon) - a \epsilon^3 \hat{y}(\epsilon)$$

\Rightarrow homogen. Diff'gl. 1. Ordnung

b) $\frac{d^2}{dx^2} y(x) - \int_{-\infty}^{\infty} dz \underbrace{h(x-z) \cdot y(z)}_{\text{Faltung}} = \delta(x)$

$$(i\epsilon)^2 \hat{y}(\epsilon) - \hat{h}(\epsilon) \cdot \hat{y}(\epsilon) = 1$$

$$\hat{h}(\epsilon) = \int_{-\infty}^{\infty} dx e^{-i\epsilon x} \cdot e^{-x} = \int_0^{\infty} dx e^{-x(i\epsilon+1)}$$

$$= \int_0^{\infty} dx \left[\frac{-1}{i\epsilon+1} e^{-x(i\epsilon+1)} \right]_0^{\infty} = 0 - \frac{-1}{i\epsilon+1} = \frac{1}{i\epsilon+1}$$

$$- \epsilon^2 \hat{y}(\epsilon) - \frac{1}{i\epsilon+1} \hat{y}(\epsilon) = 1$$

$$\hat{y}(\epsilon) \left(-\epsilon^2 - \frac{1}{i\epsilon+1} \right) = 1$$

$$\hat{y}(\epsilon) = \frac{-1}{\epsilon^2 + \frac{1}{i\epsilon+1}} = - \frac{i\epsilon+1}{i\epsilon^3 + \epsilon^2 + 1}$$

$$y(x) = \frac{1}{2\pi} \int_{-\infty}^{\infty} d\epsilon e^{+i\epsilon x} \cdot \frac{i\epsilon+1}{i\epsilon^3 + \epsilon^2 + 1}$$

$$v = \frac{-3\epsilon^2 + 3i\epsilon^2 + 2i\epsilon^2 + 2\epsilon}{(i\epsilon^3 + \epsilon^2 + 1)^2}$$

$$= \frac{-2\epsilon^3 - 4i\epsilon^2 - 2\epsilon + i}{(i\epsilon^3 + \epsilon^2 + 1)^2}$$

$$\textcircled{2} \quad \vec{r}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = \begin{pmatrix} t \\ t^2 \end{pmatrix} \quad t \in [0, 1] \quad \frac{d\vec{r}}{dt} = \begin{pmatrix} 1 \\ 2t \end{pmatrix} \quad \left| \frac{d\vec{r}}{dt} \right| = \sqrt{1+4t^2}$$

$$(i) \quad \int_C d\vec{r} \cdot \vec{r} = \int_C \frac{d\vec{r}}{dt} dt \cdot \vec{r} = \int_0^1 \begin{pmatrix} 1 \\ 2t \end{pmatrix} \begin{pmatrix} t \\ t^2 \end{pmatrix} dt =$$

$$\int_0^1 t + 2t^3 dt = \left[\frac{1}{2}t^2 + \frac{1}{2}t^4 \right]_0^1 = 1$$

$$(ii) \quad \int_C d\vec{r} \times (t) y(t) = \int_C \frac{d\vec{r}}{dt} dt \cdot t^3 = \int_0^1 \begin{pmatrix} t^3 \\ 2t^4 \end{pmatrix} dt$$

$$= \left[\begin{pmatrix} \frac{1}{4}t^4 \\ \frac{2}{5}t^5 \end{pmatrix} \right]_0^1 = \begin{pmatrix} \frac{1}{4} \\ \frac{2}{5} \end{pmatrix}$$

$$(iii) \quad \int_C ds \frac{1}{\sqrt{1+4x^2}} = \int_C \left| \frac{d\vec{r}}{dt} \right| dt \frac{1}{\sqrt{1+4x^2}}$$

$$= \int_0^1 dt \cdot 1 = 1$$

$$(iv) \quad \int_C ds = \int_0^1 \sqrt{1+4t^2} dt = \int_0^2 \frac{1}{2} \sqrt{1+u^2} du \quad \begin{matrix} 2t=u \\ \frac{d^2u}{dt^2} = 2 \end{matrix}$$

$$= \left[\frac{1}{4} u \sqrt{1+u^2} + \frac{1}{2} \sinh^{-1} u \right]_0^2$$

$$= 0.837$$

$$\textcircled{3} \quad \vec{e}_\phi = \frac{\partial \vec{r}}{\partial \phi} = \begin{pmatrix} -R \sin \phi \sin \theta \\ R \cos \phi \sin \theta \\ 0 \end{pmatrix}$$

$$\vec{e}_\theta = \frac{\partial \vec{r}}{\partial \theta} = \begin{pmatrix} R \cos \phi \cos \theta \\ R \sin \phi \cos \theta \\ -R \sin \theta \end{pmatrix}$$

$$\begin{aligned} \vec{e}_\phi \times \vec{e}_\theta &= \begin{pmatrix} -R^2 \cos \phi \sin^3 \theta & -R^2 \sin \phi \sin^3 \theta \\ -R^2 \sin^2 \phi \sin \theta \cos \theta & -R^2 \cos^2 \phi \sin \theta \cos \theta \\ -R^2 \sin \theta \cos \theta (\sin^2 \phi + \cos^2 \phi) \end{pmatrix} \\ &= R^2 \begin{pmatrix} \cos \phi \sin^3 \theta & \sin \phi \sin^3 \theta \\ -\sin \theta \cos \theta & -\sin \theta \cos \theta \end{pmatrix} \end{aligned}$$

~~$$|\vec{e}_\phi \times \vec{e}_\theta| = R^2 \sqrt{\cos^2 \phi \sin^6 \theta + 2 \cos \phi \sin^3 \theta \sin \phi \cos^2 \theta + \sin^2 \phi \cos^4 \theta + \cos^2 \phi \cos^4 \theta - 2 \cos \phi \cos^2 \theta \sin \phi \sin^3 \theta + \sin^2 \phi \sin^6 \theta + \sin^2 \theta \cos^2 \theta}$$~~

~~$$= R^2 \sqrt{\cos^4 \theta + \sin^4 \theta + \sin^2 \theta \cos^2 \theta}$$~~

~~$$= R^2 \sqrt{\cos^4 \theta + \sin^4 \theta} = R^2 \sqrt{\cos^4 \theta + 1 - \cos^2 \theta}$$~~

$$\begin{aligned} |\vec{e}_\phi \times \vec{e}_\theta| &= \sqrt{\cos^2 \phi \sin^6 \theta + \sin^2 \phi \sin^6 \theta + \sin^2 \theta \cos^2 \theta} \\ &= \sqrt{\sin^6 \theta + \sin^2 \theta \cos^2 \theta} \\ &= \sqrt{\sin^4 \theta} \\ &= \sin \theta \end{aligned}$$

$$\int = \int_0^\pi d\theta \int_0^{2\pi} d\phi R^2 \sin \theta = \int_0^\pi d\theta 2\pi R^2 \sin \theta = 4\pi R^2$$