

17 (a) $f(0) = 0$, $g(0) = \int_0^1 \frac{1}{1+t^2} dt = \arctan 1 = \frac{\pi}{4}$

$$f'(x) = 2 \cdot \left(\frac{d}{dx} \int_0^x e^{-t^2} dt \right) \cdot \int_0^x e^{-t^2} dt = 2 e^{-x^2} \int_0^x e^{-t^2} dt$$

\Rightarrow All. int. \Rightarrow diff'bar.

$$f'(x) = \frac{d}{dx} \int_0^1 \frac{1}{1+t^2} e^{-x^2(1+t^2)} dt \stackrel{(*)}{=} \int_0^1 \frac{1}{1+t^2} \frac{\partial}{\partial x} e^{-x^2(1+t^2)} dt$$

Satz 2, 4.11.0 (16)

$$= \int_0^1 -2x e^{-x^2(1+t^2)} dt = -2x \int_0^1 e^{-t^2(1+x^2)} dt$$

$x \cdot t = s$

Wekt.: $x \cdot t = s \Rightarrow \frac{ds}{dt} = x \Rightarrow dt = \frac{1}{x} ds$

$\frac{ds}{dt} = x$

$dt = \frac{1}{x} ds$

$$= \int_0^x -2 e^{-\frac{s^2}{x^2}(1+t^2)} ds = -\int_0^x 2 e^{-\frac{s^2}{x^2} - \frac{s^2}{x^2} t^2} ds$$

(b) $\lim_{x \rightarrow \infty} g(x)$

$$f_g(t) = \frac{1}{t^2+1} e^{-t^2(1+t^2)}$$

$$g(t) = \frac{1}{1+t^2} \Rightarrow |f_g(t)| \leq g(t)$$

$g \in L^1(\mathbb{R})$ da Riemann-int'bar \Rightarrow gilt Lebesgue'satz:

$$\lim_{x \rightarrow \infty} \int_0^1 \frac{1}{1+t^2} e^{-x^2(1+t^2)} dt = \int_0^1 \lim_{x \rightarrow \infty} e^{-x^2(1+t^2)} \frac{1}{1+t^2} dt = \int_0^1 0 \cdot \frac{1}{1+t^2} dt = 0$$

(b,c) $f(x) = f(0) + \int_0^x f'(\tilde{x}) d\tilde{x} \xrightarrow{x \rightarrow \infty} \frac{\pi}{4}$

$$g(x) = \underbrace{g(0)}_{\frac{\pi}{4}} + \underbrace{\int_0^x g'(\tilde{x}) d\tilde{x}}_{-\frac{\pi}{4}} \xrightarrow{x \rightarrow \infty} 0$$

$$\Rightarrow \int_0^x g'(\tilde{x}) d\tilde{x} \xrightarrow{x \rightarrow \infty} \frac{\pi}{4}$$

$$\begin{aligned} \int_{-\infty}^{+\infty} e^{-t^2} dt &= 2 \cdot \int_0^{+\infty} e^{-t^2} dt = 2 \cdot \left(\int_0^{+\infty} e^{-t^2} dt \right)^{2/2} \\ &= 2 \sqrt{\lim_{x \rightarrow \infty} f(x)} = 2 \cdot \sqrt{\frac{\pi}{4}} = \sqrt{\pi} \end{aligned}$$

$$(2) \quad \underline{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} ar \cos \theta \cos \varphi \\ br \cos \theta \sin \varphi \\ cr \sin \theta \end{pmatrix}, \quad r \in (0,1), \varphi \in (0,2\pi), \theta \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$$

$$|\underline{J}| = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \varphi} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \varphi} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \varphi} \end{vmatrix} = \begin{vmatrix} a \cos \theta \cos \varphi & -a \sin \theta \cos \varphi & -a r \cos \theta \sin \varphi \\ b \cos \theta \sin \varphi & -b r \sin \theta \sin \varphi & b r \cos \theta \cos \varphi \\ c \sin \theta & c r \cos \theta & 0 \end{vmatrix} \quad r^2 abc$$

Euler.

$$\begin{aligned} &= \sin \theta [-\sin \theta \cos \theta \cos^2 \varphi - \sin \theta \cos \theta \sin^2 \varphi] \cdot r^2 abc \\ &\quad + \cos \theta [\cos^2 \theta \cos^2 \varphi + \cos^2 \theta \sin^2 \varphi] \cdot r^2 abc \\ &= -\sin \theta (\sin \theta \cos \theta) - \cos \theta (\cos^2 \theta) \cdot r^2 abc \\ &= -\cos \theta \cdot r^2 abc \end{aligned}$$

$$\begin{aligned} (a) \quad \text{vol}(E) &= \left| \int_0^1 dr \int_0^{2\pi} d\varphi \int_{-\pi/2}^{\pi/2} d\theta \quad 1 \cdot (-\cos \theta r^2 abc) \right| \\ &= \left| \int_0^1 dr \underbrace{\int_0^{2\pi} d\varphi}_{2\pi} r^2 abc \cdot \sin \theta \Big|_{-\pi/2}^{\pi/2} \right| \\ &= \left| -4\pi abc \left[\frac{1}{3} r^3 \right]_0^1 \right| \\ &= \left| -\frac{4}{3} \pi abc \right| = \frac{4}{3} \pi abc \end{aligned}$$

$$(b) \quad \int_B 1 d\underline{x} = \frac{1}{8} \int_0^R dr \int_0^{2\pi} d\varphi \int_{-\pi/2}^{\pi/2} d\theta \quad 1 \cdot \sin \theta r^2 = \frac{1}{8} \cdot 2\pi \cdot 2 \cdot \frac{1}{3} R^3 = \frac{1}{6} \pi R^3.$$

$$\begin{aligned} \int_B x_i d\underline{x} &= \int_0^R dr \int_0^{2\pi} d\varphi \int_{-\pi/2}^{\pi/2} d\theta \quad \underbrace{\sin \theta \cos \theta}_{\frac{1}{2} \sin 2\theta} r^2 \\ &= \int_0^R dr \quad \frac{1}{2\pi} r^3 \quad \frac{1}{2} \sin^2 \theta \Big|_0^{\pi/2} \\ &= \frac{1}{4} R^4 \cdot \frac{1}{2\pi} \cdot \frac{1}{2} \cdot 1 = \frac{R^4}{16} \pi. \end{aligned}$$

Wg. Symmetrie gilt das für alle x_i !

$$\underline{S} = \frac{R^3}{8} (1, 1, 1)^T$$

IV

$$(a) \int x \, dx = \int_0^1 \int_0^{(1-y^{2/3})^{3/2}} x \, dx \, dy = \int_0^1 \frac{1}{2} (1-y^{2/3})^3 \, dy$$

$$y^{2/3} = \theta \quad \frac{d\theta}{dy} = \frac{2}{3} \cdot y^{-1/3} = \frac{2}{3} \theta^{-1/2}$$

$$\Rightarrow dy = \frac{3}{2} \cdot \sqrt{\theta} \cdot d\theta$$

$$\int_0^1 \frac{1}{2} \cdot \frac{3}{2} \cdot (1-\theta)^3 \sqrt{\theta} \, d\theta$$

$$(1-\theta)^3 = 1 \cdot 1 - 3 \cdot \theta + 3 \theta^2 - 1 \theta^3$$

$$\int_0^1 \frac{3}{4} \cdot \theta^{1/2} - 3 \theta^{3/2} + 3 \theta^{5/2} - \theta^{7/2} \, d\theta =$$

$$\frac{3}{4} \cdot \left[\frac{2}{3} \theta^{3/2} - \frac{6}{5} \theta^{5/2} + \frac{6}{7} \theta^{7/2} - \frac{2}{9} \theta^{9/2} \right]_0^1 = \frac{8}{105}$$

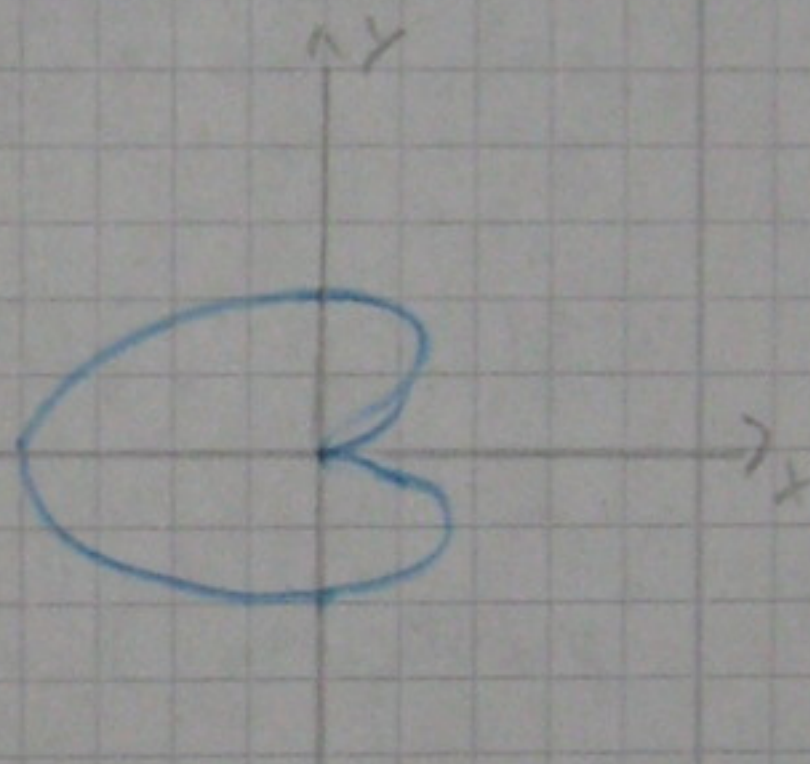
(b) $\text{vol}(K) =$

$$\int_0^{2\pi} d\varphi \int_0^{1-\cos\varphi} 1 \cdot r \, dr$$

$$|\underline{g}| = \begin{vmatrix} \cos\varphi & \sin\varphi \\ -\sin\varphi & \cos\varphi \end{vmatrix} = r \cos^2\varphi + r \sin^2\varphi = r$$

$$= \int_0^{2\pi} d\varphi \frac{1}{2} (1-\cos\varphi)^2$$

$$= \frac{1}{2} \int_0^{2\pi} d\varphi \underbrace{1}_{\frac{2\pi}{2\pi}} - 2 \underbrace{\cos\varphi}_0 + \underbrace{\cos^2\varphi}_{\frac{\pi}{2\pi}}$$



$$= \pi + \frac{\pi}{2} = \frac{3}{2} \pi$$

9)

$$M_h: \left\| \underline{x} - \begin{pmatrix} 2 \cos x_3 \\ 2 \sin x_3 \\ x_3 \end{pmatrix} \right\|_2 \leq 1$$

$$\underline{x} = \begin{pmatrix} 2 \cos x_3 + \tilde{x} \\ 2 \sin x_3 + \tilde{y} \\ x_3 + \tilde{z} \end{pmatrix}$$

$$M_h = \left\{ \left\| \begin{pmatrix} \tilde{x} \\ \tilde{y} \\ \tilde{z} \end{pmatrix} \right\|_2 \leq 1 \right\}$$

$$\sqrt{\tilde{x}^2 + \tilde{y}^2 + \tilde{z}^2} \leq 1$$

$$\begin{pmatrix} \tilde{x} \\ \tilde{y} \\ \tilde{z} \end{pmatrix} = \begin{pmatrix} r \cos \theta \\ r \sin \theta \\ \tilde{z} \end{pmatrix}$$

$$r \in (0, 1) \quad \theta \in [0, 2\pi), \quad \tilde{z} \in [0, 4]$$

$$\underline{x} = \begin{pmatrix} 2 \cos x_3 + r \cos \theta \\ 2 \sin x_3 + r \sin \theta \\ x_3 + \tilde{z} \end{pmatrix}$$

$$|\underline{\tilde{x}}| = r \quad (\text{Zylinder Coord.})$$

$$\text{Vol}(M_h) = \int_0^4 d\tilde{z} \int_0^{2\pi} d\varphi \int_0^1 dr \quad r \quad 1$$

$$= h \quad 2\pi \quad \frac{1}{2} = \pi \cdot h$$

(\leadsto S. v. Cavalieri: $\text{Vol}(M_h)$ ident. mit Vol. eines Zyl.

d. Rad. $r=1$, $h=h$.)

