

GowinSynthesis

User Guide

SUG550-2.0E, 02/28/2025

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Revision History

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12/09/2019	1.1E	"Naming Rules of Objects before/after Synthesis" added. (Gowin Software V1.9.3 and above)	
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02/28/2025	2.0E	 The syn_radhardlevel attribute constraint added. Descriptions of syn_maxfan updated. The object of syn_looplimit updated. 	

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1 About This Guide 1.1 Purpose

1 About This Guide

1.1 Purpose

It mainly describes functions and operations of GowinSynthesis and aims to help you learn how to use this software and improve design efficiency. The software screenshots in this manual are based on Gowin Software 1.9.11.01. As the software is subject to change without notice, some information may not remain relevant and may need to be adjusted according to the software that is in use.

1.2 Related Documents

The user guides are available on the GOWINSEMI Website. You can find the related documents at www.gowinsemi.com: SUG100, Gowin Software User Guide.

1.3 Terminology and Abbreviation

Table 1-1 shows the abbreviations and terminology that are used in this guide.

Table 1-1 Abbreviations and Terminology

Terminology and Abbreviation	Meaning
BSRAM	Block Static Random Access Memory
DSP	Digital Signal Processing
FPGA	Field Programmable Gate Array
FSM	Finite State Machine
GSC	Gowin Synthesis Constraint File
SSRAM	Shadow Static Random Access Memory

1.4 Support and Feedback

Gowin Semiconductor provides customers with comprehensive technical support. If you have any questions, comments, or suggestions, please feel free to contact us directly by the following ways.

Website: www.gowinsemi.com
E-mail: support@gowinsemi.com

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2 Overview

This is the user guide of Gowin RTL design synthesis tool GowinSynthesis.

GowinSynthesis is designed in-house by GOWINSEMI, and it uses Gowin original EDA algorithm to realize RTL design extraction, arithmetic optimization, inference, resource sharing, parallel synthesis and mapping based on product hardware characteristics and hardware circuit resources, which can quickly optimize your RTL design, resource check, and timing analysis.

GowinSynthesis, targeting Gowin FPGA chips, provides the most efficient design implementation method for FPGA designers. GowinSynthesis can generate a post-synthesis netlist based on the Gowin device primitive library, which can be used as an input file for the PnR, achieving the optimal balance of area and speed, improving software compilation efficiency, and routing rate. The software has the following features:

- Supports Verilog/SystemVerilog, VHDL and mixed design input.
- Supports ultra-large-scale design, providing an excellent synthesis solution for complex programmable logic designs.
- Supports inferred mapping of look-up tables, registers, latches, and arithmetic logic units.
- Supports memory inferred mapping and logic resources balancing.
- Supports DSP inferred mapping and logic resources balancing.
- Supports synthesis optimization of FSM
- Supports synthesis attributes and instructions to meet the synthesis requirements in different applications.

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3 GowinSynthesis Usage

3.1 Input and Output of GowinSynthesis

GowinSynthesis reads user's RTL file in the format of project file (.prj), and the project file is automatically generated by Gowin Software. In addition to the specified user RTL file, GowinSynthesis project file also specifies the synthesis device, the user constraints file including attribute constraints, post-synthesis netlists file (.vg), and some synthesis options, such as top module, files including paths, etc.

3.2 Use GowinSynthesis for Synthesis

Right-click "Synthesize" in the "Process" view of Gowin Software, select "Configuration". In the Configuration page, you can specify top module, set include path, and select language versions, and configure options.

Double-click "Synthesize" in "Process" view of Gowin Software to perform synthesis, and the "Output" view will output the synthesis information. The synthesis report and gate level netlist file will be generated after synthesis. Double-click the "Synthesis Report" and "Netlist File" in the "Process" view to check the specific contents.

For the further detailed operation, see <u>SUG100, Gowin Software User</u> <u>Guide</u> > 4.4.3 Synthesize.

3.3 Naming Rules of Objects Pre/Post Synthesis

For user-friendly verification and debugging, GowinSynthesis synthesis tool will reserve the original user RTL design info. in maximum, such as the module info., primitive/module instance name, the user-defined wire/reg name in user designs, etc. For the objects that must be optimized/converted and to be regenerated, the name will be created according to the user-defined wiring name and some derivative rules. The rules are described in the sections below.

3.3.1 Naming of the Post-synthesis Netlist File

The post-synthesis netlist file name depends on the specified output netlist file name in project file (*.prj).

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If the post-synthesis netlist file name is not specified in project file, the name is created as the same as the project file with a .vg suffix.

3.3.2 Naming of the Post-synthesis Netlist Module

The post-synthesis netlist module name is consistent with RTL design name. Modules that are instantiated multiple times are distinguished by the suffix "_idx", and the module's instantiation name is consistent with the RTL design.

3.3.3 Naming of the Post-synthesis Netlist Instance

If there is Instance in user RTL design and it is not optimized in the process of synthesis, the Instance name stays the same in the post-synthesis netlist.

For the Instance generated in the process of synthesis, the Instance name comes from the the external output signal name of the function design module in the user RTL. If the function design module has multiple output signal, the Instance name depends on the first output signal name.

For the Instance generated in the process of synthesis, the Instance name contains the names described above, and they are also followed by a suffix based on type. The "buf" types are suffixed with "_ibuf", "_obuf", "_iobuf", and for others with "_s", the number after "s" is the number of times the name is referenced by the node.

When flatten is specified to output, if the original submodule Instance name needs hierarchy, "/" can be used as hierarchical separator.

3.3.4 Naming of the Post-synthesis Netlist Wiring

For the user-defined wire/reg signal in RTL design, if the signal is not optiminzed in the process of synthesis, the related module name of the post-synthesis netlist stays the same.

In the process of synthesis using GowinSynthesis, some whole functional design modules in some RTL designs will be replaced or optimized. After synthesis, the output signal name of these functional design modules in netlist will be kept. For the internal signal of these modules, the name will be derived from the name of the output signal. The related digital suffix (_idx) will be added on the basis of the original signal name.

When the multi-bit signal name (the bus format) is used as the derived signal name and other signal names or Instance name is derived, the bus bit in the singal name will be kept in the form of "_idx".

When flatten is specified to output, "_" can be used as hierarchical separator.

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4 HDL Code Support

4.1 Register HDL Code Support

4.1.1 An Introduction to Register Features

The registers contain flip-flops and latches.

Flip-flop

The flip-flops are all D flip-flops, and the initial value is assigned when defined. There are two types of reset/set: Synchronous and asynchronous. Synchronous reset/set means that only when the posedge or negedge of CLK arrives, and reset/set is at high level, can the reset/set be completed. Asynchronous reset/set means the level change from low to high of reset/set will lead to the output change immediately, but not controlled by CLK.

Latch

The latches trigger includes high-level trigger and low-level trigger, and the initial value is assigned when defined. In FPGA design, it is best to avoid latches. High level trigger is when the control signal is high; the latch allows the data signal to pass through. Low level trigger is when the control signal is low; latch allows the data signal to pass through.

4.1.2 Constraints Related with Register

You can constrain register by the preserve attribute. When this constraint exists, except the registers that are suspended will be optimized, all the other registers will be preserved in the synthesis results. Please see synthesis results.

4.1.3 Register Code Example

The initial value of Gowin synchronous reset clock flip-flop can only be set to 0. The initial value of synchronous set clock flip-flop can only be set to 1. When the initial value of the synchronous clock flip-flop in the RTL is different from the initial value of Gowin synchronous clock, GowinSynthesis will convert the type of synchronous clock flip-flop based on the initial value in the RTL. Asynchronous clock flip-flop does not be handled. Specific conversion strategies are:

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- 1. RTL is designed as synchronous reset clock flip-flop. When the initial value is set to 1, GowinSynthesis will replace it with synchronous set clock flip-flop. Add related logic to the original synchronous reset signal to realize synchronous set function.
- 2. RTL is designed as synchronous set clock flip-flop. When the initial value is set to 0, GowinSynthesis will replace it with normal flip-flop. Add related logic to the original synchronous set signal as the input of the flip-flop data end.

Not specify the Initial Value of Flip-flop

The only difference between CLK posedge flip-flop and CLK negedge flip-flop is that CLK triggers in different ways, so the following list is only the examples of CLK rising edge flip-flop.

```
Example 1 can be synthesized as synchronous reset clock flip-flop.
```

```
module top (q, d, clk, reset).

input d.

input clk.

input reset.

output q.

reg q_reg.

always @(posedge clk)begin

if(reset)

q_reg<=1'b0.

else

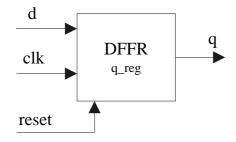
q_reg<=d.

end

assign q = q_reg.
```

Synchronous reset clock flip-flop is as shown in Figure 4-1.

Figure 4-1 Synchronous Reset Clock Flip-flop in Example 1



endmodule

Example 2 can be synthesized as synchronous set flip-flop with clock enable.

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```
module top (q, d, clk, ce, set).

input d.

input clk.

input set.

output q.

reg q_reg.

always @(posedge clk)begin

if(set)

q_reg<=1'b1.

else if(ce)

q_reg<=d.

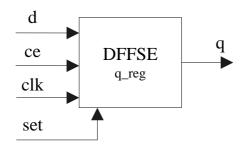
end

assign q = q_reg.

endmodule
```

Synchronous set flip-flop with clock enable is as shown in Figure 4-2.

Figure 4-2 Synchronous Set Flip-flop with Clock Enable in Example 2



Example 3 can be synthesized as asynchronous reset flip-flop with clock enable.

```
module top (q, d, clk, ce, clear).

input d.

input clk.

input ce.

input clear.

output q.

reg q_reg.

always @(posedge clk or posedge clear)begin

if(clear)

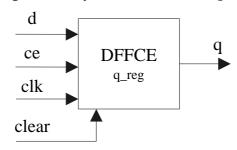
q_reg<=1'b0.
```

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```
else if(ce)
q_reg<=d.
end
assign q = q_reg.
endmodule
```

Asynchronous reset flip-flop with clock enable is as shown in Figure 4-3.

Figure 4-3 Asynchronous Reset Flip-flop with Clock Enable in Example 3



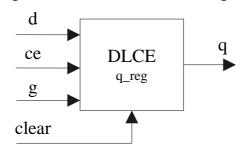
Example 4 can be synthesized as latch with reset and high level enable.

```
module top(d,g,clear,q,ce);
input d,g,clear,ce;
output q;
reg q_reg;
always @(g or d or clear or ce) begin
  if(clear)
        q_reg <= 0;
    else if(g && ce)
        q_reg <= d;
end
assign q = q_reg;
endmodule</pre>
```

The latch with reset and high level enable is shown as in Figure 4-4.

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Figure 4-4 Latch with Reset and High Level Enable in Example 4



Specify the Initial Value of Flip-flop

Example 5 is synchronous reset clock flip-flop with an initial value of 0. Set an initial value of 1 in RTL, which will be synthesized as synchronous set clock flip-flop with an initial value of 1 and a logic circuit for synchronous reset.

```
module top (q, d, clk, reset).

input d.

input clk.

input reset.

output q.

reg q_reg = 1'b1.

always @(posedge clk)begin

if(reset)

q_reg<=1'b0.

else

q_reg<=d.

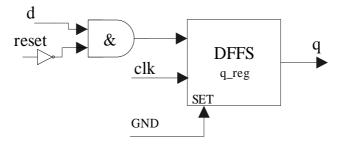
end

assign q = q_reg.

endmodule
```

Synchronous reset clock flip-flop above is as shown in Figure 4-5.

Figure 4-5 Synchronous Reset Clock Flip-flop and Logic Circuit in Example 5



Example 6 is synchronous set clock flip-flop with an initial value of 1, but its initial value is 0 in RTL; and this synchronous set clock flip-flop will

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be synthesized as common clock flip-flop with an initial value of 0 and a logic circuit for synchronous set.

```
module top (q, d, clk, set).

input d.

input clk.

input set.

output q.

reg q_reg = 1'b0.

always @(posedge clk)begin

if(set)

q_reg<=1'b1.

else

q_reg<=d.

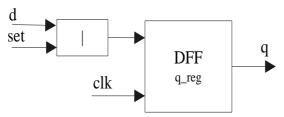
end

assign q = q_reg.

endmodule
```

The common clock flip-flop with the initial value of 0 and logic circuit are shown in Figure 4-6.

Figure 4-6 Common Clock Flip-flop with an Initial Value of 0 and Logic Circuit in Example 6



Example 7 is an asynchronous set flip-flop with an initial value of 1. module top (q, d, clk, ce, preset).

input d.

input clk.

input ce.

input preset.

output q.

 $reg q_reg = 1'b1.$

always @(posedge clk or posedge preset)begin

if(preset)

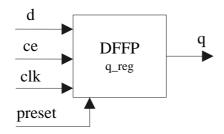
q_reg<=1'b1.

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```
else if(ce)
q_reg<=d.
end
assign q = q_reg.
endmodule
```

Asynchronous set flip-flop above is as shown in Figure 4-7.

Figure 4-7 Asynchronous Set Flip-flop in Example 7



4.2 RAM HDL Code Support

4.2.1 An Introduction to RAM Inference Function

RAM inference is one step in RTL synthesis to infer block memory primitives (BSRAM and SSRAM) in FPGA to implement memory functions in user design so that you can write device-independent RTL or use embedded block ram functionality in FPGA. For RTL memory blocks, GowinSynthesis will infer the RTL that meets the corresponding conditions to RAM module according to RTL description.

If the design needs to implement by BSRAM, the following principles need to be met:

- 1. All output registers have the same control signal.
- 2. RAM must be synchronous memory and can not connect to asynchronous control signal. GowinSynthesis does not support asynchronous RAM.
- 3. It needs to connect registers at read address or output port.

4.2.2 An Introduction to RAM Features

BSRAM

There are four configuration modes for BSRAM: single-port, dual-port, semi-dual-port and read-only. Read mode includes pipeline and bypass. Write mode includes normal, write-through and read-before-write.

SSRAM

There are three configuration modes for SSRAM: Single-port, semi-dual-port and read-only. SSRAM does not support dual-port mode.

4.2.3 Constraints Related with RAM Inference

Syn ramstyle specifies how memory is inferenced, and syn romstyle

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specifies how read-only memory is implemented.

If the design needs to generate SSRAM or BSRAM, please use ram_style, rom_style or syn_srlstyle constraint statement.

4.2.4 RAM Inference Code Example

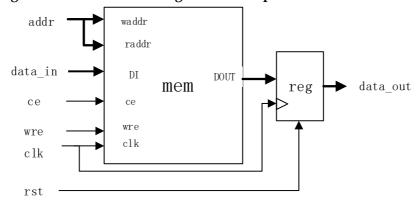
According to the different features of RAM, examples are as follows:

Example 1 is a memory with one write port, one read port and the same read and write address, which can be synthesized to a single port BSRAM in normal mode.

```
module normal(data_out, data_in, addr, clk,ce, wre,rst).
output [7:0]data_out.
input [7:0]data_in.
input [7:0]addr.
input clk,wre,ce,rst.
reg [7:0] mem [255:0].
reg [7:0] data_out.
always@(posedge clk or posedge rst)
if(rst)
   data out <= 0.
else
     if(ce & !wre)
         data_out <= mem[addr].
 always @(posedge clk)
    if (ce & wre)
         mem[addr] <= data in.
endmodule
```

The above single-port BSRAM circuit diagram is shown in Figure 4-8.

Figure 4-8 RAM Circuit Diagram in Example 1



Example 2 is a memory with one write port, one read port and the

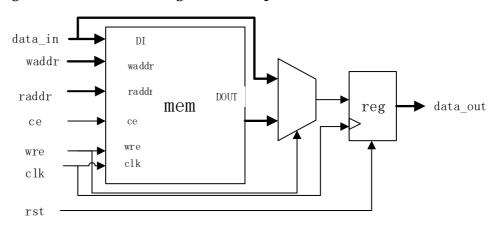
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same read and write address. When wre is 1, input data can be transferred directly to output, which can be synthesized to single-port BSRAM in normal write mode.

```
module wt11(data out, data in, addr, clk, wre,rst);
output [31:0]data_out;
input [31:0]data_in;
input [6:0]addr;
input clk,wre,rst;
reg [31:0] mem [127:0];
reg [31:0] data_out;
always@(posedge clk or posedge rst)
if(rst)
    data out <= 0;
else if(wre)
     data out <= data in;
else
     data_out <= mem[addr];</pre>
always @(posedge clk)
if (wre)
     mem[addr] <= data in;
endmodule
```

The above single-port BSRAM circuit diagram is shown in Figure 4-9.

Figure 4-9 RAM Circuit Diagram in Example 2



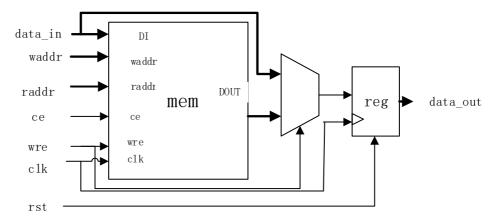
Example 3 is a memory with one write port, one read port and the same read and write address. When wre is 1, input data is written to memory, which can be synthesized to single-port BSRAM in read-before-write mode.

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```
module read_first_01(data_out, data_in, addr, clk, wre);
output [31:0]data_out;
input [31:0]data_in;
input [6:0]addr;
input clk,wre;
reg [31:0] mem [127:0];
reg [31:0] data_out;
always @(posedge clk)
begin
    if (wre)
        mem[addr] <= data_in;
        data_out <= mem[addr];
end
endmodule
```

The above single-port BSRAM circuit diagram is shown in Figure 4-10.

Figure 4-10 RAM Circuit Diagram in Example 3



Example 4 is a memory with two write ports and one read port. One of the two write ports has a wre signal and the other does not. The read port absorbs asynchronous reset register. This example can be synthesized to asynchronous reset dual-port BSRAM with A port in normal write mode and B port in read-before-write mode or in register output read mode.

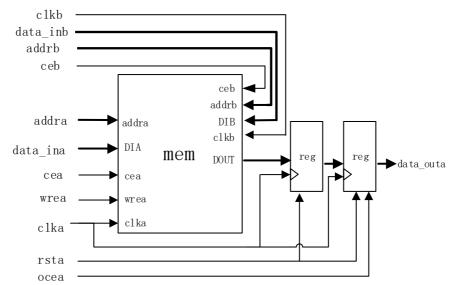
```
module read_first_02_1(data_outa, data_ina, addra, clka, rsta,cea, wrea,ocea, data_inb, addrb, clkb, ceb);
output [17:0]data_outa;
input [17:0]data_ina,data_inb;
input [6:0]addra,addrb;
input clka, rsta,cea, wrea,ocea;
input clkb, ceb;
```

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```
reg [17:0] mem [127:0];
reg [17:0] data_outa;
reg [17:0] data_out_rega,data_out_regb;
always @(posedge clkb)
if (ceb)
   mem[addrb] <= data_inb;
always@(posedge clka or posedge rsta)
if(rsta)
    data_out_rega <= 0;
else begin
    data_out_rega <= mem[addra];
end
always@(posedge clka or posedge rsta)
if(rsta)
    data_outa <= 0;
else if (ocea)
    data_outa <= data_out_rega;
always @(posedge clka)
if (cea & wrea)
   mem[addra] <= data_ina;
endmodule
```

The above dual-port BSRAM circuit diagram is shown in Figure 4-11.

Figure 4-11 RAM Circuit Diagram in Example 4



SUG550-2.0E 15(83)

Example 5 is a memory with one read port and one write port and different read and write addresses, which can be synthesized to semi-dual-port BSRAM in normal write mode or in bypass read mode.

```
module read_first_wp_pre_1(data_out, data_in, waddr, raddr,clk,
rst,ce);
  output [10:0]data_out;
  input [10:0]data_in;
  input [6:0]raddr,waddr;
  input clk, rst,ce;
  reg [10:0] mem [127:0];
  reg [10:0] data_out;
  always@(posedge clk or posedge rst)
  if(rst)
    data_out <= 0;</pre>
```

endmodule

The above semi-dual-port BSRAM circuit diagram is shown in Figure

Figure 4-12 RAM Circuit Diagram in Example 5

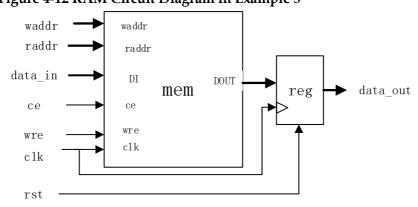
data out <= mem[raddr];

if (ce) mem[waddr] <= data in;

always @(posedge clk)

else if(ce)

4-12.



Example 6 is a memory with one read port and an initial value, which can be synthesized to asynchronous set read-only memory in bypass read mode.

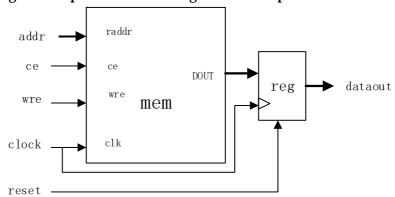
```
module test_invce (clock,ce,oce,reset,addr,dataout);
input clock,ce,oce,reset;
input [5:0] addr;
output [7:0] dataout;
```

SUG550-2.0E 16(83)

```
reg [7:0] dataout;
always @(posedge clock or posedge reset)
if(reset) begin
   dataout <= 0;
end else begin
if (ce & oce) begin
case (addr)
6'b000000: dataout <= 32'h87654321;
6'b000001: dataout <= 32'h18765432;
6'b000010: dataout <= 32'h21876543;
6'b111110: dataout <= 32'hdef89aba;
6'b111111: dataout <= 32'hef89abce:
default: dataout <= 32'hf89abcde:
endcase
end
end
endmodule
```

The above read-only memory circuit diagram is shown in Figure 4-13.

Figure 4-13 pROM Circuit Diagram in Example 6



Example 7 is a memory with shift-register mode, which can be synthesized to simple-dual-port BSRAM in normal mode.

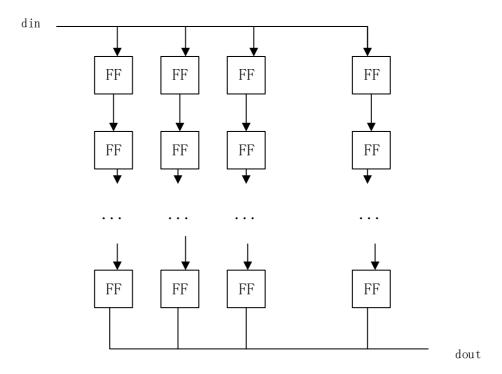
```
module seqshift_bsram (clk, din, dout);
parameter SRL_WIDTH = 65;
parameter SRL_DEPTH = 16;
input clk;
input [SRL_WIDTH-1:0] din;
```

SUG550-2.0E 17(83)

```
output [SRL_WIDTH-1:0] dout;
reg [SRL_WIDTH-1:0] regBank[SRL_DEPTH-1:0];
integer i;
always @(posedge clk) begin
    for (i=SRL_DEPTH-1; i>0; i=i-1) begin
        regBank[i] <= regBank[i-1];
    end
    regBank[0] <= din;
end
assign dout = regBank[SRL_DEPTH-1];
endmodule</pre>
```

The above semi-dual-port BSRAM circuit diagram is shown in Figure 4-14.

Figure 4-14 RAM Circuit Diagram in Example 7



Note!

For more examples, please see <u>GowinSynthesis Inference Coding Template</u> at Gowinsemi official website.

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4.3 DSP HDL Code Support

4.3.1 Basic Introduction to DSP Inference

DSP inference is an algorithm that infers and permutes multiplication and partial addition in user design to DSP in RTL synthesis. When designing RTL, you can either instantiate DSP or write DSP description in device-independent RTL. For the multiplication and addition module of RTL, GowinSynthesis will permute RTL description meeting corresponding conditions with corresponding DSP module.

DSP module has functions of multiplication, addition and register. GowinSynthesis uses logic circuits to realize multiplier functions when the current device does not support DSP modules.

4.3.2 Introduction to DSP Features

Gowin DSP includes multiplier, multiply add accumulator and preadder. The following functions are supported:

- 1. Supports multiplication permutation of different sign bits input
- 2. Supports synchronous or asynchronous mode
- 3. Supports multiplication chain addition
- 4. Supports multiplication accumulation
- 5. Supports pre-add function
- 6. Supports register absorption, including input register, output register, bypass register

4.3.3 Constraints Related with DSP

Syn_dspstyle is used to control the multipliers or specific objects using DSP or logic circuits.

Syn_perserve is used to reserve registers. When register around the DSP has this property, the DSP cannot absorb this register.

For the constraint statements, please see syn_dspstyle and syn_preserve.

4.3.4 DSP Inference Code Example

Example 1 can be synthesized to synchronous set multiplier with sign bit. The input registers are ina and inb. The output register is out_reg, and the bypass register is pp_reg.

```
module top(a,b,c,clock,reset,ce).

parameter a_width = 18.

parameter b_width = 18.

parameter c_width = 36.

input signed [a_width-1:0] a.

input signed [b_width-1:0] b.
```

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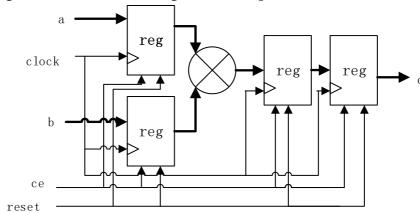
```
input clock.
input reset.
input ce.
output signed [c_width-1:0] c.
reg signed [a width-1:0] ina.
reg signed [b_width-1:0] inb.
reg signed [c_width-1:0] pp_reg.
reg signed [c_width-1:0] out_reg.
wire signed [c_width-1:0] mult_out.
always @(posedge clock) begin
   if(reset)begin
       ina<=0.
       inb<=0.
   end else begin
       if(ce)begin
           ina<=a.
          inb<=b.
       end
   end
end
assign mult_out=ina*inb.
always @(posedge clock) begin
   if(reset)begin
       pp_reg<=0.
   end else begin
       if(ce)begin
          pp_reg<=mult_out.
       end
   end
end
always @(posedge clock) begin
   if(reset)begin
       out_reg<=0.
   end else begin
       if(ce)begin
```

SUG550-2.0E 20(83)

```
out_reg<=pp_reg.
end
end
end
assign c=out_reg.
endmodule
```

The above multiplier circuit diagram is shown in Figure 4-15.

Figure 4-15 DSP Circuit Diagram in Example 1



Example 2 can be synthesized to a multiplier accumulator in asynchronous mode, which has input registers a0_reg, a1_reg, b0_reg and b1_reg, output register s_reg and bypass registers p0_reg and p1_reg.

```
module top(a0, a1, b0, b1, s, reset, clock, ce).
parameter a0_width=18.
parameter a1 width=18.
parameter b0_width=18.
parameter b1_width=18.
parameter s width=37.
input unsigned [a0_width-1:0] a0.
input unsigned [a1 width-1:0] a1.
input unsigned [b0_width-1:0] b0.
input unsigned [b1_width-1:0] b1.
input reset, clock, ce.
output unsigned [s_width-1:0] s.
wire unsigned [s width-1:0] p0, p1, p.
reg unsigned [a0_width-1:0] a0_reg.
reg unsigned [a1_width-1:0] a1_reg.
reg unsigned [b0_width-1:0] b0_reg.
```

SUG550-2.0E 21(83)

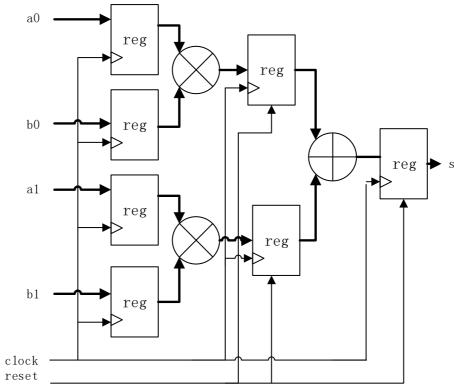
```
reg unsigned [b1_width-1:0] b1_reg.
reg unsigned [s_width-1:0] p0_reg, p1_reg, s_reg.
always @(posedge clock or posedge reset)
begin
   if(reset)begin
       a0_reg <= 0.
       a1\_reg \le 0.
       b0 reg \le 0.
       b1_{reg} <= 0.
   end else begin
       if(ce)begin
           a0\_reg \le a0.
           a1 reg \le a1.
           b0\_reg \le b0.
           b1 reg \le b1.
       end
   end
end
assign p0 = a0_reg*b0_reg.
assign p1 = a1\_reg*b1\_reg.
always @(posedge clock or posedge reset)
begin
   if(reset)begin
       p0_reg <= 0.
       p1 reg \le 0.
   end else begin
       if(ce)begin
           p0\_reg \le p0.
           p1\_reg \le p1.
       end
   end
end
assign p = p0\_reg - p1\_reg.
always @(posedge clock or posedge reset)
begin
```

SUG550-2.0E 22(83)

```
if(reset)begin
    s_reg <= 0.
end else begin
    if(ce) begin
    s_reg <= p.
    end
end
end
assign s = s_reg.
endmodule</pre>
```

The above multiplier accumulator circuit diagram is shown in Figure 4-16.

Figure 4-16 DSP Circuit Diagram in Example 2



Example 3 can be synthesized to two unsigned bit multipliers, which are in chain addition relation.

```
module top(a0, a1, a2, b0, b1, b2, a3, b3, s).

parameter a_width=18.

parameter b_width=18.

parameter s_width=36.

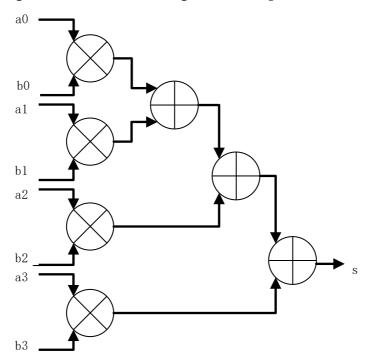
input unsigned [a_width-1:0] a0, a1, a2, b0, b1, b2, a3, b3.
```

SUG550-2.0E 23(83)

```
output unsigned [s_width-1:0] s.
assign s=a0*b0+a1*b1+a2*b2+a3*b3.
endmodule
```

The above multiplier accumulator circuit diagram is shown in Figure 4-17.

Figure 4-17 DSP Circuit Diagram in Example 3



Example 4 can be synthesized to a multiplier with sign-bit 0 and a preadder with sign-bit 0. An input port of this multiplier is connected to the output port b of the preadder.

```
module top(a, bX, bY, p).

parameter a_width=36.

parameter b_width=18.

parameter p_width=54.

input [a_width-1:0] a.

input [b_width-1:0] bX, bY.

output [p_width-1:0] p.

wire [b_width-1:0] b.

assign b = bX + bY.

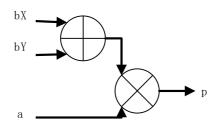
assign p = a*b.

endmodule
```

The above multiplier accumulator circuit diagram is shown in Figure 4-18.

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Figure 4-18 DSP Circuit Diagram in Example 4



Example 5 can be synthesized to a multiplier accumulator with sign-bit 0, and the output register is s.

```
module acc(a, b, s, accload, reset, ce, clock).
parameter a_width=36. //18 36
parameter b width=18. //18 36
parameter s_width=54. //54
input unsigned [a_width-1:0] a.
input unsigned [b width-1:0] b.
input accload, reset, ce, clock.
output unsigned [s width-1:0] s.
wire unsigned [s_width-1:0] s_sel.
wire unsigned [s_width-1:0] p.
reg [s_width-1:0] s.
assign p = a*b.
assign s sel = (accload == 1'b1) ? s : 54'h0000000.
always @(posedge clock)
begin
   if(reset)begin
       s \le 0.
   end else begin
       if(ce)begin
           s \le s_sel + p.
       end
   end
end
endmodule
```

4-19.

The above multiplier accumulator circuit diagram is shown in Figure

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gnd accload clock reset ce

Figure 4-19 DSP Circuit Diagram in Example 5

Note!

For more examples, please see <u>GowinSynthesis_Inference_Coding_Template</u> at Gowinsemi official website.

4.4 Synthesis Implementation Rules for Finite State Machine

4.4.1 Synthesis Rules for Finite State Machine

GowinSynthesis supports the synthesis of Finate State Machine (FSM), and the encoding mode supports one-hot code, gray code, binary code, etc. The synthesis results of finite state machine are related to its encoding mode, code number, code bit width and code constraints. Without specifying encoding constraints, GowinSynthesis automatically selects one-hot code, Gray code, or binary code to implement state machine. With specifying encoding constraints, the code method specified by the constraints should be implemented first. For the code constraints of state machine, please see syn encoding.

Note!

It should be noted that if the output of the finite state machine drives the output port directly, GowinSynthesis will not synthesize it as a state machine, and the code constraints of the state machine will be ignored.

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4.4.2 Finite State Machine Code Example

The synthesis rules for finite state machine are described below.

One-hot Code State Machine

If the state machine adopts one-hot code for coding in RTL design, GowinSynthesis will select one-hot code by default to realize the functions of the state machine with no code constraints. In the case of code constraints, the functions of the state machine are realized according to the encoding mode specified by the constraints. One-hot encoding mode example is as follows:

```
reg [3:0] state,next_state;
parameter state0=4'b0001;
parameter state1=4'b0010;
parameter state2=4'b0100;
parameter state3=4'b1000;
```

In the above example, RTL uses one-hot code and GowinSynthesis uses one-hot code to implement.

Gray Code State Machine

If the state machine adopts gray code for coding in the RTL design, GowinSynthesis will select gray code by default to realize the functions of the state machine with no code constraints. In the case of code constraints, the functions of the state machine are realized according to the encoding mode specified by the constraints. Gray code example is as follows:

```
reg [3:0] state,next_state;
parameter state0=2'b00;
parameter state1=2'b01;
parameter state2=2'b11;
parameter state3=2'b10;
```

In the above example, RTL uses gray code and GowinSynthesis uses gray code to implement.

Binary Code or other Codes State Machines

If the state machine adopts binary code in RTL design, which is neither one-hot code nor gray code, GowinSynthesis will select the corresponding code according to the number of codes and bit width for implementation with no constraints. The selection principle is as follows: If the number of code is greater than the effective bit width of code, binary code will be used for implementation. If the number of code is less than or equal to the effective bit width of code, one-hot code will be used for implementation. In the case of code constraints, the functions of state machine are realized according to the encoding mode specified by the constraints.

Example 1

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```
reg [5:0] state,next_state;

parameter state0= 6'b000001;

parameter state1= 6'b000001;

parameter state2= 6'b000000;

parameter state3= 6'b010101;
```

In the above example, the number of code is 4, the bit width of code is 6, and the effective bit width is 5, so the number of code is less than the effective bit width of code, and the implementation is carried out by one-hot code.

```
Example 2

reg [2:0] state,next_state;

parameter state0=3'b001;

parameter state1=3'b010;

parameter state2=3'b011;

parameter state3=3'b100;
```

In the above example, the number of code is 4, and the effective bit width of code is 3. The number of code is larger than the effective bit width of code, and the implementation is carried out by binary code.

```
Example 3

reg [5:0] state,next_state.

parameter state0= 1,

parameter state1= 3,

parameter state2= 6,

parameter state3= 15.
```

In the above example, the number of code is 4 in decimal, and the effective bit width converted into binary is 4 bits. The number of code is equal to the effective bit width of code, and the implementation is carried out by one-hot code.

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5 Synthesis Constraints Support

Attribute constraints is used to set various attributes of optimization selection, function implement, output netlist format in synthesis so that the synthesis results can better meet the design function and usage. Attributes can be written in constraint files or embedded in source code.

This chapter describes the syntax, scope, and priority of constraints in RTL files and GowinSynthesis Constraint (GSC) files. Verilog files are case-sensitive, so instructions and attributes must be typed exactly as described in the syntax. An attribute constraint must be written in the same line in a constraint statement and can not be separated by breaks.

Syntax of Attribute Constraints in RTL File

Constraints in the RTL file must be added in the definition statement of the constraint object, and placed before the terminating semicolon. The specific syntax is as follows:

object /*synthesis attributeName=value*/;

If the attribute value (value) is a string, it must be enclosed in double quotation marks.

Syntax of Attribute Constraints in GSC

GSC constraints include Instance constraints, Net constraints, Port constraints and global objects constraints. In GSC, if the attribute value is a string, quotation marks are not required. GSC constraints support comments, which use //. The specific syntax is as follows:

INS "object" attributeName=value;

NET "object" attributeName=value;

PORT "object" attributeName=value;

GLOBAL attributeName=value;

The constraint statement begins with INS, and the object must be the name of instance. Instance includes module/entity instance and primitive instance.

The constraint statement begins with NET, and the constraint object must be the NET name.

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The constraint statement begins with PORT, and the constraint object must be the PORT name.

The constraint statement begins with GLOBAL, indicating that the attribute constraint is global.

In GSC, the / is used to distinguish hierarchical levels in names. For example, as shown in Figure 5-1, if you want to add an attribute constraint to the mem signal in the sub_ssram module, it can be expressed as: INS "uut sp/uut ssram/mem" syn ramstyle = block ram

Figure 5-1 Design Hierarchy

Scope of Attribute Constraints

- If an attribute constraint is set at the definition of a top module, the scope of the attribute value is the entire project.
- If an attribute constraint is set at the definition of a sub module, the scope of the attribute value is from the current sub layer to its sub modules.
- If an attribute constraint is set at the instantiation of a sub module, the scope of the attribute value is from the instantiation of the sub layer to the its sub modules.
- If an attribute constraint is set on reg/wire, the scope of the attribute value is that reg/wire.

Each attribute constraint can only be applied to a single constraint object. To constrain multiple objects, the attribute constraint must be added multiple times.

For example, to add attribute constraints to reg dout1 and dout2 in an RTL design, you can use the following methods:

- Method 1: reg dout1 /*synthesis syn_preserve=1*/, dout2 /*synthesis syn_preserve=1*/;
- Method 2: reg dout1 /*synthesis syn_preserve=1*/; reg dout2 /*synthesis syn_preserve=1*/;

Attribute Priority

When the same attribute is used with different values in different locations within the project, priority rules are applied as follows:

 When different attribute constraint values are applied to the same location (e.g., constraining the top module at the same time), the priority of the attribute constraints is as follows:

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Constraints set in GSC > Constraints set in RTL > Configuration in the IDE interface.

 When different attribute constraint values are used at different locations in the design, the priority of the attribute constraints is as follows:

Constraints on registers/wires > Constraints on submodules in GSC > Constraints on submodules in RTL during its definition > Constraints on submodules in RTL during its instantiation > Constraints when defining the top module.

5.1 syn_black_box

Description

Specify a module or component as a black box. During synthesis, a black box module only defines its interface, while its contents are not accessible or optimized. A module can be designated as a black box regardless of whether it is empty or not.

Attribute Value

Table 5-1 Attribute Value

Default	Global Attribute	Object
N/A	No	module/component

Syntax

Table 5-2 Syntax Example

Verilog Constraint Syntax	object /* synthesis syn_black_box */; VerilogExample
VHDL Constraint Syntax	attribute syn_black_box: boolean; attribute syn_black_box of object: objectType is true; VHDL Example

Note!

object can only be a sub module/entity.

Examples

Verilog Constraint Example

```
module top(clk, in1, in2, out1, out2); input clk; input [1:0]in1; input [1:0]in2; output [1:0]out1; output [1:0]out2; add U1(clk, in1, in2, out1); black_box_add U2 (in1, in2, out2); endmodule
```

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```
module add (clk, in1, in2, out1);
input clk;
input [1:0]in1;
input [1:0]in2;
output [1:0]out1;
reg [1:0]out1;
always @(posedge clk)
begin
   out1 <= in1 + in2;
end
endmodule
module black_box_add(A, B, C)/* synthesis syn_black_box */;
input [1:0]A;
input [1:0]B;
output [1:0]C;
endmodule
VHDL Constraint Example
library ieee;
use ieee.std logic 1164.all;
use ieee.std_logic_unsigned.all;
entity mux2_1_top is
port(
     dina: in bit;
     dinb: in bit;
     sel: in bit;
     dout : out bit
);
end mux2_1_top;
architecture Behavioral of mux2_1_top is
component mux2_1
port(
     dina: in bit;
```

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```
dinb: in bit;
    sel: in bit;
    dout: out bit
);
end component;
    attribute syn black box: boolean;
    attribute syn_black_box of mux2_1 : component is true;
begin
    u mux2 1: mux2 1
    port map(
        dina => dina,
         dinb => dinb,
        sel => sel,
        dout => dout
    );
end Behavioral;
```

5.2 black_box_pad_pin

Description

The specified IO pads of black box are visible to the external environment. This attribute is used in conjunction with syn_black_box and only applies to the IO pads of the black box.

Attribute Value

Table 5-3 Attribute Value

Default	Global Attribute	Object
N/A	No	module/component

The table below lists the configurable attribute value and its corresponding function.

Table 5-4 Configurable Attribute Value and its Corresponding Function

•	
Value	Function
portList	Specifies the ports of the black box as I/O pads.

Syntax

Table 5-5 Syntax Example

J 1	
Verilog Constraint Syntax	object /* synthesis syn_black_box black_box_pad_pin = portList */;
	Verilog Example

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VHDL Constraint Syntax	attribute syn_black_box: boolean;
	attribute syn_black_box of object : objectType is true;
	attribute black_box_pad_pin : string;
	attribute black_box_pad_pin of object: objectType is
	portList;
	VHDL Example

Note!

The portList enclosed in double quotation marks is a comma-separated list without spaces, specifying the names of the ports on the black box.

Examples

Verilog Constraint Example

```
module top(clk, in1, in2, out1, out2, D, E);
input clk;
input [1:0]in1;
input [1:0]in2;
output [1:0]out1;
output [1:0]out2;
output D,E;
add U1(clk, in1, in2, out1);
black_box_add U2 (in1, in2, out2, D, E);
endmodule
module add (clk, in1, in2, out1);
input clk;
input [1:0]in1;
input [1:0]in2;
output [1:0]out1;
reg [1:0]out1;
always @(posedge clk)
begin
   out1 \leq in1 + in2;
end
endmodule
module black_box_add(A, B, C, D, E)/* synthesis syn_black_box
black_box_pad_pin="D,E" */;
input [1:0]A;
```

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```
input [1:0]B;
 output [1:0]C;
 output D,E;
 endmodule
VHDL Constraint Example
 library ieee;
 use ieee.std_logic_1164.all;
 entity top is
 generic (width : integer := 4);
 port (in1,in2 : in std logic vector(width downto 0);
      clk: in std logic;
      q : out std_logic_vector (width downto 0)
 );
 end top;
 architecture top1 arch of top is
 component test is
 generic (width1 : integer := 2);
 port (in1,in2: in std logic vector(width downto 0);
      clk: in std logic;
      q: out std logic vector (width downto 0)
 );
 end component;
 attribute syn black box: boolean;
 attribute syn black box of test: component is true;
 attribute black_box_pad_pin : string;
 attribute black box pad pin of test: component is "q";
 begin
     test123: test generic map (width) port map (in1,in2,clk,q);
 end top1_arch;
```

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5.3 full_case

Description

full_case is only used in Verilog RTL designs. Adding this attribute after a case, casex, or casez statement indicates that all possible values are covered, and no additional hardware is required to retain signal values.

Syntax

Table 5-6 Syntax Example

endmodule

Verilog Constraint	object /*synthesis full_case*/
Syntax	<u>Verilog Example</u>

Example

Verilog Constraint Example
module top(out, a, b, c, d, select);
output out;
input a,b,c,d;
input [3:0] select;
reg out;
always @(select or a or b or c or d)
begin
casez(select) /*synthesis full_case*/
4'b???1: out=a;
4'b???1: out=b;
4'b???: out=c;
4'b1???: out=d;
endcase
end

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5.4 parallel_case

Description

It is only used in Verilog RTL design. Adding this attribute after a case, casex, or casez statement indicates the use of a parallel multiplexer structure instead of a priority-encoded structure.

By default, case statements operate in priority order, encoding only the highest-priority signal among multiple input signals. However, the parallel_case enforces the use of a parallel multiplexer structure rather than a priority-encoded structure.

Syntax

Table 5-7 Syntax Example

endmodule

Verilog Constraint Syntax	object /*synthesis parallel_case*/
	<u>Verilog Example</u>

Example

 Verilog Constraint Example module test (out, a, b, c, d, select); output out; input a, b, c, d; input [3:0] select; reg out; always @(select or a or b or c or d) begin casez (select) /* synthesis parallel_case */ 4'b???1: out = a;4'b??1?: out = b;4'b?1??: out = c;4'b1???: out = d:default: out = 1'b0; endcase end

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5.5 syn_dspstyle

Description

Specify that the multiplier is implemented using either a dedicated DSP hardware module or logic circuits. By default, structures such as multiplication, multiply-add/subtract, multiply-accumulate, multiply-cascade, multiplier-based pre-add/subtract, multiplier-based shifting, and large add/subtract operations are inferred as DSP hardware modules.

Attribute Value

Table 5-8 Attribute Value

Global Attribute	Object
Yes	module/entity, wire/reg/signal

The table below lists the configurable attribute value and its corresponding function.

Table 5-9 Configurable Attribute Value and its Corresponding Function

Value	Function
dsp	Specifies the implementation of the multiplier as a DSP hardware module.
logic	Specifies the implementation of the multiplier as logic circuits.

Syntax

Table 5-10 Syntax Example

GSC Constraint Syntax	INS "object" syn_dspstyle = value
	GLOBAL syn_dspstyle = value
	GSC Example
Verilog Constraint Syntax	object /* synthesis syn_dspstyle = "value" */;
	<u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_dspstyle : string;
	attribute syn_dspstyle of object : objectType is "value";
	VHDL Example

Note!

If the attribute constraint with a value of dsp is applied to a device that does not support DSP hardware modules, the synthesis tool will issue a warning indicating that the attribute constraint is invalid.

Examples

GSC Constraint Example

Example 1: Specifies the implementation of the instance as logic circuits.

INS "temp" syn_dspstyle=logic;

INS "aa0/mult/c" syn_dspstyle=logic;

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Example 2: Specifies the implementation of all global multipliers as DSP hardware modules.

GLOBAL syn_dspstyle=dsp;

Verilog Constraint Example

Example 1: Specifies the implementation of all multipliers in the module as logic.

```
module mult(a,b,a0,b0,a1,b1,c,r,en,r0,r1)/*synthesis syn dspstyle =
    "logic" */;
    input [7:0] a,b;
    input [7:0] a0,b0;
    input [7:0] a1,b1;
    output [15:0]r;
    output[15:0]r0,r1;
    input [15:0]c;
    input en;
    wire [15:0] temp;
    assign temp = a*b;
    assign r = en ? temp:c;
    test aa0(a0,b0,r0,a1,b1,r1);
    endmodule
    module test(a,b,c,d,e,f);
    input [7:0]a,b,d,e;
    output [15:0] c,f;
    assign c=a*b;
    test222 mult(d,e,f);
    endmodule
    module test222(a,b,c);
    input [7:0] a,b;
    output [15:0]c;
    assign c = a*b;
    endmodule
    Example 2: Specifies the implementation of the selected multiplier as
logic.
```

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module mult(a,b,a0,b0,a1,b1,c,r,en,r0,r1);

```
input [7:0] a,b;
    input [7:0] a0,b0;
    input [7:0] a1,b1;
    output [15:0]r;
    output[15:0]r0,r1;
    input [15:0]c;
    input en;
    wire [15:0] temp/*synthesis syn_dspstyle = "logic" */;
    assign temp = a*b;
    assign r = en ? temp:c;
    test aa0(a0,b0,r0,a1,b1,r1);
    endmodule
    module test(a,b,c,d,e,f);
    input [7:0]a,b,d,e;
    output [15:0] c,f;
    assign c=a*b;
    test222 mult(d,e,f);
    endmodule
    module test222(a,b,c);
    input [7:0] a,b;
    output [15:0]c;
    assign c = a*b;
    endmodule
   VHDL Constraint Example
    Example 1: Specifies the implementation of the selected multiplier as
logic.
    library ieee;
    use ieee.std_logic_1164.all;
    use ieee.numeric_std.all;
    entity Mult is
    port(
         clk: in bit;
```

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```
ce: in bit;
    x: in signed(11 downto 0);
    y: in signed(11 downto 0);
    result: out signed(23 downto 0));
    attribute syn dspstyle: string;
    attribute syn dspstyle of result: signal is "logic";
end Mult;
architecture Behavior of Mult is
    signal x1 : signed(11 downto 0);
    signal y1 : signed(11 downto 0);
begin
     process(clk,ce)
     begin
         if(clk'event and clk = '1' and ce = '1')then
              x1 <= x;
              y1 \le y;
         end if;
     end process;
     result \leq x1 * y1;
end Behavior;
```

5.6 syn_encoding

Description

Specify the encoding method for the finite state machine. By default, the encoding method of the synthesis result matches the encoding method used in the design.

Attribute Value

Table 5-11 Attribute Value

Global Attribute	Object
No	reg/type

The table below lists the configurable attribute value and its corresponding function.

Table 5-12 Configurable Attribute Value and its Corresponding Function

	1 8
Value	Function
onehot	Specifies the encoding method for the finite state machine as

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Value	Function
	one hot.
gray	Specifies the encoding method for the finite state machine as Gray.

Syntax

Table 5-13 Syntax Example

Verilog Constraint Syntax	object /* synthesis syn_encoding = "value" */; <u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_encoding : string; attribute syn_encoding of object : objectType is "value" ; VHDL Example

Note!

value: The encoding method for the state machine. The encoding methods currently supported by Verilog are onehot, while VHDL supports onehot and gray encoding methods.

Examples

```
Verilog Example
Specify the encoding method for the finite state machine as one hot.
module test (clk,rst,data,out);
input clk,rst,data;
output out;
reg out;
reg [2:0]ps /*synthesis syn encoding="onehot"*/;
reg [2:0]ns;
parameter S0=3'b000, S1=3'b001, S2=3'b010, S3=3'b011, S4=3'b100,
S5=3'b101, S6=3'b110;
always @(posedge clk or posedge rst) begin
if(rst)
     ps \le S0;
else
     ps <= ns; end
always @(ps or data)
begin
     ns = S0;
     case (ps)
         S0: if(data)
              ns = S1;
```

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```
else ns = S0;
         S1: if(data)
             ns = S1;
         else ns = S2;
         S2: if(data)
             ns = S1;
         else ns = S3;
         S3: if(data)
             ns = S4;
         else ns = S0;
         S4: if(data)
             ns = S5;
         else ns = S2;
         S5: if(data)
             ns = S1;
         else ns = S6;
         S6: if(data)
             ns = S1;
         else ns = S3;
         default: ns = S0;
    endcase
end
always @(ps or data) begin
if ((ps == S6) && (data == 1))
    out=1;
else
    out=0;
end
endmodule
```

VHDL Example

Specify the encoding method for the finite state machine as Gray. library ieee; use ieee.std_logic_1164.all; use ieee.std_logic_unsigned.all;

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```
entity top is
    port(
         clk: in std_logic;
         rst: in std logic;
         sel: in std logic vector(1 downto 0);
         a : in std_logic_vector(7 downto 0);
         b: in std_logic_vector(7 downto 0);
         qout: out std_logic_vector(7 downto 0)
    );
end entity;
architecture rtl of top is
    type state value is ($5,$4,$3,$2,$1,$0);
    signal curr_state:state_value;
    signal next_state:state_value;
    attribute syn_encoding : string;
    attribute syn_encoding of state_value : type is "gray";
begin
    process(clk,rst)begin
         if(rst='1')then
              curr_state<=S0;
         else
              if(rising_edge(clk))then
                  curr state <= next state;
             end if;
         end if;
    end process;
    process(sel,curr state)begin
         next state <= S0;
         case curr_state is
             when S0 =>
                  if(sel ="00")then
                       next state <= S1;
```

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```
else
             next_state <= S0;
         end if;
    when S1 =>
         if(sel ="01")then
             next_state <= S2;
         else
             next_state <= S1;
         end if;
    when S2 =>
         if(sel ="10")then
             next_state <= S3;
         else
             next state <= S2;
         end if;
    when S3 =>
         if(sel ="11")then
             next_state <= S4;
         else
             next_state <= S3;
         end if;
    when S4 =>
         if(sel ="00")then
             next_state <= S4;
         else
             next state <= S5;
         end if;
    when S5 =>
         if(sel ="01")then
             next state <= S5;
         else
             next_state <= S0;
         end if;
    when others=>next_state <= S0;
end case;
```

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```
end process;
     process(clk,rst)begin
          if(rst='1')then
               qout<=(others=>'0');
          else
               if(rising_edge(clk))then
                    case curr_state is
                         when S0 \Rightarrow qout \ll a+'1';
                         when S1 => qout <= b-'1';
                         when S2 \Rightarrow qout \ll a;
                         when S3 \Rightarrow qout \leq b;
                         when S4 \Rightarrow qout \ll a+b;
                         when S5 => qout <= "10101010";
                         when others=>qout <= a-b;
                    end case;
              end if;
         end if;
    end process;
end rtl;
```

5.7 syn_insert_pad

Description

Specify whether to insert an I/O buffer, and this attribute can only be specified in GSC.

Attribute Value

The table below lists the configurable attribute value and its corresponding function.

Table 5-14 Configurable Attribute Value and its Corresponding Function

Value	Function
0	Remove I/O buffer
1	Insert I/O buffer

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Syntax

Table 5-15 Syntax Example

GSC Constraint	PORT "object" syn_insert_pad=value;
Syntax	GSC Example

Note!

The object can only be a port. This constraint only applies to input ports or output ports and does not apply to inout ports.

Example

GSC Constraint Example

Example 1: Insert the I/O buffer.

PORT "out" syn_insert_pad = 1;

Example 2: Remove the I/O buffer.

PORT "out" syn_insert_pad = 0;

5.8 syn_keep

Description

Specify the net as a placeholder and retains it without optimization. This attribute can preserve nets that may be removed during the synthesis, preventing the merging of duplicate cells during optimization.

Attribute Value

Table 5-16 Attribute Value

Default	Global Attribute	Object
N/A	No	wire/signal, port, combinational logic

The table below lists the configurable attribute value and its corresponding function.

Table 5-17 Configurable Attribute Value and its Corresponding Function

Value	Function	
0	Allows net optimization	
1	Preserve net without optimization	

Syntax

Table 5-18 Syntax Example

Verilog Constraint Syntax	object /* synthesis syn_keep = value */; <u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_keep : integer; attribute syn_keep of object : objectType is value; VHDL Example

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Difference between syn_keep and syn_preserve

Table 5-19 Difference between syn_keep and syn_preserve

syn_keep	Only applies to nets and combinational logic. This attribute can preserve the specified net during synthesis without optimization.
syn_preserve	Only applies to registers. This attribute prevents the register from being optimized or absorbed.

Examples

```
Verilog Constraint Example
 Specifies that the wires top1 and top2 are not be optimized.
 module test (out1, out2, clk, in1, in2);
 output out1, out2;
 input clk;
 input in1, in2;
 wire and out;
 wire top1 /*synthesis syn keep=1*/;
 wire top2 /*synthesis syn keep=1*/;
 reg out1, out2;
 assign and_out=in1&in2;
 assign top1=and out;
 assign top2=and out | in1;
 always @(posedge clk)begin
      out1<=top1;
      out2<=top2;
 end
 endmodule
 VHDL Constraint Example
 Specifies that signal tmp0, tmp1 are not be optimized.
 library ieee;
 use ieee.std_logic_1164.all;
 entity mux2_1 is
      port(
          dina: in bit;
          dinb: in bit;
          sel: in bit;
```

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```
dout0 : out bit;
         dout1: out bit
    );
end mux2 1;
architecture Behavioral of mux2_1 is
    signal tmp0 : bit;
    signal tmp1: bit;
    attribute syn keep: integer;
    attribute syn keep of tmp0 : signal is 1;
    attribute syn_keep of tmp1 : signal is 1;
begin
    tmp0 <= dina when sel = '0' else dinb;
    tmp1 <= dinb when sel = '0' else dina;
    dout0 \le tmp0;
    dout1 \le tmp1;
end Behavioral;
```

5.9 syn_looplimit

Description

Specify the maximum number of loops in the design. By default, this limit is set to 2000.

Syntax

Table 5-20 Syntax Example

GSC Constraint Syntax	GLOBAL syn_looplimit=value	
	GSC Example	

Note!

The GSC constraint syntax does not support VHDL's for loop, but while loop can be constrained.

Example

```
GSC Constraint Example
GLOBAL syn_looplimit=3000
```

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5.10 syn_maxfan

Description

Specify the maximum fanout. This attribute can be applied to modules, ports, and signals (wire/reg/signal), but it does not apply to clock signals, control enable signals, or reset/set signals. To achieve the specified maximum fanout value, registers or other logic resources may need to be duplicated.

Attribute Value

Table 5-21 Attribute Value

Default	Global Attribute	Object
N/A	Yes	module/entity, wire/reg/signal, port

Syntax

Table 5-22 Syntax Example

GSC Constraint Syntax	INS "object" syn_maxfan=value; NET "object" syn_maxfan=value; GLOBAL syn_maxfan=value; GSC Example
Verilog Constraint Syntax	object /* synthesis syn_maxfan = value */; <u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_maxfan : integer; attribute syn_maxfan of object : objectType is value; VHDL Example

Note!

The GSC constraint syntax does not support module.

Examples

GSC Constraint Example

Example 1: Specifies the maximum fanout of the instance as 10.

INS "d" syn maxfan=10;

Example 2: Specifies the global maximum fanout as 100.

GLOBAL syn maxfan=100;

Example 3: Specifies the maximum fanout of the instance as 10.

INS "aa0/mult/d" syn maxfan=10;

Example 4: Specifies the maximum fanout of the net as 10.

NET "aa0/mult/d" syn maxfan=10;

Verilog Constraint Example

Example 1: Specifies the maximum fanout of all instances within the module, except for the clock (clk), as 3.

module test(a, b,sel,clk,c) /*synthesis syn maxfan=3*/;

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```
input [7:0] a;
  input [7:0] b;
  input sel;
  input clk;
  output reg [7:0] c;
  always @ (posedge clk) begin
      c <= sel ? a : b;
  end
  endmodule
  Example 2: Specifies the maximum fanout of sel as 3.
  module test(a, b,sel,clk,c);
  input [7:0] a;
  input [7:0] b;
  input sel/*synthesis syn maxfan=3*/;
  input clk;
  output reg [7:0] c;
  always @ (posedge clk) begin
      c <= sel ? a : b;
  end
  endmodule
VHDL Constraint Example
  Example 1: Specifies the maximum fanout of sel as 3.
  library ieee;
  use ieee.std_logic_1164.all;
  use ieee.numeric std.all;
  entity test is
      generic (
           n:integer:=10;
           m:integer:=7
      );
      port (
           a: in std_logic_vector(7 downto 0);
```

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```
b: in std_logic_vector(7 downto 0);
          sel: in std logic;
          clk: in std_logic;
          c: out std logic vector(7 downto 0)
     );
     attribute syn maxfan: integer;
     attribute syn_maxfan of sel : signal is (n-m);
end test;
architecture rtl of test is
begin
process (clk) begin
     if (clk'event and clk = '1') then
          if (sel = '1') then
              c <= a;
          else
              c \le b;
          end if;
     end if;
end process;
end rtl;
```

5.11 syn_netlist_hierarchy

Description

Specify whether to generate a hierarchical netlist. By default, the synthesis tool generates a hierarchical netlist.

Attribute Value

Table 5-23 Attribute Value

Default	Global Attribute	Object
1	Yes	module/entity

The table below lists the configurable attribute value and its corresponding function.

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Table 5-24 Configurable Attribute Value and its Corresponding Function

Value	Function
0	Flattens the hierarchical netlist for output.
1	Generates a hierarchical netlist.

Syntax

Table 5-25 Syntax Example

GSC Constraint Syntax	GLOBAL syn_netlist_hierarchy=value; GSC Example
Verilog Constraint Syntax	object /* synthesis syn_netlist_hierarchy = value */; Verilog Example
VHDL Constraint Syntax	attribute syn_netlist_hierarchy: integer; attribute syn_netlist_hierarchy of object : objectType is value; VHDL Example

Note!

The specified object can only be the top module/entity.

Examples

GSC Constraint Example
 GLOBAL syn_netlist_hierarchy=0;

Verilog Constraint Example module fu_add (a,b,cin,su,cy); input a,b,cin; output su,cy;
assign su = a ^ b ^ cin; assign cy = (a & b) | ((a ^ b) & cin); endmodule

module rca_adder (A,B,CIN,SU,COUT); input [1:0] A,B; input CIN; output [1:0] SU; output COUT;

wire CY; fu_add FA0(.su(SU[0]),.cy(CY),.cin(CIN),.a(A[0]),.b(B[0])); fu_add FA1(.su(SU[1]),.cy(COUT),.cin(CY),.a(A[1]),.b(B[1]));

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endmodule

```
module rp_top (A1, B1,CIN,SUM,COUT)/*synthesis
syn netlist hierarchy=1 */;
    input [7:0] A1, B1;
    input CIN;
    output [7:0] SUM;
    output COUT;
    wire [2:0] CY1;
    rca adder RA0
(.SU(SUM[1:0]),.COUT(CY1[0]),.CIN(CIN),.A(A1[1:0]),.B(B1[1:0]));
    rca adder RA1
(.SU(SUM[3:2]),.COUT(CY1[1]),.CIN(CY1[0]),.A(A1[3:2]),.B(B1[3:2]));
    rca adder RA2
(.SU(SUM[5:4]),.COUT(CY1[2]),.CIN(CY1[1]),.A(A1[5:4]),.B(B1[5:4]));
    rca adder RA3
(.SU(SUM[7:6]),.COUT(COUT),.CIN(CY1[2]),.A(A1[7:6]),.B(B1[7:6]));
    endmodule
  VHDL Constraint Example
    library ieee;
    use ieee.std logic 1164.all;
    use ieee.std_logic_unsigned.all;
    entity mux4_1_top is
    port(dina: in bit;
        dinb: in bit;
        sel:in bit;
        dout : out bit);
    attribute syn_netlist_hierarchy: integer;
    attribute syn netlist hierarchy of mux4 1 top: entity is 0;
    end mux4 1 top;
    architecture Behavioral of mux4_1_top is
    component mux2 1
    port(dina : in bit;
        dinb: in bit;
```

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```
sel: in bit;
    dout : out bit);
end component;
begin
    u_mux2_1: mux2_1
    port map(dina => dina,
             dinb => dinb,
             sel => sel,
             dout => dout);
end Behavioral;
entity mux2_1 is
    port(dina: in bit;
         dinb: in bit;
         sel: in bit;
         dout : out bit);
end mux2_1;
architecture Behavioral of mux2_1 is
begin
    dout <= dina when sel = '0' else dinb;
end Behavioral;
```

5.12 syn_preserve

Description

Specify whether to optimize the register.

Attribute Value

Table 5-26 Attribute Value

Default	Global Attribute	Object
0	Yes	module/entity, module/entity instance,
		reg/signal

The table below lists the configurable attribute value and its corresponding function.

Table 5-27 Configurable Attribute Value and its Corresponding Function

Value	Function
0	Allows to optimize register.
1	Preserves register without optimization

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Syntax

Table 5-28 Syntax Example

GSC Constraint Syntax	INS "object" syn_preserve=value;
	GLOBAL syn_preserve=value;
	GSC Example
Verilog Constraint Syntax	object /* synthesis syn_preserve = value */;
	<u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_preserve : integer;
	attribute syn_preserve of object : objectType is value;
	VHDL Example

Examples

```
GSC Constraint Example
  Example 1: Specifies reg1 without optimization.
  INS "reg1" syn preserve = 1;
  Example 2: Preserves all registers in the design.
  GLOBAL syn_preserve = 1;
Verilog Constraint Example
  Example 1: Preserves all registers in the module.
  module test (out1,out2,clk,in1,in2)/*synthesis syn preserve = 1*/;
  output out1, out2;
  input clk;
  input in1, in2;
  reg out1;
  reg out2;
  reg reg1;
  reg reg2;
  always @(posedge clk)begin
      reg1 <= in1 & in2;
      reg2 <= in1& in2;
      out1 <= !reg1;
      out2 <= !reg1 & reg2;
  end
  endmodule
  Example 2: Specifies reg1 without optimization.
  module test (out1,out2,clk,in1,in2);
  output out1, out2;
  input clk;
```

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```
input in1, in2;
 reg out1;
 reg out2;
 reg reg1/*synthesis syn preserve = 1*/;
 reg reg2;
 always @(posedge clk)begin
      reg1 <= in1 & in2;
      reg2 <= in1& in2;
      out1 <= !reg1;
      out2 <= !reg1 & reg2;
 end
 endmodule
VHDL Constraint Example
 Example1: Preserves reg1.
 library ieee;
 use ieee.std_logic_1164.all;
 entity syn_test is
      port (out1 : out std_logic;
          out2 : out std logic;
          in1,in2,clk : in std_logic);
 end syn test;
 architecture behave of syn_test is
      signal reg1 : std_logic;
      signal reg2 : std_logic;
      attribute syn_preserve : integer;
      attribute syn preserve of reg1: signal is 1;
 begin
 process
 begin
      wait until clk'event and clk = '1';
      reg1 <= in1 and in2;
      reg2 <= in1 and in2;
      out1 <= reg1;
      out2 <= reg1 and reg2;
 end process;
```

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end behave;

5.13 syn_probe

Description

This attribute constraint is used to test and debug internal signals in the design by inserting probe points. The specified probe points will appear as ports in the top-level port list.

Attribute Value

Table 5-29 Attribute Value

Default	Global Attribute	Object
N/A	No	wire/reg/signal

The table below lists the configurable attribute value and its corresponding function.

Table 5-30 Configurable Attribute Value and its Corresponding Function

Value	Function
0	Probing is not allowed.
1	Inserts a probe point, automatically generating the probe port name based on the net name.
portName	Inserts a probe point with a specified name.

Syntax

Table 5-31 Syntax Example

Verilog Constraint Syntax	object /* synthesis syn_probe = "value" */; Verilog Example
VHDL Constraint Syntax	attribute syn_probe: string; attribute syn_probe of object: objectType is "value"; VHDL Example

note!

The value of "value" cannot be the same as the object name or the module's port name

Examples

Verilog Constraint Example

After setting this attribute constraint, probe_alu_tmp will be listed in the top-level output port list.

```
module alu(out1, opcode, clk, a, b, sel);
output [7:0] out1;
input [2:0] opcode;
input [7:0] a, b;
input clk, sel;
```

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```
reg [7:0] alu_tmp/*synthesis syn_probe=1*/;
    reg [7:0] out1;
    always @(opcode or a or b or sel)
    begin
         case (opcode)
             3'b000: alu tmp <= a+b;
             3'b001: alu tmp <= a-b;
             3'b010: alu tmp \leq a^b;
             3'b100: alu_tmp <= sel ? a:b;
             default: alu tmp<= a | b;
         endcase
    end
    always @(posedge clk)
         out1 <= alu tmp;
    endmodule
   VHDL Constraint Example
    After setting this attribute constraint, probe_string will be listed in the
top-level output port list.
    library ieee;
    use ieee.std_logic_1164.all;
    entity halfadd is
    port(a,b: in std logic;
         s,c : out std_logic);
    end halfadd;
    architecture add of halfadd is
         signal probe tmp: std logic;
         attribute syn_probe: string;
         attribute syn probe of probe tmp: signal is "probe string";
    begin
         s \le a \times b;
         probe tmp <= a and b;
         c <= probe_tmp;
    end;
```

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5.14 syn_radhardlevel

Description

This attribute constraint is used to specify Triple Modular Redundancy (TMR) to implement register functions. TMR is a form of redundancy where a module is triplicated, and all three copies receive identical inputs. The outputs of the three modules are connected to a majority voter, which masks errors by following the "majority rule", thereby detecting and masking most soft errors in practical circuits.

Attribute Value

Table 5-32 Attribute Value

Default	Global Attribute	Object
none	Yes	module/entity, reg/signal, module/entity instance

The table below lists the configurable attribute value and its corresponding function.

Table 5-33 Configurable Attribute Value and its Corresponding Function

Value	Function
None (Default)	Uses standard design techniques without TMR.
tmr	Uses TMR. Each register is realized using three flip-flops, whose states are determined through voting. Since additional logic is inserted, this option may impact area and timing. Therefore, when using this option, be sure to check the area and timing objectives.

Syntax

Table 5-34 Syntax Example

GSC Constraint Syntax	GLOBAL syn_radhardlevel=setting_value INS "object" syn_radhardlevel=setting_value GSC Example
Verilog Constraint Syntax	object/* synthesis syn_radhardlevel= setting_value */; <u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_radhardlevel : string; attribute syn_radhardlevel of object: objectType is setting_value; VHDL Example

Examples

GSC Constraint Example

Example 1: Specifies the use of TMR to implement the functions of register reg1.

INS "reg1" syn radhardlevel=tmr

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Example 2: Specifies that TMR is not used to implement any registers globally.

GLOBAL syn_radhardlevel=none

Verilog Constraint Example

Example 1: In the following case, the attribute constraint is added to reg out r, and out r will be triplicated.

```
module top(clk,rst,din,out);
   input clk;
   input rst;
   input din;
   output out;
   reg out r/*synthesis syn radhardlevel=tmr*/;
   assign out=out r;
   always@(posedge clk or posedge rst)begin
        if(rst)begin
             out r <= 0;
        end
        else begin
             out r<=din;
        end
   end
   endmodule
    Example 2: In the following case, the attribute constraint is added to
the module, and all the registers in this module will be triplicated.
   module top(clk,rst,ina,inb,douta,doutb)/*synthesis
syn radhardlevel="tmr"*/;
   input clk;
   input rst;
   input ina,inb;
   output douta, doutb;
   reg douta, doutb;
   always@(posedge clk)begin
        if(rst)begin
```

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```
douta<=0;
        end
        else begin
            douta<=ina;
        end
   end
   always@(posedge clk)begin
        doutb<=inb;
   end
   endmodule
    Example 3: In the following case, the attribute constraint is added to
the top module, and the reg in both the top module and sub module to be
replicated.
   module top(clk,ce,rst,ina,inb,douta,doutb)/*synthesis
syn radhardlevel="tmr"*/;
   input clk;
   input rst,ce;
   input[1:0] ina;
   input inb;
   output reg[1:0] douta;
   output doutb;
   always@(posedge clk)begin
        if(rst)begin
            douta<=0;
        end
        else begin
            if(ce)begin
                 douta<=ina;
            end
        end
   end
   sub uut(
        .clk(clk),
```

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```
.ce(ce),
    .inb(inb),
    .doutb(doutb)
);
endmodule
module sub(clk,ce,inb,doutb);
input clk;
input ce;
input inb;
output reg doutb;
always@(posedge clk)begin
    if(ce)begin
         doutb<=inb;
    end
end
endmodule
```

VHDL Constraint Example

Example 1: In the following case, the attribute constraint is added to the entity, and all the registers within this entity will be triplicated.

```
library ieee;
use ieee.std_logic_1164.all;
use ieee.std_logic_unsigned.all;

entity top is
port(
    clk: in std_logic;
    rst: in std_logic;
    din: in std_logic_vector(1 downto 0);
    dout: out std_logic_vector(1 downto 0)
);
    attribute syn_radhardlevel :string;
    attribute syn_radhardlevel of top: entity is "tmr";
end;
```

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```
architecture rtl of top is
   begin
   process(clk)begin
        if(rising edge(clk))then
             if(rst='1')then
                  dout<="00";
             else
                  dout<=din;
             end if;
        end if;
   end process;
   end;
    Example 2: In the following case, the attribute constraint is added to
the dout reg signal, and the register corresponding to this signal will be
triplicated.
   I library ieee;
   use ieee.std logic 1164.all;
   use ieee.std logic unsigned.all;
   entity top is
   port(
        clk: in std_logic;
        rst: in std logic;
        din: in std logic vector(1 downto 0);
        dout: out std logic vector(1 downto 0)
   );
   end;
   architecture rtl of top is
        signal dout_reg: std_logic_vector(1 downto 0);
        attribute syn radhardlevel :string;
        attribute syn radhardlevel of dout reg: signal is "tmr";
   begin
   process(clk)begin
        if(rising_edge(clk))then
             if(rst='1')then
                  dout reg<="00";
```

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```
else
dout_reg<=din;
end if;
end if;
end process;
dout<=dout_reg;
end;
```

5.15 syn_ramstyle

Description

Specify the implementation for RAM. By default, the synthesis tool provides optimal inference based on the size of the RAM. For inference rules, see the sections of Guideline on BSRAM Coding and Guideline on SSRAM Coding in <u>SUG949</u>, <u>Gowin HDL Coding User Guide</u>.

Attribute Value

Table 5-35 Attribute Value

Default	Global Attribute	Object
block_ram	Yes	module/entity, reg/signal, module/entity instance

The table below lists the configurable attribute value and its corresponding function.

Table 5-36 Configurable Attribute Value and its Corresponding Function

Value	Function
registers	Specifies the implementation of RAM as registers.
block_ram	Specifies the implementation of RAM as BSRAM in the FPGA.
distributed_ram	Specifies the implementation of RAM as SSRAM in the FPGA.
rw_check	Inserts logic around the RAM to prevent undefined outputs during read and write operations on the same address, ensuring that the functional simulation of RTL matches the functional simulation of the netlist.
no_rw_check	Logic is not inserted around the RAM. By default, this function is enabled.

Syntax

Table 5-37 Syntax Example

GSC Constraint Syntax	INS " object " syn_ramstyle = value GLOBAL syn_ramstyle = value
	GSC Example

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Verilog Constraint Syntax	object /* synthesis syn_ramstyle = "value" */;
	<u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_ramstyle : string;
	attribute syn_ramstyle of object : objectType is "value";
	VHDL Example

Note!

If the attribute constraint distributed_ram is applied to a device that does not support SSRAM, the synthesis tool will issue a warning indicating that the attribute constraint is invalid.

Examples

GSC Constraint Example

Example 1: Specifies the implementation of the instance as BSRAM.

INS " object " syn_ramstyle=block_ram

Example 2: Specifies the implementation of all global RAM as SSRAM.

GLOBAL syn_ramstyle=distributed_ram

Verilog Constraint Example

Example 1: Specifies the implementation of all RAMs in the module as BSRAM.

```
module top(data out, data in, addr, clk,ce, wre,rst) /*synthesis
syn ramstyle="block ram"*/;
output [15:0]data out;
input [15:0]data in;
input [2:0]addr;
input clk,wre,ce,rst;
reg [15:0] mem [7:0]={16'h0123,16'h4567,16'h89ab,16'hcdef,
16'h0147,16'h0258,16'h789a,16'h5678};
reg [15:0] data_out=16'h0000;
always@(posedge clk )begin
    if(rst)begin
         data out \leq 0;
    end
    else begin
         if(ce & !wre)begin
             data out <= mem[addr];
         end
    end
end
```

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always @(posedge clk)begin

```
if (ce & wre)begin
        mem[addr] <= data in;
    end
end
endmodule
Example 2: Specifies the implementation of the RAM as registers.
module top(dout, din, ada, adb, clka, cea, clkb, ceb, resetb);
output reg[15:0]dout=16'h0000;
input [15:0]din;
input [9:0]ada, adb;
input clka, cea,clkb, ceb, resetb;
reg [15:0] mem [1023:0] /*synthesis syn_ramstyle="registers"*/;
always @(posedge clka)begin
    if (cea)begin
        mem[ada] <= din;
    end
end
always@(posedge clkb)begin
    if(resetb)begin
        dout \le 0;
    end
    else if(ceb)begin
        dout <= mem[adb];</pre>
    end
end
endmodule
Example 3: rw_check
module normal(data out, data in, addra, addrb, clka, cea, clkb);
parameter DATA_WIDTH = 8;
parameter ADDRESS WIDTH = 8;
output [DATA_WIDTH-1:0]data_out;
input [DATA WIDTH-1:0]data in;
input [ADDRESS_WIDTH-1:0]addra, addrb;
input clka, cea,clkb;
```

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```
reg [DATA_WIDTH-1:0] mem [2**ADDRESS_WIDTH-1:0] /*synthesis
syn ramstyle=" rw check "*/;
   reg[ADDRESS_WIDTH-1:0]addrb_reg;
   always @(posedge clka)begin
        if (cea)begin
            mem[addra] <= data in;
        end
   end
   always @(posedge clkb)begin
        addrb reg<=addrb;
   end
   assign data out=mem[addrb reg];
   endmodule
   VHDL Constraint Example
   Example 1: Specifies the implementation of the RAM as SSRAM.
   library ieee;
   use ieee.std logic 1164.all;
   use ieee.numeric_std.all;
   entity top is
     port(
        dout: out std_logic_vector(15 downto 0);
        din: in std logic vector(15 downto 0);
        ada: in std_logic_vector(9 downto 0);
        adb: in std_logic_vector(9 downto 0);
        clka: in std logic;
        cea: in std logic;
        clkb: in std logic;
        ceb: in std_logic;
        resetb: in std logic
     );
   end top;
   architecture behavioral of top is
     type memory_array is array(0 to 1023) of std_logic_vector(15 downto
   0);
```

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```
signal mem : memory array := (others => (others => '0'));
    attribute syn ramstyle:string;
    attribute syn_ramstyle of mem: signal is " distributed_ram";
  signal dout reg: std logic vector(15 downto 0) := (others => '0');
begin
  process(clka)
  begin
    if rising_edge(clka) then
       if cea = '1' then
         mem(to integer(unsigned(ada))) <= din;</pre>
       end if;
    end if;
  end process;
  process(clkb)
  begin
    if rising_edge(clkb) then
       if resetb = '1' then
         dout reg <= (others => '0');
       elsif ceb = '1' then
         dout reg <= mem(to integer(unsigned(adb)));</pre>
       end if;
    end if;
  end process;
  dout <= dout reg;
end behavioral;
```

5.16 syn_romstyle

Description

Specify the implementation for ROM. By default, the synthesis tool provides optimal inference based on the size of the ROM. For inference rules, see the sections of Guideline on BSRAM Coding and Guideline on SSRAM Coding in *SUG949*, *Gowin HDL Coding User Guide*.

Attribute Value

Table 5-38 Attribute Value

Global Attribute	Object
Yes	module/entity, reg/signal, module/entity instance

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The table below lists the configurable attribute value and its corresponding function.

Table 5-39 Configurable Attribute Value and its Corresponding Function

Value	Function
logic	Specifies the implementation of ROM as logic circuits.
block_rom	Specifies the implementation of ROM as BSRAM in the FPGA.
distributed_rom	Specifies the implementation of ROM as ROM16.

Syntax

Table 5-40 Syntax Example

GSC Constraint Syntax	INS "object" syn_romstyle = value
	GLOBAL syn_romstyle = value
	GSC Example
Verilog Constraint Syntax	object /* synthesis syn_romstyle = "value" */;
	<u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_romstyle : string;
	attribute syn_romstyle of object : objectType is "value";
	VHDL Example

Note!

If an attribute constraint distributed_rom is applied to a device that does not support ROM16, the synthesis tool will issue a warning indicating that the attribute constraint is invalid.

Examples

GSC Constraint Example

Example 1: Specifies the implementation of the instance as BSRAM.

INS "object "syn romstyle=block rom

Example 2: Specifies the implementation of all global ROM as ROM16.

GLOBAL syn romstyle=distributed rom

Verilog Constraint Example

Example 1: Specifies the implementation of all ROMs in the module as ROM16.

```
module top(addr,dataout)/*synthesis
syn_romstyle="distributed_rom"*/;
input [3:0] addr;
output reg dataout=1'h0;
always @(*)begin
case(addr)
4'h0: dataout <= 1'h0;
```

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```
4'h1: dataout <= 1'h0;
       4'h2: dataout <= 1'h1;
       4'h3: dataout <= 1'h0:
       4'h4: dataout <= 1'h1;
       4'h5: dataout <= 1'h1;
       4'h6: dataout <= 1'h0;
       4'h7: dataout <= 1'h0;
       4'h8: dataout <= 1'h0;
       4'h9: dataout <= 1'h1;
       4'ha: dataout <= 1'h0;
       4'hb: dataout <= 1'h0;
       4'hc: dataout <= 1'h1;
       4'hd: dataout <= 1'h0;
       4'he: dataout <= 1'h0;
       4'hf: dataout <= 1'h0;
       default: dataout <= 1'h0;
   endcase
endmodule
```

VHDL Constraint Example

end

Example 1: Specifies the implementation of all memories in the module as BSRAM.

```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL;
use IEEE.STD_LOGIC_ARITH.ALL;
use IEEE.STD LOGIC UNSIGNED.ALL;
entity top is
    port (
        clk: in std_logic;
        rst: in std logic;
        ce: in std logic;
        addr: in std_logic_vector(4 downto 0);
        dout: out std logic vector(31 downto 0)
    );
end top;
```

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```
architecture Behavioral of top is
    signal dout reg : std logic vector(31 downto 0) := (others => '0');
    attribute syn romstyle:string;
    attribute syn romstyle of dout reg : signal is "block rom";
begin
    dout <= dout reg;
    process(clk)
    begin
        if rising edge(clk) then
            if rst = '1' then
                 dout reg \leq (others \Rightarrow '0');
             elsif ce = '1' then
                 case addr is
                     when "00000" => dout reg \leq x"52853FD5";
                     when "00001" => dout reg <= x"38581BD2";
                     when "00010" => dout reg \leq x"040D53E4";
                     when "00011" => dout reg <= x"22CE7D00";
                     when "00100" => dout_reg <= x"73D90E02";
                     when "00101" => dout reg <= x"C0B4BF1C";
                     when "00110" => dout reg \leq x"EC45E626";
                     when "00111" => dout reg \leq x"D9D000D9";
                     when "01000" => dout reg <= x"AACF8574";
                     when "01001" => dout reg \leq x"B655BF16";
                     when "01010" => dout reg \leq x"8C565693";
                     when "01011" => dout reg \leq x"B19808D0";
                     when "01100" => dout reg <= x"E073036E";
                     when "01101" => dout reg <= x"41B923F6";
                     when "01110" => dout reg \leq x"DCE89022";
                     when "01111" => dout reg <= x"BA17FCE1";
                     when "10000" => dout reg <= x"D4DEC5DE";
                     when "10001" => dout reg <= x"A18AD699";
                     when "10010" => dout_reg <= x"4A734008";
                     when "10011" => dout reg \leq x"5C32AC0E";
                     when "10100" => dout reg <= x"8F26BDD4";
                     when "10101" => dout reg <= x"B8D4AAB6";
```

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```
when "10110" => dout reg \leq x"F55E3C77";
                      when "10111" => dout reg \leq x"41A5D418";
                      when "11000" => dout reg \leq x"BA172648";
                      when "11001" => dout reg <= x"5C651D69";
                      when "11010" => dout reg \leq x"445469C3";
                      when "11011" => dout reg \leq x"2E49668B";
                      when "11100" => dout reg <= x"DC1AA05B";
                      when "11101" \Rightarrow dout reg \Rightarrow x"CEBFE4CD";
                      when "11110" => dout reg <= x"1E1F0F1E";
                      when "11111" => dout reg <= x"86FD31EF";
                      when others => dout reg <= x"8E9008A6";
                 end case;
             end if:
        end if:
    end process;
end Behavioral;
```

5.17 syn_srlstyle

Description

Specify the implementation for shift registers. By default, the synthesis tool provides optimal inference based on the size of the shift registers. For inference rules, see the sections of Guideline on BSRAM Coding and Guideline on SSRAM Coding in *SUG949*, *Gowin HDL Coding User Guide*.

Attribute Value

Table 5-41 Attribute Value

Global Attribute	Object
Yes	module/entity, reg/signal, primitive instance

The table below lists the configurable attribute value and its corresponding function.

Table 5-42 Configurable Attribute Value and its Corresponding Function

value	Function
registers	Specifies the implementation of shift registers as registers.
block_ram	Specifies the implementation of shift registers as BSRAM in the FPGA.
distributed_ram	Specifies the implementation of shift registers as SSRAM in the FPGA.
bsram_sdp	Specifies the implementation of shift registers as BSRAM in semi-dual port mode.

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Syntax

Table 5-43 Syntax Example

GSC Constraint Syntax	INS "object" syn_ srlstyle = value
	GLOBAL syn_ srlstyle = value
	GSC Example
Verilog Constraint Syntax	object /* synthesis syn_ srlstyle = "value" */;
	<u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_ srlstyle: string;
	attribute syn_ srlstyle of object : objectType is "value";
	VHDL Example

Note!

If an attribute constraint distributed_ram is applied to a device that does not support SSRAM, the synthesis tool will issue a warning indicating that the attribute constraint is invalid.

Examples

GSC Constraint Example

```
Example 1: Specifies the implementation of the instance as BSRAM.
```

```
INS "mem" syn sristyle=block ram
```

Example 2: Specifies the implementation of all global shift registers as SSRAM.

GLOBAL syn_srlstyle=distributed_ram

Verilog Constraint Example

Example 1: Specifies the implementation of shift registers in the module as BSRAM.

```
module p_seqshift(clk, we, din, dout) /* synthesis syn_srlstyle =
"block_ram" */;
parameter width=18;
parameter depth=4;
input clk, we;
input [width-1:0] din;
output [width-1:0] dout;
reg [width-1:0] regBank[depth-1:0];
always @(posedge clk) begin
    if (we) begin
        regBank[depth-1:1] <= regBank[depth-2:0];
        regBank[0] <= din;
        end
end
assign dout = regBank[depth-1];</pre>
```

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```
endmodule
    Example 2: Specifies the implementation of the instance as SSRAM.
    module p seqshift(clk, we, din, dout);
    parameter width=18;
    parameter depth=16;
    input clk, we;
    input [width-1:0] din;
    output [width-1:0] dout;
    reg [width-1:0] regBank[depth-1:0] /* synthesis syn srlstyle =
    "distributed_ram" */;
    always @(posedge clk) begin
       if (we) begin
           regBank[depth-1:1] <= regBank[depth-2:0];
           regBank[0] <= din;
       end
    end
    assign dout = regBank[depth-1];
    endmodule
   VHDL Constraint Example
    Example 1: Specifies the implementation of shift registers in the
module as registers.
    library IEEE;
    use IEEE.STD LOGIC 1164.ALL;
    use IEEE.STD LOGIC ARITH.ALL;
    use IEEE.STD LOGIC UNSIGNED.ALL;
    entity p_seqshift is
        generic (
             width: integer := 18;
             depth: integer := 1024
        );
        port (
             clk
                 : in std_logic;
             we
                   : in std logic;
                 : in std logic vector(width-1 downto 0);
             dout : out std logic vector(width-1 downto 0)
```

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);

```
end p_seqshift;
architecture Behavioral of p seqshift is
    type regBank_type is array (0 to depth-1) of
std logic vector(width-1 downto 0);
    signal regBank : regBank_type := (others => '0'));
    attribute syn srlstyle:string;
    attribute syn srlstyle of regBank : signal is "registers";
begin
    process(clk)
    begin
         if rising edge(clk) then
             if we = '1' then
                  for i in depth-1 downto 1 loop
                       regBank(i) <= regBank(i-1);</pre>
                  end loop;
                  regBank(0) <= din;
              end if:
         end if;
    end process;
    dout <= regBank(depth-1);</pre>
end Behavioral:
```

5.18 syn_tlvds_io/syn_elvds_io

Description

Specify the attribute of the differential I/O buffer mapping.

Attribute Value

Table 5-44 Attribute Value

Default	Global Attribute	Object
0	Yes	module/entity, port, signal

The table below lists the configurable attribute value and its corresponding function.

Table 5-45 Configurable Attribute Value and its Corresponding Function

Value	Function
0	Disables automatic inference of differential I/O buffers.
1	Enables automatic inference of differential I/O buffers.

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Syntax

Table 5-46 Syntax Example

GSC Constraint Syntax	PORT "object" syn_tlvds_io/syn_elvds_io = value GLOBAL syn_tlvds_io/syn_elvds_io = value
	GSC Example
Verilog Constraint Syntax	object /* synthesis syn_tlvds_io/syn_elvds_io = value */;
	<u>Verilog Example</u>
VHDL Constraint Syntax	attribute syn_tlvds_io/syn_elvds_io: integer;
	attribute syn_tlvds_io/syn_elvds_io of object : objectType is value;
	VHDL Example

Examples

GSC Constraint Example

```
Example 1: Specifies the implementation of the buffer as TLVDS. PORT "io" syn tlvds io =1;
```

```
PORT "iob" syn tlvds io =1;
```

Example 2: Specifies the implementation of all global buffers as ELVDS.

```
GLOBAL syn elvds io =1;
```

Verilog Constraint Example

```
Example 1: Specifies the implementation of the buffer as TLVDS.
```

```
module tlvds_ibuf_test(in1_p, in1_n, out);
input in1_p /* synthesis syn_tlvds_io = 1*/;
input in1_n /* synthesis syn_tlvds_io = 1*/;
output reg out;
always@(in1_p or in1_n) begin
    if (in1_p != in1_n) begin
    out = in1_p;
    end
end
```

VHDL Constraint Example

endmodule

Example 1: Specifies the implementation of the buffer as ELVDS.

```
library IEEE;
use IEEE.STD_LOGIC_1164.ALL;
entity elvds_obuf_test is
port (
```

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```
in0 : in std_logic;
    out1 : buffer std_logic;
    out2 : buffer std_logic
    );
attribute syn_elvds_io: integer;
attribute syn_elvds_io of out1,out2: signal is 1;
end elvds_obuf_test;
architecture Behavioral of elvds_obuf_test is
begin
    out1 <= in0;
    out2 <= not out1;
end Behavioral;</pre>
```

5.19 translate_off/Translate_on

Description

The statements after translate_off will be skipped during the synthesis until translate_on appears. This is commonly used to automatically mask certain statements during synthesis. translate_off/translate_on must appear in pairs.

Syntax

Table 5-47 Syntax Example

Verilog Constraint Syntax	/* synthesis translate_off*/ Statements ignored during the synthesis. process./* synthesis translate_on*/ Verilog Example
VHDL Constraint Syntax	synthesis translate_off Statements ignored during the synthesis synthesis translate_on VHDL Example

Examples

Verilog Constraint Example

The statement assign Nout =a*b between /*synthesis translate_off*/ and /*synthesis translate_on*/ will be ignored during the synthesis. module top(a, b, dout, Nout);

input [1:0] a; input [1:0] b; output [1:0] dout; output [3:0] Nout;

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```
assign dout = a+b;
 /*synthesis translate off*/
 assign Nout = a*b;
 /*synthesis translate on*/
 endmodule
VHDL Constraint Example
 library ieee;
 use ieee.std_logic_1164.all;
 use ieee.std logic unsigned.all;
 entity top is
 port(
    a: in std_logic_vector(1 downto 0);
    b: in std_logic_vector(1 downto 0);
    dout : out std_logic_vector(1 downto 0);
    Nout : out std_logic_vector(3 downto 0)
);
 end top;
 architecture rtl of top is
 begin
 dout \le a + b;
 --synthesis translate off
 Nout <= a * b;
 --synthesis translate_on
 end rtl;
```

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6 Report Document 6.1 Synthesis Message

6 Report Document

The report document is the statistical report generated after synthesis. The file name is *_syn.rpt.html (* is the name of specified output netlist vg file). It includes Synthesis Message, Synthesis Details, Resource, and Timing, etc.

6.1 Synthesis Message

Synthesis Message refers to the basic information of Synthesis. As shown in Figure 6-1. It mainly includes design file, GowinSynthesis version, configuration information, and created time, etc.

Figure 6-1 Synthesis Message

Synthesis Messages



6.2 Synthesis Details

Synthesis Details includes the information of top level module, synthesis process, total time and memory usage, as shown in Figure 6-2.

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6 Report Document 6.3 Resource

Figure 6-2 Synthesis Details

Synthesis Details

Top Level Module	top
Synthesis Process	Running parser: CPU time = 0h 0m 0.109s, Elapsed time = 0h 0m 0.123s, Peak memory usage = 52.926MB Running netlist conversion: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 52.992MB Running device independent optimization: Optimizing Phase 0: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.133MB Optimizing Phase 1: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.191MB Optimizing Phase 1: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.254MB Running inference: Inferring Phase 0: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.344MB Inferring Phase 1: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.402MB Inferring Phase 2: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.430MB Inferring Phase 3: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.430MB Inferring Phase 0: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.465MB Running technical mapping: Tech-Mapping Phase 0: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.465MB Tech-Mapping Phase 2: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 53.473MB Tech-Mapping Phase 3: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 54.289MB Tech-Mapping Phase 3: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 54.289MB Tech-Mapping Phase 4: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 54.289MB Tech-Mapping Phase 4: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 54.289MB Tech-Mapping Phase 4: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 54.289MB Tech-Mapping Phase 4: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 54.289MB Tech-Mapping Phase 4: CPU time = 0h 0m 0s, Elapsed time = 0h 0m 0s, Peak memory usage = 54.289MB
Total Time and Memory Usage	CPU time = 0h 0m 0.148s, Elapsed time = 0h 0m 0.159s, Peak memory usage = 57.043MB

6.3 Resource

Resource shows the resource information. It mainly includes resource and chip utilization statistics.

The resource usage summary table counts the number of I/O PORT, I/O BUF, REG, LUT, etc. The resource utilization summary table is used to estimate the resource utilization of CFU Logics, Register, BSRAM, DSP in the current device, as shown in Figure 6-3.

Figure 6-3 Resource

Resource

Resource Usage Summary

Resource	Usage
I/O Port	32
I/O Buf	32
IBUF	24
OBUF	8
Register	1032
DFFE	1032
LUT	680
LUT2	128
LUT3	512
LUT4	40
INV	1
INV	1

Resource Utilization Summary

Resource	Usage	Utilization
Logic	681(681 LUT, 0 ALU) / 4608	15%
Register	1032 / 4020	26%
Register as Latch	0 / 4020	0%
Register as FF	1032 / 4020	26%
BSRAM	0 / 10	0%

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6 Report Document 6.4 Timing

6.4 Timing

Timing shows the timing statistics. It includes Clock Summary, Max. Frequency Summary, and Detail Timing Paths Information, etc.

Clock Summary mainly describes the clock signals of netlists, as shown in Figure 6-4. It shows a default clock with 100MHz and a period of 10ns, a rising edge at 0ns and a falling edge at 5ns.

Figure 6-4 Timing

Timing

Clock Summary:

NO.	Clock Name	Туре	Period	Frequency(MHz)	Rise	Fall	Source	Master	Object	
1	clk	Base	10.000	100.0	0.000	5.000			clk_ibuf/l	

Max. Frequency Summary mainly counts the time frequency of netlist file in order to measure whether the timing meets the requirements. As shown in Figure 6-5, the requested frequency is 100MHz and the actual frequency is 747.2MHz, and which meet the timing requirements. If the requirements can not be met, the specific timing path needs to be further checked.

Figure 6-5 Max Frequency Summary

Max Frequency Summary:

No.	Clock Name	Constraint	Actual Fmax	Logic Level	Entity
1	clk	100.0(MHz)	747.2(MHz)	1	ТОР

Detail Timing Paths Information shows the details of timing path. The default is 5 paths, and the unit is nanoseconds. Path Summary describes the key path, nodes and delays in the netlist file, as shown in Figure 6-6; Data Arrival Path and Data Require Path are key paths, and you can see from/to nodes and fanout in Figure 6-7. Path Statistics shows the path delay information, as shown in Figure 6-8.

Figure 6-6 Path Summary

Detail Timing Paths Information

Path 1

Path Summary:

Slack	8.662
Data Arrival Time	2.283
Data Required Time	10.945
From	reg2_s0
То	out2
Launch Clk	clk[R]
Latch Clk	clk[R]

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6 Report Document 6.4 Timing

Figure 6-7 Connection Relation, Delay and Fanout Information Data Arrival Path:

AT	DELAY	TYPE	RF	FANOUT	NODE
0.000	0.000				clk
0.000	0.000	tCL	RR	1	clk_ibuf/I
0.982	0.982	tINS	RR	3	clk_ibuf/O
1.345	0.363	tNET	RR	1	reg2_s0/CLK
1.803	0.458	tC2Q	RF	3	reg2_s0/Q
2.283	0.480	tNET	FF	1	out2/D

Data Required Path:

AT	DELAY	TYPE	RF	FANOUT	NODE
10.000	0.000				clk
10.000	0.000	tCL	RR	1	clk_ibuf/I
10.982	0.982	tINS	RR	3	clk_ibuf/O
11.345	0.363	tNET	RR	1	out2/CLK
10.945	-0.400	tSu		1	out2

Figure 6-8 Path Statistics

Path Statistics:

Clock Skew:	0.000
Setup Relationship:	10.000
Logic Level:	1
Arrival Clock Path Delay:	cell: 0.982, 73.009%; route: 0.363, 26.991%
Arrival Data Path Delay:	cell: 0.000, 0.000%; route: 0.480, 51.155%; tC2Q: 0.458, 48.845%
Required Clock Path Delay:	cell: 0.982, 73.009%; route: 0.363, 26.991%

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