```
In [1]: import numpy as np
   import pandas as pd
   import matplotlib.pyplot as plt
   import seaborn as sns
   import warnings
   from scipy.spatial.distance import cdist
   from sklearn import datasets
```

# 1. KMeans

```
In [2]: # import dataset and view head
        compounds = pd.read_csv('compounds.csv')
        compounds.head()
Out[2]:
            Α
                В
                     С
                         D
                             type
        0 6.4 2.9 4.3 1.3
                            amide
         1 5.7 4.4 1.5 0.4 phenol
        2 6.7 3.0 5.2 2.3
                             ether
        3 5.8 2.8 5.1 2.4
                             ether
        4 6.4 3.2 5.3 2.3
                             ether
```

### 1a

Rescale the features to a value between 0 and 1 by dividing the column by the max of that feature.

```
In [3]: def rescale_df(df):
    """
    Rescale the features of a dataframe to a value between 0 and 1 by dividi

    Parameters
    _____
    df: pandas DataFrame
    The dataframe whose columns you wish to transform

    Returns
    _____
    df: pandas DataFrame
    The dataframe with transformed columns
    """
    for col in df.columns:
        df[col] = df[col] / df[col].max()

    return df
```

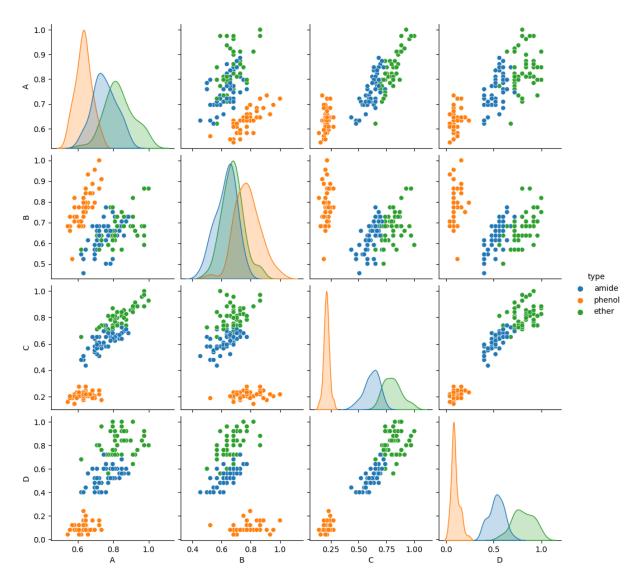
```
In [4]: # make a copy of compounds
    compounds_copy = compounds.copy()
    # remove type column since it's a string and can't be rescaled
    compounds_copy = compounds_copy.drop(columns = 'type')
    # rescale features (columns A - D)
    compounds_rescaled = rescale_df(compounds_copy)
    # make a copy with just features (to use in 1b)
    compounds_rescaled_features_only = compounds_rescaled.copy()
    # add type column back
    compounds_rescaled['type'] = compounds['type']
    # show head to see if I've done the last few steps correctly
    compounds_rescaled.head()
```

# Out [4]: A B C D type 0 0.810127 0.659091 0.623188 0.52 amide 1 0.721519 1.000000 0.217391 0.16 phenol 2 0.848101 0.681818 0.753623 0.92 ether 3 0.734177 0.636364 0.739130 0.96 ether 4 0.810127 0.727273 0.768116 0.92 ether

Now we plot to visualize any correlation between features.

```
In [5]: sns.pairplot(data=compounds_rescaled, hue='type', diag_kind='auto')
```

Out[5]: <seaborn.axisgrid.PairGrid at 0x142cf72d0>

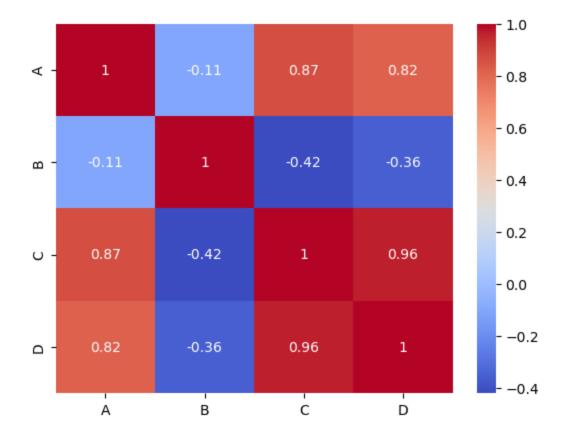


Looking at the graphs above, we see these correlations:

- C & D have a strong positive correlation
- I think A is correlated with C and D as well. It looks like a steep positive correlation

Now let's try a heatmap.

```
In [6]: # get a correlation matrix for features
    correlation_matrix = np.corrcoef(compounds_rescaled_features_only.T)
    # Create a heatmap of the correlation matrix
    sns.heatmap(correlation_matrix, annot=True, cmap='coolwarm', xticklabels=com
    # Show the plot
    plt.show()
```



Once again we see a high correlation between C and D (0.96), A and C are correlated (0.87), and A and D are too (0.82). Because the heatmap gives actual correlation values, it is much easier to see which ones are correlated than it is with the pairplot.

### 1b

```
In [7]: class KMeans():
            def __init__(self, K, maximum_iters=100):
                # K: number of clusters to be created
                # distance matrix is Eucledian distance
                self.K = K
                self.maximum_iters = maximum_iters
            def cluster(self, input_points):
                Do KMeans clustering
                Parameters
                input_points: np.array shape(ndata,nfeatures).
                    Each feature is assumed to be normalized within range of [0,1]
                .....
                centroids = np.random.random((self.K, input_points.shape[1]))
                assignments = np.zeros_like(input_points.shape[0])
                new_assignments = self.create_new_assignments(centroids, input_point
                # restart if run into bad initialization (number of unique clusters
                # Comment out this part for Q1.(d)
```

```
if len(np.unique(new assignments)) < self.K:</pre>
        return self.cluster(input_points)
    n iters = 1
    # while cluster assignments are changing (not converged)
    while (new assignments != assignments).any() and n iters < self.maxi</pre>
        ### Compute the centroid given new assignment ###
        centroids = [np.mean(input points[new assignments== k], axis=0)
        assignments = new assignments
        assignments = new assignments
        ### Update the assignment with current centroids ###
        new assignments = self.create new assignments(centroids, input p
        if len(np.unique(new assignments)) < self.K:</pre>
            warnings.warn('At least one centroid vanishes')
        n iters += 1
        if n_iters == self.maximum_iters:
            print("Warning: Maximum number of iterations reached!")
    return new assignments
def create_new_assignments(self, centroids, data_points):
    Assign each datapoint to its nearest centroid.
    centroid: 2d array of the current centroid for each cluster
    data points: 2d arrays recording the features of each data point.
    ###Compute the distances that stores the Eucledian distances between
    #shape (ndata,ncentroid)
    #centroids.shape = data_points.shape
    distances = cdist(data points, centroids, 'euclidean')
   # distances = np.sum(np.square(data points - centroids), axis=1)
    new_assignments = np.argmin(distances, axis=-1)
    return new assignments
```

We will do K Means clustering with K = 2, 3 and 4 clusters.

```
In [8]: # initiate KMeans with 2, 3 and 4 clusters
kmeans_2 = KMeans(K= 2)
kmeans_3 = KMeans(K= 3)
kmeans_4 = KMeans(K= 4)

# cluster with 2, 3 and 4 clusters
assignments_k2 = kmeans_2.cluster(compounds_rescaled_features_only)
assignments_k3 = kmeans_3.cluster(compounds_rescaled_features_only)
assignments_k4 = kmeans_4.cluster(compounds_rescaled_features_only)
```

Now we visualize our results. Since C and D have the highest correlation, let's use them as features. for the first set of plots. We'll use A and C next.

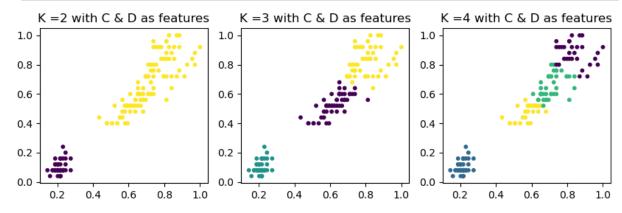
```
In [9]: # visualize your results
plt.figure(figsize=(10, 6))
# scatter plot for 2 clusters. Use C & D as features
```

```
plt.subplot(2,3,1)
plt.scatter(compounds_rescaled['C'], compounds_rescaled['D'], c=assignments_
plt.title('K =2 with C & D as features')

# scatter plot for 3 clusters
plt.subplot(2,3,2)
plt.scatter(compounds_rescaled['C'], compounds_rescaled['D'], c=assignments_
plt.title('K =3 with C & D as features')

# scatter plot for 4 clusters
plt.subplot(2,3,3)
plt.scatter(compounds_rescaled['C'], compounds_rescaled['D'], c=assignments_
plt.title('K =4 with C & D as features')

plt.show()
```



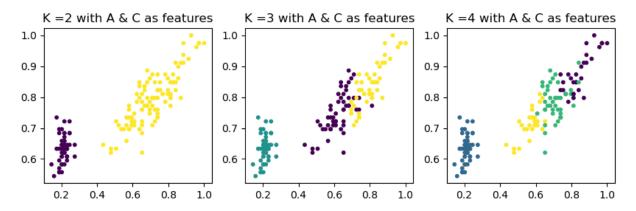
```
In [10]: # visualize your results
plt.figure(figsize=(10, 6))

# scatter plot for 2 clusters. Use C & D as features
plt.subplot(2,3,1)
plt.scatter(compounds_rescaled['C'], compounds_rescaled['A'], c=assignments_
plt.title('K =2 with A & C as features')

# scatter plot for 3 clusters
plt.subplot(2,3,2)
plt.scatter(compounds_rescaled['C'], compounds_rescaled['A'], c=assignments_
plt.title('K =3 with A & C as features')

# scatter plot for 4 clusters
plt.subplot(2,3,3)
plt.scatter(compounds_rescaled['C'], compounds_rescaled['A'], c=assignments_
plt.title('K =4 with A & C as features')

plt.show()
```



Three clusters makes the most sense. Although the two clusters are more neatly separated, they have members with very different characteristics. For example, a compound with 0.4 C value and 0.4 D value and another compound with 1.0 C value and 1.0 D value, although very different, are in the same cluster if we only make two.

### 1c

For K=3 clustering result, compare it to the true data label. How good is the classification?

```
In [11]: def validate(y hat,y):
             Print accuracy of prediction for each class for the compounds dataset
             yhat: np.array shape(ndata).
                 Your prediction of classes
             y: np.array of str shape(ndata)
                 Data labels / ground truths.
             .....
             # correct classification
             compounds = np.unique(y) # should be ['amide', 'phenol', 'ether'] for comp
             clusters =[np.where((y==c)) for c in compounds]
             pred class = np.unique(y hat)
             #remove −1 for noise point in DBSCAN
             pred class= np.delete(pred class,np.where(pred class==-1))
             assert len(pred class) == len(compounds), f'y hat has less or more than
             for i in range(3):
                 #loop over solutions
                 counts=[]
                 scores=[]
                 for j in range(3):
                     #loop over clusters of true assignments
                     sol_i= np.where((y_hat==pred_class[i]))
                     counts.append(len(np.intersect1d(sol_i, clusters[j])))
                     scores.append(counts[-1]/len(clusters[j]))
                 idx = np.argmax(scores)
                 print(f'Class {pred_class[i]} - {compounds[idx]}: {counts[idx]} out
         of {np.count_nonzero(clusters[idx])} are classified correctly')
```

```
In [12]: validate(assignments_k3, compounds['type'])

Class 0 - amide: 48 out of 49 are classified correctly
Class 1 - phenol: 50 out of 50 are classified correctly
Class 2 - ether: 46 out of 50 are classified correctly
```

This is a very good (>90% correct) classification.

### 1d

Comment out the part of the code that reinitialize the centroid if the initial assignment is not good. Run the KMeans algorithm multiple times with K=4, what problem do you see? Comment on how the choice of initial centroids might affect the results and what are the possible solutions

```
In [13]: import warnings
         class KMeans():
             def __init__(self, K, maximum_iters=100):
                 # K: number of clusters to be created
                 # distance matrix is Eucledian distance
                  self.K = K
                  self.maximum_iters = maximum_iters
             def cluster(self, input points):
                 Do KMeans clustering
                 Parameters
                  input points: np.array shape(ndata,nfeatures).
                     Each feature is assumed to be normalized within range of [0,1]
                  centroids = np.random.random((self.K, input_points.shape[1]))
                 assignments = np.zeros_like(input_points.shape[0])
                 new_assignments = self.create_new_assignments(centroids, input_point
                 # restart if run into bad initialization (number of unique clusters
                 # Comment out this part for Q1.(d)
                 # if len(np.unique(new assignments)) < self.K:</pre>
                       return self.cluster(input points)
                 n iters = 1
                 # while cluster assignments are changing (not converged)
                 while (new_assignments != assignments).any() and n_iters < self.maxi</pre>
                     ### Compute the centroid given new assignment ###
                     centroids = [np.mean(input_points[new_assignments== k], axis=0)
                     assignments = new assignments
                     assignments = new assignments
                     ### Update the assignment with current centroids ###
                     new_assignments = self.create_new_assignments(centroids, input_r
                     if len(np.unique(new_assignments)) < self.K:</pre>
                          warnings.warn('At least one centroid vanishes')
```

```
n_iters += 1
    if n_iters == self.maximum_iters:
        print("Warning: Maximum number of iterations reached!")

return new_assignments

def create_new_assignments(self, centroids, data_points):
    """

Assign each datapoint to its nearest centroid.
    centroid: 2d array of the current centroid for each cluster data_points: 2d arrays recording the features of each data point.
    """

###Compute the distances that stores the Eucledian distances between #shape (ndata,ncentroid)
    #centroids.shape = data_points.shape
    distances = cdist(data_points, centroids, 'euclidean')

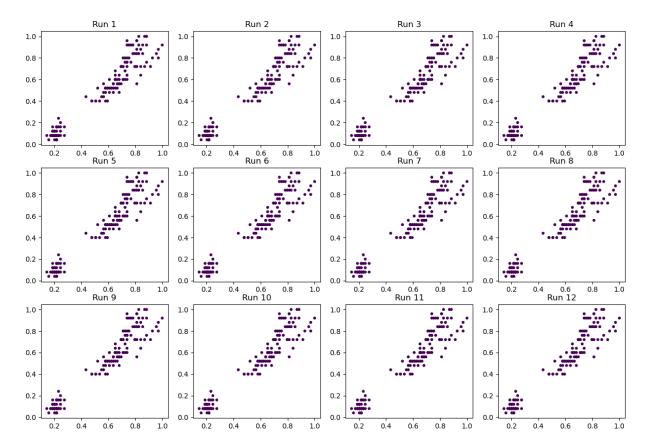
# distances = np.sum(np.square(data_points - centroids), axis=1)
    new_assignments = np.argmin(distances, axis=-1)
    return new_assignments
```

```
In [14]: # initiate KMeans with 4 clusters again
kmeans_4_again = KMeans(K= 4)
# make 4 clusters again
reassignments_k4 = kmeans_4_again.cluster(compounds_rescaled_features_only)

# to visualize 12 runs, create 3 rows and 4 columns of subplots
fig, axes = plt.subplots(3, 4, figsize=(15, 10))
# loop to run K=4 12 times and visualize as scatter plots
for i, ax in enumerate(axes.ravel()):
    # Scatter plot for the i-th run
    ax.scatter(compounds_rescaled['C'], compounds_rescaled['D'], c=reassignn
    ax.set_title(f'Run {i + 1}')
```

Warning: Maximum number of iterations reached!

```
/var/folders/m8/skfw9g2x4_g4pq5cv80_g24w0000gn/T/ipykernel_4349/143941416.p
y:38: UserWarning: At least one centroid vanishes
warnings.warn('At least one centroid vanishes')
```



All the centroids disappear and we end up with one cluster (which defeats the purpose of clustering).

The initial choice of centroids is important; if they are not well-chosen, the algorithm could converge to a local minimum instead of a global minimum. A way to prevent this would be to randomly choose initial centroids from within the dataset.

# 2 DBSCAN

DBSCAN Documentation: https://scikit-

learn.org/stable/modules/generated/sklearn.cluster.DBSCAN.html#sklearn.cluster.DBSCAN

### 2a

Use DBSCAN to classify compounds dataset. Adjust the Rcut and MinPts hyperparameters so that we have 3 clusters. How many core, border and noise points do you have respectively? Compared to KMeans, is DBSCAN more effective?

```
In [15]: from sklearn.cluster import DBSCAN

# eps = Rcut, minsamples = MinPts
db1 = DBSCAN(eps= 0.1, min_samples= 3)
clustering = db1.fit(compounds_rescaled_features_only)

# Cluster labels assigned to each point in compounds_rescaled_features_only.
```

```
#print(f'Clustering labels: \n {clustering.labels_}\n')
# Indices of core samples
#print(f'Core sample indices:\n {clustering.core_sample_indices_}\n')

# Check number of clusters
num_clusters = np.unique(clustering.labels_)
print(f'There are {num_clusters.size - 1} clusters') # minus 1 bc one of the
# Number of core points
print(f'There are {clustering.core_sample_indices_.size} core points')
# Number of noise points
noise_points = np.count_nonzero(clustering.labels_ == -1) # check how many v
print(f'There are {noise_points} noise points')
# Number of border points
border_points = clustering.labels_.size - clustering.core_sample_indices_.si
print(f'There are {border_points} border points')
```

```
There are 3 clusters
There are 134 core points
There are 11 noise points
There are 5 border points
```

The Rcut and MinPts that give 3 clusters and the smallest number of noise and border points are Rcut = 0.1 and MinPts = 3.

Core points: 134

Border points: 5

Noise points: 11

DBSCAN is a more effective classification method because the clusters are a lot more cleanly separated.

### 2b

Let's work on the noisy moon dataset (provided in the reference code) instead. Try using DBSCAN and one of KMeans with K=2. Visualize the clustering result. This time which method works better?

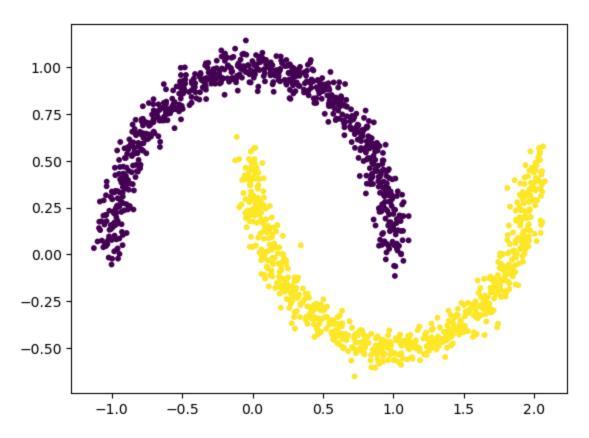
```
In [16]: np.random.seed(0)

# =============

# Generate datasets. We choose the size big enough to see the scalability
# of the algorithms, but not too big to avoid too long running times
# ============

n_samples = 1500
noisy_circles = datasets.make_circles(n_samples=n_samples, factor=0.5, noise
noisy_moons = datasets.make_moons(n_samples=n_samples, noise=0.05)
# print(noisy_moons)
X, y = noisy_moons
plt.scatter(X[:, 0], X[:, 1], s=10,c=y)
```

Out[16]: <matplotlib.collections.PathCollection at 0x17b47f4d0>



```
In [17]: db2 = DBSCAN(eps= 0.14, min_samples= 10)
    clustering = db2.fit(X)

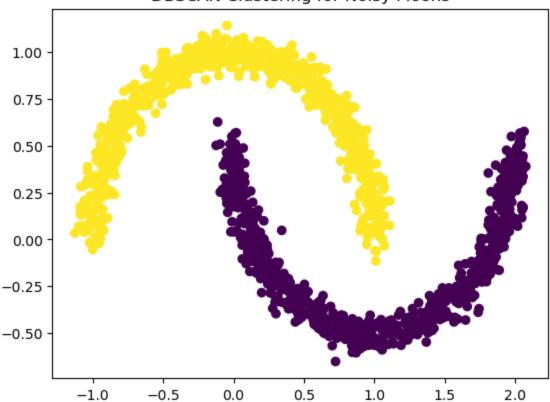
# Check number of clusters
    num_clusters = np.unique(clustering.labels_)
    print(f'There are {num_clusters.size - 1} clusters') # minus 1 bc one of the
# Number of core points
    print(f'There are {clustering.core_sample_indices_.size} core points')
# Number of noise points
    noise_points = np.count_nonzero(clustering.labels_ == -1) # check how many v
    print(f'There are {noise_points} noise points')
# Number of border points
border_points = clustering.labels_.size - clustering.core_sample_indices_.si
    print(f'There are {border_points} border points')
```

There are 1 clusters There are 1496 core points There are 0 noise points There are 4 border points

Visualize results

```
In [18]: plt.scatter(X[:, 0], X[:, 1], c=clustering.labels_, cmap='viridis')
    plt.title('DBSCAN Clustering for Noisy Moons')
    plt.show()
```

# **DBSCAN Clustering for Noisy Moons**

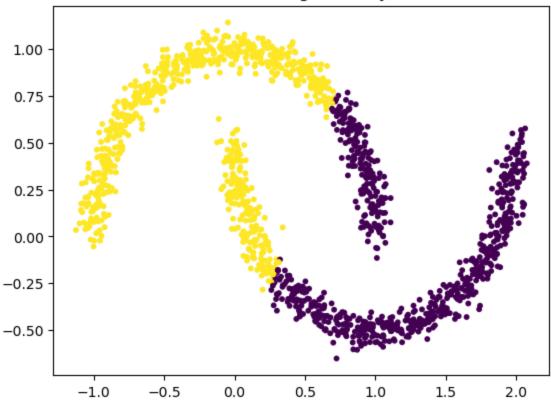


```
In [20]: # initialize k means and form clusters with noisy moons
kmeans_moons = KMeans(K= 2)
moon_assignments = kmeans_2.cluster(X)

# scatter plot to visualize
plt.scatter(X[:, 0], X[:, 1], c=moon_assignments, s=10)
plt.title('KMeans Clustering for Noisy Moons')
```

Out[20]: Text(0.5, 1.0, 'KMeans Clustering for Noisy Moons')





In this case, density-based clustering is obviously the better choice. The result from KMeans clustering is laughable.