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Pruning Algorithm for Multi-Objective Optimization with Decision Maker's Preferences of System Redundancy Allocation Problem

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Outline

- Introduction to Multi-Objective Optimization
- Related Work
- Problem Statement:
Pruning Algorithm According to The Decision
Maker's Preferences
- Redundancy Allocation Problem
- Preference-Based Ranking Method
- Experimental Result
- Conclusion

Introduction to Multi-Objective Optimization

The mathematical formulation

Maximize/Minimize $f_i(\mathbf{x})$ for $i = 1, 2, \dots, n$

Subject to $g_j(\mathbf{x}) \geq 0$ $j = 1, 2, \dots, J$
 $h_k(\mathbf{x}) = 0$ $k = 1, 2, \dots, K$
 $x_i^{(L)} \leq x_i \leq x_i^{(U)}$

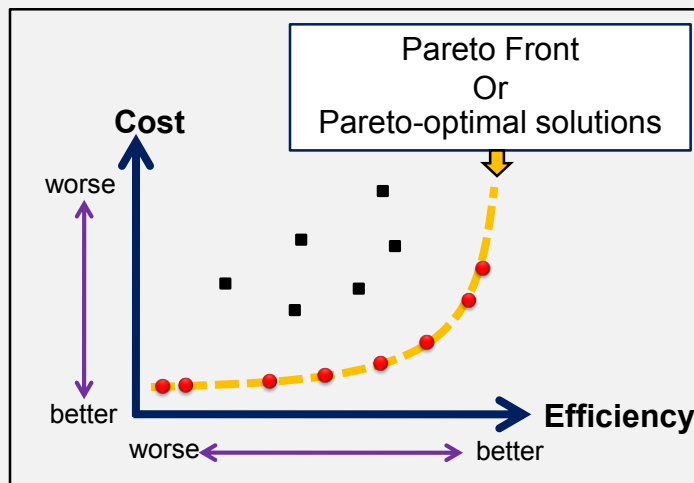
where \mathbf{x} is a vector of n decision variable(s):

$$\mathbf{x} = (x_1, x_2, \dots, x_n)^T.$$

$$\mathbf{f}(\mathbf{x}) = (f_1(\mathbf{x}), f_2(\mathbf{x}), \dots, f_M(\mathbf{x}))^T.$$

Multi-Objective Optimization Characteristics

Figure 1 The Pareto front or Pareto-optimal solutions



Related Work

- There exists many searching algorithms such as genetic algorithm, non-dominated sorting genetic algorithm-II (NSGA-II), particle swarm optimization algorithm, ant colony algorithm, etc.
- A challenging task of multi-objective optimization is to select the appropriate solutions among a large number of non-dominated solutions.
- Preference-based methods according to the Decision maker (DM)'s preferences should be considered to identify the preferred solution(s).

Related Work

- A non-numerical ranking preference (NNRP) method [1]
 - The DM gives all relations of ordering objective functions.
 - For example, "the objective 1 is more important than objective 2; objective 2 is more important than objective 3".
 - The ranked objectives functions is: $f_1 \succ f_2 \succ f_3$
 - The weights are generated randomly
 - A relative order is $w_1 > w_2 > w_3$
 - Likelihood of different weight combination
- An expanding of NNRP method [2] is presented for post-Pareto optimality method to solve a 5-objective problem.
 - Require large amount of mathematical calculation to derive the weights.

$$f = w_1 f_1(x) + \dots + w_n f_n(x)$$

Problem Statement

- Which solution is the most appropriate one?
- A large possible solution set

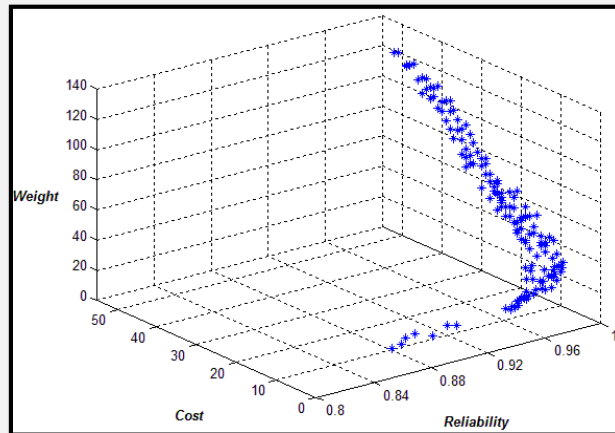
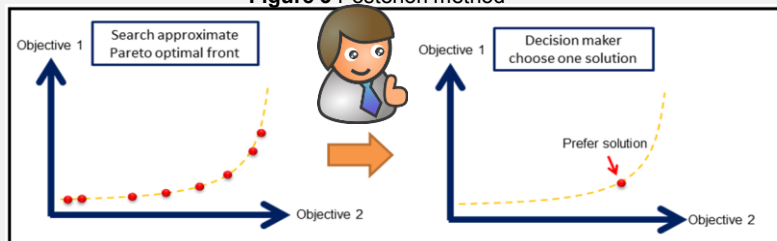


Figure 2 The approximated Pareto-optimal solutions in 3-objective plane. Each point represents the possible alternative in objective space.

Problem Statement

- Propose a **preference-based ranking method** as a pruning algorithm for multi-objective optimization.
- Consider a posteriori pruning approach.
- Help the DM **identify** the preferred solutions from the approximation of the Pareto front according to the DM's preferences.
- The parameter requirements
 - A **ranking priority** of the objective functions.

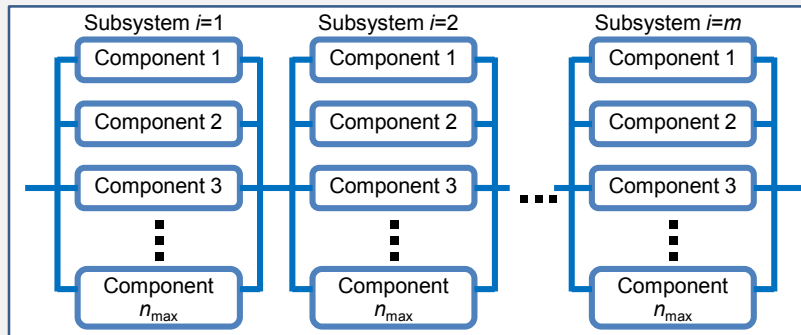
Figure 3 Posteriori method



Redundancy Allocation Problem

- Determining an optimal system design choice by allocating redundant components from the design alternatives.
- The problem can be very complex when mixing of non-identical components is allowed in each subsystem

Figure 4 A redundancy allocation problem with series-parallel structure



Notation

R_{sys}	system reliability
C_{sys}	system cost
W_{sys}	system weight
R_i	reliability in subsystem i
r_{ij}	reliability of the j^{th} component in subsystem i
c_{ij}	cost of the j^{th} component in subsystem i
w_{ij}	weight of the j^{th} component in subsystem i
\mathbf{x}, \mathbf{x}_i	a vector which defines the number of components type j in subsystem i
x_{ij}	number of components of type j in subsystem i
n_{\max}	number of maximum components in subsystem i
t_i	number of component type choices in subsystem i
m	number of subsystems connected in series

Multi-objective Optimization of Series-Parallel System Model

$$\max R_{sys}(\mathbf{x}) = \prod_{i=1}^m R_i(\mathbf{x}_i)$$

$$\min C_{sys}(\mathbf{x}) = \sum_{i=1}^m \sum_{j=1}^{t_i} c_{ij} x_{ij}$$

$$\min W_{sys}(\mathbf{x}) = \sum_{i=1}^m \sum_{j=1}^{t_i} w_{ij} x_{ij}$$

$$\text{s.t.} \quad 1 \leq \sum_{j=1}^{t_i} x_{ij} \leq n_{\max}$$

$$R_i(\mathbf{x}) = 1 - \prod_{j=1}^{t_i} (1 - R_{ij}(\mathbf{x}))^{x_{ij}}$$

where $x_{ij} \in \{0, 1, 2, \dots, n_{\max}\}$, $i = 1, 2, \dots, m$ and $j = 1, 2, \dots, t_i$

Problem Assumption

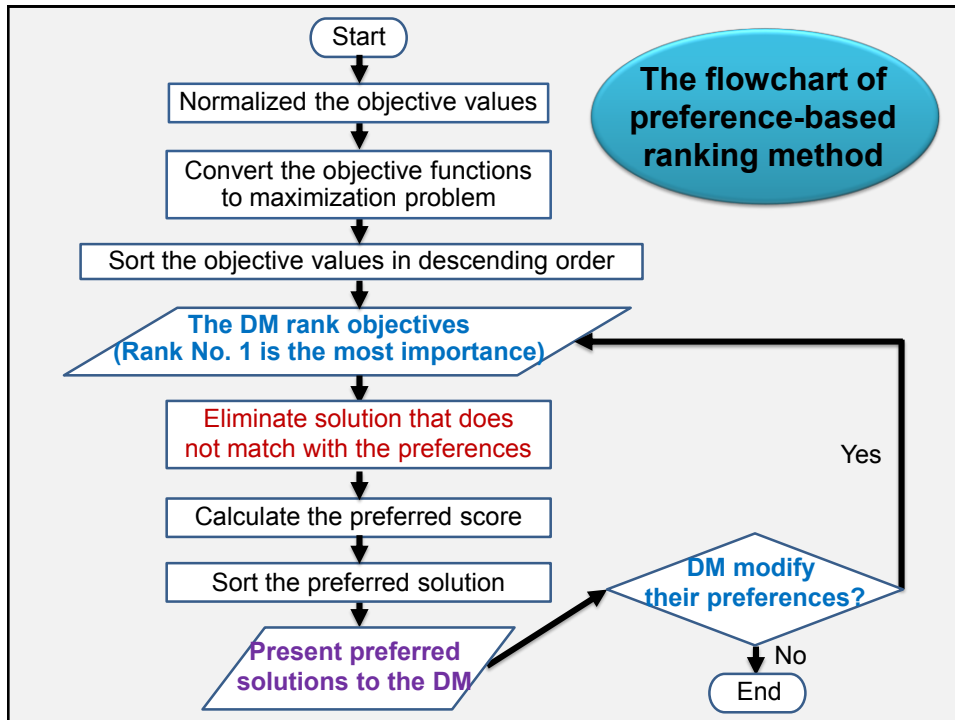
- Mixing of non-identical component types is allowed.
- NSGA-II is used as the searching algorithm.
- The alternative component choices have s-independent component.
- The components and the system have only two possible states: work or else fail.

Table I. Available Component Types for Each Subsystem

Subsystem i	Design alternative j														
	Component Choice 1			Component Choice 2			Component Choice 3			Component Choice 4			Component Choice 5		
	r_{ij}	c_{ij}	w_{ij}	r_{ij}	c_{ij}	w_{ij}	r_{ij}	c_{ij}	w_{ij}	r_{ij}	c_{ij}	w_{ij}	r_{ij}	c_{ij}	w_{ij}
1	0.95	2	5	0.93	1	4	0.91	2	2	0.90	1	3	0.95	2	8
2	0.99	4	4	0.98	3	6	0.97	1	5	0.96	2	7	-	-	-
3	0.90	6	5	0.85	5	4	0.82	3	3	0.79	3	5	0.99	2	4

Note: r = reliability, c = cost, w = weight.

“-” means that a design alternative is not available



Preference-Based Ranking Method

- The DM gives **ranking priority** of the objective functions.
 - Rank #1 means the highest priority for the objective function.
- The experiments vary the ranking priority preferences of the objective functions into four cases as following:
 - Reliability \succ Cost \succ Weight
 - Cost \succ Reliability \succ Weight
 - Weight \succ Reliability \succ Cost
 - Reliability \succ Weight \succ Cost

Parameter Setting for NSGA-II

- Encoding: The chromosomes are represented as decimal strings. Each gene in the chromosomes represent the number of selected component type j for subsystem i , (x_{ij}) where $i = \{1, 2, 3, \dots, m\}$ and $j = \{1, 2, 3, \dots, t_i\}$.

	Subsystem 1					Subsystem 2				Subsystem 3				
Component type	1	2	3	4	5	1	2	3	4	1	2	3	4	5
x_{ij}	0	0	2	0	0	1	0	0	0	0	0	0	0	1

- Selection: Binary tournament selection
- Crossover: SBX crossover
- Mutation: Polynomial mutation operators

Table II. The parameter setting of NSGA-II

Parameter	Value
Population size	200
Mutation probability	0.07
Crossover probability	0.9
Max generation	1000

Pareto-optimal solutions

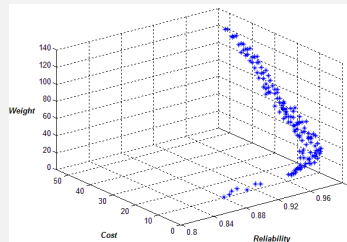


Figure 5 The approximated Pareto-optimal solutions in 3-objective plane.

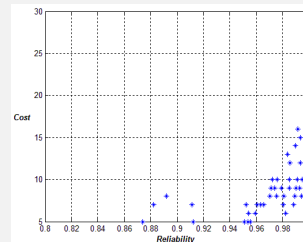


Figure 7 The approximated Pareto-optimal solutions with **reliability** and **cost**.

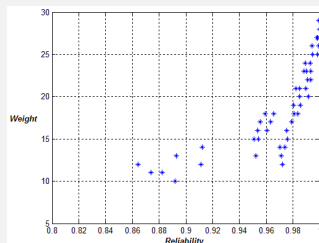


Figure 6 The approximated Pareto-optimal solutions with **reliability** and **weight**.

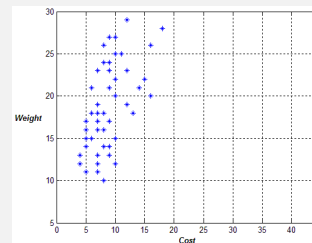
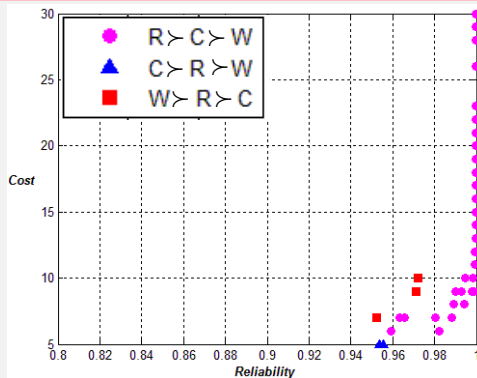


Figure 8 The approximated Pareto-optimal solutions with **cost** and **weight**.

Experimental Results

The preferred solutions for 3 preferences



The preferred solutions for $R \succ W \succ C$

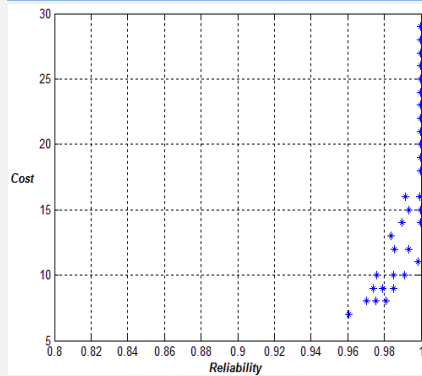


Table III. The preferred solutions for $W \succ R \succ C$

			Subsystem 1					Subsystem 2				Subsystem 3					Prefer score
			Choice					Choice				Choice					
Reliability	Cost	Weight	1	2	3	4	5	1	2	3	4	1	2	3	4	5	
0.972161	10	12	0	0	2	0	0	1	0	0	0	0	0	0	0	1	0.213636
0.971279	9	13	0	0	1	1	0	1	0	0	0	0	0	0	0	1	0.153788
0.952522	7	13	0	0	2	0	0	0	0	1	0	0	0	0	0	1	0.070455

Conclusion

- A pruning algorithm with preference information for multi-objective optimization problems is proposed.
 - The non-numerical ranking preference method
 - Applying after the Pareto Front is obtained by an efficient multi-objective optimization algorithm, NSGA-II.
- Solving redundancy allocation problem
- Identifying the preferred solution set without using quantitative numerical preference parameters.

Conclusion (2)

Research Contribution

- The DM can see the whole picture of the Pareto Front before making a decision for final choice.
- Helping the DM identify appropriate solution(s) among a large set of Pareto-optimal solutions and also satisfy the DM's preferences which are specified as raking/relative priority of the objective functions.
- The DM does not have to be an expert in the problem solving.

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