General GA Structure

- encoding
- objective function (fitness) evaluation
- initial population of solutions
 - number of solutions
 - generating solutions
- evolution operators (move operators)
 - mutation stochastic perturbation, usually to neighboring solution
 - recombination selection of *parent* solutions and blending to form *child* solutions
 - population maintenance method replacing old solutions with new solutions
- termination method

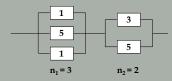
Solution Encoding – Example I

- A system has three subsystems (s=3)
 connected in series, where each subsystem
 consists of one hardware component and one
 software component.
- There are 4 available component types for HW and SW components: type 0, 1, 2, 3

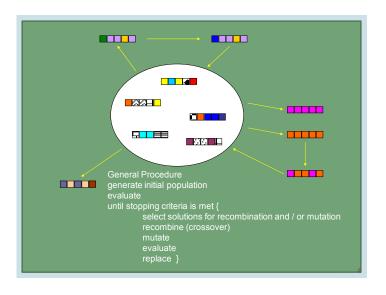
 \circ V = (1 3 | 2 2 | 0 3) = (01 11 | 10 10 | 00 11)

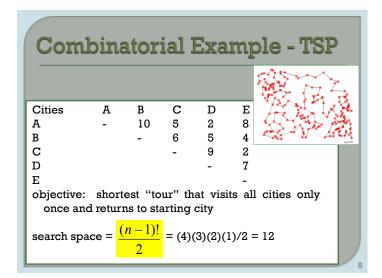
Solution Encoding - Example II

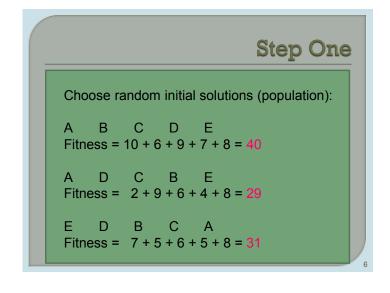
- $_{\odot}$ A system has two subsystems (s=2) with 5 available parts for first (m_1 =5) and 7 available parts for second (m_2 =7) subsystem
- n_{max} is set to 4

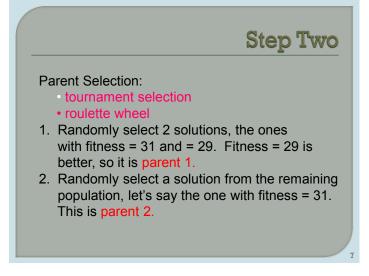


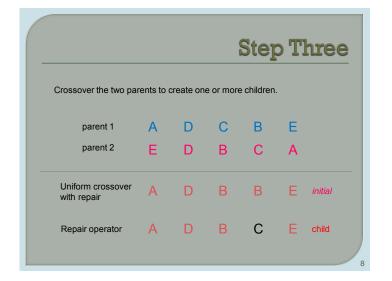
 \circ V = (1 1 5 6 | 3 5 8 8)











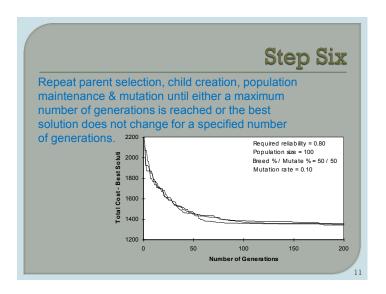
Step Four

Evaluate child.

A D B C E

Fitness = 2 + 5 + 6 + 2 + 8 = 23

The child replaces the worse solution in the population (the one with fitness = 40).



Step Five

Mutate with small probability.

Randomly choose a solution, say the one with fitness = 31.

E D B C A

Swap two cities, randomly to create mutated solution;

E D B A C
Fitness =
$$7 + 5 + 10 + 5 + 2 = 29$$

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