

Kosma Krzyżanowski

Born: 2000

Mobile: +48 696831319

Email: kosmakrzyzanowski@gmail.com

Linkedin: www.linkedin.com/in/kosmak

EDUCATION

Master of Science - Systems and Control

2024-present

Delft University of Technology

Courses: Control Theory, Machine Learning, Statistical Signal Processing, Optimization, ...

Pre-Master - Moral and Political Philosophy

2025-present

Leiden University

Bachelor of Science - Aerospace Engineering

2020-2023

Delft University of Technology

PROFESSIONAL EXPERIENCE

Delft Hyperloop

2023-2024

Chief Engineer

Team developing a Hyperloop prototype, showcasing a first fully scalable Hyperloop lane switch

- **Project management:** Planned and executed design, production and testing of an advanced Hyperloop prototype with a team of 25 engineers.
- **Systems engineering:** Ensured smooth integration of mechanical, levitation, powertrain, sense & control and powertrain subsystems.
- **Leadership:** Led a diverse team of engineers, fostering collaboration and effective communication across various disciplines.

Delft Aerospace Rocket Engineering, Stratos V, NEAR

2021-2023

Propulsion and Active Apogee Control Engineer

Student team developing liquid bi-prop rocket to reach an apogee of 35km and demonstrate reusability

- **Propulsion and feed system design:** Designed a Quick Disconnect system - requirements, conceptual, detailed design, manufacturing and testing plan. Designed a cold flow test setup. Analysed hot fire test data.
- **Mechanical Design:** Optimized the functioning of the airbrake deployment mechanism by implementing a permutation based **Python** algorithm to decrease the acting friction forces, resulting in a **50% decrease** in the torque required, compared with the initial design.

Refinitiv Metadata Analyst

2019 - 2020

Company a part of the London Stock Exchange Group delivering financial data.

- **Data Analysis:** Analysed vast amounts of data using **Excel**, worked on extensive databases with the use of **SQL**, Developed multiple classification systems for varying commodities data, conducted research in multiple fields and standards.
- **Cooperation:** Worked in team of experts in fields such as: IT, energy, gas, metals and agriculture. Learning and applying the best practices from their respective fields.

PROJECTS

Robotic Arm with Computer Vision (Python, Computer Vision, Control, Linux, Raspberry Pi): Fully designed, manufactured and programmed a robotic arm to pick up objects and manipulate them based on the inputs from a camera using OpenCV and reverse kinematics for motion planning. (Present)

Winner of Project X – NATO, Boeing, Unmanned Valley Design Sprint: Designed an autonomous collaborative drone system for application in rapidly changing environments under the guidance of senior Boeing engineers, NATO officials and industry leading experts. Developed a **decentralized, token based decision making solution** allowing for unprecedented flexibility, scalability and robustness. (February 2022)

Package Delivery Robot (Motion Planning, Robotics, Python): As part of the Robotics Student Association, developing a motion planning and decision making system for a LIDAR based package delivery robot, using an RRT path planning algorithm. (Present)

SKILLS SUMMARY

Management:	Project management, Stakeholder management, Leadership, Public Speaking
Prog. Languages:	Intermediate: Python, MATLAB, Arduino
CAD:	CATIA (intermediate), Siemens NX (intermediate), Fusion 360 (intermediate)
Languages:	English (fluent), Dutch (beginner+), Polish (fluent)
Interests:	Robotics, Political Science, Philosophy
Hobbies:	Bouldering, Surfing, Windsurfing