Macroeconomics II Homework 2

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(a)

At the optimal consumption, the budget constraint holds with equality:

$$c_t = Ak_t^{\alpha} - k_{t+1}$$

Define

$$w(k_0) = \max_{\{k_{t+1}\}_{t=0}^{\infty}} \sum_{t=0}^{\infty} \beta^t \log c_t$$

Then, this is equivalent to

$$w(k_0) = \max_{\{k_{t+1}\}_{t=0}^{\infty}; k_0 \text{ given}} \sum_{t=0}^{\infty} \beta^t \log c_t$$

$$= \max_{k_1; k_0 \text{ given}} \log c_0 + \beta \left[\max_{\{k_{t+1}\}_{t=1}^{\infty}; k_1 \text{ given}} \sum_{t=1}^{\infty} \beta^{t-1} \log c_t \right]$$

$$= \max_{k_1; k_1 \text{ given}} \log(Ak_0^{\alpha} - k_1) + \beta w(k_1)$$

with conditions $0 \le k_1 \le Ak_0^{\alpha}$ for all $t = 0, \dots, \infty$. This is the recursive problem of the social planner.

(b)

(i): Guess and Verify

Guess $V(k) = X + Y \log Ak^{\alpha}$ where X and Y are coefficients to be determined. Then, the Bellman equation is

$$V(k) = \max_{0 \le k' \le Ak^{\alpha}; k \text{ given}} \log(Ak^{\alpha} - k') + \beta(X + Y \log Ak'^{\alpha})$$

The first-order condition is

$$\begin{split} \frac{\partial V(k)}{\partial k'} &= -\frac{1}{Ak^{\alpha} - k'} + \alpha \beta Y \frac{1}{k'} = 0 \\ & \therefore \quad k' = \frac{\alpha \beta Y}{1 + \alpha \beta Y} Ak^{\alpha} \end{split}$$

Evaluating the value function at the optimal k', we have

$$V(k') = \log\left(Ak^{\alpha} - \frac{\alpha\beta Y}{1 + \alpha\beta Y}Ak^{\alpha}\right) + \beta(X + Y\log A\left(\frac{\alpha\beta Y}{1 + \alpha\beta Y}Ak^{\alpha}\right)^{\alpha})$$
$$= \beta X + \log\left(\frac{1}{1 + \alpha\beta Y}\right) + \alpha\beta Y\log\left(\frac{\alpha\beta Y}{1 + \alpha\beta Y}\right) + \alpha(1 + \beta Y)\log(Ak^{\alpha})$$

Solving this, we have

$$X = \frac{1}{1 - \beta} \left[\log \left(\frac{1}{1 + \alpha \beta Y} \right) + \alpha \beta Y \log \left(\frac{\alpha \beta Y}{1 + \alpha \beta Y} \right) \right]$$
$$Y = \frac{1}{\alpha (1 - \beta)}$$

(ii): Value Function Iteration

(iii): Policy Function Iteration

Using the result in (i), we have the true policy function:

$$k' = \frac{\alpha \beta Y}{1 + \alpha \beta Y} A k^{\alpha} = \frac{\alpha \beta}{1 - \beta + \alpha \beta} A k^{\alpha}$$

Using this policy function, we can caluculate the value function.

$$V_{h_j}(k_0) = \sum_{t=0}^{\infty} \beta^t \log \left(A k_t^{\alpha} - \frac{\alpha \beta}{1 - \beta + \alpha \beta} A k^{\alpha} \right)$$
$$= \frac{1}{1 - \beta} \log \left(\frac{1 - \beta}{1 - \beta + \alpha \beta} A \right) + \sum_{t=0}^{\infty} \beta^t \log k_t^{\alpha}$$

Since the second term is caluculated as

$$\sum_{t=0}^{\infty} \beta^t \log k_t^{\alpha} = \sum_{t=0}^{\infty} \beta^t \alpha^{t+1} \log k_0 + \sum_{t=0}^{\infty} \beta^t (\alpha + \dots + \alpha^t) \log \left(\frac{\alpha \beta}{1 - \beta + \alpha \beta} A \right)$$
$$= \frac{\alpha}{1 - \alpha \beta} \log k_0 + \frac{\alpha \beta}{(1 - \beta)(1 - \alpha \beta)} \log \left(\frac{\alpha \beta}{1 - \beta + \alpha \beta} A \right)$$

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(a)

The agent's life-time budget constraint is

$$\sum_{t=0}^{\infty} p_t \left(c_t + \frac{b_{t+1}}{1 + r_{t+1}} - b_t - e \right)$$

(b)

Define the Lagrangian as

$$\mathcal{L} = \sum_{t=0}^{\infty} \beta^t \left[\log c_t + \lambda_t \left(p_t \left(c_t + \frac{b_{t+1}}{1 + r_{t+1}} - b_t - e \right) \right) \right]$$

The first-order conditions are

$$\begin{split} \frac{\partial \mathcal{L}}{\partial c_t} &= U'(c_t) - \lambda_t p_t = 0\\ \frac{\partial \mathcal{L}}{\partial b_t + 1} &= -\beta^t \frac{\lambda_t p_t}{1 + r_{t+1}} + \beta^{t+1} \lambda_{t+1} p_{t+1} = 0 \end{split}$$

Thus, the Euler equation is

$$U'(c_t) = \beta U'(c_{t+1})(1 + r_{t+1})$$

The transversality condition is

$$\lim_{t \to \infty} \beta^t (1 + r_{t+1}) U'(c_t) b_t = 0$$

with $c_t = b_t - \frac{b_{t+1}}{1 + r_{t+1}} + e$.

(c)

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