

## Session 5 : Square matrices, determinant, change of basis

Def : Determinant of a square matrix  $\det : \text{square matrix} \rightarrow \mathbb{R}$

- Recursive recipe {
- 1)  $\det$   $1 \times 1$  matrix  $[x]$   
 $\det([x]) = x$
  - 2)  $A = (a_{ij})$        $i = \text{row}$   
                                 $j = \text{column}$   
 $\in \mathbb{R}^{n \times n}$        $M_{ij} = (i,j)$ -minor  
                                of matrix A
- $M_{ij} = \begin{bmatrix} \text{---} & \text{---} \\ \text{---} & \text{---} \end{bmatrix}_{n-1} \quad \begin{bmatrix} \text{---} & \text{---} \\ \text{---} & \text{---} \end{bmatrix}_{n-1} \cdot i$
- $M_{ij} = \begin{bmatrix} \text{---} & \text{---} \\ \text{---} & \text{---} \end{bmatrix}_{n-1}$

$$\dots \det(A) = \sum_{i=1}^n (-1)^{i+1} a_{i1} \det(M_{i1})$$

Example:

3x3 matrix  $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$

$$i=1 \quad \det(A) = a_{11} (-1)^{1+1} \det(M_{11}) +$$

$$i=2 \quad a_{21} (-1)^{2+1} \det(M_{21}) +$$

$$i=3 \quad a_{31} (-1)^{3+1} \det(M_{31}) =$$

$$= a_{11} \det \begin{pmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{pmatrix} - a_{21} \det \begin{pmatrix} a_{12} & a_{13} \\ a_{32} & a_{33} \end{pmatrix} + a_{31} \det \begin{pmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{pmatrix}$$

Finish this computation

Example :

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = a \cdot \det([d]) - c \det([b]) \\ = ad - cb$$

base  
case



"what are determinants  
useful for"

### Properties of determinant

1)  $\det(A) \neq 0 \iff A$  is full-rank

$$A \in \mathbb{R}^{n \times n} \quad \text{rank}(A) = n$$

$\iff$  columns are a basis of  $\mathbb{R}^n$

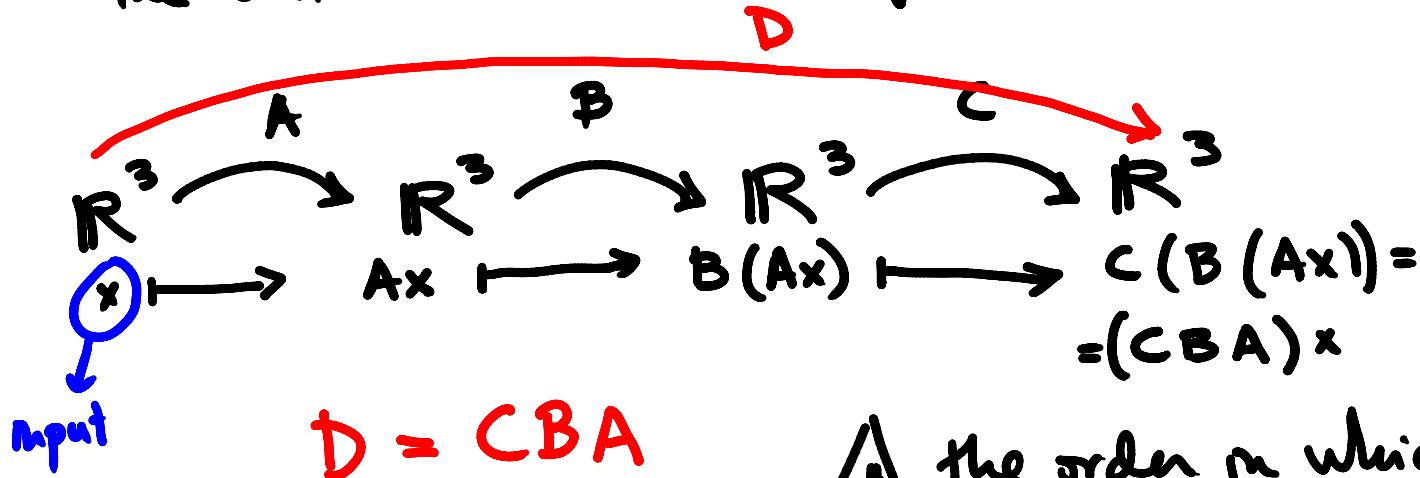
$\iff$  rows are a basis of  $\mathbb{R}^n$

$\iff$   $A$  is invertible, i.e., there  
is some matrix  $A^{-1}$  such that

$$A^{-1}A = AA^{-1} = \text{Id}_{n \times n} = \begin{bmatrix} 1 & & & \\ & \ddots & & \\ & & \ddots & \\ 0 & & & 1 \end{bmatrix}$$

$$2) \det(AB) = \det(A) \cdot \det(B)$$

the determinant is "multiplicative" w.r.t. matrix mult.



the order in which we multiply matrices reverses the order in which we compose linear transformations

$$3) \text{ If } A = \text{diagonal}(\lambda_1, \dots, \lambda_n)$$

$$\det(A) = \lambda_1 \lambda_2 \dots \lambda_n$$

$$4) \text{ If } A \text{ is triangular}$$

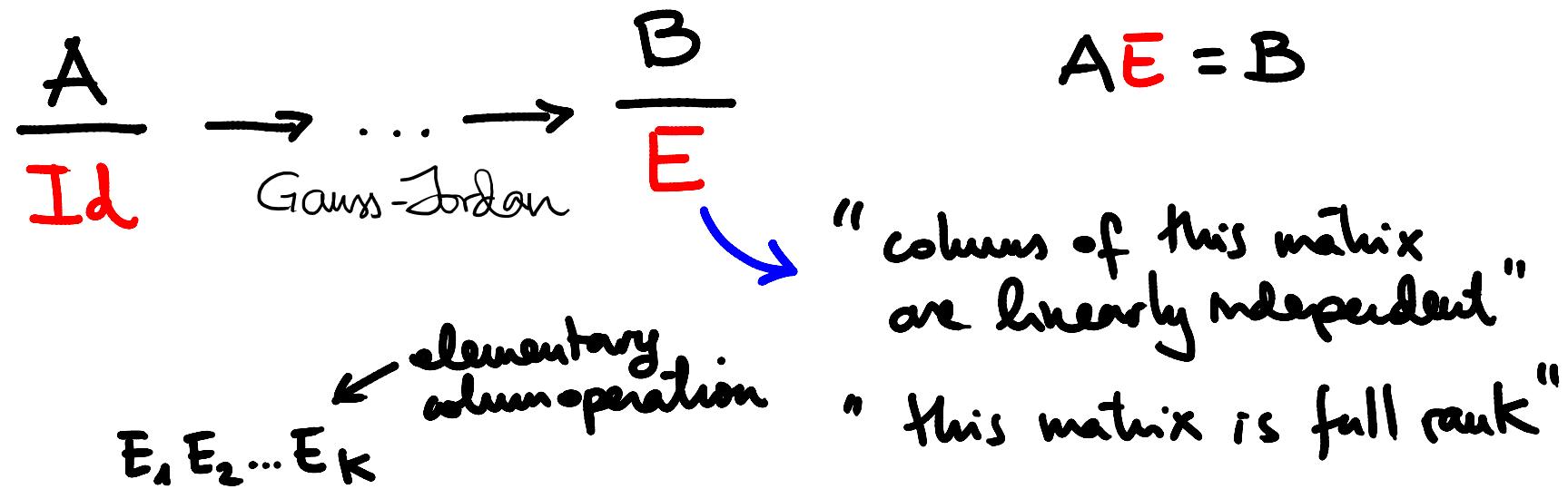
$$\det(A) = \text{product of diagonal entries}$$

$$A = \begin{bmatrix} \lambda_1 & & 0 \\ 0 & \ddots & \lambda_n \end{bmatrix}$$

$$A = \begin{bmatrix} * & * & * \\ 0 & * & * \\ 0 & 0 & \ddots \end{bmatrix} \text{ upper}$$

$$A = \begin{bmatrix} * & & & \\ * & \ddots & 0 \\ * & * & \ddots & * \\ 0 & 0 & \cdots & * \end{bmatrix} \text{ lower}$$

## Examples ( elementary column operations)



$$Id \rightarrow \dots \rightarrow E$$

$$E = E_1 E_2 \dots E_k$$

$$\det(E) = \frac{\det(E_1)}{\begin{matrix} + \\ 0 \end{matrix}} \frac{\det(E_2)}{\begin{matrix} + \\ 0 \end{matrix}} \dots \frac{\det(E_k)}{\begin{matrix} + \\ 0 \end{matrix}}$$

$$\Rightarrow \det(E) \neq 0 \Rightarrow E \text{ full rank}$$

This is related to [Exercise 1 - Session 3]

check it out!

1)  $\det(\text{Permutation}) = \text{Sign}(\text{Permutation})$  →

$= \pm 1 (\neq 0)$

$$\begin{bmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{bmatrix} \xrightarrow{\text{rearrange columns}} \begin{bmatrix} 0 & 1 & 0 & \dots \\ 1 & 0 & 0 & \\ 0 & 1 & 0 & \\ 0 & 0 & 1 & \end{bmatrix}$$

2)  $\det \left( \begin{bmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \right) = \lambda (\neq 0)$

3)  $\det \left( \begin{bmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & & & 1 \end{bmatrix} \right) = 1 (\neq 0)$

# Change of basis

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$f(e_1) \leftarrow$

$f(e_2) \leftarrow$

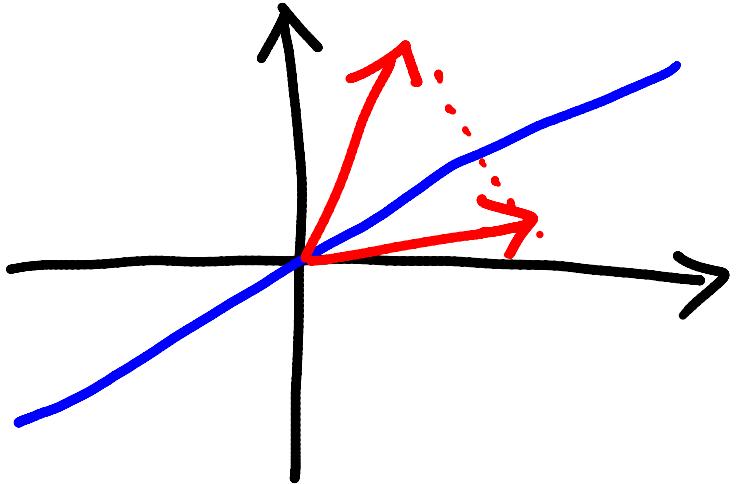
$$\begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Matrices define  
linear transf.

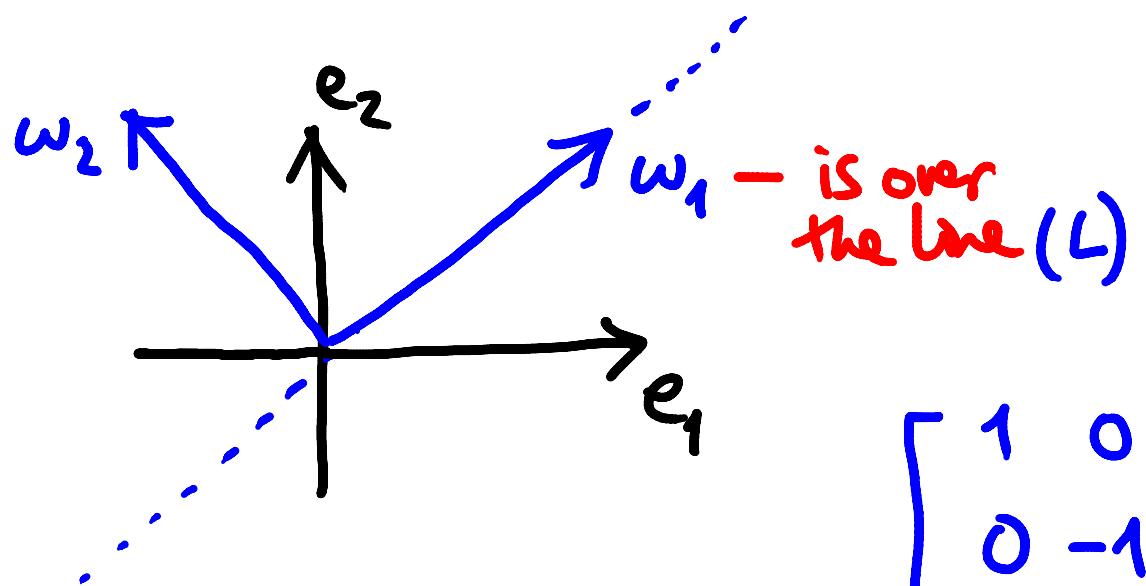
0, 0, ...

outputs of  
the canonical  
basis



Imagine a linear transf.  
that reflects vectors  
wrt  $\overline{(L)}$  I desired

$$\begin{bmatrix} * & * \\ * & * \end{bmatrix}$$



Sometimes matrices  
of a linear transformation  
are not intuitive enough

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

if we define  
the reflection  
using  $\{w_1, w_2\}$   
then the matrix  
is easier to understand.

Square  
Full-rank  
matrices

→ dictionaries

how to change basis

$\{w_1, \dots, w_n\}$  basis of  $\mathbb{R}^n$

$v \in \mathbb{R}^n$

$$v = \lambda_1 w_1 + \dots + \lambda_n w_n$$

coordinates of  $v$  w.r.t.  
basis  $\{w_1, \dots, w_n\}$

## DECODER

Given  $\mathcal{V}$  with coordinates  $(\lambda_1, \dots, \lambda_n)$   
wrt basis  $\{\omega_1, \dots, \omega_n\}$

What are the coords. of  $\mathcal{V}$  in canonical basis?

$\mathbb{R}^2$     Example :  $\left\{ \overbrace{(1,0)}^{u_1}, \overbrace{(1,1)}^{u_2} \right\}$  basis of  $\mathbb{R}^2$

$$\begin{aligned} e_1 &= (1,0) \\ e_2 &= (0,1) \end{aligned}$$

$$\begin{aligned} \mathbb{R}^3 \\ e_1 &= (1,0,0) \\ e_2 &= (0,1,0) \\ e_3 &= (0,0,1) \end{aligned}$$

$$\begin{aligned} u_1 &= (1,0) \\ u_2 &= (1,1) \end{aligned}$$

$$\mathcal{V} = 2u_1 + 3u_2$$

$$= \mu_1 e_1 + \mu_2 e_2$$

the DECODER will  
find  $\mu_1, \mu_2$

$$\text{v} = \textcolor{green}{2u_1 + 3u_2} \longrightarrow \begin{matrix} 2(1,0) + 3(1,1) \\ " \\ (2,0) + (3,3) \\ " \\ (5,3) \end{matrix}$$

Coordinates of v  
in the basis  $\{u_1, u_2\}$

INPUT

$$\boxed{5} \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \boxed{3} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

"                          "

$\mu_1$                            $\mu_2$

OUTPUT

You may simply write  
 $(\mu_1, \mu_2)$

Another example

$$v = 5u_1 + 3u_2 \quad \leftarrow \text{input}$$

$$\begin{aligned} u_1 &= (-1, 0) \\ u_2 &= (1, 1) \end{aligned} \quad \left\{ \begin{array}{l} \{u_1, u_2\} \text{ is a basis of } \\ \mathbb{R}^2 \end{array} \right.$$

Q? how is  $v$  written in the canonical basis  
 !!!

$$v = 5(-1, 0) + 3(1, 1)$$

component-wise

$$= (-5, 0) + (3, 3)$$

$$= (-2, 3)$$

matrix :

output

$$\begin{bmatrix} -1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 5 \\ 3 \end{bmatrix} = 5 \begin{bmatrix} -1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -5 \\ 0 \end{bmatrix} + \begin{bmatrix} 3 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$$



$\{v_1, v_2\}$  basis of  $\mathbb{R}^2$

$$u = \begin{pmatrix} \lambda_1 v_1 + \lambda_2 v_2 \\ \vdots \\ \vdots \\ \mu_1 e_1 + \mu_2 e_2 \end{pmatrix}$$

Canonical basis of  $\mathbb{R}^2$

# DE GODE R :

input :  $\lambda_1, \lambda_2$   
output :  $\mu_1, \mu_2$

A diagram illustrating the generative process. On the left, a bracketed pair of latent variables  $\gamma_1$  and  $\gamma_2$  is shown above a horizontal arrow. This arrow points to the right and is labeled "DECODER" in capital letters. Below the arrow, three vertical tick marks ("|||") indicate the flow continues to the final stage. On the right, another bracketed pair of observed variables  $\mu_1$  and  $\mu_2$  is shown.

$$\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} = A \cdot \begin{bmatrix} \gamma_1 \\ \gamma_2 \end{bmatrix}$$

multiplying by matrix

$$A = \begin{bmatrix} S_1 | S_2 \end{bmatrix}$$

# ENCODER

$\{v_1, v_2\}$  basis of  $\mathbb{R}^2$

input :  $\mu_1, \mu_2 \rightarrow ??$

output :  $\lambda_1, \lambda_2 \leftarrow$

$$\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} = A \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix}$$

$$A = [v_1 \mid v_2]$$



$A$  is invertible  
because  $A$  is full rank



$\bar{A}^{-1} \downarrow$   
 $\bar{A}^{-1}$  satisfies

$$\bar{A}^{-1} A = Id$$

$$\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} = A \begin{bmatrix} \gamma_1 \\ \gamma_2 \end{bmatrix}$$

$$A^{-1} \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} = A^{-1} A \begin{bmatrix} \gamma_1 \\ \gamma_2 \end{bmatrix} = \text{Id} \begin{bmatrix} \gamma_1 \\ \gamma_2 \end{bmatrix} = \begin{bmatrix} \gamma_1 \\ \gamma_2 \end{bmatrix}$$

In particular I have solved the ENCODER problem

$$\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \rightsquigarrow \boxed{A^{-1} \begin{bmatrix} \gamma_1 \\ \gamma_2 \end{bmatrix}} \quad \checkmark$$

*we know how to  
compute this, i.e. Gaus-Jordan*

$$\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \xrightarrow{\text{ENCODER}} \begin{bmatrix} \gamma_1 \\ \gamma_2 \end{bmatrix}$$

!!!

multiplying by matrix

$$A^{-1}$$

## Final Summary

Coords in  
new basis  
 $\{u_1, \dots, u_n\}$

"decoding"

$$\begin{array}{ccc} & A & \\ \xrightarrow{\hspace{2cm}} & & \xleftarrow{\hspace{2cm}} \\ & A^{-1} & \end{array}$$

Coords in  
Canonical basis

"encoding"

$$\begin{array}{ccc} v & \xrightarrow{\hspace{2cm}} & Av \\ \bar{A}^{-1}w & \xleftarrow{\hspace{2cm}} & w \end{array}$$

where

$$A = \begin{bmatrix} u_1 & \cdots & u_n \end{bmatrix}$$