# Weekly Presentation Week 40

Luleå University of Technology

September 28, 2020

## Group members

- Y-students
  - Martin Blaszczyk Project leader and object detection
  - Edward Cedergård -Arm and gripping tool
  - Niklad Dahlqvist Arm and gripping tool
  - Måns Norell Movable base
- D-students
  - Edward Källstedt Object detection
  - Albin Martinsson Arrowhead and Git

#### Overview

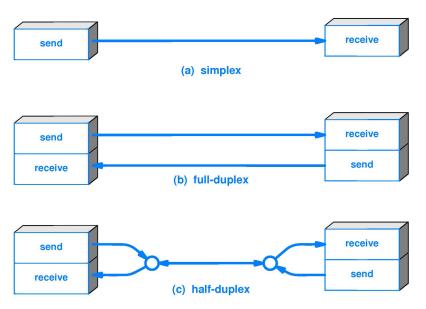
What we have done and what we are working on:

- Duplex to simplex
- Serial communication
- Dynamixel data packages
- Arm construction

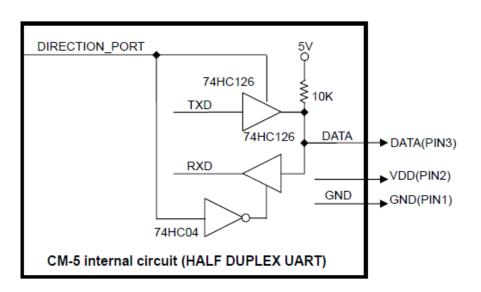
# Duplex to simplex

- Raspberry pi Tx, Rx
- Circuit

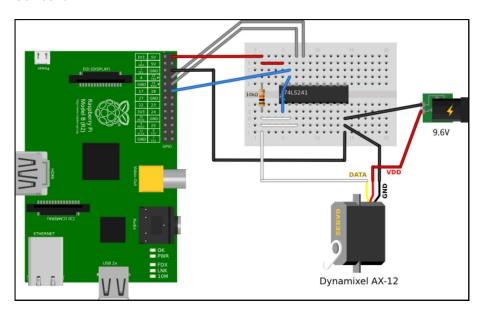
## Full-duplex to half-duplex



# Dynamixel communication



#### Curcuit



#### Serial communication

Logic analyzer

# Dynamixel data packages

- Structure
- Response

#### Arm construction

• Use the official plastic pieces

#### Overall timetable

Sep	Oct	Nov	Dec
Concept generation	Evaluation	Evaluation	
Theory	Prototyping	Evaluation	Finishing up
Simulation	Evaluation	Evaluation	
Prototyping	Final Design	Evaluation	

# Time plan for September

Subproject	Week 1	Week 2	Week 3	Week 4
Arrowhead	Reading	Setup	API	Prototyping
Movable base	Reading	Modeling	Simulation	Implementation
Arm and grip	Reading	Kinematics	Simulation	Prototyping
Object detection	Reading	Testing	Prototyping	Evaluation

# Questions?