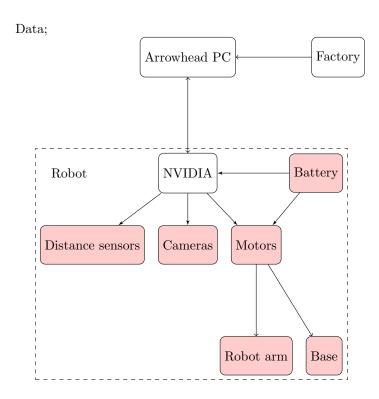
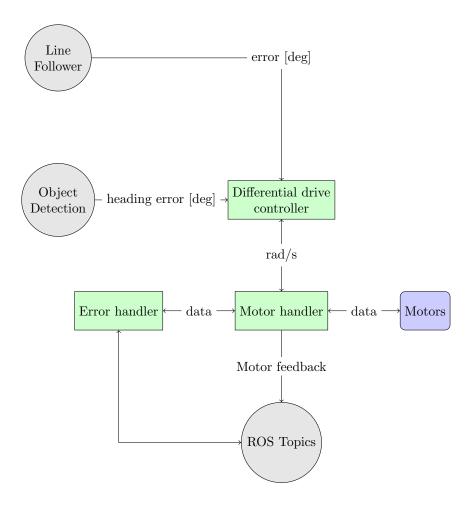
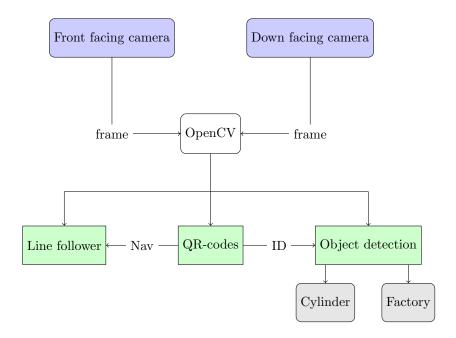
Hardware



Base

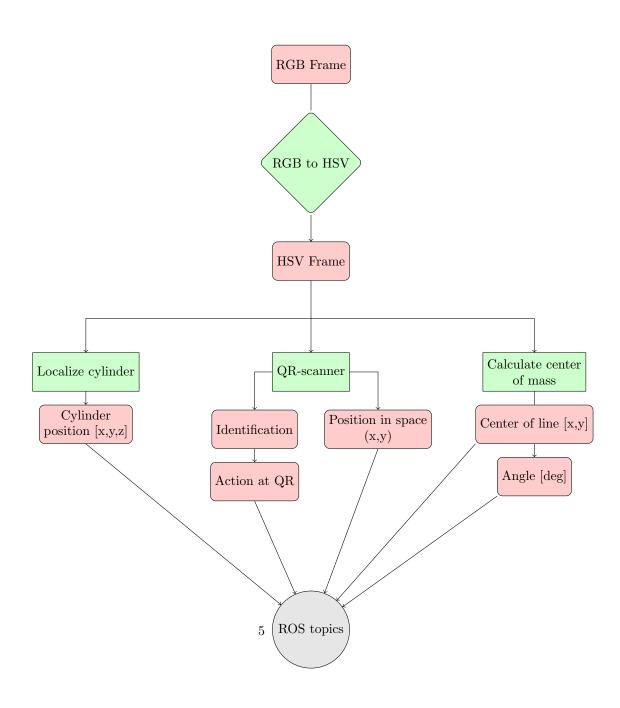


Machine vision

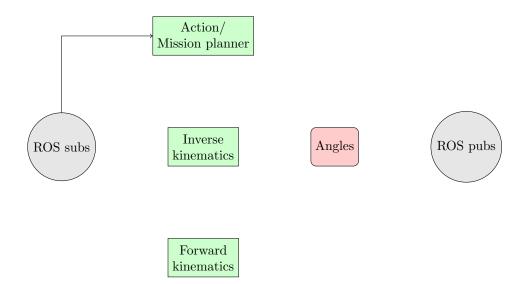




OpenCV

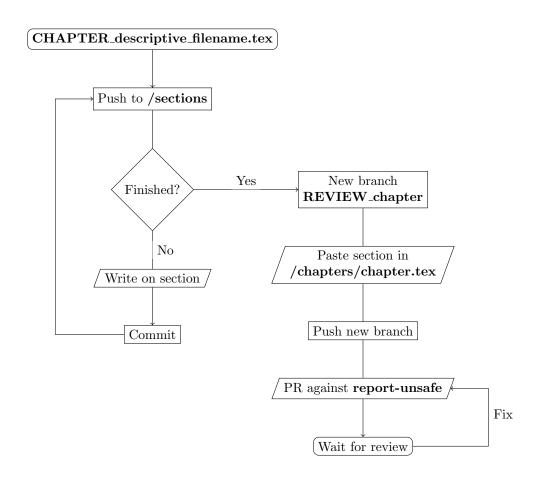


Robotic arm



Chapter 1

Report-unsafe workflow



Chapter 2

Arrowhead positioning

