Weekly Presentation Week 41

Luleå University of Technology

October 5, 2020

Overview

- Status update
 - Time plan
 - Report workflow

Positioning - Arrowhead

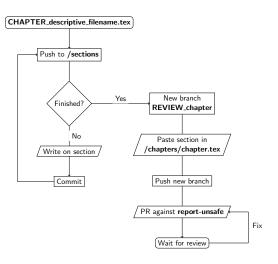
Overall timetable

Sep	Oct	Nov	Dec
Concept generation	Evaluation	Evaluation	
Theory	Prototyping	Evaluation	Finishing up
Simulation	Evaluation	Evaluation	
Prototyping	Final Design	Evaluation	

Time plan for October

Subproject	Week 1	Week 2	Week 3	Week 4
Arrow	Working	Structure	Fusion	
Base	CAD	ROS	Evaluation	Final
Arm	Assembly	Gripper / ROS	Evaluation	Final
MV	Porting to NVIDIA	Feature detection	Evaluation	

Report workflow



https://github.com/kottz/D7039E/tree/report-unsafe

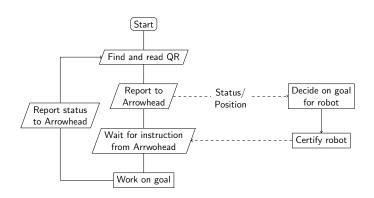
Week 41 - Bot V1

🗎 Due by October 11, 2020 0% complete

Assemble V1 of robot, make the base move with the robot arm

□ ① 10 Open ✓ 0 Closed		
Make the base move (movable base) respheri pl #26 opened 5 hours ago by Partins	(0)	
Gripping Mechanism (robot am) #22 opened 6 days ago by NiklasDahlquist1	œ	Ç 1
Make the arm move Tobot arm #27 opened 5 hours ago by Partins	œ	
Make two PCBs with TTL parts movable base robot arm #28 opened 5 hours ago by Partins	۵	
Plan how to integrate everything arrowhead #29 opened 5 hours ago by Partins	0	
□ O Finish report workflow - Niklas report #30 opened 5 hours ago by Partins		
☐ ⑤ Finish report workflow - Edward K report #31 opened 5 hours ago by Partins	8	
O Finish report workflow - Albin report #32 opened 5 hours ago by Partins	0	
Sinish report workflow - Mans report #33 opened 5 hours ago by Partins		
□ WIKI for communcation Raspberry pi and Dynamixel #25 opened 21 hours ago by edwced	0	

Positioning - Arrowhead



Questions?