Weekly Presentation Week 41

Luleå University of Technology

October 6, 2020

Overview

- Status update
 - Time plan
 - Report workflow

Positioning - Arrowhead

Overall timetable

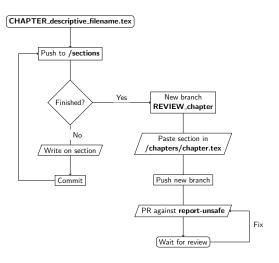
Sep	Oct	Nov	Dec
Concept generation	Evaluation	Evaluation	
Theory	Prototyping	Evaluation	Finishing up
Simulation	Evaluation	Evaluation	
Prototyping	Final Design	Evaluation	

Time plan for October

Subproject	Week 1	Week 2	Week 3	Week 4
Arrow	Working	Structure	Fusion	
Base	CAD	ROS	Evaluation	Final
Arm	Assembly	Gripper / ROS	Evaluation	Final
MV	Porting to NVIDIA	API	Evaluation	

4/7

Report workflow



https://github.com/kottz/D7039E/tree/report-unsafe

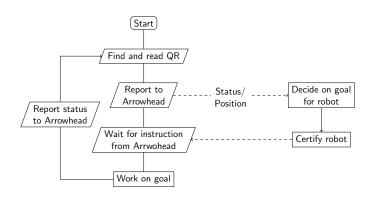
Week 41 - Bot V1

🗎 Due by October 11, 2020 0% complete

Assemble V1 of robot, make the base move with the robot arm

□ ① 10 Open ✓ 0 Closed			
☐ ① Make the base move (movable base) (raspberrip) #26 opened 5 hours ago by Partins ☐ 1 of 7 =		60	
Gripping Mechanism robot arm #22 opened 6 days ago by Niklas Dahlquist1		(199)	□ 1
Make the arm move robot arm #27 opened 5 hours ago by Partins		(199)	
☐ Make two PCBs with TTL parts movable base robot arm #28 opened 5 hours ago by Partins		ø	
Plan how to integrate everything arrowhead #29 opened 5 hours ago by Partins		0	
☐ ⑤ Finish report workflow - Niklas report #30 opened 5 hours ago by Partins	Îù 1	•	
☐ ⑤ Finish report workflow – Edward K report #31 opened 5 hours ago by Partins		8	
☐ ⑤ Finish report workflow - Albin report #32 opened 5 hours ago by Partins		0	
☐ ⑤ Finish report workflow - Mâns report #33 opened 5 hours ago by Partins			
□ ① WIKI for communcation Raspberry pi and Dynamixel #25 opened 21 hours ago by edwced		0	

Positioning - Arrowhead



Questions?