Transaktionssysteme – Übungsblatt 3

Gruppe 1, Team Zoidberg

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Aufgabe 1

a) $S := w_0(x)w_0(y)w_0(z)r_1(y)r_2(y)w_1(y)r_3(z)r_2(x)w_2(x)w_1(x)c_1c_2c_3$

$$H_S(w_0(x)) = f_0^x()$$
$$H_S(w_0(y)) = f_0^y()$$
$$H_S(w_0(z)) = f_0^z()$$
$$H_S(r_1(y)) = H_S(w_0(y)) = f_0^y()$$
$$H_S(r_2(y)) = H_S(w_0(y)) = f_0^y()$$
$$H_S(w_1(y)) = H_S(r_1(y), r_2(y)) = f_1^y(f_0^y(), f_0^y())$$
$$H_S(r_3(z)) = H_S(w_0(z)) = f_0^z()$$
$$H_S(w_3(z)) = H_S(r_3(z)) = f_3^z(f_0^z())$$
$$H_S(r_2(x)) = H_S(w_0(x)) = f_0^x()$$
$$H_S(w_2(x)) = H_S(r_2(x)) = f_2^x(f_0^x())$$
$$H_S(w_1(x)) = H_S(r_2(x)) = f_1^x(f_0^x())$$

b)

Aufgabe 2

$S := w_0(x)w_0(y)w_0(z)c_0r_1(x)r_2(x)w_2(y)r_3(x)c_1r_2(z)w_3(z)c_3w_2(z)c_2$

a)

$$H_S(w_0(x)) = f_0^x()$$
$$H_S(w_0(y)) = f_0^y()$$
$$H_S(w_0(z)) = f_0^z()$$
$$H_S(r_1(x)) = H_S(w_0(x)) = f_0^x()$$
$$H_S(r_2(x)) = H_S(w_0(x)) = f_0^x()$$
$$H_S(w_2(y)) = f_2^y()$$
$$H_S(r_3(x)) = H_S(w_0(x)) = f_0^x()$$
$$H_S(r_2(z)) = H_S(w_0(z)) = f_0^z()$$
$$H_S(w_3(z)) = H_S(r_2(z)) = f_3^z(f_0^z())$$
$$H_S(w_2(z)) = H_S(r_2(z)) = f_2^z(f_0^z())$$

b)

$$H[S](x) = H_S(w_0(x)) = f_0^x()$$
$$H[S](y) = H_S(w_2(y)) = f_2^y()$$
$$H[S](z) = H_S(w_2(z)) = f_2^z(f_0^z())$$

c) $S' := w_0(x)w_0(y)w_0(z)c_0w_2(y)c_1r_2(z)c_3w_2(z)c_2$

Aufgabe 3

a)

Aufgabe 4

a)

b)