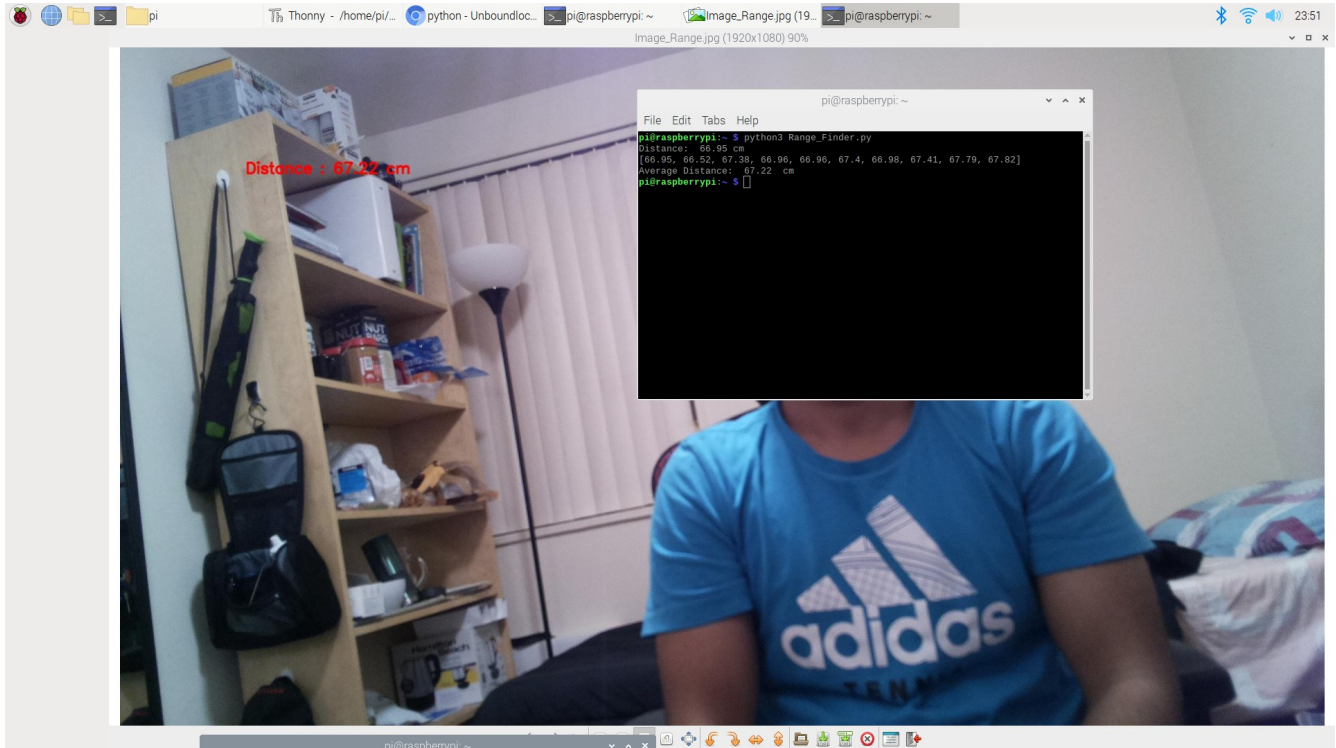


## Home Work -4

**Q1:** The folder got created on Raspi to save pictures and videos.

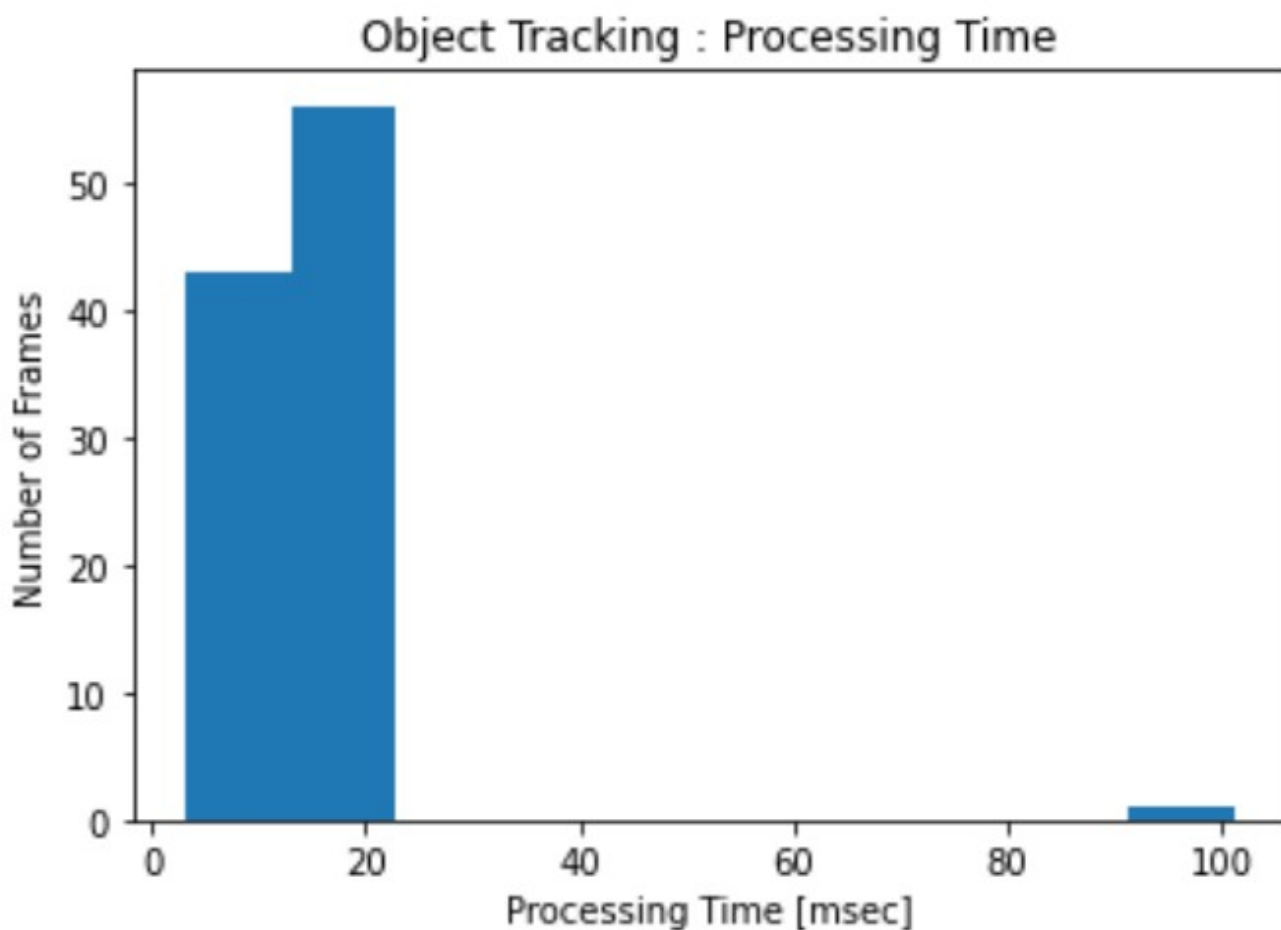
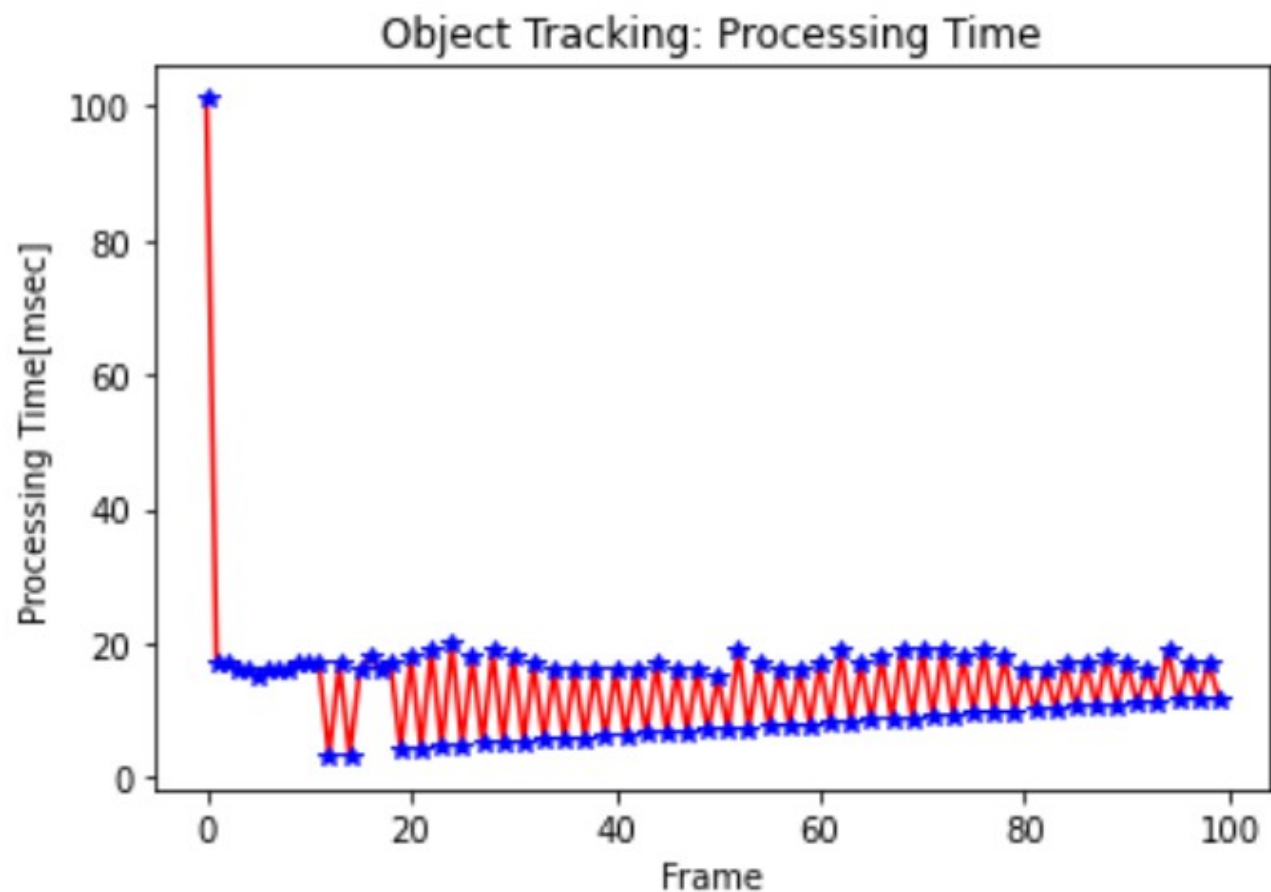
**Q2:**



**Q3:**

The video link for the video of arrow orientation detection can be seen [here](#).

The plots obtained are as follows:



### Limitations of Raspberry Pi:

- 1.)The main problem faced is because of Lighting during the video capture. As the light is being varied the masking values change based on the lighting conditions.
- 2.)The raspberry pi has very little processing power. Because of which it is really difficult for us to debug any infinite loop statements.
- 3.) If the object is moved too quickly due to low processing power in the Pi module, corners will not be detected properly.