

Visual Reconstruction of Human Activities from data generated using Inertial Motion sensors



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Motivation

For **Human Activity Recognition** (HAR) research, **generating a comprehensive dataset** with diverse activities & subject demographics is often a **laborious process** needing a huge amount of time, money, & effort.

To fix this problem, generative models can be used to synthetically produce data, but there is no method to visually reconstruct sensor data & validate its consistency with activity labels. This visual reconstruction can aid in recognition of bad training data for generative networks & provide a metric to assess the reliability of the synthetically generated data.

Objective

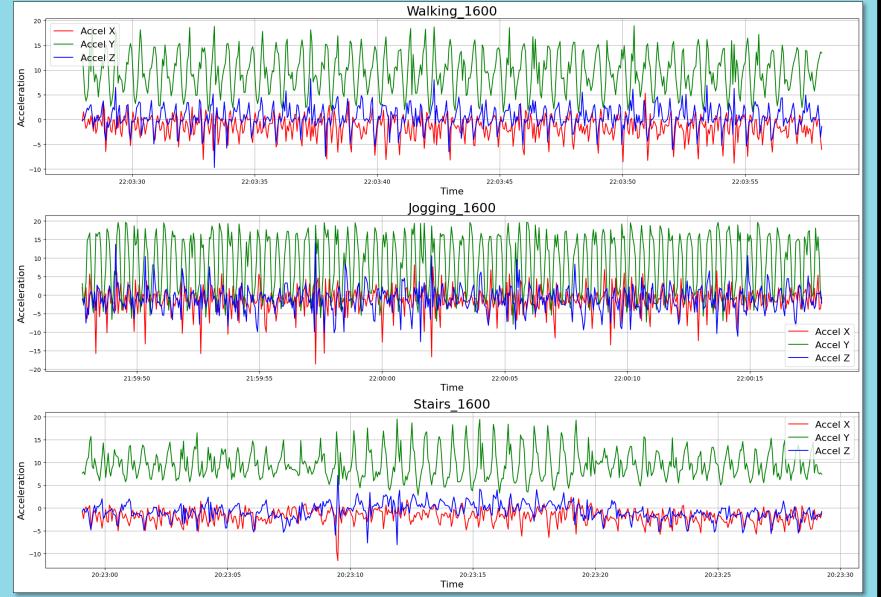
This project aims to use motion tracking data to **visually reconstruct human movement** in 3 dimensions with **6 degrees of freedom**, with the intention of manually classifying human activities & validating them against a set of ground truth labels.

Dataset & Framework

- ➤ WISDM dataset [1] was chosen
- as it offers **ample training data** for generative networks.
- Its **raw data format** allows for customized preprocessing, correction of inconsistencies & real-world data scale for visual reconstruction.
- It includes recordings from **both accelerometer** & **gyroscope sensors** of smartphones.

Out of 17 available activities, we chose the below 3 activities

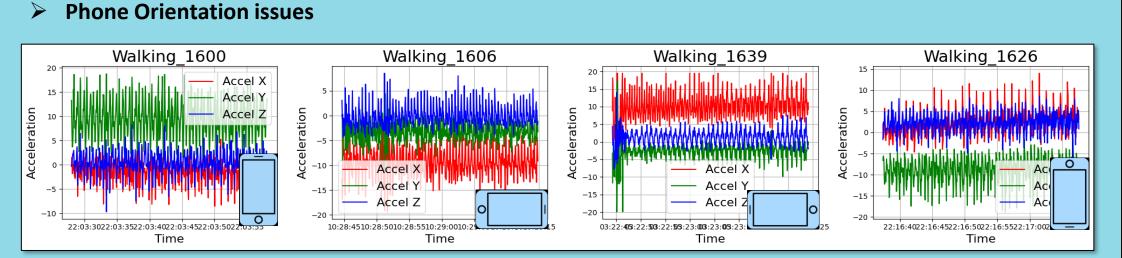
Activity Classes	Walking	Jogging	Stairs		
Observations	32.60%	33.01%	34.39%		
Walking 1600					



After exploring multiple frameworks, assessing their limitations & fit with respect to our requirements, we chose the **Unity [2]** game engine for visual reconstruction of human activity data. It provided us with a platform to use both displacement & orientation data to reconstruct the motion data.

Methodology

<u>Data Issues fixed</u>



We fixed this by shifting the signals, i.e., adding two times the absolute average of the amplitude and exchange X and Y axes if the average amplitude of the X-axis was more significant than the average amplitude of the Y-axis [3].

> Sampling issues

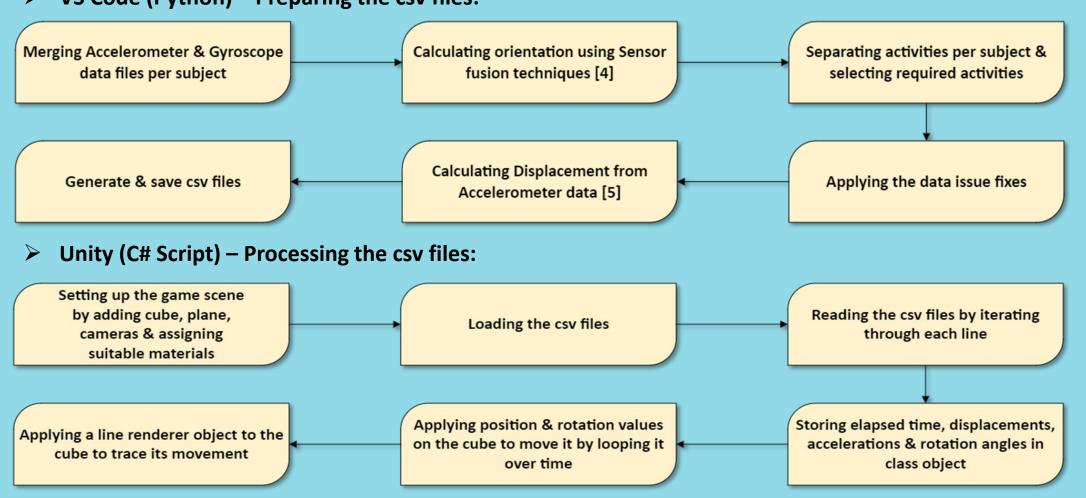
Data collected on different smartphones resulted in different sampling frequencies. For example, No. of sample points: ~3600 points for subjects 1600, 1602, 1604, ~4500 points for subjects 1601, 1647, ~14280 points for subject 1629, etc. We fixed this by resampling the frequency to 20 Hz [3].

Bad data removal

For some activities, in case of some subjects, there is not enough data. For e.g., in case of Jogging, subjects 1614, 1641, 1642, 1644, 1645, 1646., have **less than 300 data points**. We removed them.

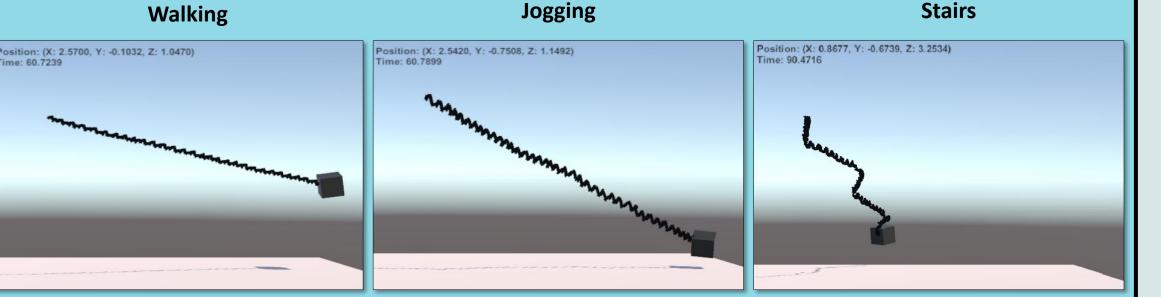
Visual Reconstruction process

➤ VS Code (Python) – Preparing the csv files:



Visual Reconstruction outputs

- For Jogging, the cube portraying the phone kept in the subject's hip pocket showed more frequent ups & downs as compared to Walking & Stairs.
- The distance travelled was more in the case of Jogging than Walking & Stairs over a fixed period.
- The Stairs movement showed a change in pace & orientation in fixed intervals which was a result of the landing area after a flight of stairs.



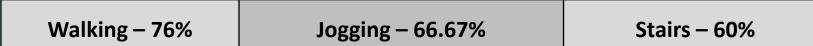
Results

Result Collection

- 15 test cases were created 5 sets for 3 activities.
- A form was sent out with unnamed labels for surveyors to fill out.

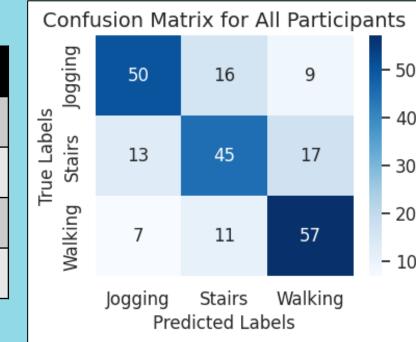
Metrics

Percentage of Activities Predicted Correctly:



Classification Report & Confusion Matrix:

		Precision	Recall	F1-score
	Walking	0.69	0.76	0.72
	Jogging	0.71	0.67	0.69
	Stairs	0.63	0.60	0.61
	Overall Accuracy		0.68	



Discussion

Evaluation

- The current setup used to visually reconstruct human activities showed that the outputs can be identified by humans with some accuracy.
- Its easier to compare reconstructed visuals and label them than looking at an isolated visual when viewing it without prior context.
- Its easier to identify Walking activity compared to other two, since Stairs and Walking was almost similar in case of some reconstructions, and some Jogging reconstructions showed deviation away from a straight line of motion.

Limitations

- The reconstructions showed a sinking effect in the Y-axis which might be due to accumulation of errors while converting acceleration to displacement.
- The current setup is not useful in case of multi sensor data obtained from sensors placed in multiple body locations of a human subject.

Future Work

We look to address the limitations discussed above by exploring filtering techniques and better sensor fusion algorithms. The multi sensor approach can be looked at using a humanoid model in Unity and applying forces in different joints. While this can be a starting point for future work, it needs rigorous experimentation to make a multi sensor visual reconstruction model work due to error accumulation and calibration issues.

References

- ➤ [1] G. M. Weiss, K. Yoneda, and T. Hayajneh. "Smartphone and Smartwatch-Based Biometrics Using Activities of Daily Living". In: IEEE Access 7 (2019), pp. 133190–133202.
- > [2] A. Juliani et al. Unity: A General Platform for Intelligent Agents. 2020. arXiv: https://arxiv.org/abs/1809.02627
- [3] M. Heydarian and T. E. Doyle. "rWISDM: Repaired WISDM, a Public Dataset for Human Activity Recognition". In: arXiv preprint arXiv:2305.10222 (2023).
- [4] Reference listTechnologies, x-io (2024). xioTechnologies/Fusion. [online] GitHub. Available at: https://github.com/xioTechnologies/Fusion?tab=readme-ov-file [Accessed 31 Jul. 2024].
- > [5] A. Blake, G. Winstanley, and W. Wilkinson. "Deriving Displacement from 3-Axis Accelerometers". In: Computer Games, Multimedia & Allied Technology. 2009.

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