

# FNU Koustubh

College Park, Maryland, USA

☎ +1(240)-481-5720 ✉ [koustubh1012@gmail.com](mailto:koustubh1012@gmail.com) 🌐 [github.com/koustubh1012](https://github.com/koustubh1012) 🔗 [linkedin.com/in/koustubh-j/](https://linkedin.com/in/koustubh-j/)

## EDUCATION

### University of Maryland, College-Park

May 2025

*Master of Engineering in Robotics*

*GPA: 3.8/4.0*

*Courses:* Autonomous Unmanned Aerial Vehicles(UAVs), Object-Oriented Programming, Path Planning, Robot Perception, Manufacturing and Automation, Software Development, Deep Learning and AI

### Institute of Engineering and Technology, Lucknow (Affiliated to AKTU, Lucknow)

August 2021

*Bachelor of Technology in Electrical Engineering*

*GPA: 8.0/10.0*

*Courses:* Control Systems, Embedded Systems, Power Systems, Electrical Machines, Engineering Mathematics

## PROJECTS

### UAV-Based 3D Reconstruction with MAST3R | *PX4 Autopilot, VOXL, ROS2, Python, C++, OpenCV, SFM*

- Developed an optimized UAV image acquisition pipeline using MAST3R for 3D reconstruction, reducing data redundancy by 60% while maintaining model quality; integrated with PX4, ROS2, and VOXL SDK for real-time onboard capture and telemetry.
- Containerized the pipeline with Docker and deployed it on AWS EC2 for scalable, reproducible 3D model generation from aerial imagery.

### Early Detection of Autism in children using AI | *Neural Networks, TensorFlow, Keras*

- Developed a neural network to detect autism in children using eye-tracking data by analyzing eye movement patterns during visual stimuli aiming to improve early diagnosis and intervention.
- Achieved a significant improvement over the baseline accuracy of 79.14 %, reaching over 87.8% accuracy in classifying autism using eye-tracking data, with a recall of 89.89 % .

### Autonomous TurtleBot3 Navigation using Visual Cues | *ROS2, Python, C++, OpenCV*

- Developed and deployed a ROS2 package for autonomous navigation, incorporating horizon detection and optical flow for enhanced perception, along with YOLOv8-based stop sign detection.
- Successfully implemented the system in Gazebo simulation and TurtleBot3 hardware, demonstrating adaptive path tracking, real-time obstacle avoidance, and automated stop sign recognition in a controlled testing arena.

## EXPERIENCE

### Maryland Applied Graduate Engineering, UMD College Park | *Grading Assistant* Aug. 2024 – May 2025

- Evaluating assignments and projects for ENPM662: Introduction to Robot Modeling and ENPM661: Planning for Autonomous Robots.
- Developed structured grading rubrics ensuring fair evaluation and constructive feedback for student learning.

### Tata Consultancy Services | *Assistant Systems Engineer* Oct. 2021 – Aug. 2023

- Managed the e-commerce platform of a fashion brand using Salesforce Commerce Cloud and Splunk monitoring, improving uptime and performance.
- Reduced MTTR by 65% through proactive issue resolution and automated monitoring strategies.
- Recognized with “Best Team Award” for outstanding performance and contribution to the project.

### Indian Institute of Technology, Bombay | *Research Intern* May 2020 – June 2020

- Developed educational content for Mobile Robotics MOOCs, impacting over 500 students globally by integrating practical simulations and coding exercises in technologies such as ROS, SLAM and path planning.
- Enhanced organizational outreach by actively contacting South African and Namibian university students to promote participation in the eYantra Robotics Competition and designing the eYantra yearbook.

## SKILLS

**Languages:** C++, Python, Bash, MATLAB

**Robotics:** Robot Operating System(ROS), Gazebo, SLAM, MoveIt, Navigation Stack, PX4 Autopilot, SolidWorks

**AI, Machine Learning and Computer Vision:** PyTorch, TensorFlow, Keras, OpenCV, YOLOv8

**DevOps & Cloud:** Linux, Docker, AWS EC2, Git, Unix Shell, Salesforce Commerce Cloud, Splunk, CI/CD