

# Algorithm 1015: A Fast Scalable Solver for the Dense Linear (Sum) Assignment Problem

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This document contains the instructions for building and testing the software bundle as well as instructions on how to use the software in your own project.

CCS Concepts: • **Mathematics of computing** → **Combinatorial algorithms**; **Combinatorial optimization**.

Additional Key Words and Phrases: Successive Shortest Path Algorithm, Parallel Processing, Epsilon Scaling

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## 1 Linux

This section contains the instructions for building and running under Linux. For Windows, refer to Section 2.

### 1.1 Requirements

The following software is required to build the source code that comes with this publication:

- CMake 3.5
- GCC
- CUDA 10 (or later, optional for the GPU build)

### 1.2 Build Instructions

To build the test package that was used to generate all the performance measurements in the main publication, run the following commands inside the `lap_solver` directory:

- `mkdir build`
- `cd build`
- `cmake ../gcc`
- `make`

Since the makefile is set up to compile the same code with multiple sets of defines, it is not possible to use the parallel build, e.g. `make -j4`, as this will cause the build to fail.

\*Work done while at TU Darmstadt.

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## 2 Windows

### 2.1 Requirements

The following software is required to build the source code that comes with this publication:

- Visual Studio (at least Community Edition) 2014, 2017 or 2019
- CUDA 10.2 (other versions require build files to be patched manually)

### 2.2 Build Instructions

To build the test package that was used to generate all the performance measurements in the main publication, the following steps are required:

- load solution from vc14, vc17 or vc19
- press Ctrl+Shift+B

## 3 Running Tests

The following commands will re-produce the data found in the figures and tables of the paper (Figure 1, 2 & 3 require special debug builds) using Linux. For Windows, the relative path is different (../../../../../../images/, when executing in the build directory).

- Table 1 & Figure 4:  

```
./test_cpu_evaluated -table_min 1000 -table_max 32000 -sanity -random -geometric
-geometric_disjoint -random_low_rank -rank_min 1 -rank_max 8 -double -single -runs
5 -omp
./test_cpu_evaluated -table_min 1000 -table_max 128000 -sanity -random -geometric
-geometric_disjoint -random_low_rank -rank_min 1 -rank_max 8 -double -epsilon -runs
5 -omp
```
- Figure 5:  

```
./test_cpu -table_min 1000 -table_max 32000 -sanity -geometric_disjoint
-random_low_rank -rank_min 1 -rank_max 8 -double -single -runs 5
./test_cpu -table_min 1000 -table_max 128000 -random -geometric -double -single
-runs 5
./test_cpu -table_min 1000 -table_max 128000 -sanity -random -geometric
-geometric_disjoint -random_low_rank -rank_min 1 -rank_max 8
-double -epsilon -runs 5
```
- Figure 6:  

```
./test_cpu -memory 257698037760 -cached_min 1000 -cached_max 1024000
-geometric_cached -geometric_disjoint_cached -sanity_cached -random_low_rank_cached
-rank_min 1 -rank_max 8 -double -epsilon -runs 5 -omp
```
- Figure 7:  

```
./test_gpu -memory 3221225472 -table_min 1000 -table_max 128000 -random -double
-epsilon -runs 5
./test_gpu -memory 3221225472 -cached_min 1000 -cached_max 1024000
-geometric_cached -geometric_disjoint_cached -sanity_cached -random_low_rank_cached
-rank_min 1 -rank_max 8 -double -epsilon -runs 5
```
- Figure 8:  

```
./test_gpu -memory 15032385536 -table_min 1000 -table_max 128000 -random -double
-epsilon -runs 5
./test_gpu -memory 15032385536 -cached_min 1000 -cached_max 1024000
-geometric_cached -geometric_disjoint_cached -sanity_cached -random_low_rank_cached
-rank_min 1 -rank_max 8 -double -epsilon -runs 5
```
- Figure 9:

```

./test_cpu -memory 128849018880 -img ../../images/img1s.ppm -img
../../images/img2s.ppm -img ../../images/img3s.ppm -img ../../images/img4s.ppm
-img ../../images/img5s.ppm -img ../../images/img6s.ppm -img ../../images/img7s.ppm
-img ../../images/img8s.ppm -img ../../images/img9s.ppm -img
../../images/img10s.ppm -float -single
./test_cpu -memory 128849018880 -img ../../images/img1m.ppm -img
../../images/img2m.ppm -img ../../images/img3m.ppm -img ../../images/img4m.ppm
-img ../../images/img5m.ppm -img ../../images/img6m.ppm -img ../../images/img7m.ppm
-img ../../images/img8m.ppm -img ../../images/img9m.ppm -img
../../images/img10m.ppm -float -single
./test_cpu -memory 128849018880 -img ../../images/img1s.ppm -img
../../images/img2s.ppm -img ../../images/img3s.ppm -img ../../images/img4s.ppm
-img ../../images/img5s.ppm -img ../../images/img6s.ppm -img ../../images/img7s.ppm
-img ../../images/img8s.ppm -img ../../images/img9s.ppm -img
../../images/img10s.ppm -float -epsilon -omp
./test_cpu -memory 128849018880 -img ../../images/img1m.ppm -img
../../images/img2m.ppm -img ../../images/img3m.ppm -img ../../images/img4m.ppm
-img ../../images/img5m.ppm -img ../../images/img6m.ppm -img ../../images/img7m.ppm
-img ../../images/img8m.ppm -img ../../images/img9m.ppm -img
../../images/img10m.ppm -float -epsilon -omp
./test_cpu -memory 257698037760 -img ../../images/img1l.ppm -img
../../images/img2l.ppm -img ../../images/img3l.ppm -img ../../images/img4l.ppm
-img ../../images/img5l.ppm -img ../../images/img6l.ppm -img ../../images/img7l.ppm
-img ../../images/img8l.ppm -img ../../images/img9l.ppm -img
../../images/img10l.ppm -float -epsilon -omp
/test_gpu -memory 3221225472 -img ../../images/img1s.ppm -img
../../images/img2s.ppm -img ../../images/img3s.ppm -img ../../images/img4s.ppm
-img ../../images/img5s.ppm -img ../../images/img6s.ppm -img ../../images/img7s.ppm
-img ../../images/img8s.ppm -img ../../images/img9s.ppm -img
../../images/img10s.ppm -float -epsilon
/test_gpu -memory 3221225472 -img ../../images/img1m.ppm -img
../../images/img2m.ppm -img ../../images/img3m.ppm -img ../../images/img4m.ppm
-img ../../images/img5m.ppm -img ../../images/img6m.ppm -img ../../images/img7m.ppm
-img ../../images/img8m.ppm -img ../../images/img9m.ppm -img
../../images/img10m.ppm -float -epsilon
/test_gpu -memory 3221225472 -img ../../images/img1l.ppm -img
../../images/img2l.ppm -img ../../images/img3l.ppm -img ../../images/img4l.ppm
-img ../../images/img5l.ppm -img ../../images/img6l.ppm -img ../../images/img7l.ppm
-img ../../images/img8l.ppm -img ../../images/img9l.ppm -img
../../images/img10l.ppm -float -epsilon
/test_gpu -memory 15032385536 -img ../../images/img1s.ppm -img
../../images/img2s.ppm -img ../../images/img3s.ppm -img ../../images/img4s.ppm
-img ../../images/img5s.ppm -img ../../images/img6s.ppm -img ../../images/img7s.ppm
-img ../../images/img8s.ppm -img ../../images/img9s.ppm -img
../../images/img10s.ppm -float -epsilon
/test_gpu -memory 15032385536 -img ../../images/img1m.ppm -img
../../images/img2m.ppm -img ../../images/img3m.ppm -img ../../images/img4m.ppm
-img ../../images/img5m.ppm -img ../../images/img6m.ppm -img ../../images/img7m.ppm
-img ../../images/img8m.ppm -img ../../images/img9m.ppm -img
../../images/img10m.ppm -float -epsilon
/test_gpu -memory 15032385536 -img ../../images/img1l.ppm -img
../../images/img2l.ppm -img ../../images/img3l.ppm -img ../../images/img4l.ppm

```

```
-img ../../images/img51.ppm -img ../../images/img61.ppm -img ../../images/img71.ppm
-img ../../images/img81.ppm -img ../../images/img91.ppm -img
../../images/img101.ppm -float -epsilon
```

- Table 2: Requires Auction solver which is not included in this package.
- Table 3: Data found in other tables except for limiting the number of threads to 8

## 4 Own Project

In order to use the software package in your own project, you need to include the `lap.h` file after setting the desired defines in your project. To get the same behaviour as the `test_cpu` program, use the following:

```
// enable OpenMP support
#ifdef _OPENMP
# define LAP_OPENMP
#endif
// quiet mode
#define LAP_QUIET
// increase numerical stability for non-integer costs
#define LAP_MINIMIZE_V
```

In case you would like to use GPU support, use the following as a starting point:

```
// enable CUDA support
#define LAP_CUDA
// OpenMP required for multiple devices
#define LAP_CUDA_OPENMP
// quiet mode
#define LAP_QUIET
// increase numerical stability for non-integer costs
#define LAP_MINIMIZE_V
```

### 4.1 High-Level Interface

The high-level interface can be found in the `test_cpu.cpp` and `test_gpu.cu` files. The CPU functions are:

```
template <class SC, class TC, class CF, class TP>
void solveAdaptiveOMP(TP &start_time, int N1, int N2, CF &get_cost, int *rowsol,
                     int entries, bool epsilon)
```

and

```
template <class SC, class TC, class CF, class TP>
void solveAdaptive(TP &start_time, int N1, int N2, CF &get_cost, int *rowsol,
                  int entries, bool epsilon)
```

Where:

- SC is the type used within the solver.
- TC is the type for storing the cost values.
- TP &start\_time is starting time of the test returned by `std::chrono::high_resolution_clock::now();`
- int N1 and int N2 specify the size of the problem
- CF &get\_cost is the cost function lambda that takes two parameters int x, int y ( $0 \leq x < N1$  and  $0 \leq y < N2$ ) and returns the cost of type TC

- `int *rowsol` points to the row solution being returned
- `bool epsilon` enables out  $\epsilon$ -Pricing and should always be enabled.

The corresponding GPU functions are:

```
template <class SC, class TC, class CF, class STATE, class TP>
void solveCUDA(TP& start_time, int N1, int N2, CF& get_cost_gpu, STATE* state,
               lap::cuda::Worksharing& ws, long long max_memory, int* rowsol,
               bool epsilon, bool silent)
```

and

```
template <class SC, class TC, class CF, class TP>
void solveTableCUDA(TP& start_time, int N1, int N2, CF& get_cost_cpu,
                   lap::cuda::Worksharing& ws, long long max_memory,
                   int* rowsol, bool epsilon, bool sequential, bool pinned,
                   bool silent)
```

The difference between these functions is that the first one uses a device lambda `CF &get_cost_gpu` with parameters `(int x, int y, STATE &state)` while the second function uses a regular `cpu` lambda as in the `cpu` code above. Additional parameters are:

- A work sharing struct `ws`, constructed using `lap::cuda::Worksharing ws(int N1, int multiple, std::vector<int> &devices, int max_devices, bool silent);` with `multiple` usually set to 256 for better memory and thread alignment
- `STATE *state` is a used defined per GPU state passed to the `get_cost_gpu` function, including pointer to memory locations used inside the device lambda
- `long long max_memory` defines how much memory should be allocated on a single GPU for holding the cost values (either cache or table)
- `bool sequential` specifies if the `get_cost_cpu` lambda can only be called from a single thread
- `bool pinned` if true, the entire CPU cost table will be stored in pinned memory

## 4.2 Low-Level Interface

The low-level interface can be found in the `lap.h` include files. The single threaded CPU code consists of the following functions for solving the linear assignment and calculating the final costs:

```
namespace lap
{
    template <class SC, class CF, class I> void solve(
        int dim, CF &costfunc, I &iterator, int *rowsol, bool use_epsilon);
    template <class SC, class CF, class I> void solve(
        int dim, int dim2, CF &costfunc, I &iterator, int *rowsol,
        bool use_epsilon);
    template <class SC, class CF> SC cost(
        int dim, CF &costfunc, int *rowsol);
    template <class SC, class CF> SC cost(
        int dim, int dim2, CF &costfunc, int *rowsol);
}
```

The multi threaded CPU code uses the following interface:

```
namespace lap
{
    namespace omp
```

```

{
    template <class SC, class CF, class I> void solve(
        int dim, CF &costfunc, I &iterator, int *rowsol, bool use_epsilon);
    template <class SC, class CF, class I> void solve(
        int dim, int dim2, CF &costfunc, I &iterator, int *rowsol,
        bool use_epsilon);
    template <class SC, class CF> SC cost(
        int dim, CF &costfunc, int *rowsol);
    template <class SC, class CF> SC cost(
        int dim, int dim2, CF &costfunc, int *rowsol);
}
}

```

The GPU version of the interface is as follows:

```

namespace lap
{
    namespace cuda
    {
        template <class SC, class TC, class CF, class I> void solve(
            int dim, CF &costfunc, I &iterator, int *rowsol, bool use_epsilon);
        template <class SC, class TC, class CF, class I> void solve(
            int dim, int dim2, CF &costfunc, I &iterator, int *rowsol,
            bool use_epsilon);
        template <class SC, class TC, class CF> SC cost(
            int dim, CF &costfunc, int *rowsol, cudaStream_t stream);
        template <class SC, class TC, class CF> SC cost(
            int dim, int dim2, CF &costfunc, int *rowsol, cudaStream_t stream);
    }
}

```

Please refer to the same file for additional helper classes that can be used for the low-level interface.

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