CSE 546 HW #0

Sam Kowash

October 4, 2018

(1) Analysis

- 1. A set $A \subseteq \mathbb{R}^n$ is convex if $\lambda x + (1 \lambda)y \in A$ for all $x, y \in A$. A norm $\|\cdot\|$ on \mathbb{R}^n is non-negative, absolutely scalable, and satisfies the triangle inequality.
 - (a) Let $A = \{x \in \mathbb{R}^n : ||x|| \le 1\}$ for some norm $||\cdot||$, take $x, y \in A$, and take $\lambda \in [0, 1]$. By the triangle inequality,

$$\|\lambda x + (1 - \lambda)y\| \le \|\lambda x\| + \|(1 - \lambda)y\|.$$

Scalability then tells us

$$\|\lambda x\| + \|(1 - \lambda)y\| = |\lambda| \|x\| + |1 - \lambda| \|y\|.$$

and since $0 \le ||x||, ||y|| \le 1$,

$$|\lambda| ||x|| + |1 - \lambda| ||y|| \le |\lambda| + |1 - \lambda|.$$

Lastly, with $\lambda \in [0, 1]$, $|\lambda| = \lambda$ and $|1 - \lambda| = 1 - \lambda$, so by applying transitivity through the chain of (in)equalities, we find

$$\|\lambda x + (1-\lambda)y\| \leq 1$$
,

so $\lambda x + (1 - \lambda)y \in A$ and A is convex, regardless of the norm used.

- (b) Consider the function $f(x) = \left(\sum_{i=1}^{n} |x_i|^{\frac{1}{2}}\right)^2$ for $x \in \mathbb{R}^n$. It is clearly non-negative for all inputs since it is a square of a sum of real numbers. Further, it is absolutely scalable, since a factor λ will come out of the sum as $\sqrt{|\lambda|}$, then be squared to give an overall scaling $|\lambda|$. However, consider $x = (1,0,0,\ldots,0)$ and $y = (0,1,0,\ldots,0)$. We have f(x) = f(y) = 1, but $f(x+y) = (\sqrt{1} + \sqrt{1})^2 = 4$, so f(x+y) > f(x) + f(y) meaning that this function does not satisfy the triangle inequality and cannot be a norm. (We can also see this by plotting a level set of this function and noting that the region bounded by it is non-convex, in contradiction to the previous result.)
- 2. For $x \in \mathbb{R}^n$, define the norms

$$||x||_1 = \sum_{i=1}^n |x_i|,$$
 $||x||_2 = \sqrt{\sum_{i=1}^n |x_i|^2},$ $||x||_{\infty} = \max_{i=1,\dots,n} |x_i|.$

Each norm must obey the triangle inequality, so in particular (if we apply the inequality repeatedly),

$$||x|| = \left\| \sum_{i=1}^{n} x_i e_i \right\| \le \sum_{i=1}^{n} ||x_i e_i|| = \sum_{i=1}^{n} |x_i| = ||x||_1,$$

where e_i are unit basis vectors with respect to the given norm and the second equality comes by absolute scalability. Thus, we see that no norm exceeds the Manhattan norm. Further,

$$||x||_2 = \sqrt{\sum_{i=1}^n |x_i|^2} \geqslant \sqrt{(\max_{i=1,\dots,n} |x_i|)^2} = \max_{i=1,\dots,n} |x_i| = ||x||_{\infty},$$

so the infinity norm cannot exceed the Euclidean norm. This gives the ranking $||x||_{\infty} \leq ||x||_{1}$, as desired.

3. For $A, B \in \mathbb{R}^{n \times n}$, $c \in \mathbb{R}$, and $f(x, y) = x^T A x + y^T B x + c$ acting on $x, y \in \mathbb{R}^n$, we define the derivative

$$\nabla_z f(x,y) = \begin{bmatrix} \frac{\partial f(x,y)}{\partial z_1} & \frac{\partial f(x,y)}{\partial z_2} & \cdots & \frac{\partial f(x,y)}{\partial z_n} \end{bmatrix}^T.$$

It will be cleaner to compute these derivatives with matrix operations expressed componentwise, so for the rest of this problem we adopt Einstein summation notation wherein repeated indices are summed over. We will also use ∂_{z_i} to denote $\frac{\partial}{\partial z_i}$. Then,

$$(\nabla_x f(x,y))_i = \partial_{x_i} (A_{jk} x_j x_k + B_{jk} y_j x_k + c)$$

= $\delta_{ij} A_j k x_k + \delta_{ik} A_j k x_j + \delta_{ik} B_{jk} y_j$
= $A_{ik} x_k + x_j A_{ji} + y_j B_{ji}$,

so, returning to matrix notation,

$$\nabla_x f(x, y) = (A + A^T)x + B^T y. \tag{1.1}$$

Similarly,

$$(\nabla_y f(x,y))_i = \partial_{y_i} (A_{jk} x_j x_k + B_{jk} y_j x_k + c)$$
$$= \delta_{ij} B_{jk} x_k$$
$$= B_{ik} x_k,$$

SO

$$\nabla_y f(x, y) = Bx.$$

- 4. Let $A, B \in \mathbb{R}^{n \times n}$ be symmetric matrices sharing eigenvectors u_1, \ldots, u_n with corresponding eigenvalues $\alpha_1, \ldots, \alpha_n$ for A and β_1, \ldots, β_n for B.
 - (a) The matrix C = A + B shares the eigenvectors u_1, \ldots, u_n , with eigenvalues $\alpha_1 + \beta_1, \ldots, \alpha_n + \beta_n$.
 - (b) The matrix D = A B shares the eigenvectors u_1, \ldots, u_n , with eigenvalues $\alpha_1 \beta_1, \ldots, \alpha_n \beta_n$.
 - (c) The matrix E = AB shares the eigenvectors u_1, \ldots, u_n , with eigenvalues $\alpha_1 \beta_1, \ldots, \alpha_n \beta_n$.
 - (d) Assuming that A is nonsingular, the matrix $F = A^{-1}B$ shares the eigenvectors u_1, \ldots, u_n , with eigenvalues $\frac{\beta_1}{\alpha_1}, \ldots, \frac{\beta_n}{\alpha_n}$.
- 5. A symmetric matrix $A \in \mathbb{R}^{n \times n}$ is positive-semidefinite (PSD) if $x^T A x \ge 0$ for all $x \in \mathbb{R}^n$.

(a) Let $y \in \mathbb{R}^n$. For any $x \in \mathbb{R}^n$, note that $x^T y = y^T x$, so

$$x^T y y^T x = (y^T x)^2 \geqslant 0,$$

so yy^T is PSD.

- (b) Let X be a random vector in \mathbb{R}^n with covariance matrix $\Sigma = \mathbb{E}\left[(X \mathbb{E}[X])(X \mathbb{E}[X])^T\right]$. By the previous result, $(X \mathbb{E}[X])(X \mathbb{E}[X])^T$ is PSD since it's the outer product of a vector with itself. Sums of PSD matrices must be PSD, so any linear combination of PSD matrices with non-negative weights is in turn PSD. The expected value is such a combination, with weights given by the PDF of X, so Σ is PSD.
- (c) Take A to be a symmetric matrix so that (by the real spectral theorem) there exist an orthogonal matrix U and list of eigenvalues α satisfying $A = U \operatorname{diag}(\alpha)U^T$. The columns of U form basis for \mathbb{R}^n , so we can decompose any vector $x \in \mathbb{R}^n$ as $x = \sum_i c_i u_i$, where c_i are scalars and u_i are the columns of U. Because that basis is in fact orthonormal, we know that $Uu_i = e_i$, so

$$x^{T}Ax = \left(\sum_{i} c_{i} u_{i}^{T}\right) U \operatorname{diag}(\alpha) U^{T} \left(\sum_{j} c_{j} u_{j}\right)$$
$$x^{T}Ax = \left(\sum_{i} c_{i} e_{i}^{T}\right) \operatorname{diag}(\alpha) \left(\sum_{j} c_{j} e_{j}\right)$$
$$x^{T}Ax = \sum_{i} c_{i}^{2} \alpha_{i},$$

where orthonormality collapses one of the sums. The resulting sum can only be non-negative for all choices of components c_i if the eigenvalues α_i are each non-negative, which is to say that $\min_i \alpha_i \ge 0$.

- 6. Consider real independent variables X and Y with PDFs f and g, respectively. Let h be the PDF of Z = X + Y.
 - (a) The PDF for the sum of X and Y will be the convolution of their respective PDFs:

$$h(x) = \int_{-\infty}^{\infty} f(y)g(x - y) dy.$$

We can understand this as accounting for the probabilities of all of the different ways that outcomes of X and Y can add to a particular outcome x of Z.

(b) In particular we take X and Y both uniformly distributed on [0,1]. It is easy to think about the convolution geometrically as sliding one unit square past the other and measuring the area of overlap. This falls to zero outside of (0,2) and rises to a maximum of 1 at x = 1, with linear change in between, so we can write

$$h(x) = \begin{cases} x & : 0 \le x \le 1 \\ 2 - x & : 1 < x \le 2 \\ 0 & : \text{else} \end{cases}.$$

(c) We now wish to find $\mathbb{P}(X \leq 1/2 \mid X + Y \geq 5/4)$ for these distributions. This, too, we can think of geometrically: if we put values of X on the x-axis and those of Y on the

y-axis, the joint distribution has support on the unit square in the first quadrant. The event $X + Y \ge 5/4$ has probability equal to the area of the upper triangle bounded by y = 5/4 - x, and $(X \le 1/2) \cap (X + Y \ge 5/4)$ is the portion of that triangle in the left half of the unit square. The diagonal boundary line for the triangle meets the edges of the square at (1, 1/4) and (1/4, 1), so the triangle has base and height 3/4 and so area 9/32. The smaller triangle has base and height 1/4 and area 1/32, so the conditional probability is 1/9. See Fig. '1.1 for clarification.

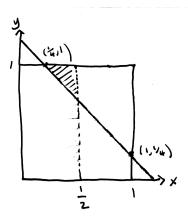


Figure 1.1: Geometry of conditional probability calculation

7. Given a random variable $X \sim \mathcal{N}(\mu, \sigma^2)$, we wish to define Y = aX + b such that $Y \sim \mathcal{N}(0, 1)$. We can do this just by inspecting the differential probability

$$d\mathbb{P}(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{(x-\mu)^2}{2\sigma^2}\right] dx.$$

If we define $x = \frac{y-b}{a}$, we see

$$d\mathbb{P}(y) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{\left(\frac{y-b}{a} - \mu\right)^2}{2\sigma^2}\right] \frac{dy}{a},$$

which we can rearrange into

$$d\mathbb{P}(y) = \frac{1}{\sqrt{2\pi(a\sigma)^2}} \exp\left[-\frac{(y - (b + a\mu))^2}{2(a\sigma)^2}\right] dy.$$

It is then clear that $a=1/\sigma$ and $b=-\frac{\mu}{\sigma}$ gives a Gaussian distribution with zero mean and unit variance, as desired.

8. Let X_1, \ldots, X_n be i.i.d. random variables with CDF F(x). We define $\hat{F}_n(x) = \frac{1}{n} \sum_{i=1}^n \mathbf{1}\{X_i \leq x\}$, where $\mathbf{1}(A)$ is the indicator function for a Boolean event A, which is 1 when A is true and 0 otherwise.

(a) We know that for any random variable X, $\mathbb{E}[\mathbf{1}\{X \leq x\}]$ is equal to the CDF of X. Since all of our n variables have the same CDF,

$$\mathbb{E}[\hat{F}_n(x)] = \frac{1}{n} \sum_{i=1}^n F(x) = \frac{nF(x)}{n} = F(x).$$

(b) We now wish to find $\mathbb{E}[(\hat{F}_n(x) - F(x))^2]$, which by the previous result we recognize is equal to $\mathbb{E}[\hat{F}_n(x)^2] - F(x)^2$, so we should focus on computing $\mathbb{E}[\hat{F}_n^2]$.

$$\left(\hat{F}_n(x)\right)^2 = \frac{1}{n^2} \sum_{i,j=1}^n \mathbf{1}\{X_i \le x\} \mathbf{1}\{X_j \le x\}$$

This double sum has two types of terms. There are n diagonal terms where i = j and we get a square of an indicator function, which is just the same indicator function back again and has expectation F(x). There are also $n^2 - n$ off-diagonal terms where $i \neq j$ and we should think of the product as the indicator function for the event $(X_i \leq x) \cap (X_j \leq x)$ and its expected value as the joint CDF for X_i and X_j . Because all of our variables are independent, that joint CDF is just the product of CDFs for the variables, which are here the same, so these off-diagonal terms give $(F(x))^2$. Thus,

$$\mathbb{E}[(\hat{F}_n(x) - F(x))^2] = \frac{1}{n^2} \left[nF(x) + (n^2 - n) (F(x))^2 \right] - (F(x))^2$$

$$\mathbb{E}[(\hat{F}_n(x) - F(x))^2] = \frac{F(x) (1 - F(x))}{n}.$$

(c) Looking at the numerator of the previous result as a quadratic function of F(x), we see that it is maximal when F(x) = 1/2, which gives the numerator a maximum value of 1/4. This means that

$$\sup_{x \in \mathbb{R}} \mathbb{E}\left[\left(\hat{F}_n(x) - F(x) \right)^2 \right] \leqslant \frac{1}{4n}.$$

(2) Programming

9. We investigate the central limit theorem numerically, using the family of random variables $Y^{(k)} = \frac{1}{\sqrt{k}} \sum_{i=1}^{k} B_i$, where each B_i takes values -1 and 1 with equal probability. The last result above tells us that

$$\sup_{x} \sqrt{\mathbb{E}[(\hat{F}_n(x) - F(x))^2]} \leqslant \frac{1}{2\sqrt{n}},$$

so for n = 40000 we can guarantee that the standard deviation of the empirical CDF $\hat{F}_n(x)$ is no greater than 0.0025.

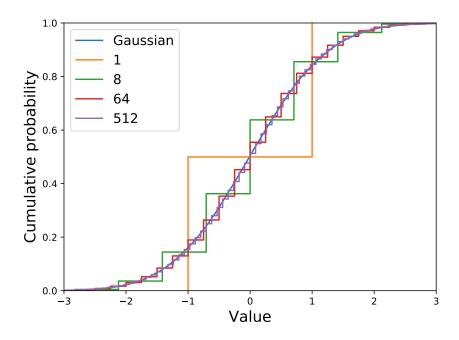


Figure 2.1: Empirical CDFs of Gaussian and of $Y^{(k)}$ for various k

Figure 2.1 plots the estimator $\hat{F}_n(x)$ for a Gaussian random variable and for our family $Y^{(k)}$ at various values of k. We can see that as k increases, $\hat{F}_n^{(k)}$ tends toward \hat{F}_n , justifying the claim of the central limit theorem that $Y^{(k)}$ tends toward a normal random variable as $k \to \infty$. Code follows on next page.

```
\#!/usr/bin/env python
import numpy as np
import matplotlib.pyplot as plt
n = 40000
\#gaussian \ cdf
Z = np.random.randn(n)
plt. step (sorted (Z), np. arange (1, n+1)/n, label="Gaussian")
\#y^{(k)} c dfs
for k in [1,8,64,512]:
    Yk = np.sum(np.sign(np.random.randn(n,k))*np.sqrt(1/k), axis=1)
    plt. step (sorted(Yk), np. arange (1, n+1)/n, label=k)
#plot details
plt . xlim ((-3,3))
plt.ylim((0,1))
plt.xlabel("Value", fontsize=16)
plt.ylabel ("Cumulative_probability", fontsize=16)
plt.legend(fontsize=14)
#uncomment if testing
\#plt.show()
#comment out if testing
plt.tight_layout()
plt.savefig('../figures/cdfs.pdf')
```