Root-Cause Analysis through Reinforcement Learning To AFLRL (AMERICAN FUZZY LOP FOR REINFORCEMENT LEARNING)

By KP

Overview

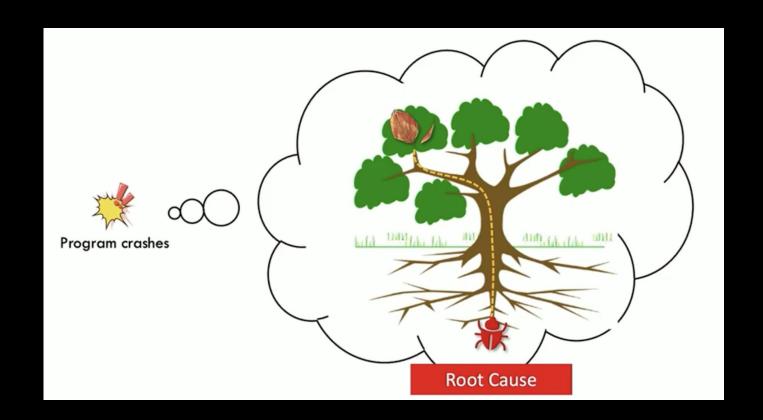
- RCA: For finding security vulnerabilities through fuzzing.
- RCA is slow, I mean very slow.
- Proper mutation for sample needed.
- Reinforcement Learning Implementation.
- Counterexamples are the key.
- Approach of using RACING increasing scalability and better than today's RCA.

Introduction

- Need for automation for faster devops cycle.
- CVE-2017-5380, CVE-2018-4145 and CVE-2022-36320.
- Try to find the crash is the key
- How to achieve that? Through mutation of test cases.
- Root cause analysis which has been done manually.

SLow Slow Slowwww......

RCA



Example

```
eopt = get_data (NULL, filedata, options_offset, 1,
                                                                     An example: CVE-2019-9077
                          sect->sh_size, _("options"));
     if (eopt)
       iopt = (Elf_Internal_Options *)
             cmalloc ((sect->sh_size / sizeof (eopt)), sizeof (* iopt));
       ...
                      sect->sh size=1 < 8
                                                                Root Cause
       offset = 0;
       option = iopt;
                            sect->sh_size=1 < 8
       while (offset <= sect->sh_size - sizeof (* eopt))
16198
         Elf External Options * option;
         eoption = (Elf_External_Options *)((char *) eopt + offset);
         option->kind = BYTE_GET (eoption->kind);
         option->size = BYTE_GET (eoption->size);
                                                              Program crashes
         offset += option->size;
         ++option;
       ...
```

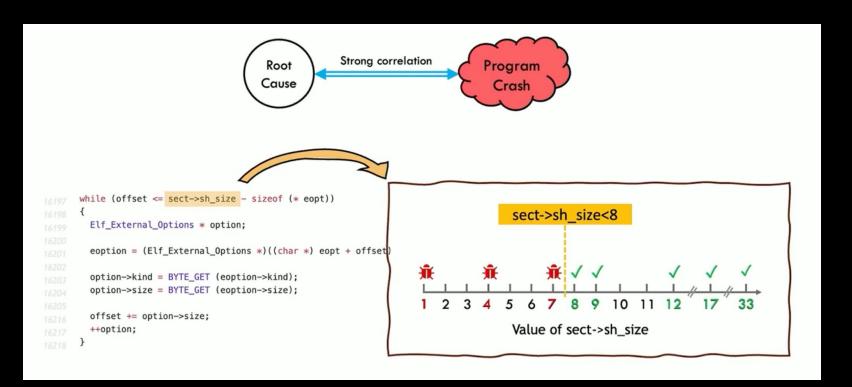
Automated RCA Challenges

- Having a pipeline with bucket of analysis tools.
- They rely on rules and types for finding bug.
- Lead to type-confusion flaws.

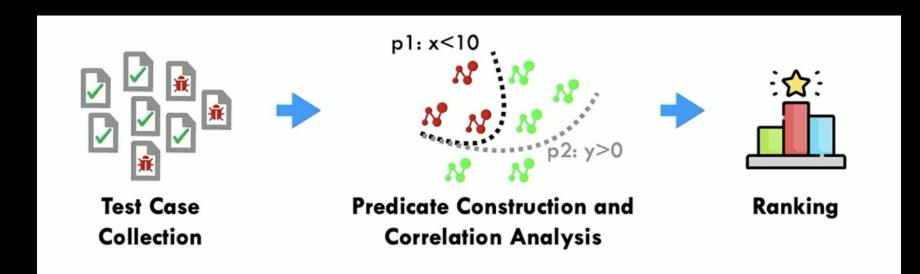
Spectrum Based Fault Localization (SFL)

- Finding bug without explicit data dependency.
- They outperform traditional automated RCA.
- They try to correlate crash and root cause through statistics.
- Ranking highly correlated test case and find the crash.
- Takes lot of time 12 hours or even week.

Statistical RCA



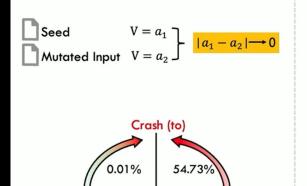
General Workflow of Statistical RCA



Racing

What is Racing? Root-cAuse-analysis on Counter-examples based reinforcement-learnING.....

How to mutate test case?



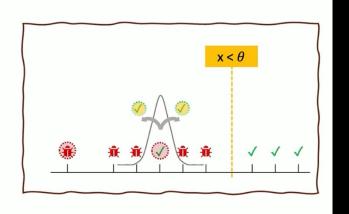
Crash (from)

45.27%

Non-Crash (to)

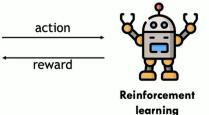
Non-Crash (from)

99.99%



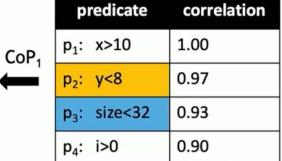


AFL Fuzzer



All about Correlation

predicate	correlation
p ₁ : x>10	1.00
p ₂ : y<8	0.95 👢
p ₃ : size<32	0.93
p ₄ : i>0	0.90

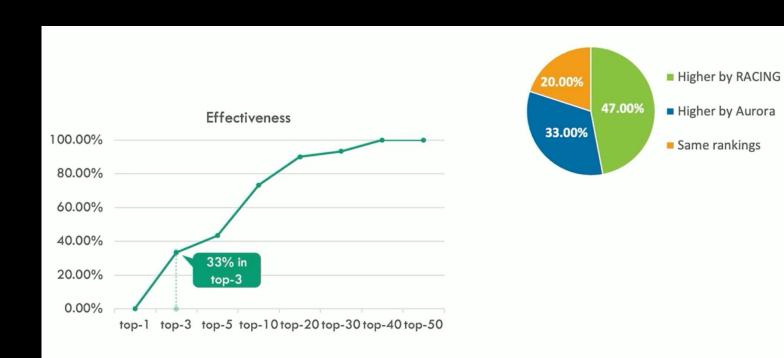


predicate	correlation
p ₁ : x>10	1.00
p ₃ : size<32	0.93
p ₂ : y<8	0.91 🎩
p ₄ : i>0	0.90

CoP₂

$$g_t = g_t^{count} + g_t^{order}$$

Existing Results



Algorithm code

```
# RACING Algorithm Template
     # Initialize the algorithm state
     St = []
                      # Initial state
     gamma t = 0.5 # Exploration-Exploitation tradeoff parameter
     t = 1
                      # Iteration counter
     # Function placeholders (to be implemented based on your needs)
     def select_action(S_prev):
10
         """Select an action based on the previous state."""
11
12
     def sample action(d t, gamma t):
14
         """Sample an action based on the decision and gamma parameter."""
15
         pass
16
17
     def generate input(action):
         """Generate a test input based on the selected action."""
18
19
         pass
20
     def run program(prog, inputs):
22
         """Run the program with the given inputs and return execution results."""
23
         pass
24
     def rank results(results):
26
         """Rank the predicates based on the execution results."""
27
28
     def compute_reward(results, S_prev):
30
         """Compute the reward for the generated inputs and state."""
31
         pass
32
     def update state(S prev, rankings, reward, results):
34
         """Update the state based on new information."""
35
```

```
def update gamma(rewards, decisions, actions):
    """Update the gamma parameter based on rewards and actions."""
    pass
def has converged(state):
    """Check if the algorithm has converged."""
    pass
# Main loop
while True:
   d t = select action(S t)
                                                   # Select an action
    a_t = sample_action(d_t, gamma_t)
                                                   # Sample an action
    inputs = generate_input(a_t)
                                                   # Generate inputs
    results = run program("Prog", inputs)
                                                   # Run the program
    rankings = rank results(results)
                                                   # Rank the results
    reward = compute_reward(results, S_t)
                                                   # Compute the reward
    S_t = update_state(S_t, rankings, reward, results) # Update state
    gamma_t = update_gamma(reward, d_t, a_t)
                                                   # Update gamma parameter
    if has converged(S t):
                                                   # Check convergence
        break
# Final step: Select top-50 predicates
top 50 predicates = sorted(rankings, key=lambda x: x[1], reverse=True)[:50]
r star = [predicate for predicate, score in top 50 predicates]
# Output results
print("Top-50 Predicates:", top 50 predicates)
print("True Order (r*):", r star)
```

Optimization in a code

```
optimized_racing.py > ...
      import random
                                                                                                      def generate input(action):
      import numpy as np
                                                                                                          Generate a new test input based on the action.
      from collections import defaultdict
                                                                                                          # Simple mutation logic. Replace with advanced input generation if necessary.
      # Initialize state and parameters
                                                                                                          return f"Input based on {action}"
                       # Initial state
      gamma_t = 0.5  # Exploration-Exploitation tradeoff parameter
                       # Iteration counter
                                                                                                      def run program(prog, inputs):
      MAX ITERATIONS = 100 # Maximum iterations to avoid infinite loops
      CONVERGENCE THRESHOLD = 0.01 # Threshold for convergence
                                                                                                          Run the program with the given inputs.
      top k = 50
                       # Number of top predicates to select
                                                                                                          Mock execution results here for demonstration purposes.
11
12
      # Helper functions for optimization
                                                                                                          results = [{"predicate": f"Predicate {i}", "value": random.random()} for i in range(10)]
14
      def select action(S prev):
                                                                                                          return results
 15
16
          Select an action based on the previous state.
                                                                                                      def rank results(results):
 17
          Here, a simple weighted random selection is implemented. Replace with a more sophisticated
 18
                                                                                                          Rank predicates based on their impact (value).
19
          if not S prev:
              return random.choice(["Action1", "Action2", "Action3"])
 20
                                                                                                          return sorted(results, key=lambda x: x["value"], reverse=True)
          # Weighted selection based on state information
 21
          return random.choices(["Action1", "Action2", "Action3"], weights=[0.3, 0.5, 0.2])[0]
 22
                                                                                                      def compute reward(results, S prev):
 23
 24
      def sample action(d t, gamma t):
                                                                                                          Compute a reward for the current iteration based on improvements.
                                                                                                          Reward is based on discovering new predicates or improving ranks.
 26
          Sample an action by balancing exploration and exploitation.
 27
                                                                                                          new coverage = sum([result["value"] for result in results])
          if random.random() < gamma t:</pre>
 28
                                                                                                          old_coverage = sum([state["value"] for state in S_prev]) if S_prev else 0
              return f"Explore {d t}" # Exploration
29
                                                                                                          return new coverage - old coverage
30
          return f"Exploit {d t}"
                                      # Exploitation
```

Continuation

```
# Main optimization loop
def update state(S prev, rankings, reward, results):
                                                                                       prev state = []
                                                                                       while t <= MAX_ITERATIONS:</pre>
    Update the state based on new rankings and results.
                                                                                           d t = select action(S t)
                                                                                                                                           # Select an action
                                                                                           a t = sample action(d t, gamma t)
                                                                                                                                           # Sample an action
    updated state = S prev + results
                                                                                           inputs = generate input(a t)
                                                                                                                                           # Generate inputs
    # Keep only unique predicates
                                                                                           results = run program("Prog", inputs)
                                                                                                                                           # Run the program
    unique state = {result["predicate"]: result for result in updated state}
                                                                                           rankings = rank results(results)
                                                                                                                                           # Rank predicates
    return list(unique state.values())
                                                                                           reward = compute_reward(results, S_t)
                                                                                                                                           # Compute the reward
                                                                                           prev state = S t
def update gamma(rewards, decisions, actions):
                                                                                           S t = update state(S t, rankings, reward, results) # Update state
                                                                                           gamma t = update gamma(reward, d t, a t)
                                                                                                                                           # Update gamma parameter
    Update the gamma parameter dynamically based on the rewards.
                                                                                           if has converged(S t, prev state):
                                                                                                                                           # Check convergence
    if rewards > 0:
                                                                                               print(f"Converged after {t} iterations.")
        return min(1.0, gamma t + 0.05) # Favor exploitation
                                                                                               break
    return max(0.1, gamma t - 0.05)
                                        # Favor exploration
                                                                                           t += 1
def has_converged(state, prev_state):
                                                                                       # Final step: Select top-k predicates
                                                                                       top predicates = rank results(S t)[:top k]
    Check if the state has converged.
                                                                                       print(f"Top-{top k} Predicates: {top predicates}")
    if not prev state:
        return False
    diff = sum(abs(curr["value"] - prev["value"]) for curr, prev in zip(state, prev state))
    return diff < CONVERGENCE THRESHOLD
```

Unexpected Turn

The original code base from authors were not producing proper results.

```
clang++ llvm-contig --cxxtlags -Wl.-znodelete -tno-rtti -tpic -U3 -tunroll-loops -Wall -D FURILFY
                                                                                                     rm -t texinto/doc/Maketile texinto/po/POIFILES
  riadic-macros -shared full trace.cpp afl-llvm-pass.so.cc -o ../afl-llvm-pass.so `llvm-config --ldfl
                                                                                                     rmdir texinfo/doc texinfo/info texinfo/intl texinfo/lib 2>/dev/null
   full_trace.cpp:28:10: fatal error: 'llvm/IR/CallSite.h' file not found
                                                                                                    make: [Makefile:2069: local-distclean] Error 1 (ignored)
                                                                                                     rmdir texinfo/makeinfo texinfo/po texinfo/util 2>/dev/null
                                                                                                     make: [Makefile:2070: local-distclean] Error 1 (ignored)
  1 error generated.
                                                                                                     rmdir fastjar gcc gnattools gotools libcc1 libiberty 2>/dev/null
  afl-llvm-pass.so.cc:64:10: fatal error: 'llvm/Transforms/IPO/PassManagerBuilder.h' file not found
                                                                                                     make: [Makefile:2071: local-distclean] Error 1 (ignored)
     64 | #include "llvm/Transforms/IPO/PassManagerBuilder.h"
                                                                                                     rmdir texinfo zlib 2>/dev/null
                                                                                                    make: [Makefile:2072: local-distclean] Error 1 (ignored)
  1 error generated.
                                                                                                     find . -name config.cache -exec rm -f {} \; \; 2>/dev/null
./02 PocExecutionInspector.sh: line 9: cd: /Racing-eval/scripts/: No such file or directory
python3: can't open file '/home/ubuntu/Racing-code/examples/1-readelf-heap-buffer-overflow/tracing.py': [Errno 2] No such file or dir
                                                                                                     make: [Makefile:2073: local-distclean] Error 1 (ignored)
python3: cnlecktrifg]:wi/lett/tertit@reitchdompinle() worlks::: ...ffo ----ff--
      configure: error: in `/home/ubuntu/Racing-code/examples/1-readelf-heap-buffer-overflow/binutils-2.32':
      configure: error: C compiler cannot create executables
      See `config.log' for more details
      make: *** No targets specified and no makefile found. Stop.
      mv: cannot stat '/home/ubuntu/Racing-code/examples/1-readelf-heap-buffer-overflow/binutils-2.32/binutils/readelf': No such file or direc
```

 Because of these errors and file issues, I changed the direction of my project.

Building AFLRL

New Focus:

- "AFLRL": Training reinforcement learning models using AFL (American Fuzzy Lop).
- Build datasets for RL model training.
- Enhance AFL's capabilities by adding vulnerable code paths to generate robust training data.

Updated Objective

Dataset Creation:

• Generate meaningful datasets for training RL models using AFL.

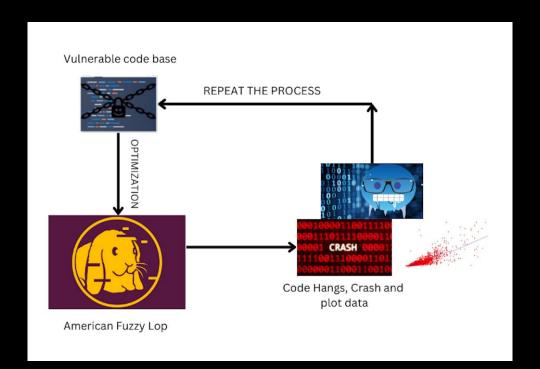
Optimization:

Focus on AFL's features to produce proper outputs for RL training.

Outcome:

• Improve path exploration and crash detection efficiency in fuzz testing.

Flowchart



OUTPUT

```
american fuzzy lop 2.57b (aflrl)
 process timing
       run time : 0 days, 0 hrs, 0 min, 6 sec
                                                        cvcles done : 0
  last new path: 0 days, 0 hrs, 0 min, 0 sec
                                                        total paths: 109
last uniq crash: 0 days, 0 hrs, 0 min, 1 sec
                                                       unia crashes : 6
 last uniq hang : none seen yet
                                                         uniq hangs: 0
cycle progress —
                                      map coverage
 now processing: 0 (0.00%)
                                         map density: 0.13% / 0.49%
paths timed out : 0 (0.00%)
                                      count coverage : 1.89 bits/tuple
                                      findings in depth -

    stage progress —

 now trying : calibration
                                      favored paths: 1 (0.92%)
stage execs: 0/8 (0.00%)
                                      new edges on : 59 (54.13%)
total execs: 22.8k
                                      total crashes: 19 (6 unique)
 exec speed: 3115/sec
                                      total tmouts: 0 (0 unique)

    fuzzing strategy yields

                                                      path geometry
  bit flips: 13/64, 1/63, 2/61
                                                         levels: 2
 byte flips: 0/8, 0/7, 1/5
                                                       pending: 109
arithmetics: 12/444, 0/31, 0/0
                                                       pend fav : 1
 known ints: 1/38, 0/196, 0/220
                                                      own finds: 107
 dictionary: 0/0, 0/0, 0/0
                                                       imported : n/a
      havoc : 0/0, 0/0
                                                      stability : 100.00%
       trim: 0.00%/1, 0.00%
                                                                  [cpu:287%]
```

```
WARNING: Vulnerability exists below
     The line of code below frees the memory block referenced by *top if
     the length of a JSON array is 0. The program attempts to use that memory
     block later in the program.
     Diff
            - Added: free(*top);
           - An empty JSON array: []
     Pavload
 Input File - emptyArray
     Triggers - Use after free in json_value_free()
free(*top):
break:
        if (! (value->u.array.values = (json_value **) json_alloc
          (state, value->u.array.length * sizeof (ison value *), 0)) )
          return 0:
```

Challenges and Future work

- Environmental and version mismatches
- Transition from RACING to AFLRL required some work.

Future work

- Train RL with generated crashes.
- Optimize AFL for better vulnerability detection and RL integration.

Thank You