



Introduction to Optimization

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A general *iterative* algorithm

for finding the minimum of $f : \mathbb{R}^n \rightarrow \mathbb{R}$

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Which direction yields the “most reduction in $f(\cdot)$ ”?

Enter Taylor's theorem

$$f(x) = f(x_0) + Df(x_0)(x - x_0) + o(\|x - x_0\|)$$

- First order approximation:

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Gradient descent

How to choose α ?

Step size

Possible to use a different α in each iteration

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Line search on $\phi_k(\alpha)$

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(see Theorem 8.2 in textbook)



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Order of convergence

a.k.a. rate of convergence

Given a sequence

$$x^{(k)} \rightarrow x^*,$$

we say that the **order of convergence** is at least $p \in \mathbb{R}$ if

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Newton's method: order of convergence is 2
if the initial guess is near the solution.

Newton's method

Quadratic approximation using Taylor's theorem

Second-order approximation (ignoring the $o(\cdot)$ term):

$$\begin{aligned} f(x^{(k+1)}) &= f(x^{(k)}) + (x^{(k+1)} - x^{(k)})^\top \nabla f(x^{(k)}) \\ &\quad + \frac{1}{2} (x^{(k+1)} - x^{(k)})^\top F(x^{(k)}) (x^{(k+1)} - x^{(k)}). \end{aligned}$$

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Newton's method

Quadratic approximation using Taylor's theorem

Second-order approximation (ignoring the $o(\cdot)$ term):

$$\begin{aligned} f(x^{(k+1)}) &= f(x^{(k)}) + (x^{(k+1)} - x^{(k)})^\top \nabla f(x^{(k)}) \\ &\quad + \frac{1}{2} (x^{(k+1)} - x^{(k)})^\top F(x^{(k)}) (x^{(k+1)} - x^{(k)}). \end{aligned}$$

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(see sections 7.5, 7.6)

An example

Newton's method for finding the minimum of a quadratic function

Let $Q \in \mathbb{R}^{n \times n}$ be symmetric, positive definite. Let

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Verify that $\nabla f(x^*) = 0$.

Newton's method

Hiccups

- Quick convergence if the starting point is near the solution.

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- Quick convergence if the starting point is near the solution.
- Not guaranteed to converge if we start far away from it.
- May not even be well-defined – the Hessian may be singular.
- May not be a descent method; it is possible that

$$f(x^{(k+1)}) \geq f(x^{(k)}).$$

Descent property for Newton's method

Theorem 9.2 in textbook

Theorem – If $F(x^{(k)}) > 0$ and $\nabla f(x^{(k)}) \neq 0$,

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(complete the proof)



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The theorem motivates the following **Newton's descent algorithm**:

$$x^{(k+1)} = x^{(k)} - \alpha_k F(x^{(k)})^{-1} \nabla f(x^{(k)})$$

where

$$\alpha_k = \arg \min_{\alpha \geq 0} f(x^{(k)} - \alpha F(x^{(k)})^{-1} \nabla f(x^{(k)})).$$

What if the Hessian is not positive definite?

Levenberg-Marquadt modification

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To ensure **descent property**, use step size as in steepest/Newton's descent.

How to avoid computing the Hessian inverse?

Quasi-Newton methods for quadratic problems

Suppose we use the update

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To ensure *descent* for small α , we need

$$\nabla f(x^{(k)})^\top H_k \nabla f(x^{(k)}) > 0.$$

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→ Ask for H_k to be positive definite.

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General structure

1. Set $k = 0$; select $x^{(0)}$ and a real symmetric p.d. H_0

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$$\Delta g^{(k)} = \nabla f(x^{(k+1)}) - \nabla f(x^{(k)})$$
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Conjugate Direction methods

Intermediate between Steepest descent and Newton's method

- Solve quadratics of n variables in n steps

$$f(x) = \frac{1}{2}x^\top Qx - x^\top b ; x \in \mathbb{R}^n, Q = Q^\top > 0.$$

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- No matrix inversion to arrive at

$$x^* = Q^{-1}b.$$

Q -conjugacy

Definition – Let $Q \in \mathbb{R}^{n \times n}$ be real, symmetric. The directions

$$d^{(0)}, d^{(1)}, \dots, d^{(k)} \in \mathbb{R}^n$$

are Q -conjugate if for all $i \neq j$, we have

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• $d^{(0)}, d^{(1)}, \dots, d^{(k)}$ nonzero, Q -conjugate \implies linearly independent
(proof left as exercise)

Minimizing a quadratic function

$$\min_{x \in \mathbb{R}^n} \frac{1}{2} x^\top Q x - x^\top b ; \quad Q = Q^\top > 0$$

Let

$$g^{(k)} = \nabla f(x^{(k)}) = Qx^{(k)} - b$$

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$$0 = \phi'(\alpha) = (x^{(k)} - \alpha g^{(k)})^\top Q(-g^{(k)}) - b^\top (-g^{(k)})$$

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Conjugate direction algorithm: Given $x^{(0)}$ and Q -conjugate directions $d^{(0)}, \dots, d^{(n-1)}$; for $k \geq 0$,

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Theorem – For any starting point $x^{(0)}$, the basic conjugate direction algorithm converges to the unique x^* in n steps.

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Note: x^* satisfies $Qx^* = b$.

(proof on board)

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~ see Theorem 10.1 in textbook

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“compute as you go”

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- At each stage, the direction is calculated as a linear combination of the **current gradient** and the **previous directions**

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- Need to ensure that $d^{(i)}$ are Q -conjugate. Choose β_k such that

$$\beta_k = \frac{g^{(k+1)\top} Q d^{(k)}}{d^{(k)\top} Q d^{(k)}}.$$

(see Proposition 10.1 and its proof)