KEVIN PALISOC

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EDUCATION

Massachusetts Institute of Technology

Candidate for B.S. in Mechanical Engineering

Class of 2018

Select Coursework: Design and Manufacturing I & II, Dynamics and Control I, Mechanics and Materials I, Thermal-Fluids Engineering I, Mechanical Engineering Tools, Numerical Computation, Differential Equations, Japanese III

EXPERIENCE

Draper Autonomous Vehicle Intern Summer 2016	 Designed and implemented chassis and electronics packaging for a novel autonomous mobility scooter as a scalable test vehicle; Designed for manufacturing and created technical drawings of over a dozen mounts and parts that were professionally machined and 3D printed; Researched path planning algorithms to improve efficiency and safety
MIT Distributed Robotics Lab Undergraduate Researcher Fall 2015	 System design and prototyping of an adaptive control module for printed hydraulic systems; Design of motor mount for printed hydraulic hexapod robot
MIT Newman Lab Undergraduate Researcher Summer 2015	☐ Developed GUI to improve capability and usability in experiments for a wearable stiffness-imposing physical therapy device
Robotech Center Program Instructor Summer 2015	☐ Taught STEM concepts to elementary school students through assembly and programming of an Arduino self driving toy car

LEADERSHIP & ACTIVITIES

Phi Kappa Theta - Mass Eta Chapter Vice President Spring 2015 – Current	☐ Spearheading chapter activities of summer tenancy, community involvement, conflict resolution, member accountability, and finances of an over \$300,000 per year budget
MakeMIT (TechX) Organizer Fall 2015 – Current	☐ Coordination of corporate sponsors, tools and materials, and mentors for MIT's hardware and prototyping hackathon hosting 250+ college students
MIT Chinese Students Club Member Outreach Chair Spring 2016 – Current	☐ Spearheading efforts to foster a welcoming environment and engage new and returning members
FIRST Robotics Team 6112 Team Lead Fall 2012 - Spring 2014	 Led mechanical design, engineering notebook documentation, business plan creation, sponsor relations, and outreach efforts for a competitive robotics team; Designed and manufactured end gripper and grappling hook winch system

TECHNICAL SKILLS

Computer Aided Drafting & Manufacturing | Solidworks, MasterCAM

Manufacturing | CNC Machining, 3D Printing, Laser Cutting, Conventional Machining

Programming | MATLAB, Python, HTML & CSS

Organizational | Microsoft Office & Visio