KEVIN PALISOC

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EDUCATION

Massachusetts Institute of Technology

Candidate for B.S. in Mechanical Engineering

Class of 2018

Select Coursework: Design and Manufacturing I & II, Dynamics and Control I & II, Mechanics and Materials I & II, Thermal-Fluids I, Measurement and Instrumentation, Mechanical Engineering Tools, Numerical Computation, Differential Equations, Japanese IV

Vecna Design for manufacturing and assembly to reduce costs for an electric vehicle

EXPERIENCE

Robotics Mechanical Intern January 2017	consumer product Developing manufacturing procedures to improve quality and marketability
Draper Autonomous Vehicle Intern Summer 2016	 Designed and implemented all chassis and electronics packaging for a novel autonomous mobility scooter as a scalable test vehicle; Designed for manufacturing and created technical drawings of over a dozen mounts and parts that were professionally machined and 3D printed; Researched path planning algorithms to improve efficiency and safety
MIT Distributed Robotics Lab Undergraduate Researcher Fall 2015	 Designed and prototyped an adaptive control module to improve capability of printed hydraulic systems; Designed motor mount for printed hydraulic hexapod robot
MIT Newman Lab Undergraduate Researcher Summer 2015	☐ Developed GUI with real time plotting, calibration, and active stiffness and damping adjustment to improve experimental data logging capabilities for a wearable physical therapy device
LEADERSHIP & ACTIVI	ITIES
Phi Kappa Theta - Mass Eta Chapter President Spring 2016 – Current	☐ Spearheading chapter activities of summer tenancy, community involvement, conflict resolution, member accountability, house maintenance, and finances of an over \$300,000 per year budget
MakeMIT (TechX) Organizer Fall 2015 – Spring 2016	☐ Coordination of corporate sponsors, tools and materials, and mentors for MIT's hardware and prototyping hackathon hosting 250+ college students
MIT Chinese Students Club Member Outreach Chair Spring 2016 – Current	☐ Spearheading efforts to foster a welcoming environment and engage new and returning members
FIRST Robotics Team 6112	☐ Led mechanical design, engineering notebook documentation, business plan

creation, sponsor relations, and outreach efforts for a competitive robotics team;

TECHNICAL SKILLS

Computer Aided Drafting & Manufacturing | Solidworks, MasterCAM

Manufacturing | CNC Machining, Injection Molding, 3D Printing, Laser Cutting, Conventional Machining

Fall 2012 - Spring 2014 Designed and manufactured end gripper and grappling hook winch system

Programming | MATLAB, Python, HTML & CSS, Tcl

Team Lead

Organizational | Microsoft Office & Visio