
EDUCATION

Massachusetts Institute of Technology

Class of 2018

Candidate for Bachelor of Science in Mechanical Engineering (Course 2)

Select Coursework: Design and Manufacturing I & II, Dynamics and Control I & II, Mechanics and Materials I & II, Thermal-Fluids I, Measurement and Instrumentation, Mechanical Engineering Tools, Numerical Computation, Differential Equations, Japanese IV

EXPERIENCE

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| Vecna
<i>Robotics Mechanical Intern</i>
<i>January 2017</i> | <ul style="list-style-type: none">❑ Designed and implemented of a test rig to evaluate a novel hydraulic actuator for use in a DARPA funded robot arm project❑ Repaired and validated performance of lifting capability of a warehouse robot |
| Draper
<i>Autonomous Vehicle Intern</i>
<i>Summer 2016</i> | <ul style="list-style-type: none">❑ Designed and implemented all chassis and electronics packaging for a novel autonomous mobility scooter as a scalable test vehicle;❑ Designed for manufacturing and created technical drawings of over a dozen mounts and parts that were professionally machined and 3D printed;❑ Researched path planning algorithms to improve efficiency and safety |
| MIT Distributed Robotics Lab
<i>Undergraduate Researcher</i>
<i>Fall 2015</i> | <ul style="list-style-type: none">❑ Designed and prototyped an adaptive control module to improve capability of printed hydraulic systems;❑ Designed motor mount for printed hydraulic hexapod robot |
| MIT Newman Lab
<i>Undergraduate Researcher</i>
<i>Summer 2015</i> | <ul style="list-style-type: none">❑ Developed GUI with real time plotting, calibration, and active stiffness and damping adjustment to improve experimental data logging capabilities for a wearable physical therapy device |
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LEADERSHIP & ACTIVITIES

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| Phi Kappa Theta - Mass Eta
<i>Chapter President</i>
<i>Spring 2016 – Current</i> | <ul style="list-style-type: none">❑ Spearheading chapter activities of summer tenancy, community involvement, conflict resolution, member accountability, house maintenance, and finances of an over \$300,000 per year budget |
| MakeMIT (TechX)
<i>Organizer</i>
<i>Fall 2015 – Spring 2016</i> | <ul style="list-style-type: none">❑ Coordination of corporate sponsors, tools and materials, and mentors for MIT's hardware and prototyping hackathon hosting 250+ college students |
| MIT Chinese Students Club
<i>Member Outreach Chair</i>
<i>Spring 2016 – Current</i> | <ul style="list-style-type: none">❑ Spearheading efforts to foster a welcoming environment and engage new and returning members |
| FIRST Robotics Team 6112
<i>Team Lead</i>
<i>Fall 2012 – Spring 2014</i> | <ul style="list-style-type: none">❑ Led mechanical design, engineering notebook documentation, business plan creation, sponsor relations, and outreach efforts for a competitive robotics team;❑ Designed and manufactured end gripper and grappling hook winch system |
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TECHNICAL SKILLS

Computer Aided Drafting & Manufacturing | Solidworks, MasterCAM

Manufacturing | CNC Machining, Injection Molding, 3D Printing, Laser Cutting, Conventional Machining

Programming | MATLAB, Python, HTML & CSS, Tcl, Ladder Logic

Electronics | Basic Circuitry

Organizational | Microsoft Office & Visio