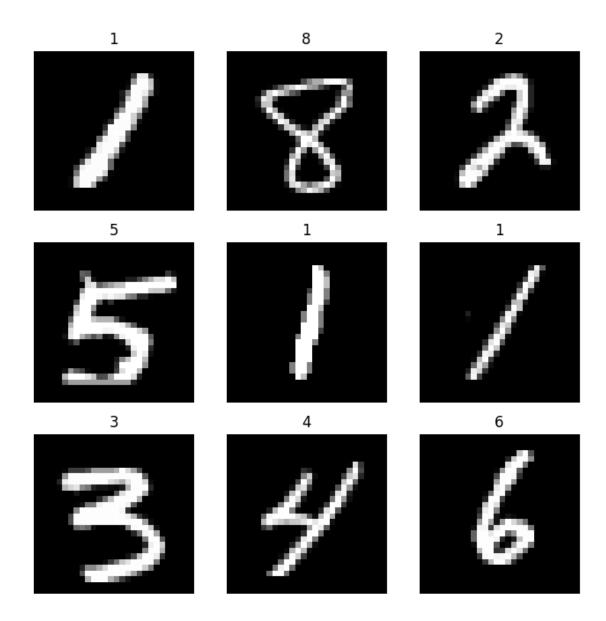
PA4

October 29, 2022

```
[67]: ## import libraries
      import numpy as np
      import matplotlib.pyplot as plt
      import skimage
      #torch
      import torch
      import torch.nn as nn
      import torchvision
      import torchvision.transforms as transforms
      import torch.nn.functional as F
      from torchvision.datasets import MNIST
      #import pca
      from sklearn.decomposition import PCA
      from sklearn.metrics import mean_squared_error as mse
 [2]: batch_size = 256
      epochs =10
      learning_rate = 0.001
 [3]: #Download the dataset
      train_dataset = MNIST(root='./data',
                          train=True,
                          transform=transforms.ToTensor(),
                          download=True)
      test_dataset = MNIST(root='./data',
                          train=False,
                          transform=transforms.ToTensor())
 [4]: # Data loader
      train_loader = torch.utils.data.DataLoader(dataset=train_dataset,
                                                 batch_size=batch_size,
                                                 shuffle=True)
      test_loader = torch.utils.data.DataLoader(dataset=test_dataset,
```

batch_size=batch_size,
shuffle=False)

```
[5]: #code taken from the official documentation
     labels_map = {
         0: "0",
         1: "1",
         2: "2",
         3: "3",
         4: "4",
         5: "5",
         6: "6",
         7: "7",
         8: "8",
         9: "9",
     }
     figure = plt.figure(figsize=(8, 8))
     cols, rows = 3, 3
     for i in range(1, cols * rows + 1):
         sample_idx = torch.randint(len(train_dataset), size=(1,)).item()
         img, label = train_dataset[sample_idx]
         figure.add_subplot(rows, cols, i)
         plt.title(labels_map[label])
         plt.axis("off")
         plt.imshow(img.squeeze(), cmap="gray")
     plt.show()
```



```
[6]: train_images = train_dataset.data
    train_labels = train_dataset.targets
    print(f"Training image shape:{train_images.shape}")
    print(f"Training Targets shape:{train_labels.shape}")

val_images = test_dataset.data
    val_labels = test_dataset.targets
    print(f"validation image shape:{val_images.shape}")
    print(f"validation Targets shape:{val_labels.shape}")
```

Training image shape:torch.Size([60000, 28, 28])

```
Training Targets shape:torch.Size([60000])
validation image shape:torch.Size([10000, 28, 28])
validation Targets shape:torch.Size([10000])
```

0.1 Q1

```
[7]: ##PCA and Autoencoder
```

```
[8]: #first 30 eigenvectors corresponding to top 30 eigenvalues
    pca_comps_n =30
    print('PCA with', pca_comps_n ,'principal components')
    train_data = np.asarray(train_images)/255
    test_data = np.concatenate((train_data,test_data))
    PCA_data = total_data.reshape(-1,28*28)
    # PCA_data = train_data.reshape(-1,28*28)

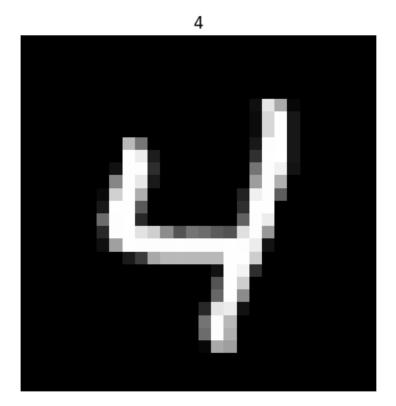
pca1 = PCA(n_components = pca_comps_n)
    pca1.fit(PCA_data)
    train_pca = pca1.transform(PCA_data)
    reconstructed_data = pca1.inverse_transform(train_pca)
    PCA_error = mse(PCA_data,reconstructed_data)
    print('Reconstruction error made by PCA: ',PCA_error)
```

PCA with 30 principal components
Reconstruction error made by PCA: 0.01805640184447451

```
[9]: \#0-5, 1-0, 2-4, 3-1, 4-9, 5-2, 7-3, 13-6, 15-7, 17-8

keys = [1,3,5,7,2,0,13,15,17,4]
```

```
for i in range(1, cols * rows + 1):
    sample_idx = torch.randint(len(train_dataset), size=(1,)).item()
    img, label = train_dataset[sample_idx]
    figure.add_subplot(rows, cols, i)
    plt.title(labels_map[label])
    plt.axis("off")
    plt.imshow(img.squeeze(), cmap="gray")
plt.show()
```



```
[11]: device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')

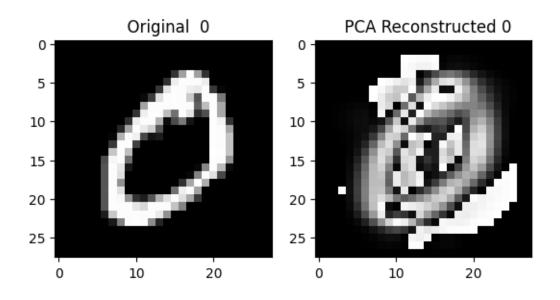
[12]: from numpy import uint8

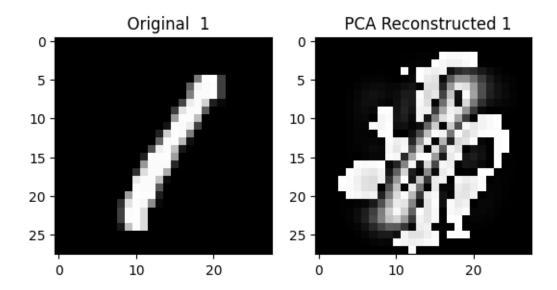
for t,j in zip(range(10),keys):
    input_image = np.asarray(255*PCA_data[j],dtype=uint8).reshape(28,28)
    reconstruct_image = np.asarray(255*reconstructed_data[j],dtype=uint8).

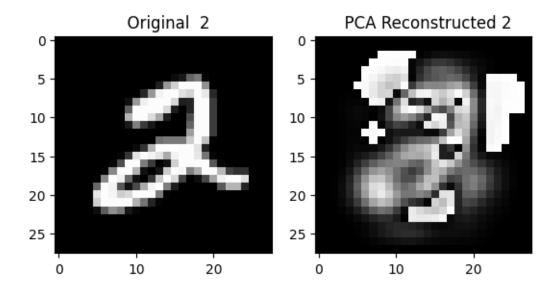
--reshape(28,28)
    plt.subplot(1,2,1)

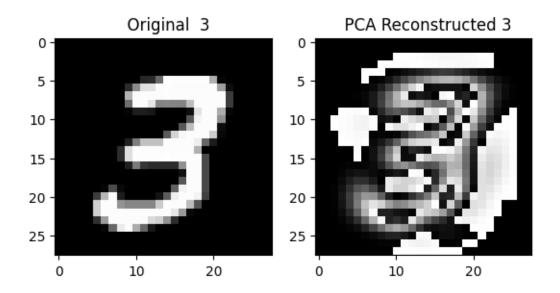
    plt.imshow(input_image,'gray')
    plt.title(' Original '+str(t))
    plt.subplot(1,2,2)

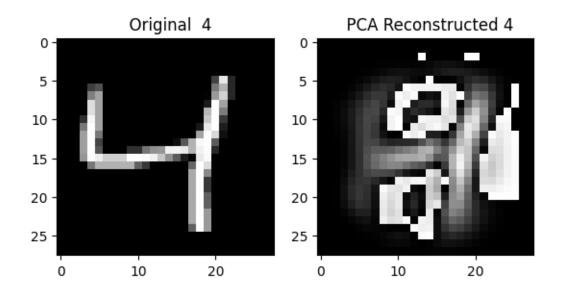
    plt.imshow(reconstruct_image,'gray')
    plt.title(' PCA Reconstructed '+str(t))
    plt.show()
```

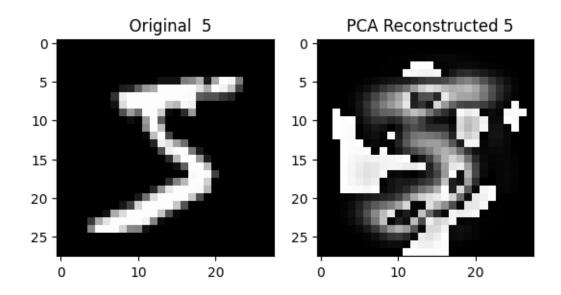


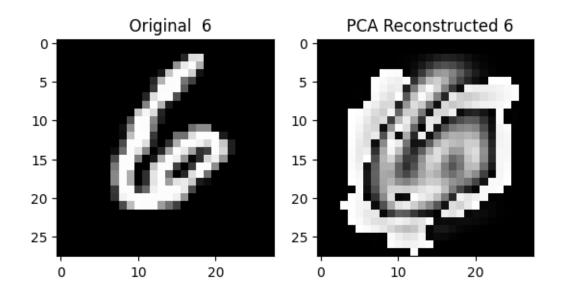


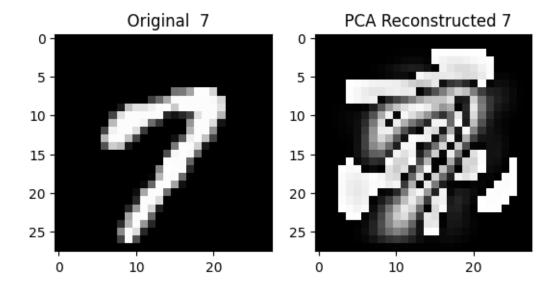


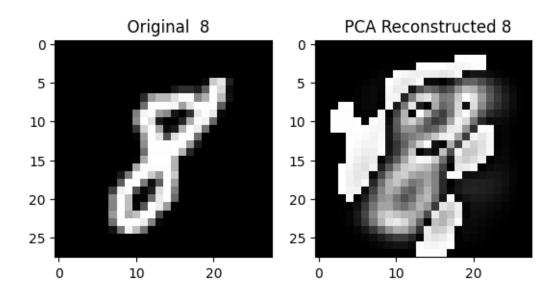


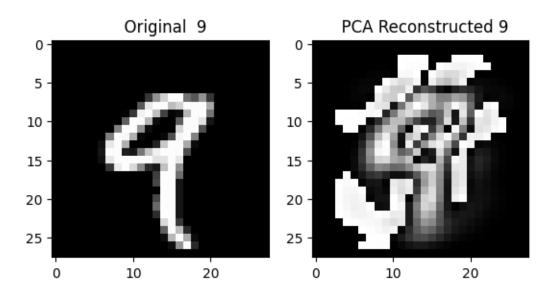












```
nn.Linear(256,128),
             nn.ReLU(),
             nn.Linear(128,30),
             nn.ReLU())
         self.decoder =nn.Sequential(
             nn.Linear(30,128),
             nn.ReLU(),
             nn.Linear(128,256),
             nn.ReLU(),
             nn.Linear(256,784),
             nn.ReLU())
       def forward(self,x):
         x = flatten(x,1)
         encoded=self.encoder(x.float())
         reconstructed =self.decoder(encoded)
         return reconstructed
                                , encoded
[15]: # Loss function
     lossfn = nn.MSELoss()
[16]: from torch import flatten
      \rightarrow3, q5_flag = False):
         model.train() #setting the model in training mode
         #initializing the total training loss to O
                     = 0
         train loss
         #loop over the training set
         for batch_idx, (data, label) in enumerate(train_dataloader): # (data, label):
      → Training data for that batch
             if denoise==True:
                 img = data.clone()
                 data = add_noise(img,noise_val)
                 data = data.to(device)
             else:
                 (data, label) = (data.to(device), label.to(device)) #sending the_
      ⇔data to the device we've chosen
             reconstruction,encoded = model(data) #our reconstruction
             if q5_flag==True:
                 loss = lossfn(reconstruction,data) #loss
             else:
                loss = lossfn(reconstruction,flatten(data,1)) #loss
```

optimizer.zero_grad() #zeroing out the gradients before backprop

loss += lambda_reg*torch.linalg.norm(encoded,1)

if sparse==True:

```
train_loss
                           += loss/len(train_dataloader)
          return train_loss #returning loss
[17]: def

¬test(model,device,test_dataloader,lossfn,lambda_reg=0,sparse=False,denoise=False,noise_val=
       43, q5_flag = False):
          model.eval()
          test_loss
                      = 0
          with torch.no_grad():
              for (data, label) in test_dataloader: # (data, label): Test data for that
       \rightarrowbatch
                  if denoise==True:
                      img = data.clone()
                      data = add_noise(img,noise_val)
                      data = data.to(device)
                  else:
                      (data, label) = (data.to(device), label.to(device)) #sending the
       ⇒data to the device we've chosen
                  #perform forward pass and compute the loss
                  reconstruction,encoded = model(data) #our prediction
                  if q5_flag==True:
                      loss = lossfn(reconstruction,data) #loss
                  else:
                       loss = lossfn(reconstruction,flatten(data,1)) #loss
                  if sparse==True:
                      loss += lambda_reg*torch.linalg.norm(encoded,1)
                              += loss/len(test_dataloader)
                  test loss
          return test_loss #returning loss
[18]: def
       otrain_test(model,device,train_loader,test_loader,optimizer,lossfn,lambda_reg=0,sparse=False
       →3,q5_flag=False):
          train losses = []
          test_losses
          for epoch in range(epochs+1):
              #train the model
              train loss =
       utrain(model,device,train_loader,optimizer,lossfn,lambda_reg,sparse,denoise,noise_val,q5_fla
              train_losses.append(train_loss.item())
              #test the model
              test_loss =
       -test(model,device,test_loader,lossfn,lambda_reg,sparse,denoise,noise_val,q5_flag)
              test_losses.append(test_loss.item())
          return train_losses, test_losses
```

#backprop from the loss
#updating the weights

loss.backward()

optimizer.step()

```
imq = torch.from_numpy(imq)
          with torch.no_grad():
              if q5_flag == False:
                  if (device==torch.device("cuda")):
                      img = img.view(-1,28,28).cuda().float()
                  else:
                      img = img.view(-1,28,28).float()
              else:
                  if (device==torch.device("cuda")):
                      img = img.reshape(1,1,28,28).cuda().float()
                  else:
                      img = img.reshape(1,1,28,28).float()
              reconstructed_image,encoded = model.forward(img) #as it is a single_u
       → image we directly run the forward pass
              reconstructed_image=reconstructed_image.detach().cpu().numpy()
              img = img.reshape(28,28).detach().cpu().numpy()
              plt.subplot(1,2,1)
              plt.imshow(img , cmap='gray')
              plt.title('input image')
              plt.subplots_adjust(right=1.5)
              plt.subplot(1,2,2)
              plt.imshow(reconstructed_image.reshape(28,28),cmap ='gray') #our_
       →reconstructed image
              plt.title("Reconstructed image using "+ str(model_name))
              plt.show()
[20]: def plot_losses(train_losses, test_losses, model_name):
          train_interval = int(len(train_losses)/epochs)
          plt.plot(np.asarray(train_losses)[::train_interval])
          plt.title("MSE train loss using "+ str(model_name))
          plt.xlabel("Epoch")
          plt.ylabel("Loss")
          plt.show()
          test_interval = int(len(test_losses)/epochs)
          plt.plot(np.asarray(test losses)[::test interval])
          plt.title("MSE test loss using "+ str(model name))
          plt.xlabel("Epoch")
          plt.ylabel("loss")
          plt.show()
[21]: model_Q1 = AE1().to(device)
      optimizer = torch.optim.Adam(model_Q1.parameters(), lr=learning_rate)
      train_losses_AE_Q1 , test_losses_AE_Q1 =
       -train_test(model_Q1,device,train_loader,test_loader,optimizer,lossfn)
```

[19]: def plot reconstructed image(model,device,img,model_name,q5_flag=False):

```
[22]:

0-7

1-2

2-1

3-0

4-4

7-9

8-5

11-6

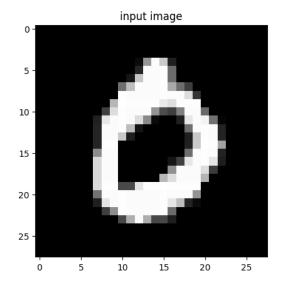
18-3

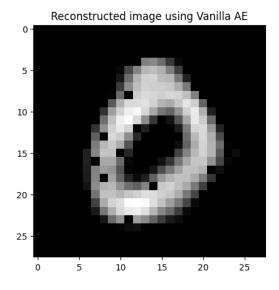
84-8

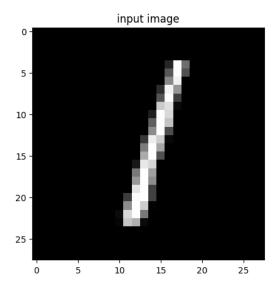
'''
```

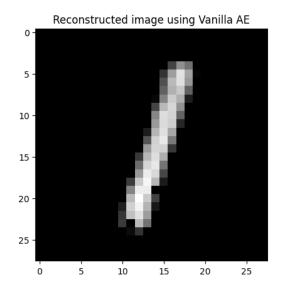
[22]: $\n0-7\n1-2\n2-1\n3-0\n4-4\n7-9\n8-5\n11-6\n18-3\n84-8\n'$

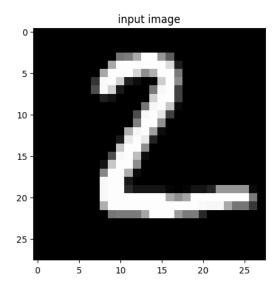
```
[23]: keys_test=[3,2,1,18,4,8,11,0,84,7]
```

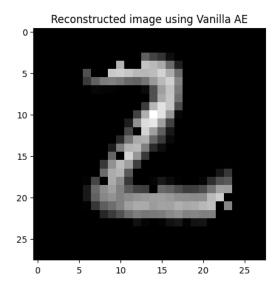


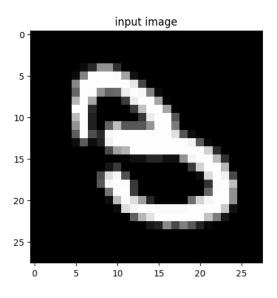


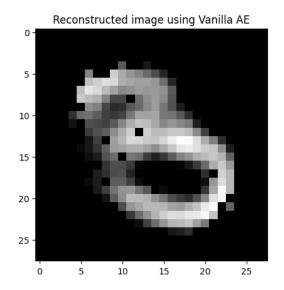


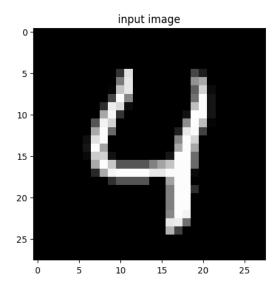


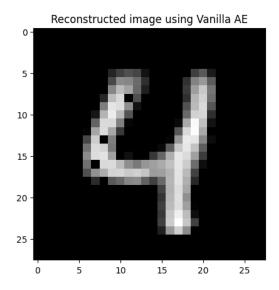


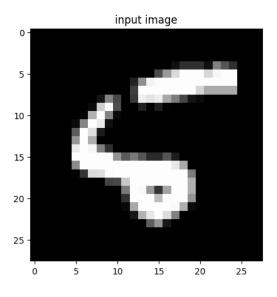


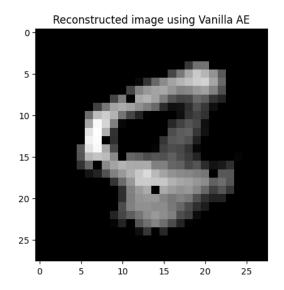


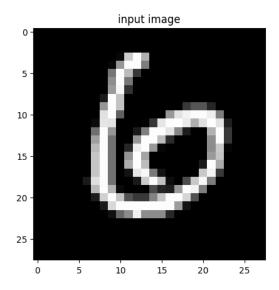


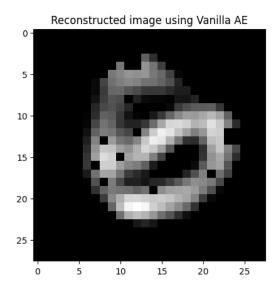


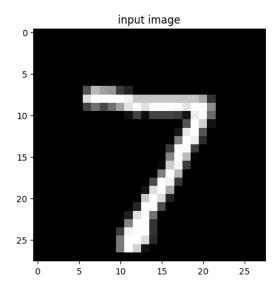


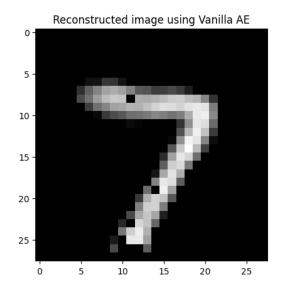


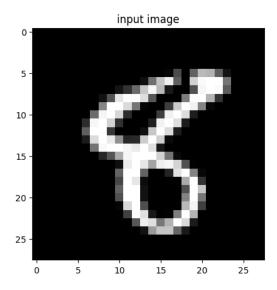


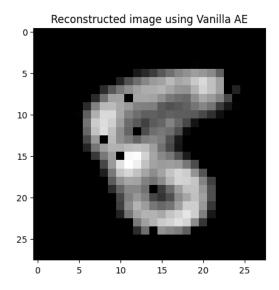


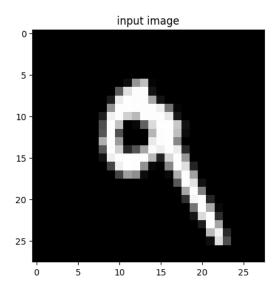


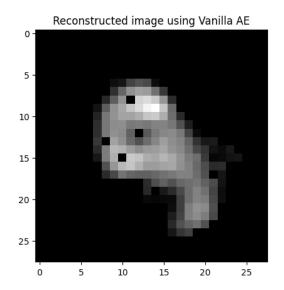




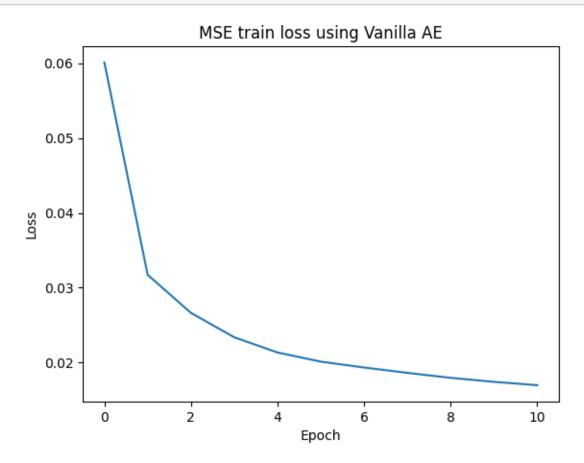


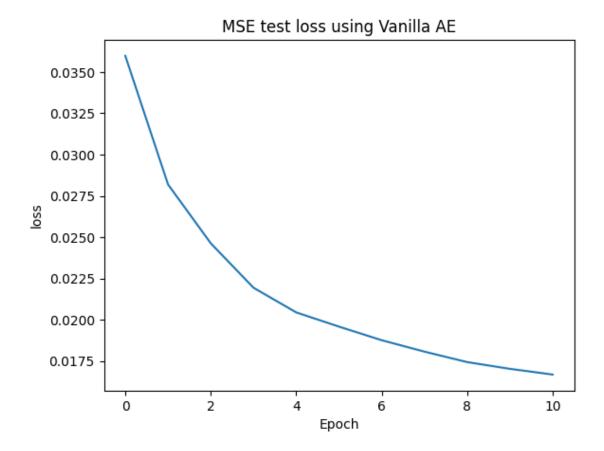






[25]: plot_losses(train_losses_AE_Q1, test_losses_AE_Q1, model_name = "Vanilla AE")





```
[26]: #MSE recommstruction error for vanilla AE
mse_error = test(model_Q1,device,test_loader,lossfn)
print("MSE Reconstruction error for Vanilla AE is ", mse_error.item())
```

MSE Reconstruction error for Vanilla AE is 0.016686905175447464

0.2 Q2

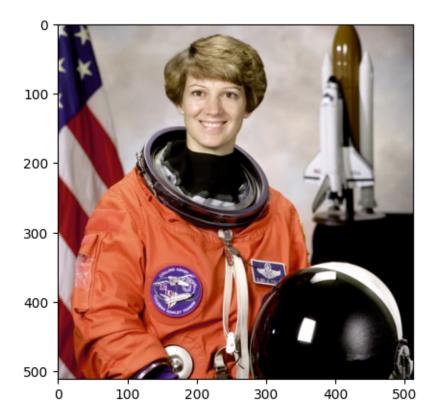
```
[27]: class AE_Q2(nn.Module):
    def __init__(self,hidden_layer):
        super(AE_Q2, self).__init__()

    self.encoder = nn.Sequential(
            nn.Linear(784,hidden_layer),
            nn.ReLU())

    self.decoder =nn.Sequential(
            nn.Linear(hidden_layer,784),
            nn.ReLU())
```

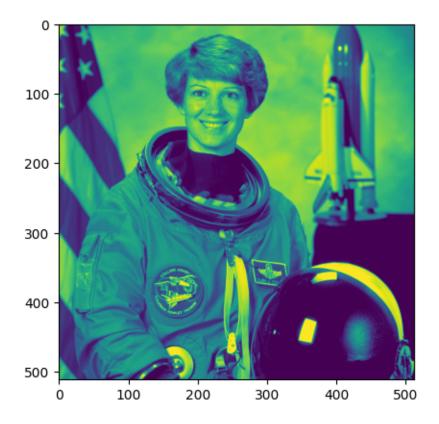
```
def forward(self,x):
    x = flatten(x,1)
    encoded=self.encoder(x.float())
    reconstructed =self.decoder(encoded)
    return reconstructed , encoded
```

```
[28]: from skimage import data
    astronaut = data.astronaut()
    plt.imshow(astronaut)
    plt.show()
    print(astronaut.shape)
    from skimage.color import rgb2gray
    grayscale_astro = rgb2gray(astronaut)
    plt.imshow(grayscale_astro)
    print(grayscale_astro.shape)
    plt.show()
    # flower = cv2.imread("flower.png")
    # flower = cv2.cvtColor(flower, cv2.COLOR_BGR2GRAY)
    # plt.imshow(flower)
```



(512, 512, 3)

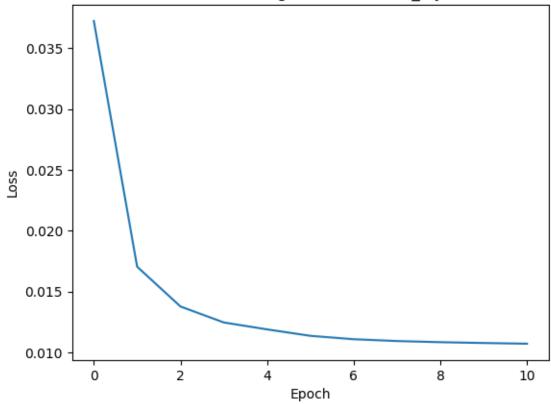
(512, 512)

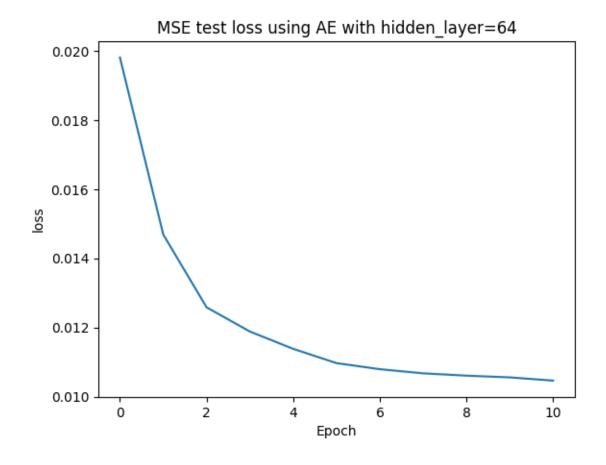


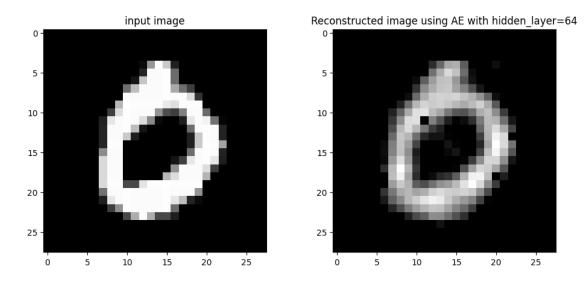
```
[29]: import skimage.transform
      from skimage import img_as_ubyte
      grayscale_astro = np.asarray(grayscale_astro)
      non_digit_image = torch.from_numpy(img_as_ubyte(skimage.transform.

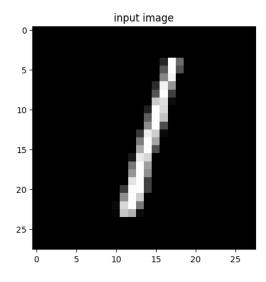
¬resize(grayscale_astro, (28,28))))
[30]: X = np.random.normal(loc=128,scale=10,size=(28,28)) #Initializing a 28x28__
       ⇔matrix with gaussian noise 1ith mean = 128, std=10
      #converting X to Tensor
      if(device==torch.device("cuda")):
          noisy_image = torch.from_numpy(X).reshape(1,1,28,28).cuda().float()
      else:
          noisy_image = torch.from_numpy(X).reshape(1,1,28,28).float()
[31]: x = [64,128,256] #size of the hidden layer
      for hidden_layer in x:
          model_Q2 = AE_Q2(hidden_layer=hidden_layer).to(device)
          optimizer = torch.optim.Adam(model_Q2.parameters(), lr=learning_rate)
          train_losses_AE_h , test_losses_AE_h = 
       →train_test(model_Q2,device,train_loader,test_loader,optimizer,lossfn)
```

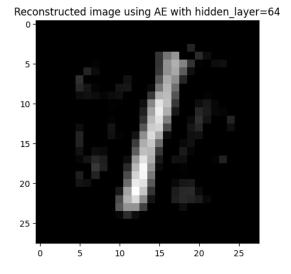
MSE train loss using AE with hidden_layer=64

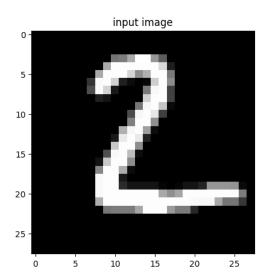


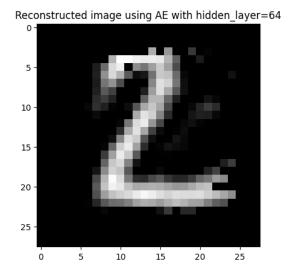


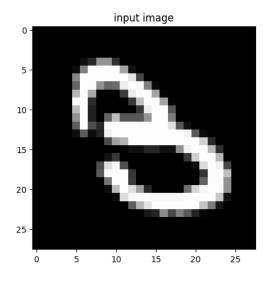


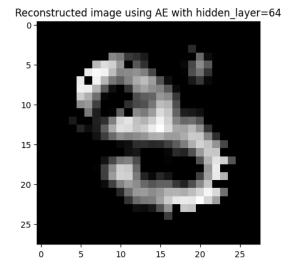


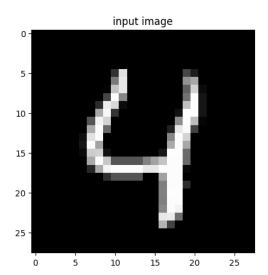


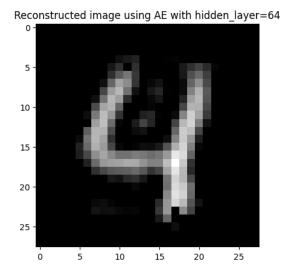


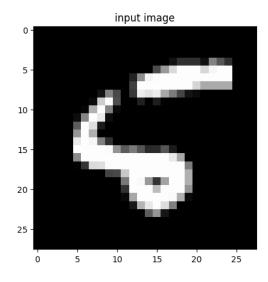


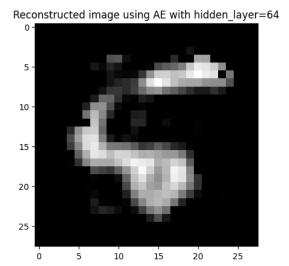


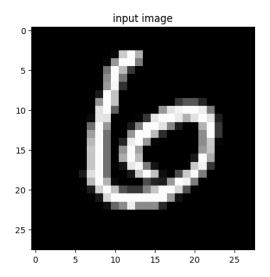


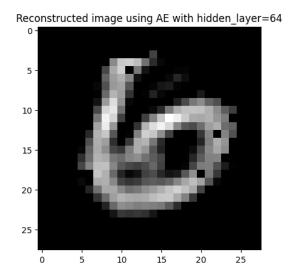


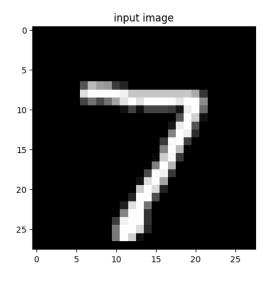


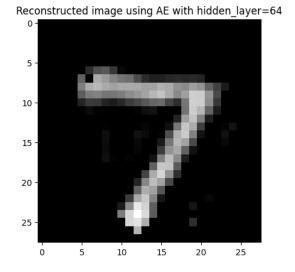


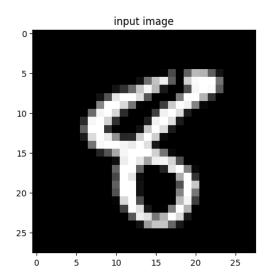


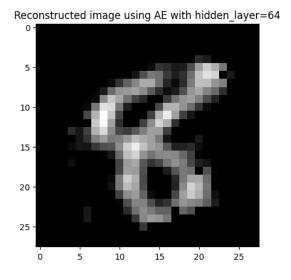


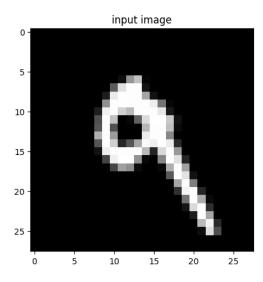


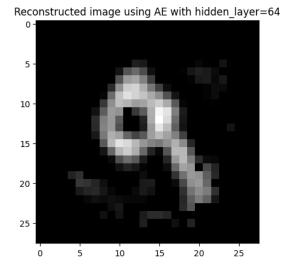


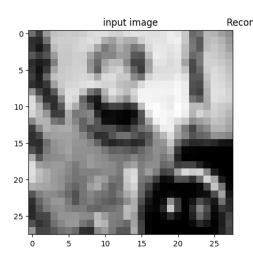


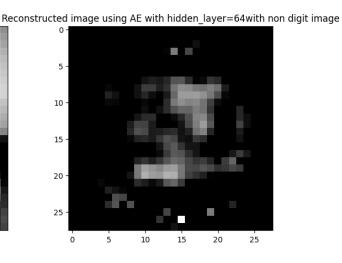


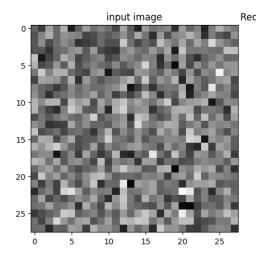


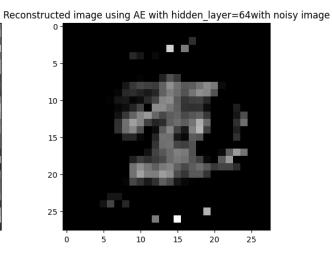


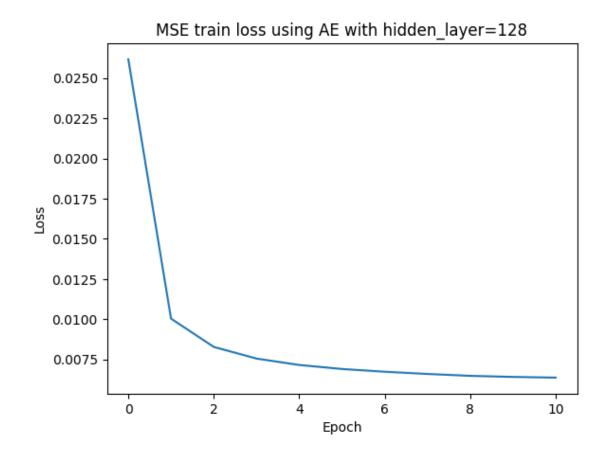


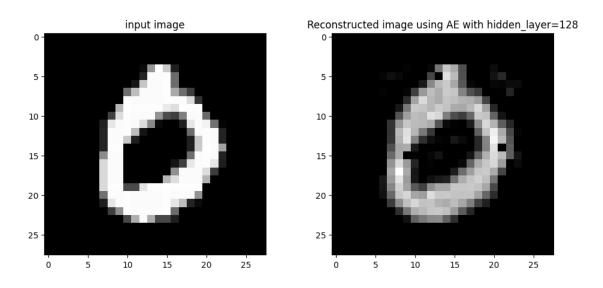


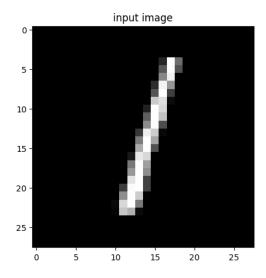


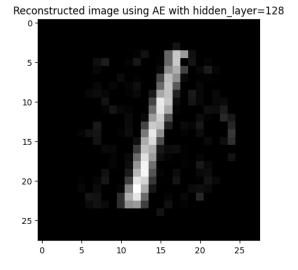


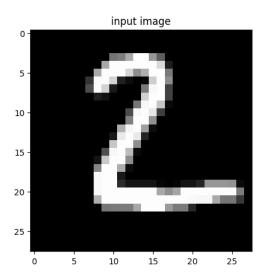


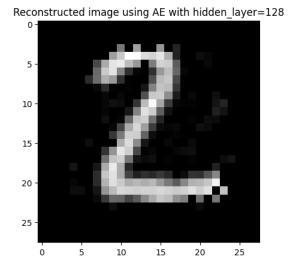


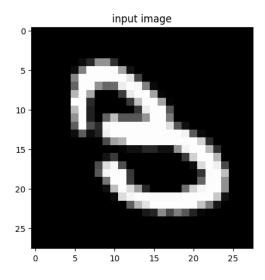


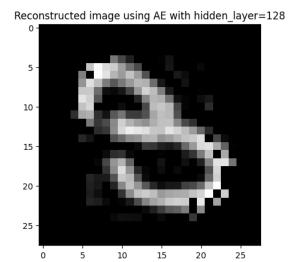


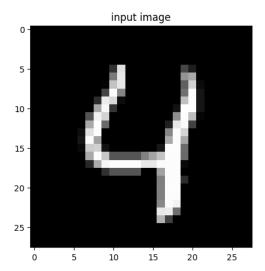


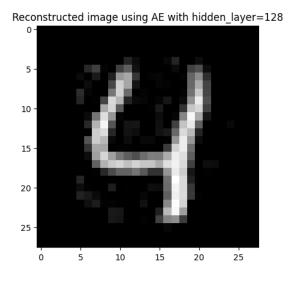


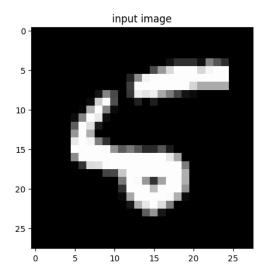


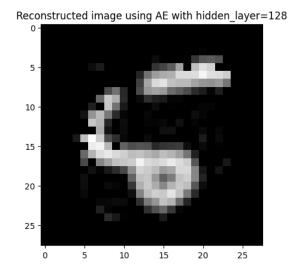


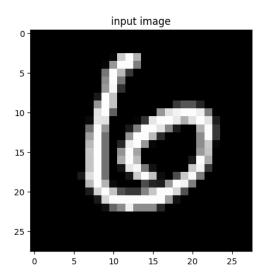


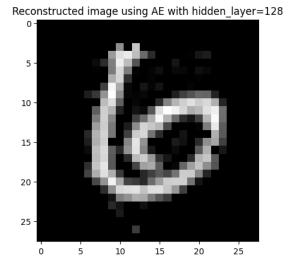


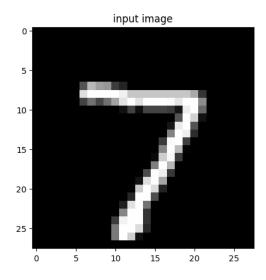


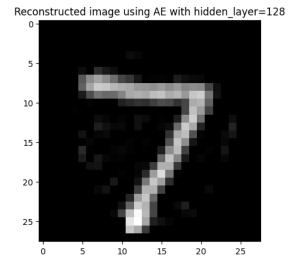


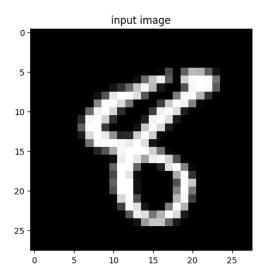


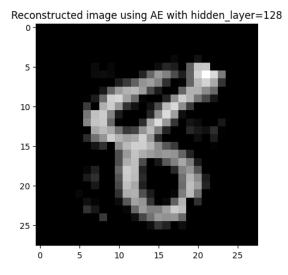


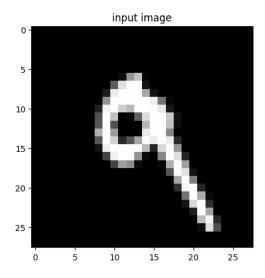


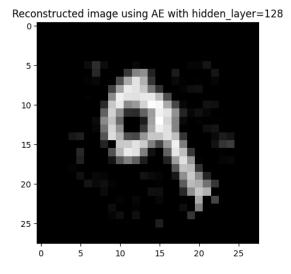


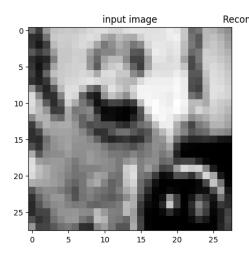


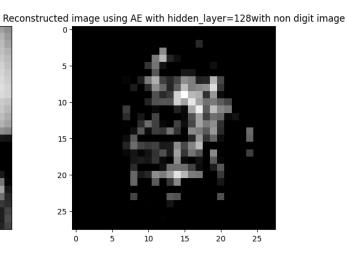


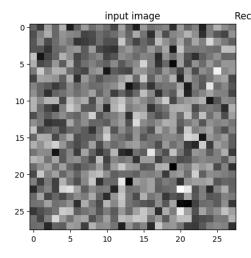


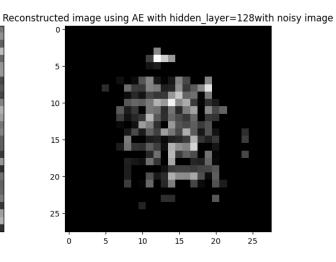


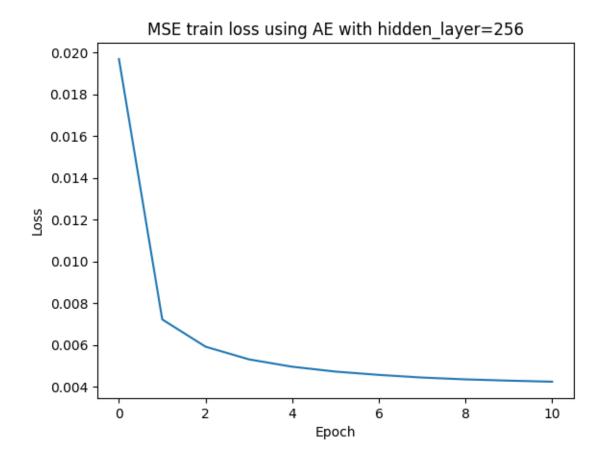


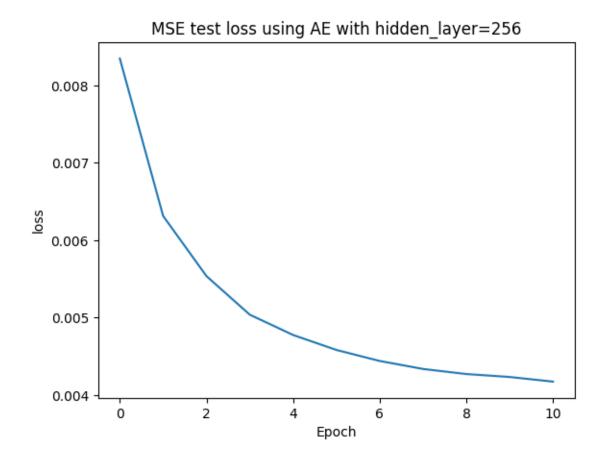




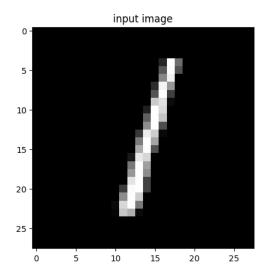


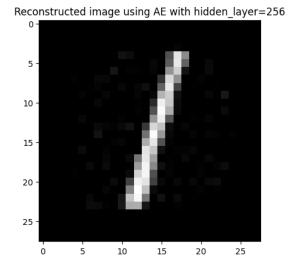


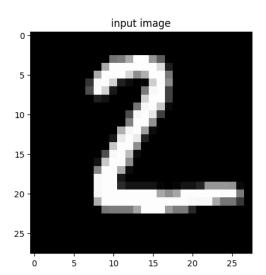


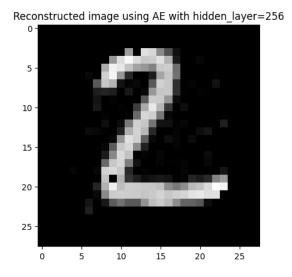


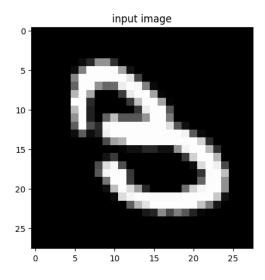


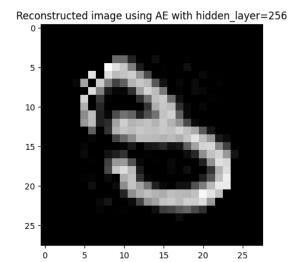


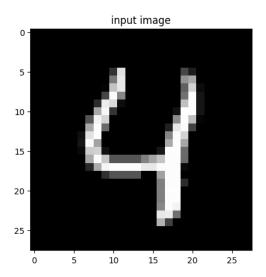


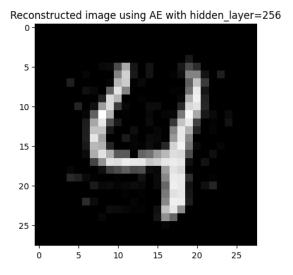


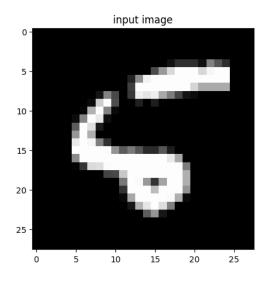


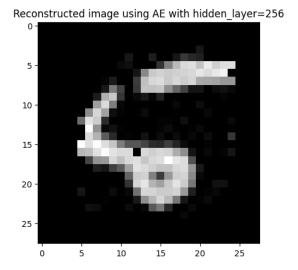


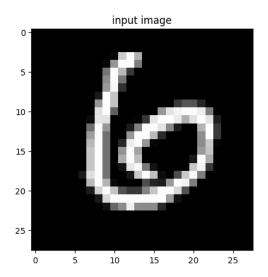


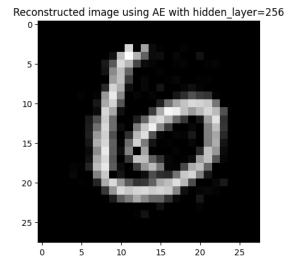


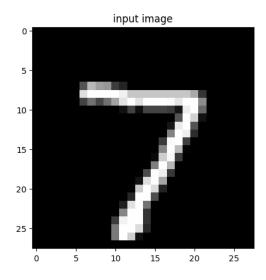


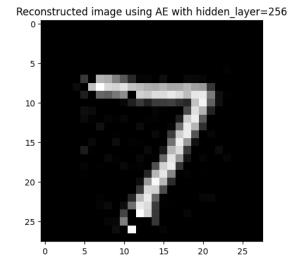


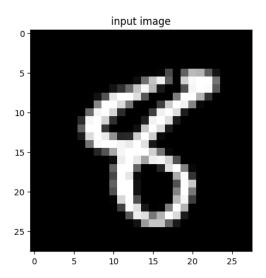


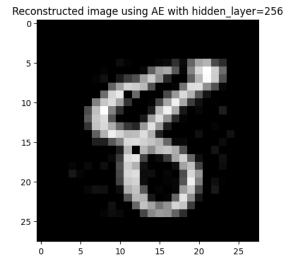


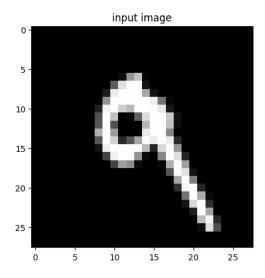


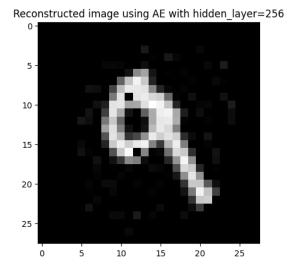


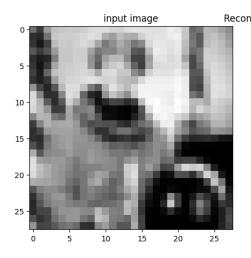


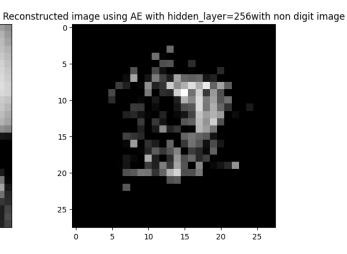


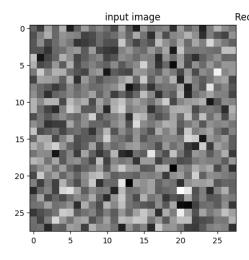


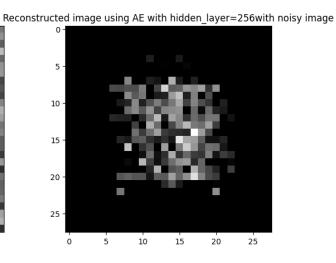












[]:

0.3 Q3

```
[32]: class AE_Q3(nn.Module):
        def __init__(self):
          super(AE Q3, self). init ()
          self.encoder = nn.Sequential(
              nn.Linear(784,1225),
              nn.ReLU())
          self.decoder =nn.Sequential(
              nn.Linear(1225,784),
              nn.ReLU())
        def forward(self,x):
          x = flatten(x,1) #flatten the image to a 784x1 vector
          encoded_input = self.encoder(x.float())
          reconstructed_input = self.decoder(encoded_input)
          return reconstructed_input,encoded_input
[33]: def avg_hl_activations(model,test_dataloader,model_name):
          model.eval()
          avg_act_val = 0
          with torch.no_grad():
              for (data,label) in test_dataloader:
                  (data,label) = (data.to(device),label.to(device))
                  reconstruction, encoded = model(data) #our prediction
                  avg_act_val += float(torch.mean(encoded))
          avg_act_val /= len(test_dataloader)
          print("The average activation of "+ str(model_name)+" is",avg_act_val)
[34]: def encoder_decoder_filters_plots(model_name,device):
          with torch.no_grad():
              encoder_filters = model.encoder[0].weight.detach().cpu().numpy()
              decoder_filters = model.decoder[0].weight.detach().cpu().numpy()
              #plot the encoder and decoder weights as an image for Oth neuron
              plt.imshow(encoder_filters[0].reshape(28,28), cmap='gray')
              plt.colorbar()
              plt.title('Encoder Filters for '+str(0)+'th neuron of '+u
       →str(model_name))
              plt.show()
              plt.imshow(decoder_filters[:,0].reshape(28,28), cmap='gray')
```

plt.colorbar()

```
plt.title('Decoder Filters for '+str(0)+'th neuron of '+⊔

⇔str(model_name))

plt.show()
```

```
[35]: def visualize activations(model,test_dataloader,model_name,device,hidden_layer):
       → #visualize the activations
          # data_ind = np.random.randint(low=0, high=9999, size=5)
          for i,ind in enumerate(keys test):
              test_image = test_dataloader.dataset.data[ind].clone()
              test label = test dataloader.dataset.targets[ind].clone()
              with torch.no grad():
                  if(device == torch.device("cuda")):
                      test_image = test_image.reshape(1,1,28,28).cuda().float()
                  else:
                      test_image = test_image.reshape(1,1,28,28).float()
                  reconstructed_image,encoded = model.forward(test_image)
                  encoded = encoded.detach().cpu().numpy()
                  plt.imshow(encoded.reshape(int(np.sqrt(hidden_layer)),int(np.

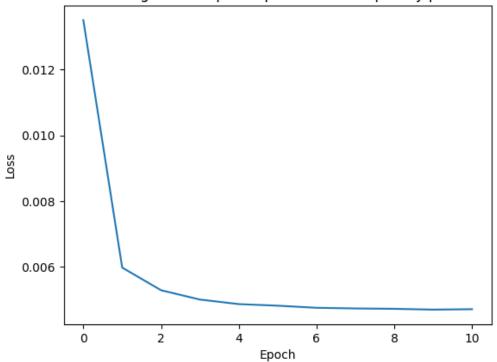
¬sqrt(hidden_layer))), cmap='gray')
                  str_title = "Activation for digit "+str(test_label.item())
                  plt.title(str_title)
                  plt.show()
```

```
[36]: lambda_reg_vals=[0.000001, 0.001, 0.1]
      for lambda_reg in lambda_reg_vals:
          model_Q3 = AE_Q3().to(device)
          optimizer = torch.optim.Adam(model_Q3.parameters(), lr=learning_rate)
          train_losses_AE_Q3 , test_losses_AE_Q3 =_
       -train_test(model_Q3,device,train_loader,test_loader,optimizer,lossfn,lambda_reg,sparse=True
          plot_losses(train_losses_AE_Q3, test_losses_AE_Q3, model_name =_

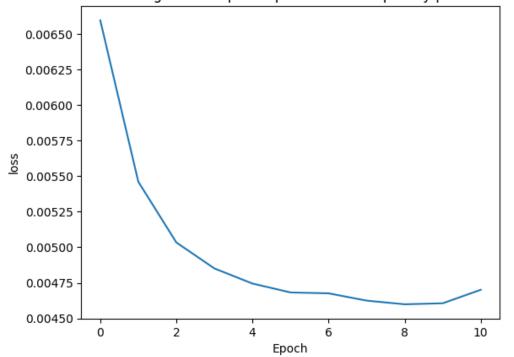
¬"overcomplete sparse AE with sparsity parameter "+str(lambda_reg))

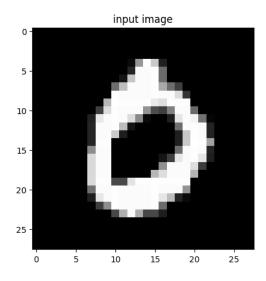
          for i in keys_test:
              test_image = test_loader.dataset.data[i, :, :].clone()
              plot_reconstructed_image(model_Q2,device,test_image, model_name="AE_U
       ⇔with hidden_layer="+str(hidden_layer))
          plot_reconstructed_image(model_Q3,device,test_image,__
       model_name="overcomplete sparse AE with sparsity parameter "+str(lambda_reg))
          avg_hl_activations(model_Q3,test_loader, "overcomplete sparse AE withu
       ⇔sparsity parameter "+str(lambda_reg))
          encoder_decoder_filters_plots(model_Q3, "sparse AE with sparsity_
       →parameter"+str(lambda_reg),device)
          visualize_activations(model_Q3,test_loader, "sparse AE with sparsity_
       →parameter"+str(lambda_reg),device,1225)
```

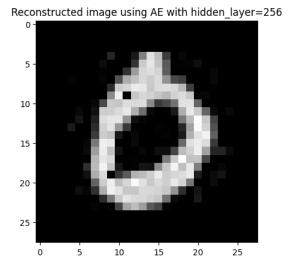
MSE train loss using overcomplete sparse AE with sparsity parameter 1e-06

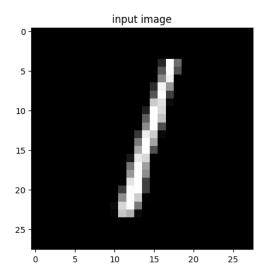


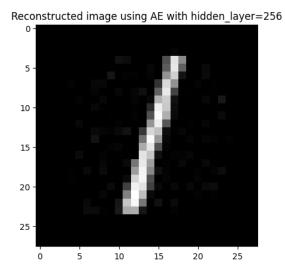
MSE test loss using overcomplete sparse AE with sparsity parameter 1e-06

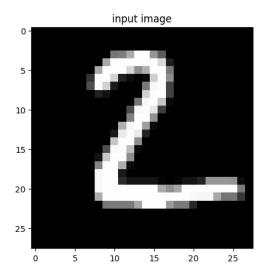


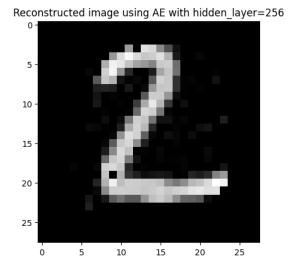


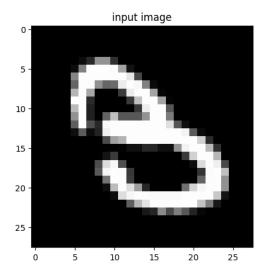


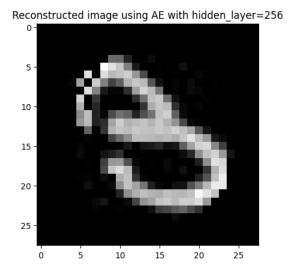


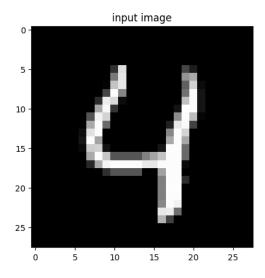


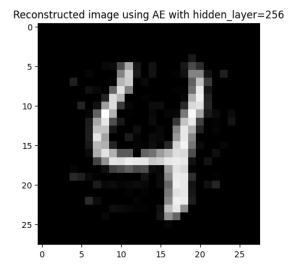


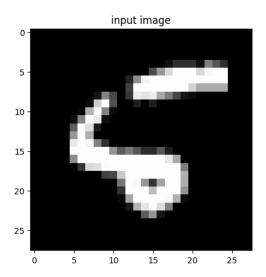


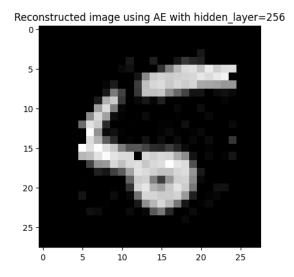


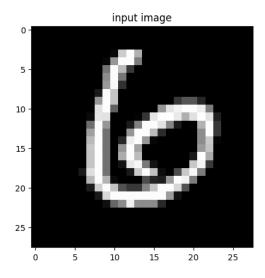


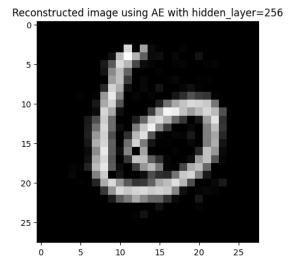


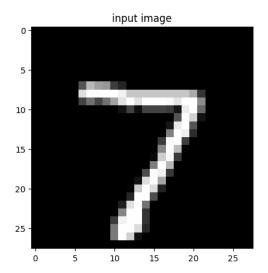


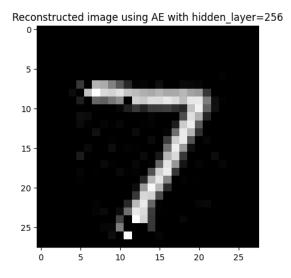


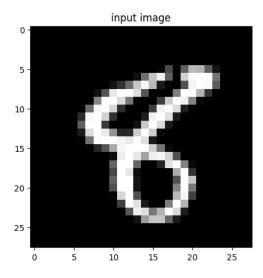


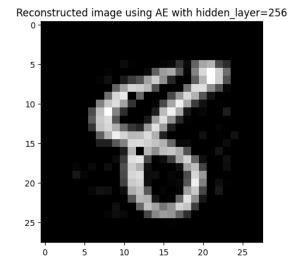


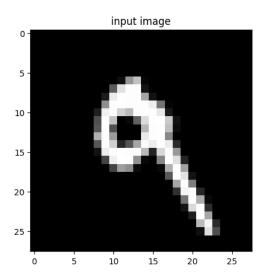


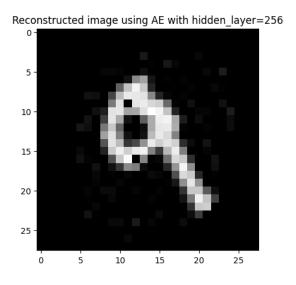


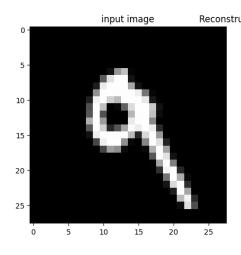


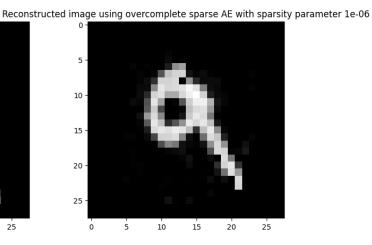






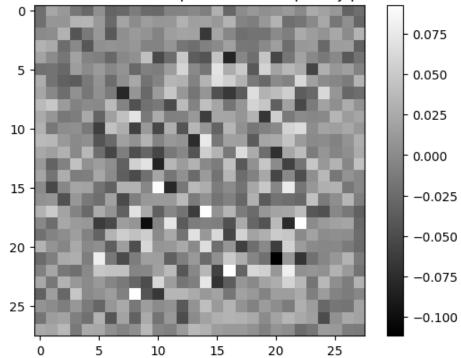




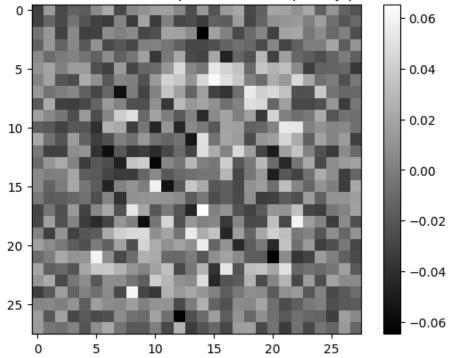


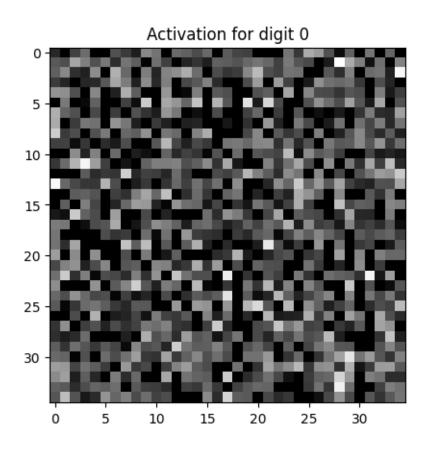
The average activation of overcomplete sparse AE with sparsity parameter 1e-06 is 0.27716308906674386

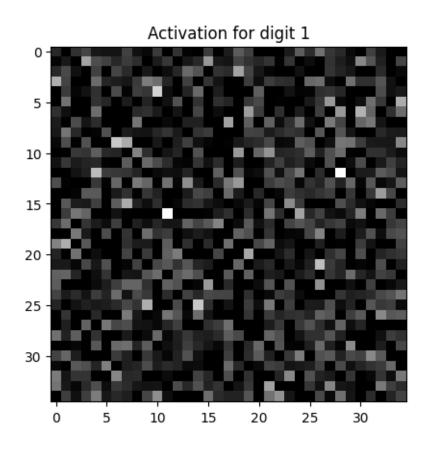
Encoder Filters for 0th neuron of sparse AE with sparsity parameter1e-06

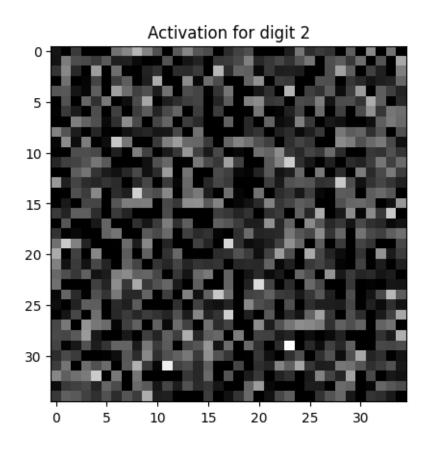


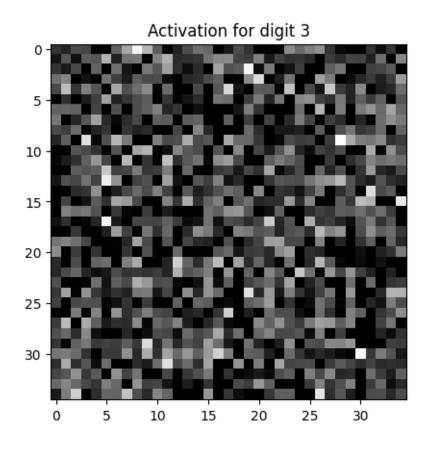
Decoder Filters for 0th neuron of sparse AE with sparsity parameter1e-06

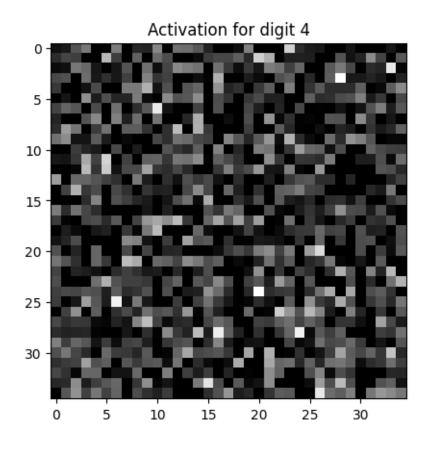


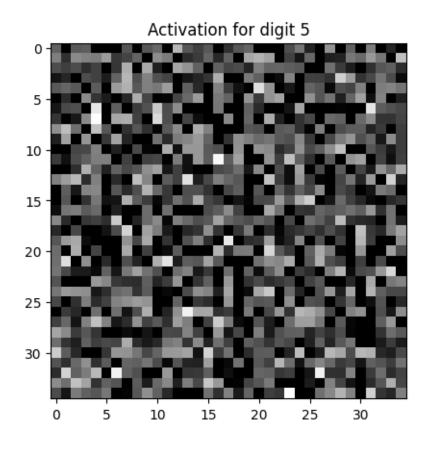


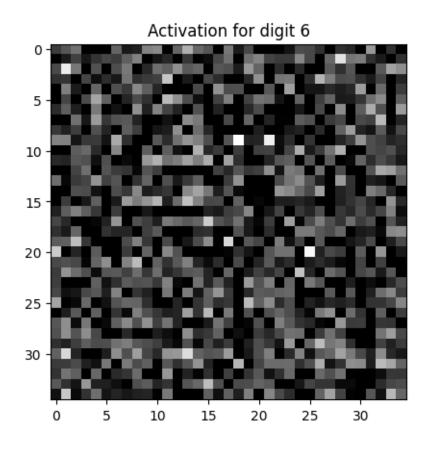


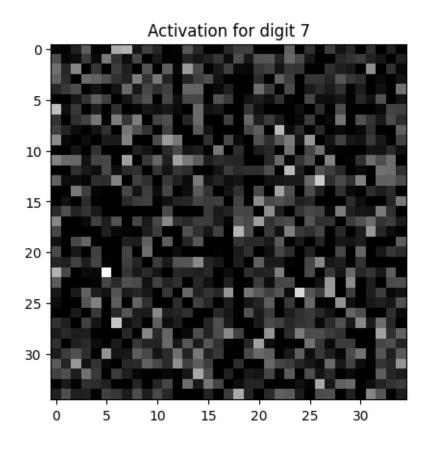


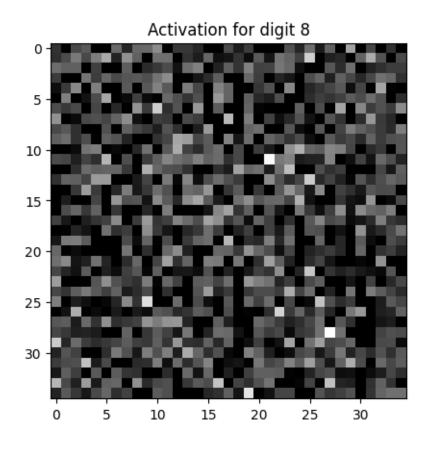


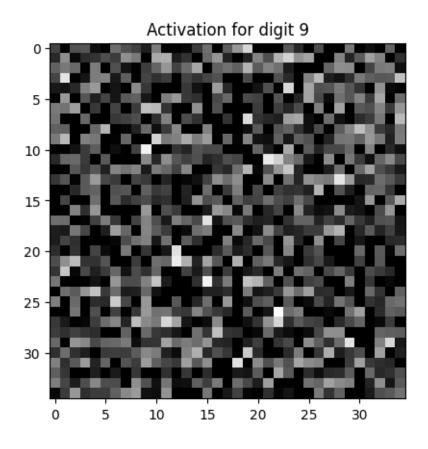




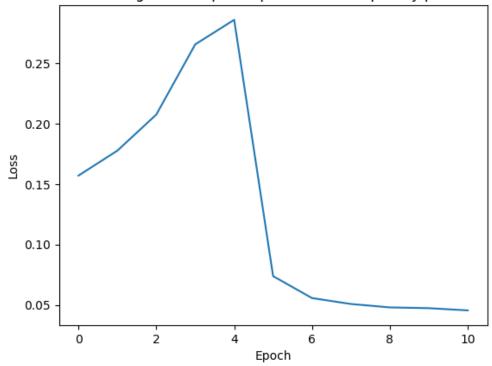




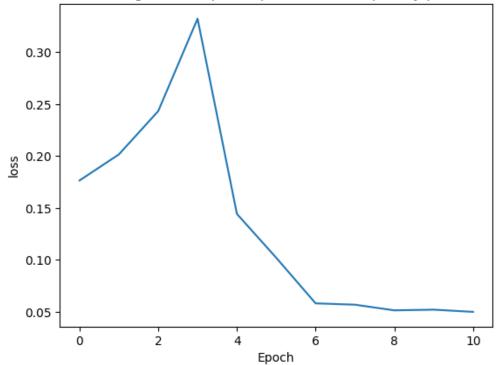


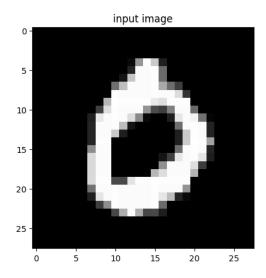


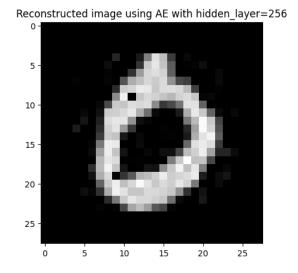
MSE train loss using overcomplete sparse AE with sparsity parameter 0.001

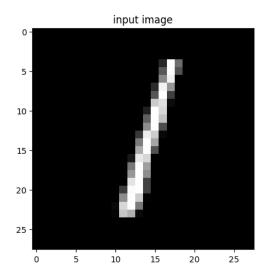


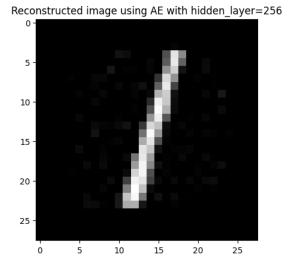
MSE test loss using overcomplete sparse AE with sparsity parameter 0.001

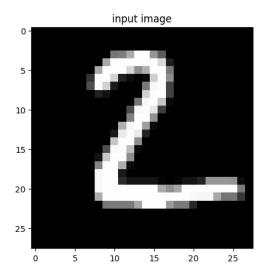


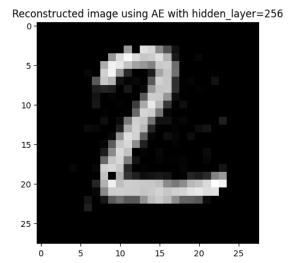


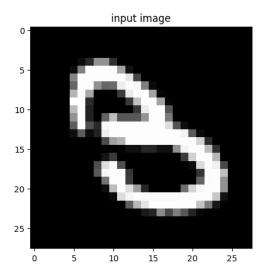


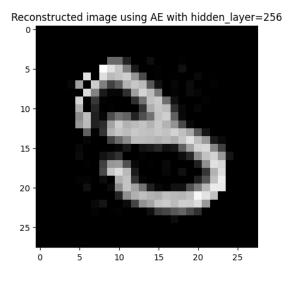


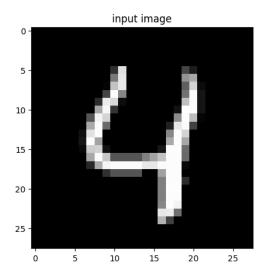


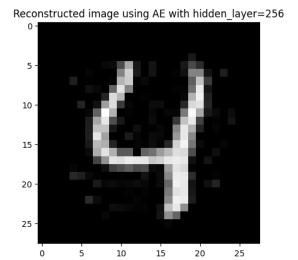


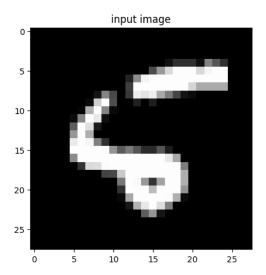


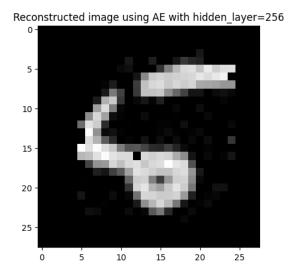


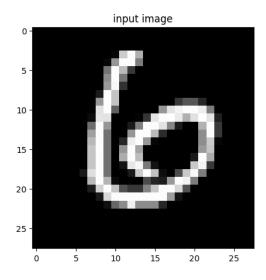


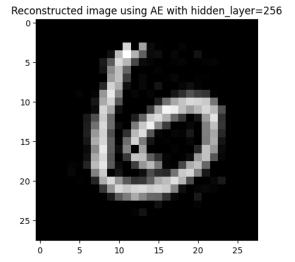


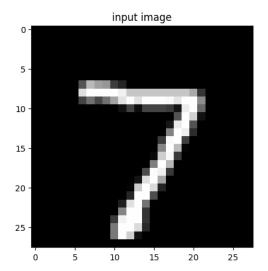


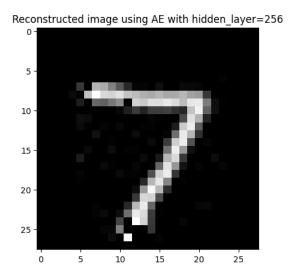


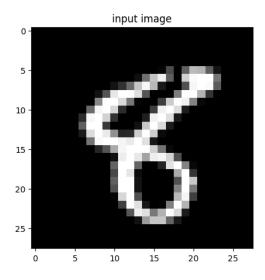


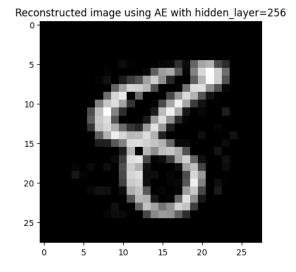


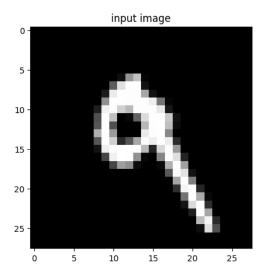


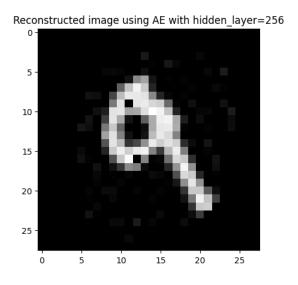


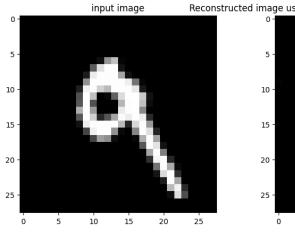


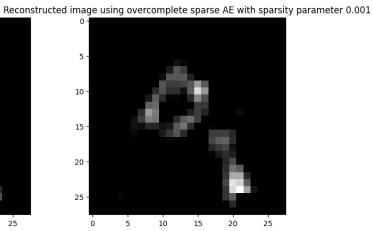






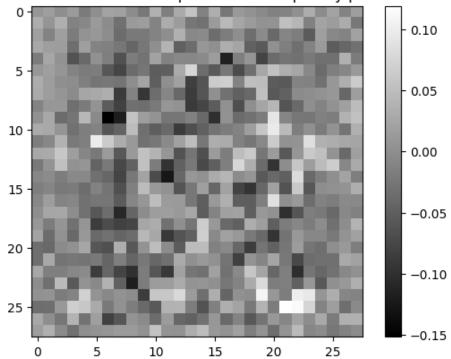




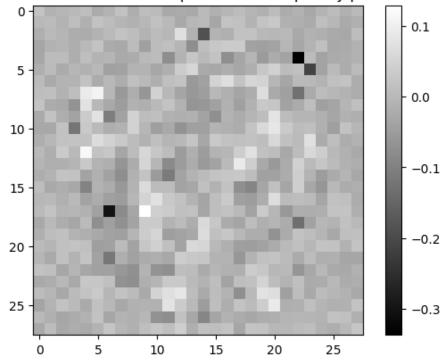


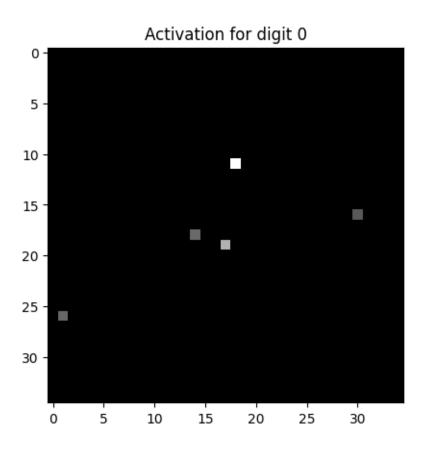
The average activation of overcomplete sparse AE with sparsity parameter 0.001 is 0.004904146178159863

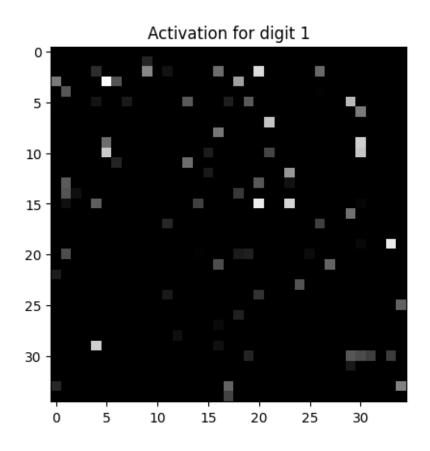
Encoder Filters for 0th neuron of sparse AE with sparsity parameter0.001

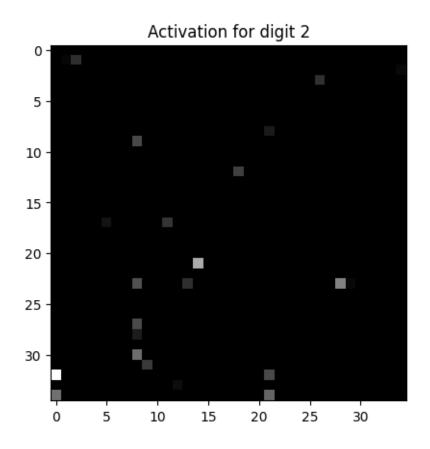


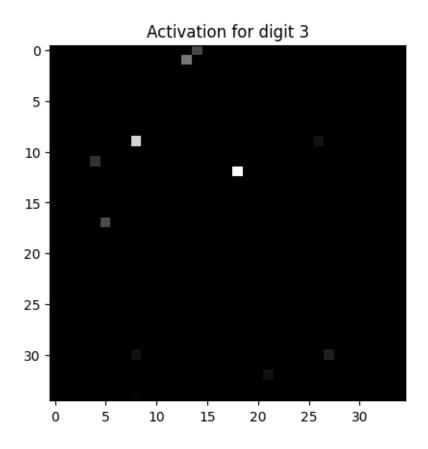
Decoder Filters for 0th neuron of sparse AE with sparsity parameter0.001

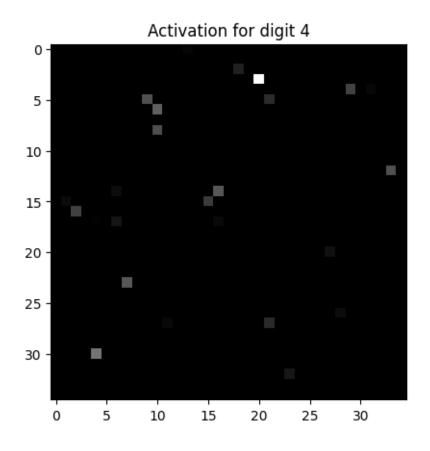


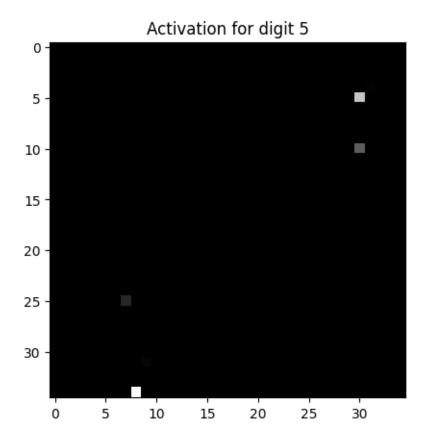


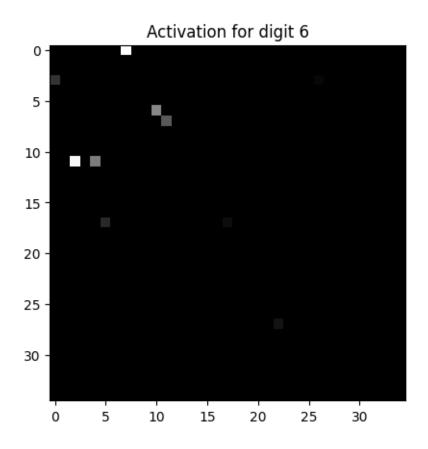


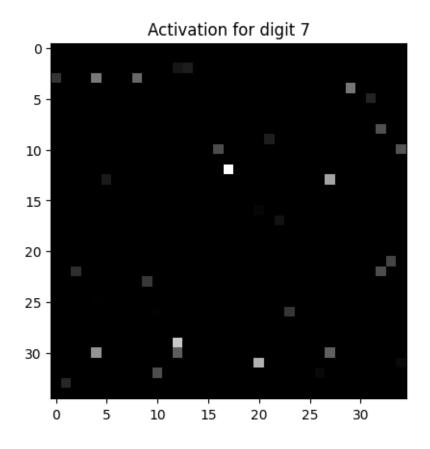


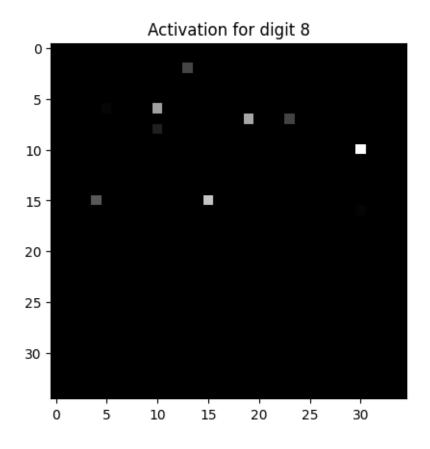


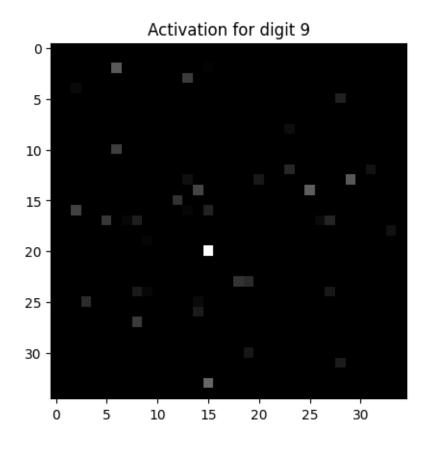




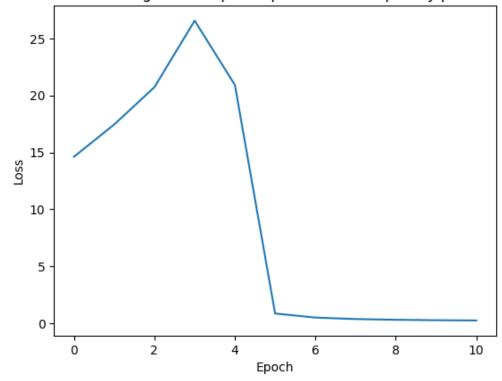




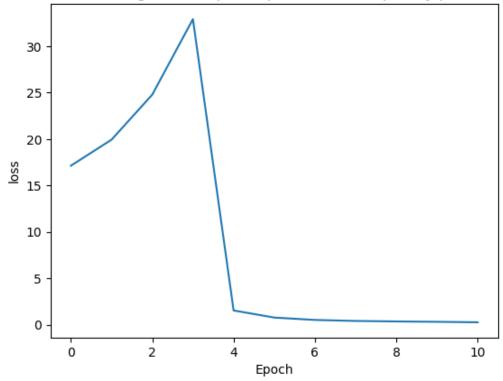


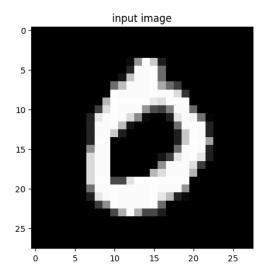


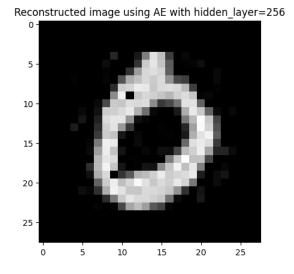
MSE train loss using overcomplete sparse AE with sparsity parameter 0.1

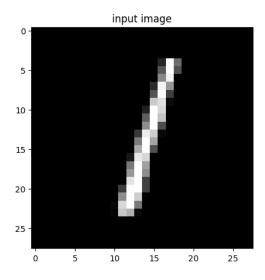


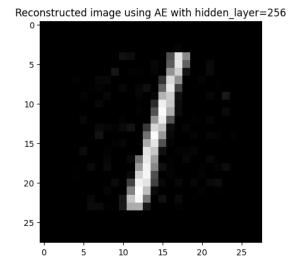
MSE test loss using overcomplete sparse AE with sparsity parameter 0.1

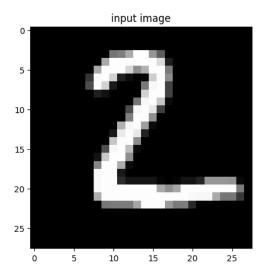


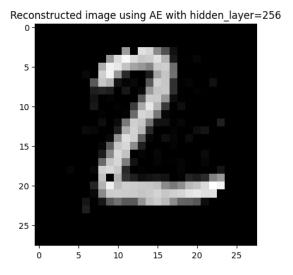


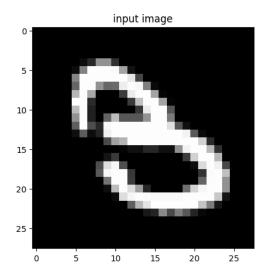


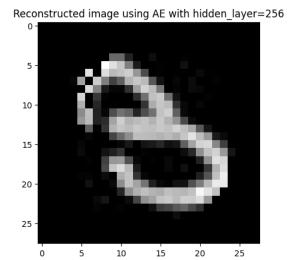


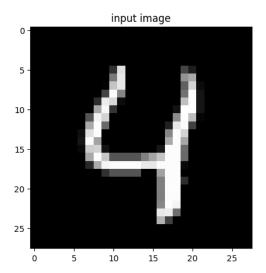


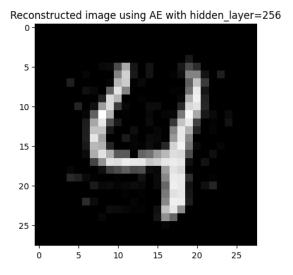


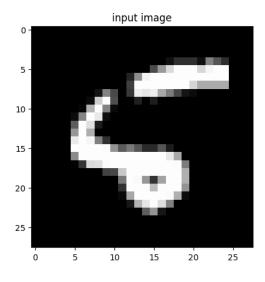


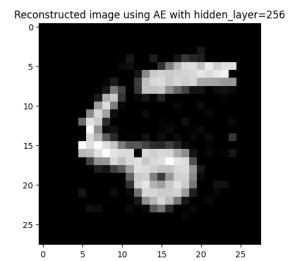


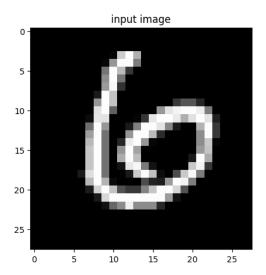


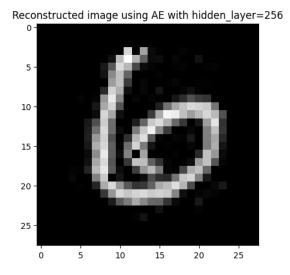


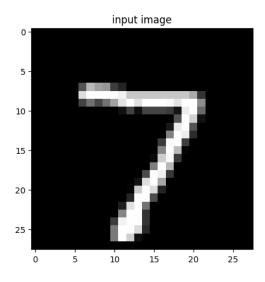


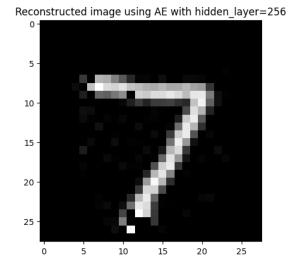


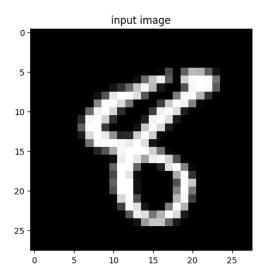


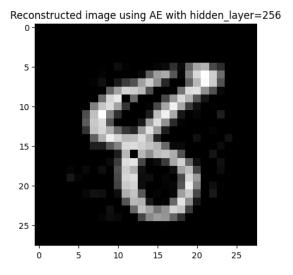


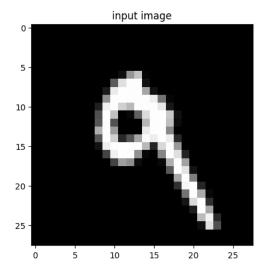


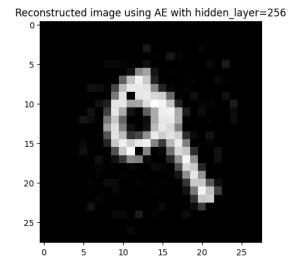


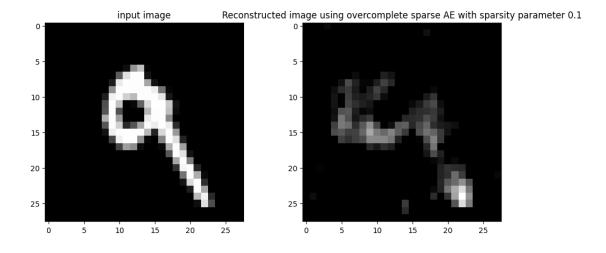






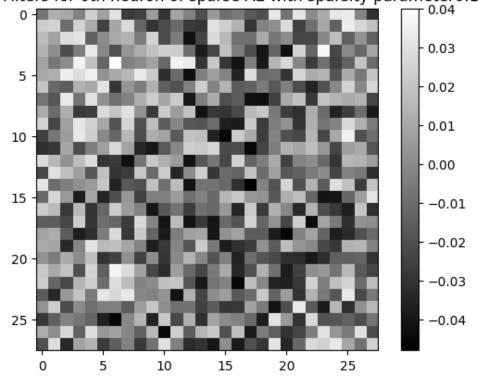




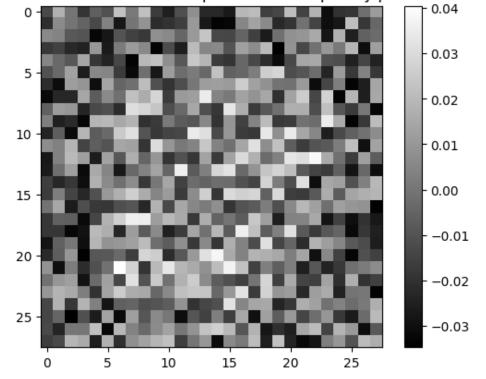


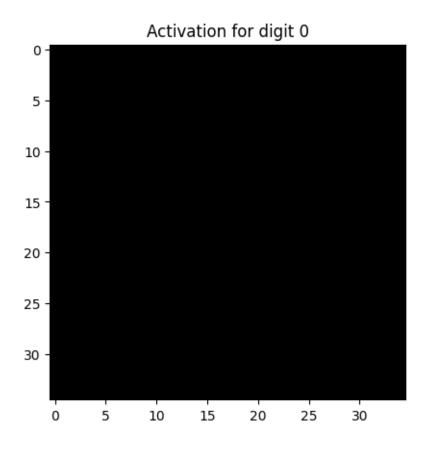
The average activation of overcomplete sparse AE with sparsity parameter 0.1 is 0.0004624879096809309

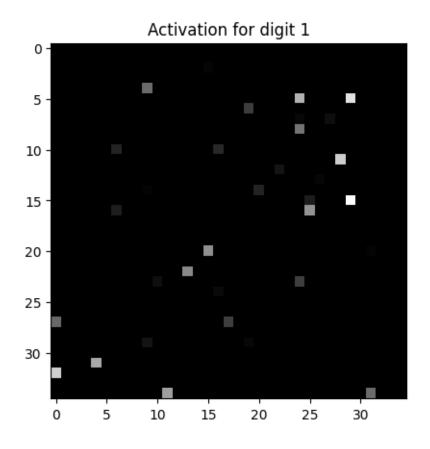
Encoder Filters for 0th neuron of sparse AE with sparsity parameter 0.1

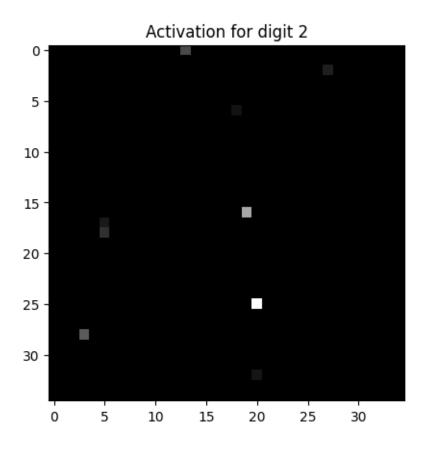


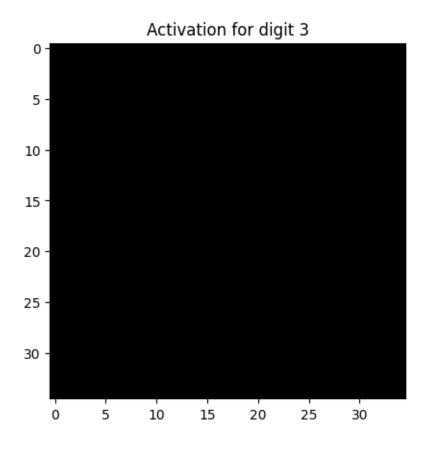
Decoder Filters for 0th neuron of sparse AE with sparsity parameter 0.1

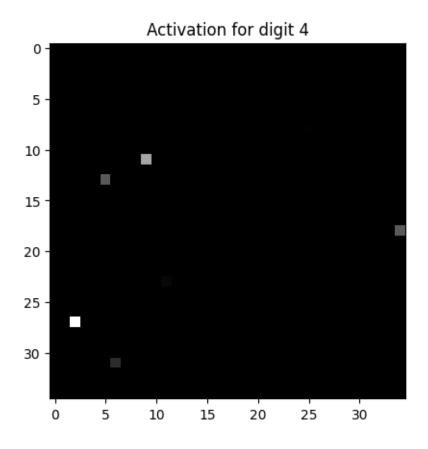


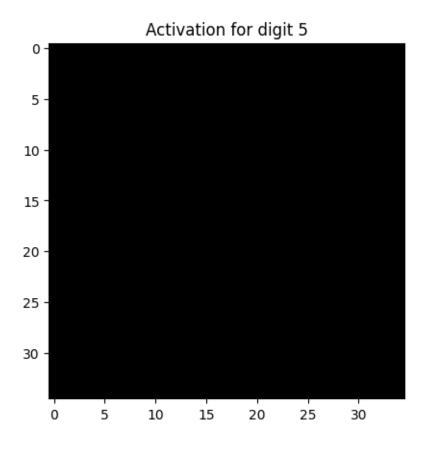


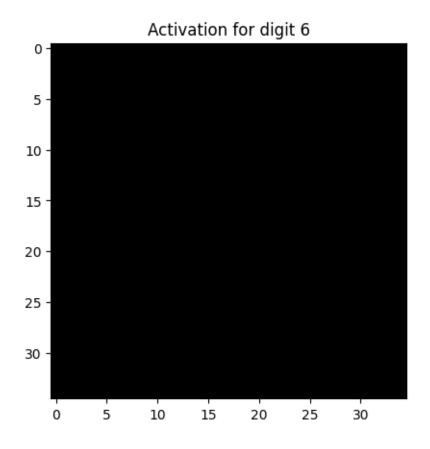


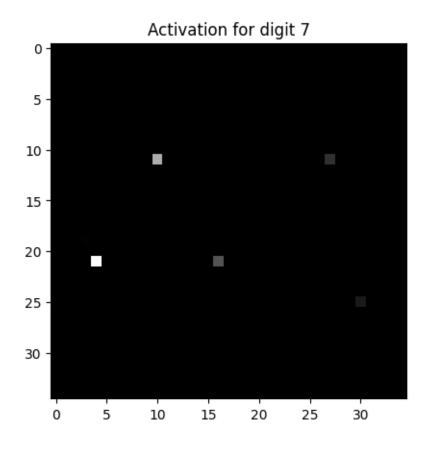


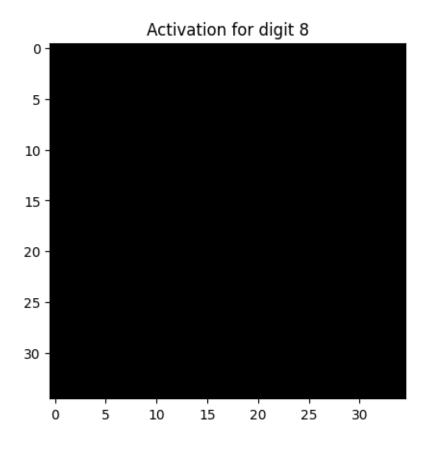


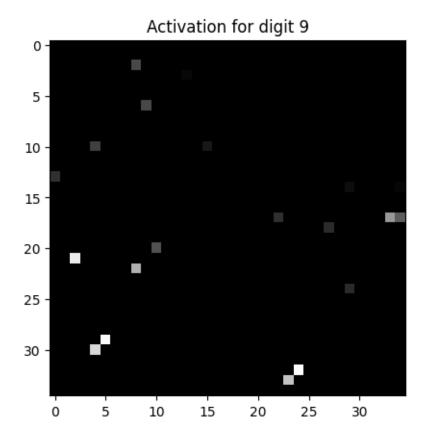




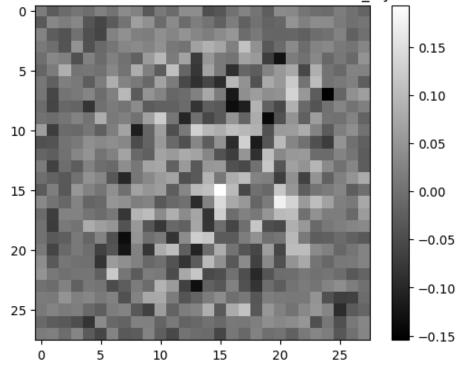




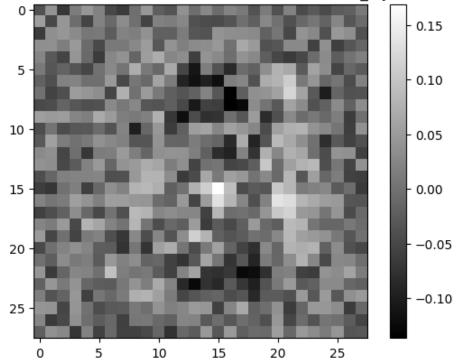




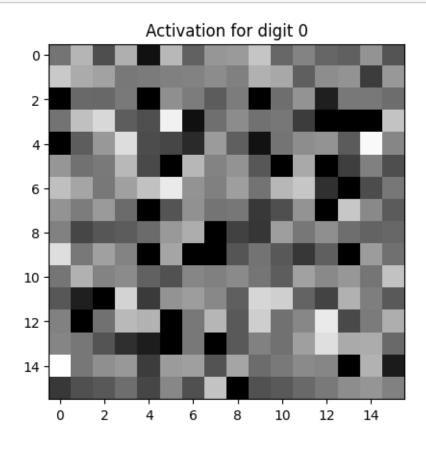
Encoder Filters for 0th neuron of standard AE with hidden_layer size 256

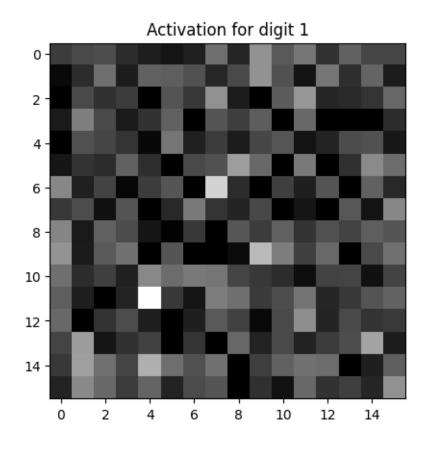


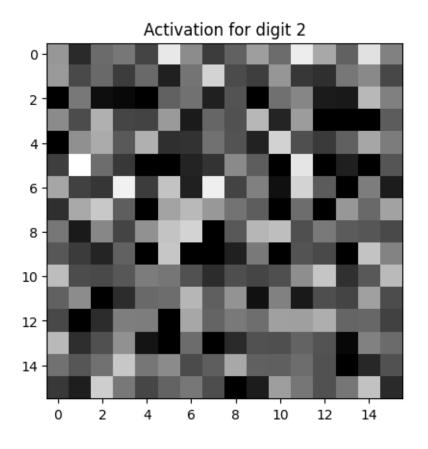
Decoder Filters for 0th neuron of standard AE with hidden_layer size 256

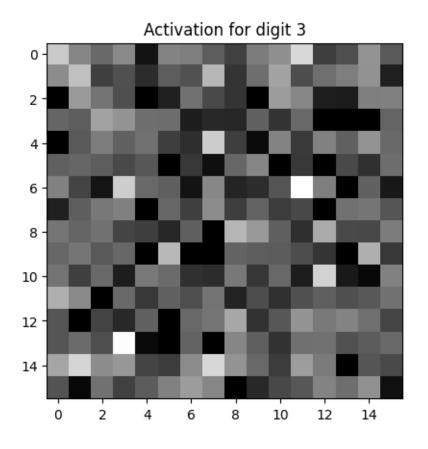


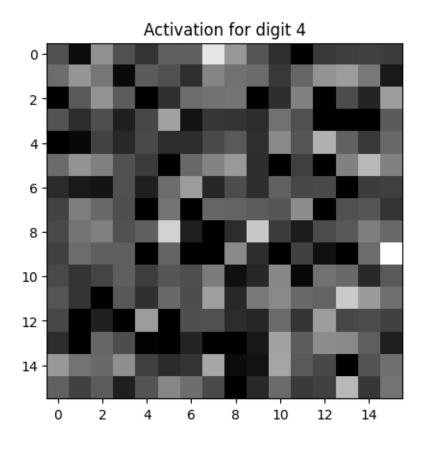
[38]: visualize_activations(model_Q2,test_loader,"Standard AE with_ hidden_layer=256",device,256)

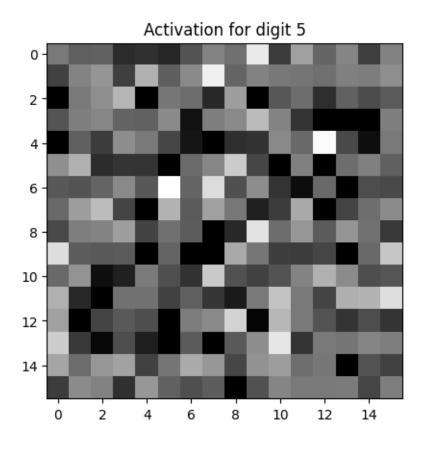


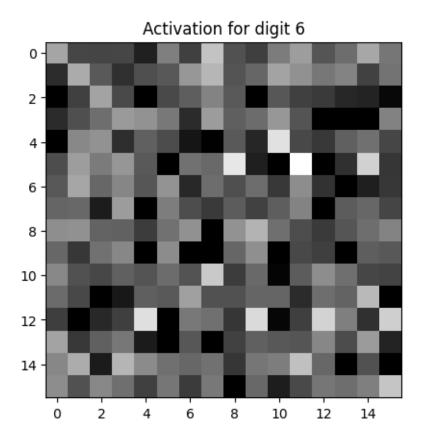


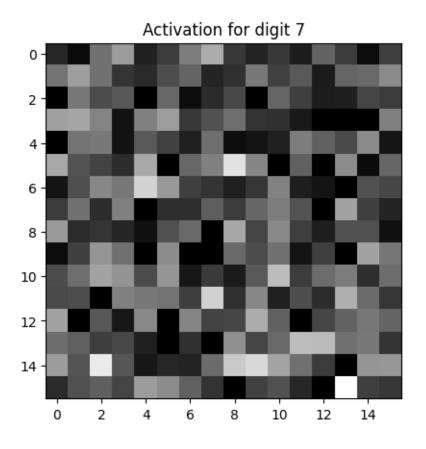


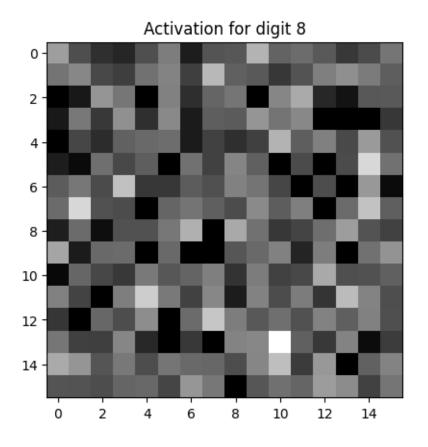


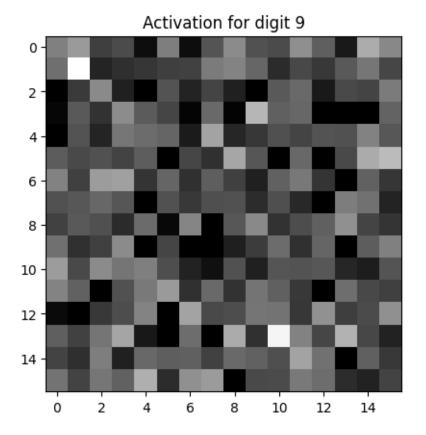












0.4 Q4

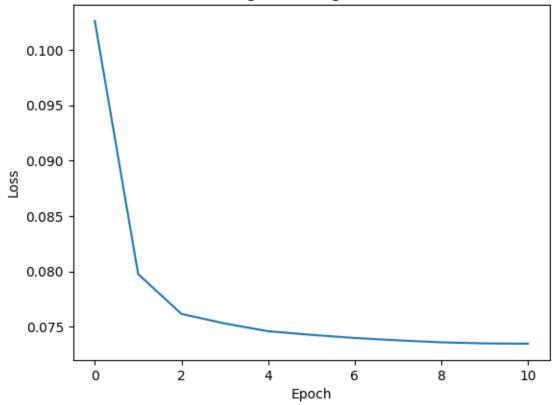
```
[39]: def add_noise(img, noise_val):
          noise = torch.randn(img.size())*noise_val
          noisy_img = img + noise
          return noisy_img
[41]: noise_vals = [0.3, 0.5, 0.8, 0.9]
      for noise_val in noise_vals:
          model_Q4 = AE_Q2(256).to(device)
          optimizer = torch.optim.Adam(model_Q4.parameters(), lr=learning_rate)
          train_losses_AE_Q4 , test_losses_AE_Q4 =_
       →train_test(model_Q4,device,train_loader,test_loader,optimizer,lossfn,denoise=True,noise_val
          plot_losses(train_losses_AE_Q4, test_losses_AE_Q4, model_name = "Denoising_
       →AE with noise level "+str(noise_val))
          #MSE recomnstruction error for vanilla AE
          mse_error = test(model_Q4,device,test_loader,lossfn)
          print(" MSE for the ",noise_val,"=", mse_error.item())
          index = random.randint(0,9999)
          test_image = test_loader.dataset.data[index, :, :].clone()
```

```
test_image = add_noise(test_image,noise_val)

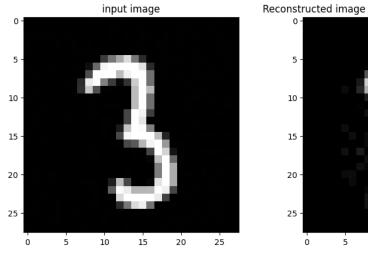
plot_reconstructed_image(model_Q4,device,test_image, model_name="Denoising_\subseteq AE with noise level "+str(noise_val))

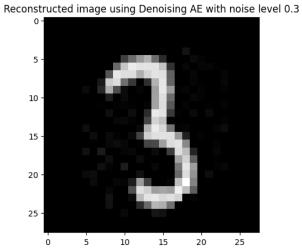
encoder_decoder_filters_plots(model_Q3,"Denoising AE with noise level_\subseteq "+str(noise_val),device)
```

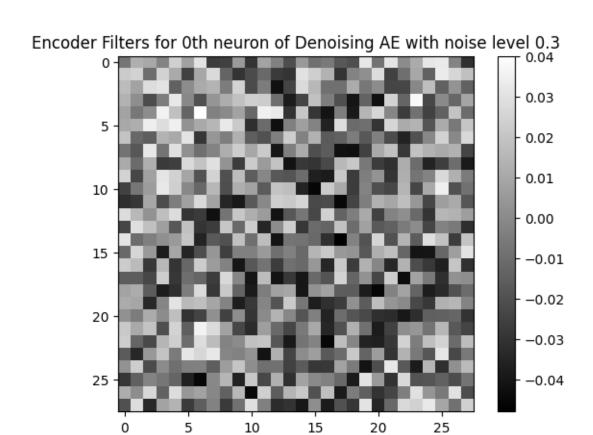
MSE train loss using Denoising AE with noise level 0.3

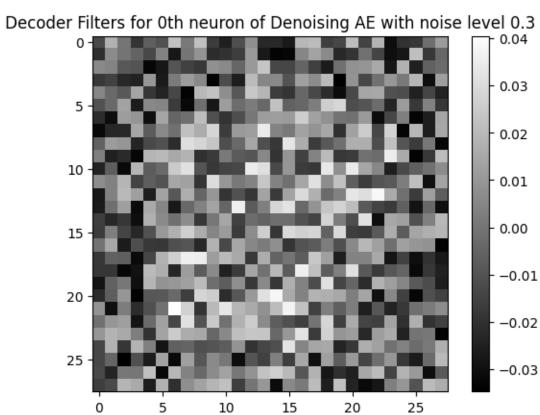


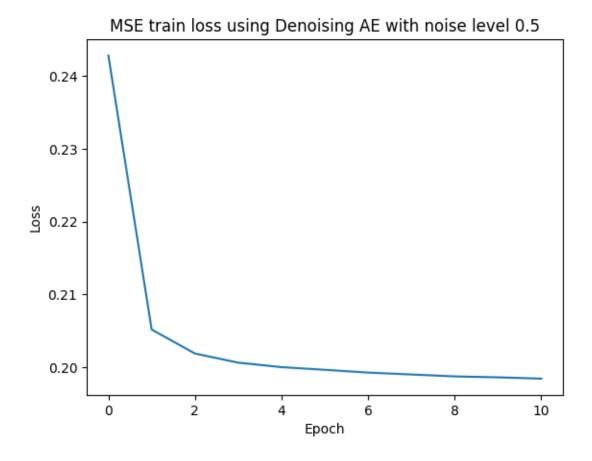
MSE for the 0.3 = 0.0033181174658238888



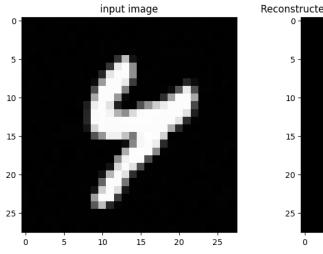


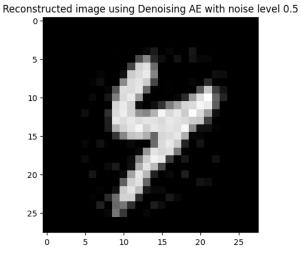


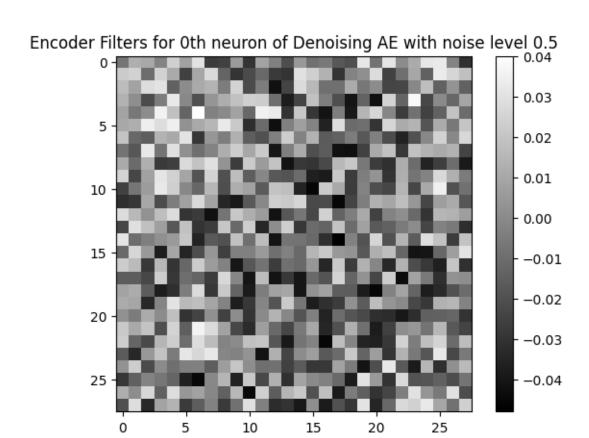


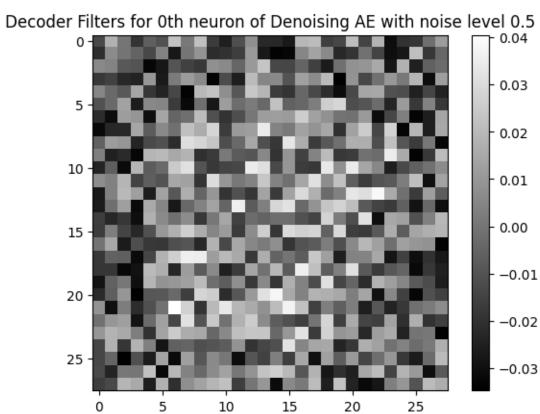


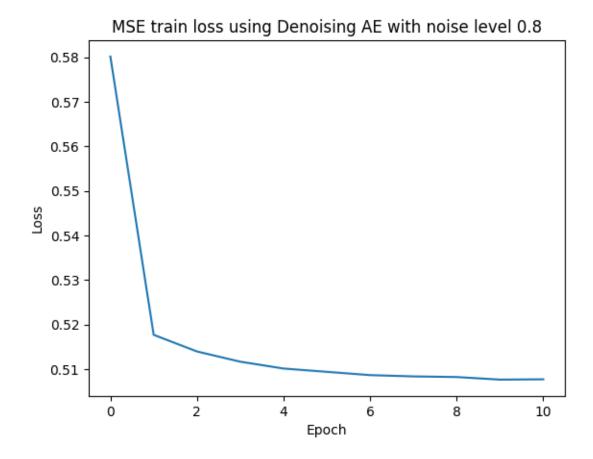
MSE for the 0.5 = 0.0038982063997536898

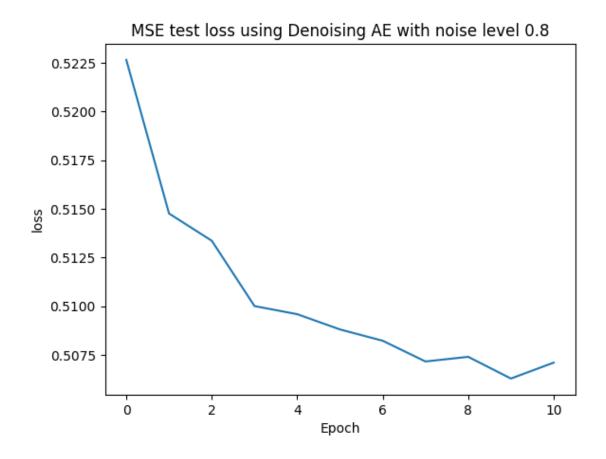




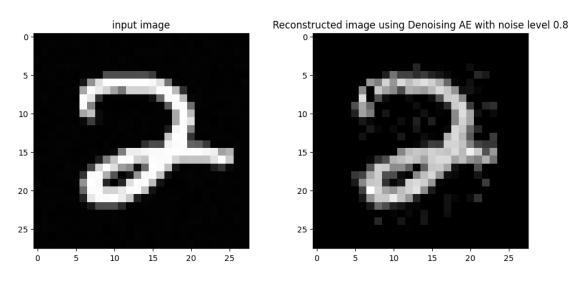


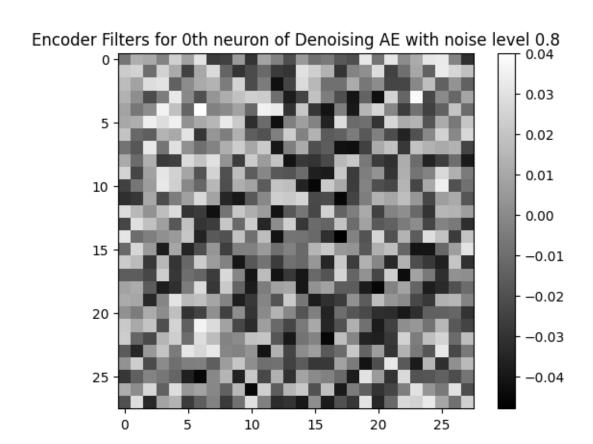




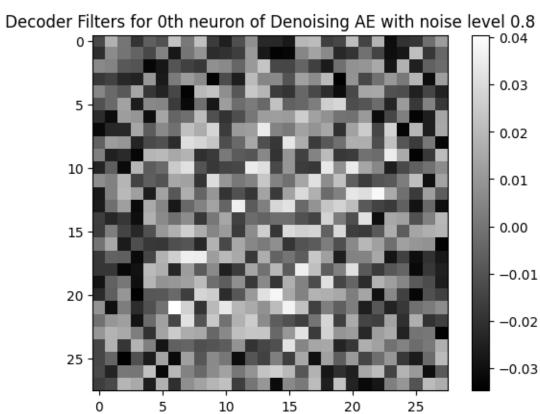


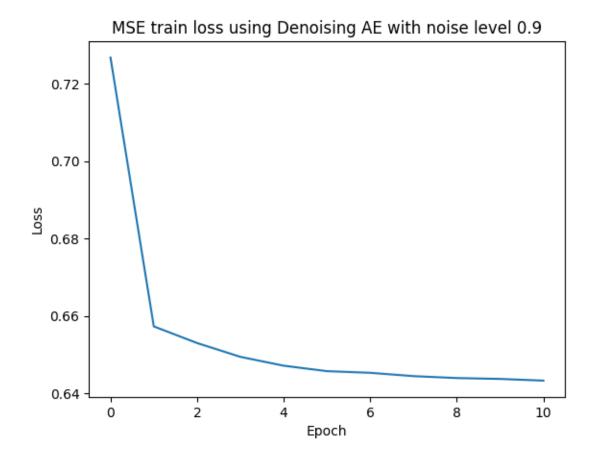
MSE for the 0.8 = 0.006269432138651609

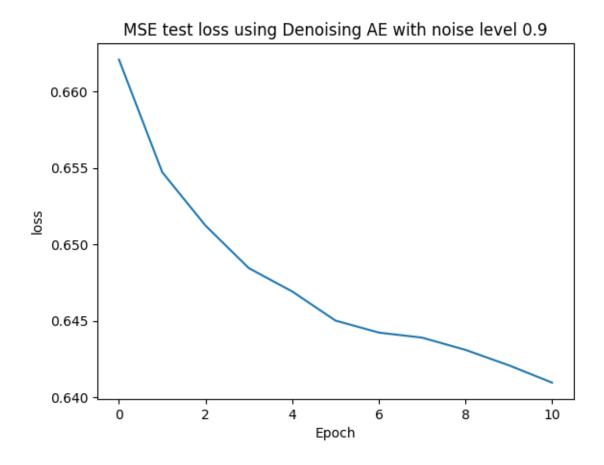




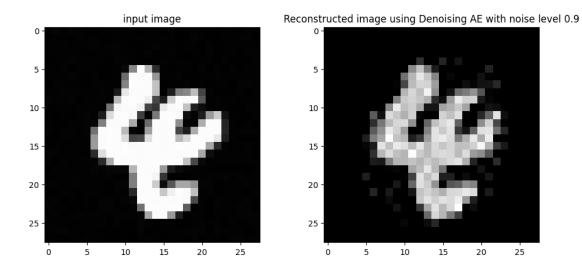


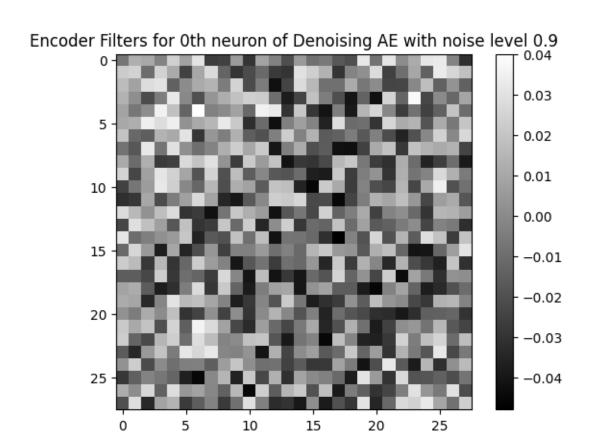




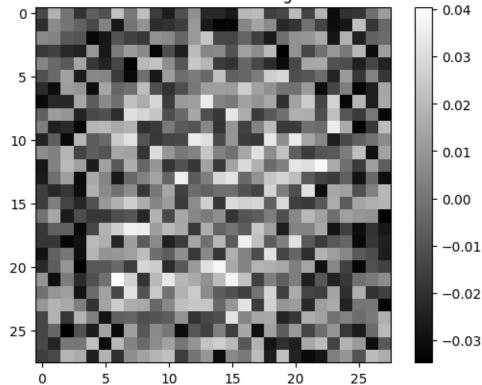


MSE for the 0.9 = 0.006520132068544626









[]: # Convolutional Autoencoders

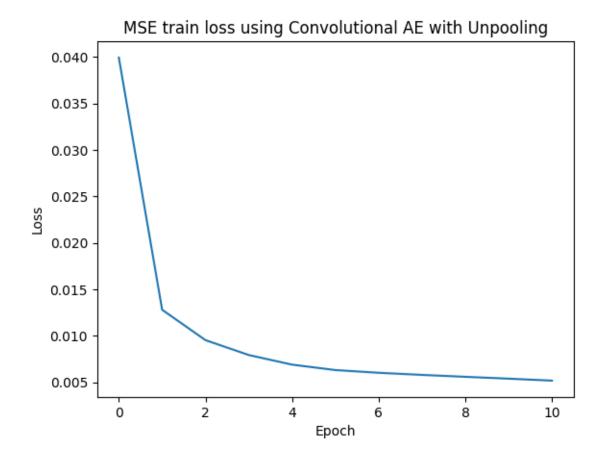
0.5 Q5

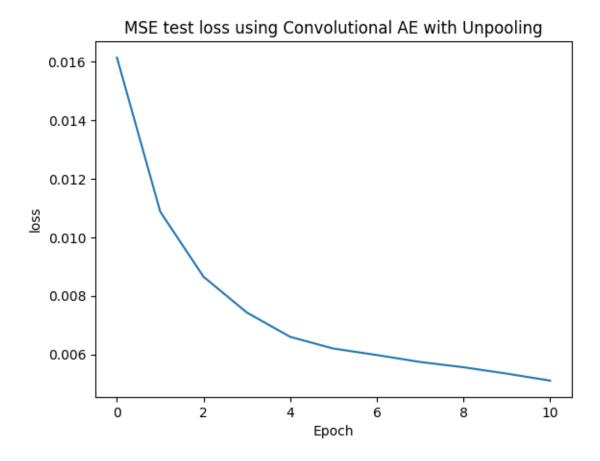
```
nn.MaxPool2d(kernel_size = (2,2),return_indices = True)
       ) #14x14x8 to 7x7x16
       self.encoder_conv3 = nn.Sequential(
           nn.Conv2d(16,16, kernel_size = 3, stride = 1,padding= 1),
           nn.ReLU(),
           nn.MaxPool2d(kernel_size = (2,2),return_indices = True)
       ) \#7x7x16 to 3x3x16
       #initializing the decoder module
       self.decoder_conv1 = nn.Sequential(nn.Identity()) #7x7x16 to 7x7x16
       self.decoder_conv2 = nn.Sequential(
           nn.Conv2d(16,8, kernel_size = 3, stride = 1,padding= 1),
           nn.ReLU()
       ) #14x14x16 to 14x14x8
       self.decoder_conv3 = nn.Sequential(
           nn.Conv2d(8,1, kernel_size = 3, stride = 1,padding= 1),
           nn.ReLU()
       ) #28x28x8 to 28x28x1
       #defining the unpooling operation
       self.unpool = nn.MaxUnpool2d(kernel_size = (2,2))
  def forward(self,x): #defines the forward pass and also the structure of □
→ the network thus helping backprop
       encoded_input,indices1 = self.encoder_conv1(x.float()) # 28x28x1 to__
\hookrightarrow 14x14x8
       encoded_input,indices2 = self.encoder_conv2(encoded_input) #14x14x8 to_{\square}
\rightarrow 7x7x16
       encoded_input,indices3 = self.encoder_conv3(encoded_input) #7x7x16 to__
\rightarrow 3x3x16
       reconstructed_input
                                = self.
ounpool(encoded_input,indices3,output_size=torch.Size([batch_size, 16, 7, □
\circlearrowleft7])) #3x3x16 to 7x7x16
      reconstructed input = self.decoder_conv1(reconstructed_input)__
\Rightarrow#7x7x16 to 7x7x16
      reconstructed_input = self.unpool(reconstructed_input,indices2)_u
\Rightarrow#7x7x16 to 14x14x16
      reconstructed_input
                               = self.
→decoder_conv2(reconstructed_input)#14x14x16 to 14x14x8
       reconstructed input
                               = self.
→unpool(reconstructed_input,indices1)#14x14x8 to 28x28x8
       reconstructed_input
                                = self.
odecoder_conv3(reconstructed_input)#28x28x8 to 28x28x1
```

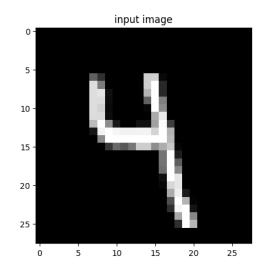
return reconstructed_input,encoded_input

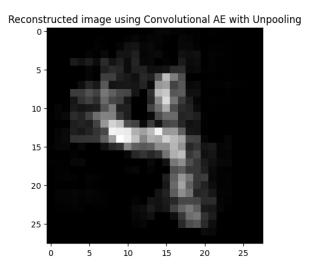
```
[43]: from torchsummary import summary
      print(conv_AE_with_unpooling().to(device))
     conv_AE_with_unpooling(
       (encoder conv1): Sequential(
         (0): Conv2d(1, 8, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU()
         (2): MaxPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil_mode=False)
       )
       (encoder_conv2): Sequential(
         (0): Conv2d(8, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU()
         (2): MaxPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil_mode=False)
       )
       (encoder_conv3): Sequential(
         (0): Conv2d(16, 16, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU()
         (2): MaxPool2d(kernel size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil mode=False)
       )
       (decoder_conv1): Sequential(
         (0): Identity()
       (decoder_conv2): Sequential(
         (0): Conv2d(16, 8, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU()
       (decoder_conv3): Sequential(
         (0): Conv2d(8, 1, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU()
       )
       (unpool): MaxUnpool2d(kernel_size=(2, 2), stride=(2, 2), padding=(0, 0))
[45]: model_Q5_a = conv_AE_with_unpooling().to(device)
      optimizer = torch.optim.Adam(model_Q5_a.parameters(), lr=learning_rate)
      train_losses_AE_Q5_a , test_losses_AE_Q5_a =_
       strain_test(model_Q5_a,device,train_loader,test_loader,optimizer,lossfn,q5_flag+True)
      plot_losses(train_losses_AE_Q5_a, test_losses_AE_Q5_a, model_name =__

¬"Convolutional AE with Unpooling")
```





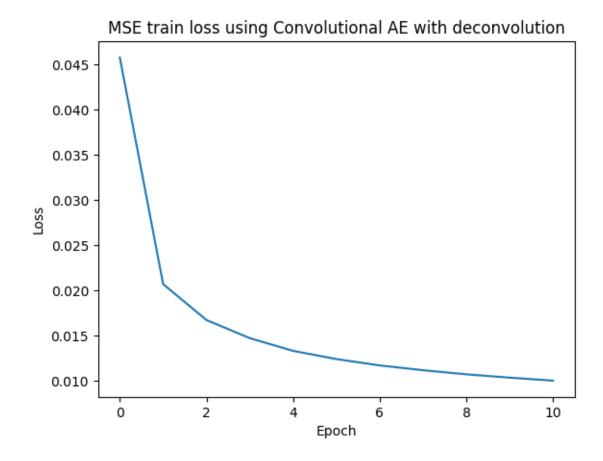


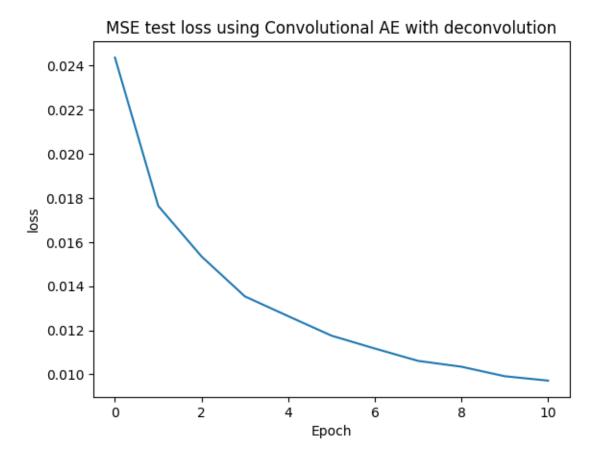


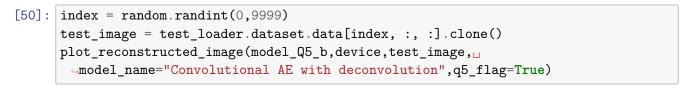
```
[47]: class conv_AE_with_deconv(nn.Module):
          def __init__(self):
              super(conv_AE_with_deconv,self).__init__()
              #encoder
              self.encoder_conv1 = nn.Sequential(
                  nn.Conv2d(1,8, kernel_size = 3, stride = 1,padding= 1),
                  nn.ReLU(),
                  nn.MaxPool2d(kernel_size = (2,2))
              )
              self.encoder conv2 = nn.Sequential(
                  nn.Conv2d(8,16, kernel_size = 3, stride = 1,padding= 1),
                  nn.ReLU(),
                  nn.MaxPool2d(kernel_size = (2,2))
              )
              self.encoder_conv3 = nn.Sequential(
                  nn.Conv2d(16,16, kernel_size = 3, stride = 1,padding= 1),
                  nn.ReLU(),
                  nn.MaxPool2d(kernel_size = (2,2))
              )
              #decoder module
              self.decoder conv1 = nn.Sequential(
                  nn.ConvTranspose2d(16,16, kernel_size = 3, stride = 2),
                  nn.ReLU()
              self.decoder_conv2 = nn.Sequential(
                  nn.ConvTranspose2d(16,8, kernel_size = 4, stride = 2, padding = 1),
                  nn.ReLU()
              )
              self.decoder_conv3 = nn.Sequential(
                  nn.ConvTranspose2d(8,1, kernel_size = 4, stride = 2, padding = 1),
                  nn.ReLU()
              )
          def forward(self,x):
              encoded input = self.encoder conv1(x.float())
              encoded_input = self.encoder_conv2(encoded_input)
              encoded_input = self.encoder_conv3(encoded_input)
              reconstructed_input = self.decoder_conv1(encoded_input)
              reconstructed_input = self.decoder_conv2(reconstructed_input)
              reconstructed_input = self.decoder_conv3(reconstructed_input)
              return reconstructed_input,encoded_input
```

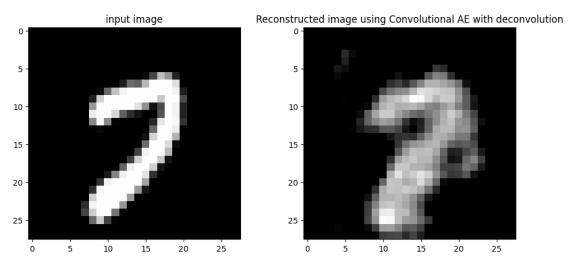
```
[48]: print(conv_AE_with_deconv().to(device))
     conv_AE_with_deconv(
       (encoder_conv1): Sequential(
         (0): Conv2d(1, 8, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU()
         (2): MaxPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil_mode=False)
       (encoder_conv2): Sequential(
         (0): Conv2d(8, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU()
         (2): MaxPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil_mode=False)
       (encoder_conv3): Sequential(
         (0): Conv2d(16, 16, kernel size=(3, 3), stride=(1, 1), padding=(1, 1))
         (2): MaxPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil_mode=False)
       (decoder_conv1): Sequential(
         (0): ConvTranspose2d(16, 16, kernel_size=(3, 3), stride=(2, 2))
         (1): ReLU()
       (decoder_conv2): Sequential(
         (0): ConvTranspose2d(16, 8, kernel_size=(4, 4), stride=(2, 2), padding=(1,
     1))
         (1): ReLU()
       )
       (decoder conv3): Sequential(
         (0): ConvTranspose2d(8, 1, kernel size=(4, 4), stride=(2, 2), padding=(1,
     1))
         (1): ReLU()
       )
     )
[49]: model_Q5_b = conv_AE_with_deconv().to(device)
      optimizer = torch.optim.Adam(model_Q5_b.parameters(), lr=learning_rate)
      train_losses_AE_Q5_b , test_losses_AE_Q5_b =
       -train_test(model_Q5_b,device,train_loader,test_loader,optimizer,lossfn,q5_flag+True)
      plot_losses(train_losses_AE_Q5_b, test_losses_AE_Q5_b, model_name =_

→ "Convolutional AE with deconvolution")
```





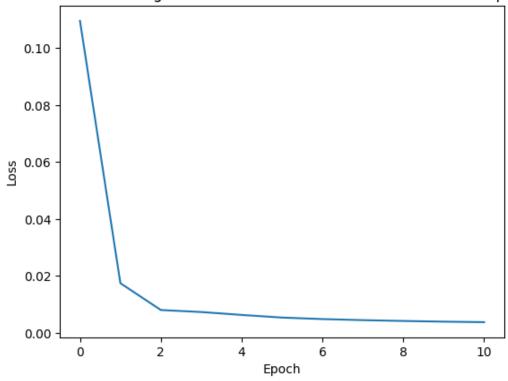




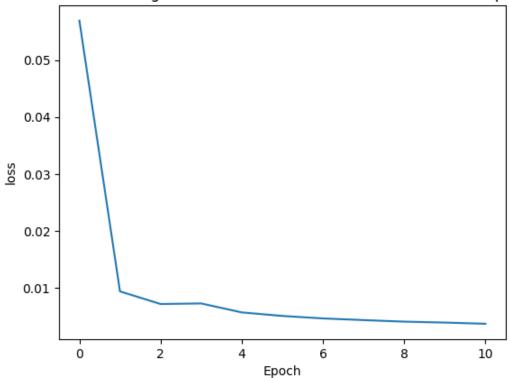
```
[51]: class conv_AE_with_deconv_unpool(nn.Module):
          def __init__(self):
              super(conv_AE_with_deconv_unpool,self).__init__()
               #encoder
              self.encoder_conv1 = nn.Sequential(
                  nn.Conv2d(1,8, kernel_size = 3, stride = 1,padding= 1),
                  nn.ReLU(),
                  nn.MaxPool2d(kernel_size = (2,2),return_indices = True)
              )
              self.encoder conv2 = nn.Sequential(
                  nn.Conv2d(8,16, kernel_size = 3, stride = 1,padding= 1),
                  nn.ReLU(),
                  nn.MaxPool2d(kernel_size = (2,2),return_indices = True)
              self.encoder_conv3 = nn.Sequential(
                  nn.Conv2d(16,16, kernel_size = 3, stride = 1,padding= 1),
                  nn.ReLU(),nn.MaxPool2d(kernel_size = (2,2),return_indices = True)
              )
              #initializing the decoder module
              self.decoder_conv1 = nn.Sequential(
                  nn.ConvTranspose2d(16,16, kernel size = 3, stride = 1, padding = 1),
                  nn.ReLU()
              )
              self.decoder conv2 = nn.Sequential(
                  nn.ConvTranspose2d(16,8, kernel_size = 3, stride = 1, padding = 1),
                  nn.ReLU()
              self.decoder_conv3 = nn.Sequential(
                  nn.ConvTranspose2d(8,1, kernel_size = 3, stride = 1, padding = 1),
                  nn.ReLU()
              )
              #unpooling
              self.unpool = nn.MaxUnpool2d(kernel_size = (2,2))
          def forward(self,x): #defines the forward pass and also the structure of |
       → the network thus helping backprop
              encoded_input,indices1 = self.encoder_conv1(x.float())
              encoded_input,indices2 = self.encoder_conv2(encoded_input)
              encoded_input,indices3 = self.encoder_conv3(encoded_input)
              reconstructed_input = self.
       unpool(encoded_input,indices3,output_size=torch.Size([batch_size, 16, 7, 7]))
```

```
reconstructed_input = self.decoder_conv1(reconstructed_input)
              reconstructed_input = self.unpool(reconstructed_input,indices2)
              reconstructed_input = self.decoder_conv2(reconstructed_input)
              reconstructed_input = self.unpool(reconstructed_input,indices1)
              reconstructed_input = self.decoder_conv3(reconstructed_input)
              return reconstructed_input,encoded_input
[52]: from torchsummary import summary
      print(conv_AE_with_deconv_unpool().to(device))
     conv_AE_with_deconv_unpool(
       (encoder_conv1): Sequential(
         (0): Conv2d(1, 8, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (2): MaxPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil_mode=False)
       (encoder_conv2): Sequential(
         (0): Conv2d(8, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (2): MaxPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil mode=False)
       (encoder conv3): Sequential(
         (0): Conv2d(16, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
         (1): ReLU()
         (2): MaxPool2d(kernel_size=(2, 2), stride=(2, 2), padding=0, dilation=1,
     ceil_mode=False)
       )
       (decoder_conv1): Sequential(
         (0): ConvTranspose2d(16, 16, kernel_size=(3, 3), stride=(1, 1), padding=(1,
     1))
         (1): ReLU()
       (decoder conv2): Sequential(
         (0): ConvTranspose2d(16, 8, kernel_size=(3, 3), stride=(1, 1), padding=(1,
     1))
         (1): ReLU()
       (decoder conv3): Sequential(
         (0): ConvTranspose2d(8, 1, kernel_size=(3, 3), stride=(1, 1), padding=(1,
     1))
         (1): ReLU()
       )
       (unpool): MaxUnpool2d(kernel_size=(2, 2), stride=(2, 2), padding=(0, 0))
```

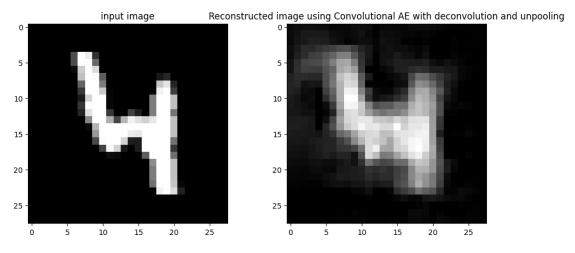
MSE train loss using Convolutional AE with deconvolution and unpooling



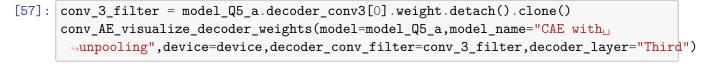
MSE test loss using Convolutional AE with deconvolution and unpooling



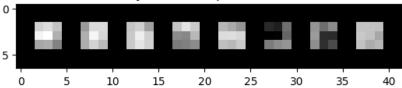




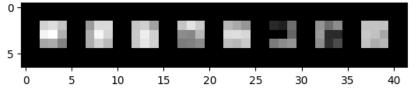
```
[55]: from torchvision.utils import make_grid
[56]: def__
       Gonv_AE_visualize_decoder_weights(model,model_name,device,decoder_conv_filter,decoder_layer
          if(device == torch.device('cuda')):
              decoder_conv_filter = decoder_conv_filter.cpu()
          #normalize the filter weights
          decoder_conv_filter -= decoder_conv_filter.min()
          decoder_conv_filter /= decoder_conv_filter.max()
          (x,y,z,w) = decoder_conv_filter.size()
          filt_ind = np.random.randint(0 ,decoder_conv_filter.size()[0],3)
          for ind in filt ind:
              image = make_grid(decoder_conv_filter[ind].reshape(y,1,z,w))
              image = image.permute(1,2,0)
              plt.imshow(image)
              plt.title("Decoder "+str(decoder_layer)+" Convolutional layer filter_
       →outputs for filter no. "+str(ind)+" of "+str(model_name))
              plt.show()
```



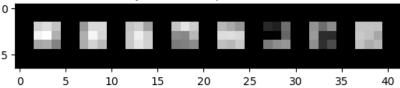
Decoder Third Convolutional layer filter outputs for filter no. 0 of CAE with unpooling



Decoder Third Convolutional layer filter outputs for filter no. 0 of CAE with unpooling

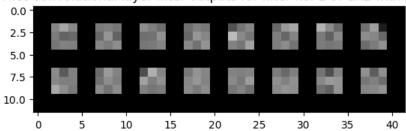


Decoder Third Convolutional layer filter outputs for filter no. 0 of CAE with unpooling

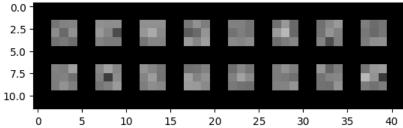


```
[58]: conv_1_filter = model_Q5_b.decoder_conv1[0].weight.detach().clone()
conv_AE_visualize_decoder_weights(model=model_Q5_b,model_name="CAE with_
deconvolution",device=device,decoder_conv_filter=conv_1_filter,decoder_layer="First")
```

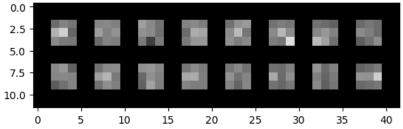
Decoder First Convolutional layer filter outputs for filter no. 1 of CAE with deconvolution



Decoder First Convolutional layer filter outputs for filter no. 7 of CAE with deconvolution

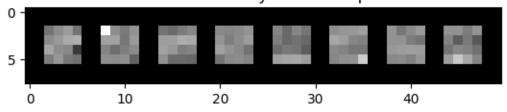


Decoder First Convolutional layer filter outputs for filter no. 13 of CAE with deconvolution

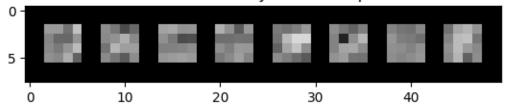


```
[65]: conv_2_filter = model_Q5_b.decoder_conv2[0].weight.detach().clone()
conv_AE_visualize_decoder_weights(model=model_Q5_b,model_name="",device=device,decoder_conv_fi
```

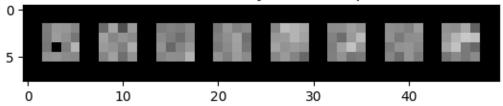
Decoder Second Convolutional layer filter outputs for filter no. 8 of



Decoder Second Convolutional layer filter outputs for filter no. 2 of

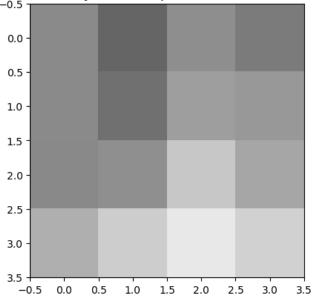


Decoder Second Convolutional layer filter outputs for filter no. 3 of

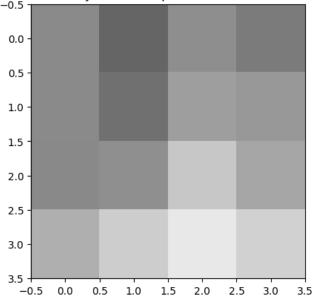


```
[66]: conv_3_filter = model_Q5_b.decoder_conv3[0].weight.detach().clone()
conv_AE_visualize_decoder_weights(model=model_Q5_b,model_name="CAE with_
deconvolution",device=device,decoder_conv_filter=conv_3_filter,decoder_layer="Third")
```

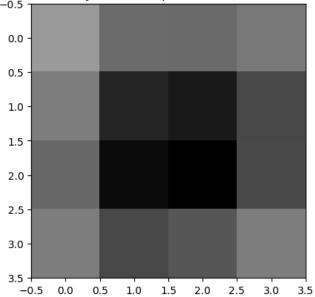
Decoder Third Convolutional layer filter outputs for filter no. 1 of CAE with deconvolution



Decoder Third Convolutional layer filter outputs for filter no. 1 of CAE with deconvolution



Decoder Third Convolutional layer filter outputs for filter no. 7 of CAE with deconvolution



[]: