

# DISCONTINUOUS ODES

DAVID LI

## 1. A DISCONTINUOUS DIFFERENTIAL EQUATION

Before jumping right into SDEs, we consider a way to numerically evaluate the differential equation,

$$x(t + dt) = \begin{cases} x(t) + dt & |x(t)| < 1 \\ 0 & |x(t)| = 1, \end{cases} \quad (1)$$

with initial condition  $x(0) = x_0 \in [0, 1]$ . A solution to this differential equation is

$$x(t) = t + x_0 \pmod{1}.$$

*Proof.* Let  $t + x_0 \pmod{1} \neq 0$ , then  $dx = dt$ . Let  $t + x_0 \pmod{1} = 0$ , then there exists  $\delta t > 0$  such that

$$|x(t + \delta t)| < \epsilon,$$

for all  $\epsilon > 0$ , therefore  $t + x_0 \pmod{1}$  is a solution (in the limit).  $\square$

## 2. ADAPTIVE TIMESTEPS

A numerical approach with default timestep  $h > 0$  to (1) could be achieved by Euler's method,

$$x_{k+1} = \begin{cases} x_k + h & |x_k + h| < 1 \\ 0 & |x_k + h| \geq 1, \end{cases} \quad (2)$$

where  $t_k = \sum_{i=1}^k \delta t_i$  and  $\delta t_k > 0$  is an adaptive timestep  $\delta t_{k+1} = \min(h, 1 - x_k)$ . By using an adaptive timestep, the solution attempts to correct itself at the boundaries. Then,  $x_k = x(t_k)$  for all  $k$ .

*Proof.* Assume that  $x_i = x(t_i)$  for some arbitrary  $i \in \mathbb{N}$ . Then by definition of (2),

$$x_{i+1} = \begin{cases} x_i + h & |x_i + h| < 1 \\ 0 & |x_i + h| \geq 1. \end{cases}$$

If  $x_i + h < 1$ , then

$$x_{i+1} = x(t_i) + h = (t_i + x_0) \pmod{1} + h < 1.$$

Using the fact that  $h = \delta t_{i+1}$ ,

$$\begin{aligned} x_{i+1} &= t_i + x_0 + h \pmod{1} \\ &= t_i + x_0 + \delta t_{i+1} \pmod{1} \\ &= t_{i+1} + x_0 \pmod{1} \\ &= x(t_{i+1}). \end{aligned}$$

If  $x_i + h \geq 1$ , then  $x_{i+1} = 0$ . Since

$$x(t_i + \delta t_{i+1}) = t_i + \delta t_{i+1} + x_0 \pmod{1} = x_i + 1 - x_i \pmod{1} = 0,$$

then  $x(t_{i+1}) = x_{i+1}$ , completing the proof by induction.  $\square$