CS395T Graphical Models: Scribe Notes

Nevzat Onur Domaniç onur@cs.utexas.edu

October 29, 2012

1 Properties of $A(\theta)$

Consider the distribution p_{θ} for some $\theta \in \Omega$. Remember $\mu = \mathbb{E}_{p_{\theta}} [\phi(X)] = \nabla A(\theta)$.

I. $\nabla A : \Omega \to \mathcal{M}$ is one-to-one iff the exponential family is minimal.

Proof. If the exponential family is not minimal then $\exists \theta_1, \theta_2$ such that $p_{\theta_1} = p_{\theta_2}$ and $\theta_1 \neq \theta_2$. Then $\nabla A(\theta_1) = \nabla A(\theta_2)$ hence ∇A is not one-to-one.

If the exponential family is minimal then A is strictly convex, $\nabla^2 A(\theta) \succ 0$, so ∇A is one-to-one.

II. $\forall \mu \in Int(\mathcal{M}), \exists \theta(\mu) \in \Omega \text{ such that } \mathbb{E}_{p_{\theta(\mu)}} [\phi(x)] = \mu, \text{ in other words } \nabla A(\theta(\mu)) = \mu, \text{ so } \nabla A \text{ is onto } Int(\mathcal{M}).$

2 Fenchel-Conjugate of A

For $\mu \in \mathbb{R}^d$ the Fenchel-Conjugate function of A is defined as:

$$A^*(\mu) := \sup_{\theta \in \Omega} \{ \langle \theta, \mu \rangle - A(\theta) \}$$

Theorem 1.

- (I) $\forall \mu \in Int(\mathcal{M}), A^*(\mu) = -H(p_{\theta(\mu)})$ (negative entropy)
- (II) $\forall \mu \notin Cl(\mathcal{M}), A^*(\mu) = +\infty$
- (III) $\forall \mu \in \partial \mathcal{M}$, there exists a sequence $\{\mu_n\} \subset Int(\mathcal{M})$ converging to m, and $A^*(\mu) = \lim_{n \to \infty} A^*(\mu_n)$

Proof. We prove property (I). Since $\mu \in Int(\mathcal{M})$, $\exists \theta(\mu) \in \Omega$ such that $\nabla A(\theta(\mu)) = \mu$. Remember the definition of A^* :

$$A^*(\mu) = \sup_{\theta \in \Omega} \left\{ \langle \theta, \mu \rangle - A(\theta) \right\}$$

The θ that achieves the supremum is $\theta(\mu)$, so $A^*(\mu) = \langle \theta(\mu), \mu \rangle - A(\theta(\mu))$. From the definition of the entropy:

$$-H(p_{\theta}) = \mathbb{E}_{p_{\theta}} [\log p_{\theta}(x)]$$

$$= \mathbb{E}_{p_{\theta}} [\langle \theta, \phi(x) \rangle - A(\theta)]$$

$$= \langle \theta, \mu(\theta) \rangle - A(\theta)$$

so
$$-H(p_{\theta(\mu)}) = \langle \theta(\mu), \mu \rangle - A(\theta(\mu)) = A^*(\mu).$$

3 Variational Principle

Theorem 2.

$$A(\theta) = \sup_{\mu \in \mathcal{M}} \left\{ \langle \theta, \mu \rangle - A^*(\mu) \right\}$$

In other words, $A(\theta) = A^{**}(\theta)$, i.e., A is the Fenchel-Conjugate of A^* .

Note that this is a convex optimization problem since both $\langle \theta, \mu \rangle$ and the negative entropy is convex. However specifying the objective function and the convex set takes exponential time.

So in Graphical Model Inference we

- (a) Approximate \mathcal{M}
- (b) Approximate entropy $-A^*(\mu)$

How to compute $A^*(\mu)$:

- (i) Obtain $\theta(\mu)$ such that $\nabla A(\theta(\mu)) = \mu$.
- (ii) Compute $-H(p_{\theta(\mu)})$

Let's look at an example:

3.1 Example: Bernoulli Distribution

Recall $p(x;\theta) = \exp\{x\theta - \log(1 + \exp(\theta))\}\$ for $x \in \{0,1\}$.

Let's check if $A^*(\mu) = \mu \log \mu + (1 - \mu) \log(1 - \mu)$. From the definition of the Fenchel-Conjugate we have:

$$A^*(\mu) = \sup_{\theta} \left\{ \theta \mu - \log(1 + \exp(\theta)) \right\}$$

Taking derivative w.r.t. θ and setting it to zero:

$$\mu = \frac{\exp \theta}{1 + \exp \theta} \implies \exp \theta = \frac{\mu}{1 - \mu} \implies \theta = \log \frac{\mu}{1 - \mu}$$

SO

$$A^*(\mu) = \theta \mu - \log(1 + \exp(\theta(\mu)))$$

= $\mu \log \frac{\mu}{1 - \mu} + \log(1 - \mu)$
= $\mu \log \mu + (1 - \mu) \log(1 - \mu)$

Now let's verify $A(\theta)$. We have:

$$A(\theta) = \sup_{\mu} \{ \theta \mu - \mu \log \mu - (1 - \mu) \log (1 - \mu) \}$$
 (1)

Taking derivative w.r.t. μ and setting it to zero:

$$\theta = \log \mu + 1 - 1 - \log(1 - \mu) = \log \frac{\mu}{1 - \mu} \implies \mu = \frac{\exp \theta}{1 + \exp \theta}$$

Substituting μ in equation (1) gives $A(\theta) = \log(1 + \exp \theta)$.

3.1.1 Approximating Polytope in Discrete Models

 $X = (X_1, \dots, X_p)$ where $X_s \in \mathcal{X} = \{0, \dots, r-1\}$. We have:

$$p_{\theta}(X) = \exp \left\{ \sum_{s,j} \mathbb{1}_{s,j}(X)\theta_{sj} + \sum_{\substack{(s,t) \in E \\ j,k}} \mathbb{1}_{st,jk}(X)\theta_{st,jk} - A(\theta) \right\}$$

We introduce the following shorthand notations:

$$\theta_s(X_s) = \sum_j \mathbb{1}_{s,j}(X_s)\theta_{s,j}$$

$$\theta_{st}(X_s, X_t) = \sum_{j,k} \mathbb{1}_{st,jk}(X_s, X_t)\theta_{st,jk}$$

so
$$p_{\theta}(X)$$
 becomes $= \exp \left\{ \sum_{s} \theta_{s}(X_{s}) + \sum_{(s,t) \in E} \theta_{st}(X_{s}, X_{t}) - A(\theta) \right\}$.
Let's have
$$\phi_{s}(X_{s}) = \sum_{j \in \mathcal{X}} \mathbbm{1}(X_{s} = j) \phi_{s}(j)$$
and
$$\phi_{st}(X_{s}, X_{t}) = \sum_{j,k \in \mathcal{X}} \mathbbm{1}(X_{s} = j, X_{t} = k) \phi_{st}(j, k)$$

so any sufficient statistics over discrete random variables can be expressed as a linear combination of indicator functions, thus the overcomplete representation is general.

Now let's look at the mean parameters. Remember that the Marginal Polytope $\mathbb{M}(G)$ is defined as:

$$\mathbb{M}(G) = \{ \mu : \exists p, \mu = \mathbb{E}_p \left[\phi(x) \right] \}$$

The mean parameters are:

$$\mu_{s,j} = \mathbb{E} \left[\mathbb{1}_{s,j}(X_s) \right] = \mathbb{P}(X_s = j)$$

$$\mu_{st,ik} = \mathbb{E} \left[\mathbb{1}_{st,ik}(X_s, X_t) \right] = \mathbb{P}(X_s = j, X_t = k)$$

So we define:

$$\mu_s(X_s) = \sum_{j} \mathbb{1}_{s,j}(X_s) \mu_{s,j}$$

$$\mu_{st}(X_s, X_t) = \sum_{jk} \mathbb{1}_{st,jk}(X_s, X_t) \mu_{st,jk}$$

Then the Marginal Polytope is:

$$\mathbb{M}(G) = \left\{ \mu_s(X_s), \mu_{st}(X_s, X_t) : \begin{array}{l} \text{node-wise and pair-wise} \\ \text{marginals of some distribution } p \end{array} \right\}$$

Note that we have the following set of constraints:

 $\mu_{s,j} \in [0,1]$ $\mu_s(X_s) \in [0,1]$ $\mu_{st}(X_s, X_t) \in [0,1]$

• Normalization Constraints

$$\sum_{X_s} \mu_s(X_s) = 1$$

$$\sum_{X_s, X_t} \mu_{st}(X_s, X_t) = 1$$

• Marginalization Constraints

$$\sum_{X_t} \mu_{st}(X_s, X_t) = \mu_s(X_s)$$
$$\sum_{X_s} \mu_{st}(X_s, X_t) = \mu_t(X_t)$$

These are called the "local" constraints and the number of constraints is $\mathcal{O}\left(|V|+|E|\right)$.

We define:

$$\mathbb{L}(G) = \left\{ \begin{array}{l} T_s(X_s) \\ T_{st}(X_s, X_t) \end{array} : T_s, T_{st} \text{ satisfy "local" constraints} \right\}$$

where T_s and T_{st} are called the pseudo-marginals.