

**Indian Institute of Technology, Kanpur.**

**Even semester, 2020 - 2021.**

**AE 630 Autonomous Unmanned Aerial Systems**

**Assignment 3**

**(Deadline - April 12<sup>th</sup>)**

**Answer all questions**

**Marks - 90**

1. Derive the flight dynamics model of a VTOL vehicle following the steps given.
  - (a) Derive the rigid-body dynamics. **(10 marks)**
  - (b) Derive the rotor aerodynamics (forces and moments). **(5 marks)**
  - (c) Derive the wing aerodynamics (forces and moments). **(5 marks)**
  - (d) Express all forces and moments in the body frame. **(5 marks)****(25marks)**
  
2. How do you define stability? Differentiate static and dynamic stability? **(8 marks)**  
Comment on the stability of the following systems. (Derive equations if required.)
  - (a)  $\dot{x} = ax$ . **(2 marks)**
  - (b)  $\dot{X} = AX$ . **(4 marks)**
  - (c) A simple pendulum. **(6 marks)**
  - (d) Pitch dynamics of fixed-wing UAV. **(10 marks)**
  - (e) Attitude dynamics of quadcopter. **(10 marks)****(40 marks)**
  
3. Find and list five kinds of VTOL vehicles based on quadcopter. Please explain their advantages and disadvantages. Also, explain their operation and control mechanisms. (Hint: Quad-plane, Bi-plane quadcopter)  
**(25 marks)**