EC3066D - ARTIFICIAL INTELLIGENCE: THEORY AND PRACTICE

COURSE PROJECT REPORT

FACE MASK DETECTION USING CNN ARCHITECTURE

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PROBLEM STATEMENT:

The COVID-19 pandemic has reshaped our life and it is important to wear face mask in public and even in home in order to prevent the spread of the virus. But the truth is not everyone is wearing the mask properly and it is still a threat to the society. Our project demonstrates how a Convolutional Neural Network (CNN) can detect if a person is wearing a face mask or not. The applications of this method may be very helpful for the prevention and the control of COVID-19 and other similar diseases that may be occur in future as it could be used in public places like airports, shopping malls etc. Detect a face and check whether a person is wearing a mask or not is a classification problem. We have to classify the images between 2 discrete classes: The ones that contain a face mask and the ones that do not.

OVERVIEW OF PROJECT WORK:

- ♣ Training Architectures with sample data
- Compare the performance of models and determining best model for facemask detection.
- ♣ Train best model for different epochs and reach out into a good final model.
- ♣ Use model trained by a large dataset collected to detect facemask by real time video streaming. (Face detection using Haar feature-based cascade classifiers)

COMPARISON OF ARCHITECTURES WITH SAMPLE DATA:

Determining a good architecture for training a model is difficult task. So we have tried lots of commonly using CNN architectures and compared different parameters by training with a sample dataset of smaller size.

Specifications of dataset used for comparison:

Train

With mask - 200 images

Without mask – 200 images

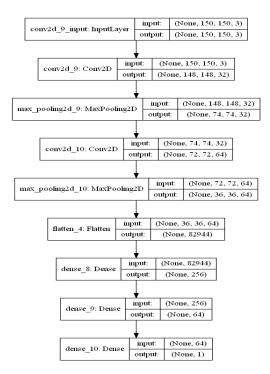
Test

With mask - 50 images

Without mask – 50 images

All photos are of different size and dimension and it is converting into fixed target size before training.

Model - 1



model1 = Sequential()
model1.add(Conv2D(32, (3, 3),
 activation='relu', input_shape=(150,
150,3)))
model1.add(MaxPooling2D())
model1.add(Conv2D(64, (3, 3),
 activation='relu'))
model1.add(MaxPooling2D())
model1.add(Flatten())
model1.add(Dense(256, activation='relu'))
model1.add(Dense(64, activation='relu'))
model1.add(Dense(1, activation='sigmoid'))

Model - 1 summary:

Layer (type)	Output	Shape	Param #
conv2d_20 (Conv2D)	(None,	148, 148, 32)	896
max_pooling2d_12 (MaxPooling	(None,	74, 74, 32)	0
conv2d_21 (Conv2D)	(None,	72, 72, 64)	18496
max_pooling2d_13 (MaxPooling	(None,	36, 36, 64)	0
flatten_4 (Flatten)	(None,	82944)	0
dense_8 (Dense)	(None,	256)	2123392
dense_9 (Dense)	(None,	64)	16448
dense_10 (Dense)	(None,	1)	65
Total params: 21,269,825 Trainable params: 21,269,825 Non-trainable params: 0			

Here we trained data by splitting data into 16 batches and with a fixed size of (150,150) and trained for 10 epochs. It is a normal sequential model. This architecture has about 21,000,000 parameters. Here the model is incrementing the number of parameters rapidly. We have tried with different activation functions and filter number and kernel sizes.

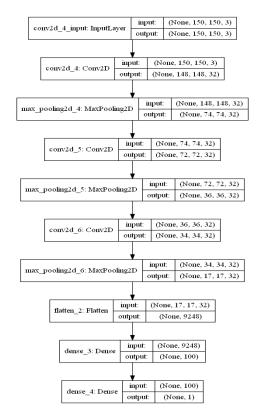
Model – 1 training details:

	400 images belonging to 2 classes.														
	100 images belonging to 2 classes.														
Epoch															
	[225	886ms/step	-	loss:	0.6084	-	accuracy:	0.7675	-	val_loss:	0.0333	-	val_accuracy:	θ.
9300															
Epoch															
25/25	[] -	145	556ms/step	-	loss:	0.1997		accuracy:	0.9375	-	val loss:	0.0445		val accuracy:	0.
9100															
Epoch															
25/25	[**************************************	14s	551ms/step		loss:	0.1528		accuracy:	0.9525		val_loss:	1.7713		val_accuracy:	0.
9300															
Epoch															
25/25	[**************************************	125	492ms/step.		loss:	0.1217		accuracy:	0.9475		val_loss:	0.5189		val_accuracy:	0.
9200															
Epoch	5/10														
25/25	[==========	125	469ms/step	-	loss:	0.0846	-	accuracy:	0.9725	-	val loss:	0.0034	-	val accuracy:	0.
9500															
Epoch															
25/25	[**************************************	125	480ms/step	-	loss:	0.0884	-	accuracy:	0.9775	-	val loss:	0.5504	-	val accuracy:	0.
9200															
Epoch															
25/25	[] -	125	472ms/step	-	loss:	0.1620	-	accuracy:	0.9400	-	val loss:	0.1350	-	val_accuracy:	0.
9600															
Epoch															
25/25	[] -	125	478ms/step		loss:	0.0885		accuracy:	0.9650	-	val_loss:	0.0010		val_accuracy:	0.
9600															
Epoch															
	[24444444444444444444444444444444444444	138	524ms/step	-	loss:	0.0740	-	accuracy:	0.9675		val_loss:	0.0066	-	val_accuracy:	0.
9800															
	10/10														
	[======================================	135	514ms/step		loss:	0.0745	-	accuracy:	0.9775		val_loss:	1.0036	-	val_accuracy:	0.
9600															

Here the values correspond to finally trained epochs are:

Loss: 0.0740, train accuracy: 0.9775, test loss: 1.0036, Test accuracy: 0.9600

Model - 2



```
model2 = Sequential()
model2.add(Conv2D(32, (3, 3),
    activation='relu', input_shape=(150,
150,3)))
model2.add(MaxPooling2D())
model2.add(Conv2D(32, (3, 3),
    activation='relu'))
model2.add(MaxPooling2D())
model2.add(Conv2D(32, (3, 3),
    activation='relu'))
model2.add(MaxPooling2D())
model2.add(MaxPooling2D())
model2.add(Flatten())
model2.add(Dense(100, activation='relu'))
model2.add(Dense(1, activation='sigmoid'))
```

Model – 2 summary:

	148, 148, 32) 74, 74, 32)	896
(None,	74 74 32)	
	/4, /4, 52)	0
(None,	72, 72, 32)	9248
(None,	36, 36, 32)	Ø
(None,	34, 34, 32)	9248
(None,	17, 17, 32)	0
(None,	9248)	0
(None,	100)	924900
(None,	1)	101
	(None, (None, (None,	(None, 36, 36, 32) (None, 34, 34, 32) (None, 17, 17, 32) (None, 9248) (None, 100) (None, 1)

Here also we trained data by splitting data into 16 batches and with a fixed size of (150,150) and trained for 10 epochs. But this model does not increment parameters rapidly as model-1. And kernel size kept remains as it is in the model -1. It is a commonly used normal architecture with relu activation at each layer and sigmoid activation at output layer. This architecture has about 945,000 parameters.

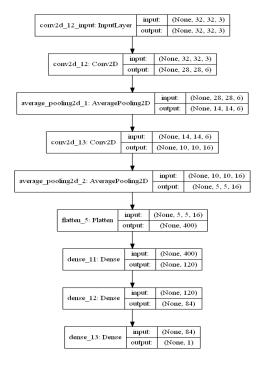
Model – 2 training details:

	400 images belonging to 2 classes.
	100 images belonging to 2 classes.
Epoch	
25/25 900	[] - 8s 339ms/step - loss: 0.5582 - accuracy: 0.7725 - val_loss: 0.1762 - val_accuracy: 0.8
Epoch	2/10
25/25 988	[
Epoch	3/10
25/25 400	[=====================================
Epoch	4/10
25/25 900	[
Epoch	5/10
25/25 100	[] - 6s 245ms/step - loss: 0.1106 - accuracy: 0.9650 - val_loss: 0.0046 - val_accuracy: 0.9
Epoch	6/10
25/25 500	[] - 7s 275ms/step - loss: 0.1475 - accuracy: 0.9400 - val_loss: 0.0075 - val_accuracy: 0.9
Epoch	7/10
25/25 500	[=======] - 6s 250ms/step - loss: 0.0052 - accuracy: 0.9650 - val_loss: 0.0112 - val_accuracy: 0.9
Epoch	8/10
25/25 200	[] - 7s 260ms/step - loss: 0.0968 - accuracy: 0.9650 - val_loss: 0.2226 - val_accuracy: 0.9
Epoch	
25/25 500	[
Epoch	10/10
25/25 688	[] - 7s 265ms/step - loss: 0.0590 - accuracy: 0.9800 - val_loss: 0.0236 - val_accuracy: 0.9

Here the values corresponds to finally trained epochs are:

Loss: 0.0590, train accuracy: 0.9800, test loss: 0.0236, Test accuracy: 0.9600

LeNET5 Model



```
model3= Sequential()
model3.add(Conv2D(6, (5,5), activation='tanh', input_shape=(32,32,3)))
model3.add(AveragePooling2D())
model3.add(Conv2D(16, (5,5), activation='tanh'))
model3.add(AveragePooling2D())
model3.add(Flatten())
model3.add(Dense(120, activation='tanh'))
model3.add(Dense(84, activation='tanh'))
model3.add(Dense(1, activation='sigmoid'))
```

LeNET5 Model summary:

Layer (type)	Output Shape	Param #
conv2d_13 (Conv2D)	(None, 28, 28, 6)	456
average_pooling2d (AveragePo	(None, 14, 14, 6)	0
conv2d_14 (Conv2D)	(None, 10, 10, 16)	2416
average_pooling2d_1 (Average	(None, 5, 5, 16)	0
flatten (Flatten)	(None, 400)	0
dense (Dense)	(None, 120)	48120
dense_1 (Dense)	(None, 84)	10164
dense_2 (Dense)	(None, 1)	85

LeNet-5 is a popular and simple architectures. Here we train the data by splitting data into 16 batchesand with a fixed size of (32, 32) and trained for 10 epochs. It has 2 convolutional and 3 fully-connected layers. In this model kernel size has changed to (5, 5) in each layer and filters. It has average-pooling layer as the subsamplinglayer. This architecture has about 60,000 parameters. It has tanh activation at each layer and sigmoid activation at output layer.

LeNET5 Model training details:

Epoch	
25/25 800	[=======] - 9s 360ms/step - loss: 0.5168 - accuracy: 0.7650 - val_loss: 0.2913 - val_accuracy: 0.8
Epoch	2/10
25/25 100	[========] - 3s 109ms/step - loss: 0.2026 - accuracy: 0.9275 - val_loss: 0.2823 - val_accuracy: 0.9
Epoch	3/10
25/25 500	[] - 3s 117ms/step - loss: 0.2264 - accuracy: 0.9350 - val_loss: 0.2292 - val_accuracy: 0.9
Epoch	4/10
25/25 00	[=======] - 2s 99ms/step - loss: 0.1569 - accuracy: 0.9425 - val_loss: 0.2229 - val_accuracy: 0.92
Epoch	5/10
25/25 00	[========] - 2s 87ms/step - loss: 0.1476 - accuracy: 0.9525 - val_loss: 0.1981 - val_accuracy: 0.95
Epoch	6/10
25/25 00	[========] - 2s 89ms/step - loss: 0.1388 - accuracy: 0.9550 - val_loss: 0.2577 - val_accuracy: 0.89
Epoch	7/10
25/25 00	[========] - 2s 91ms/step - loss: 0.1728 - accuracy: 0.9450 - val_loss: 0.2132 - val_accuracy: 0.92
Epoch	8/10
25/25 00	[=====================================
Epoch	9/10
25/25 00	[========] - 2s 91ms/step - loss: 0.1446 - accuracy: 0.9550 - val_loss: 0.1905 - val_accuracy: 0.96
Epoch	10/10
25/25	[=====================================

Here the values corresponds to finally trained epochs are:

Loss: 0.1438, train accuracy: 0.9450, test loss: 0.2087, Test accuracy: 0.9400

RESULT OF COMPARISON

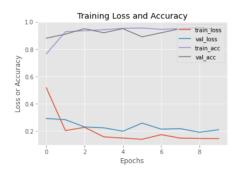
Model - 1:



Model - 2:



LeNET5 Model:

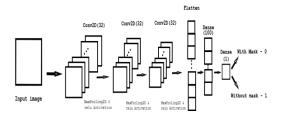


From the observations of the different architecture it is recommended to choose model 2 for training our dataset. Model 2 has more test accuracy compare to other models given here. And it is found that test accuracy with other standard models like VGG-16 and AlexNet which exhibits low for the given small datasets. Some models show more fluctuation in the values of train_loss, val_loss, train_accuracy and val_accuracy. It is good to follow a normal architecture like Model 2 to build a good trained model which has a test accuracy value of 0.9600 and low variations in Loss

or Accuracy with respect to change in epochs.

TRAING MODEL FOR MASK DETECTION

Based on the result of comparison of architecture we come up with a good model and trained it with dataset containing around 8000 images.



First objective is to train model for large number of epochs and find out the variations with respect to number of epochs. The result of the model trained with large dataset for 25 epochs:

Dataset specifications:

Data set consists of 7553 RGB images in 2 folders as with mask andwithout mask. Images are named as label with maskandwithout mask. Images of faces with mask are 3725 and images of faces without mask are 3828.

Source:

https://www.kaggle.com/omkargurav/face-mask-dataset



From the result of the above training it is obvious that at 15 to 20 epochs loss and accuracy curve became almost flat and attained minimum loss and maximum accuracy values. So we can finalize our model by training around 20 epochs with a large dataset.

Dataset specifications for the final model:

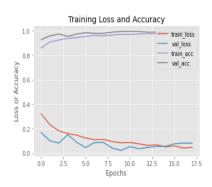
Data set consists of 7553 RGB images in 2 folders as with mask andwithout mask. Images are named as label with mask and without mask. Images of faces with mask are 3725 and images of faces without mask are 3828.

Final Model training details:

Epoch 10/18	
473/473 [======] - 2025 426ms/step - loss; 0.0037 - accuracy; 0.9710 - val_loss; 0.0028 - val_accur	acy:
0.9948	
Epoch 11/18	
473/473 [======] - 202s 427ms/step - loss; 0.0068 - accuracy; 0.9695 - val_loss; 0.0532 - val_accur	acy:
0.9948	
Epoch 12/18	
473/473 [======] - 202s 427ms/step - loss; 0.0762 - accuracy; 0.9743 - val_loss; 0.0362 - val_accur	acy:
0.9948	
Epoch 13/18	
473/473 [======] - 204s 432ms/step - loss: 0.0635 - accuracy: 0.9782 - val_loss: 0.0465 - val_accur	acy:
0.9897	
Epoch 14/18	
473/473 [======] - 204s 431ms/step - loss: 0.0678 - accuracy: 0.9768 - val_loss: 0.0548 - val_accur	acy:
0.9897	
Epoch 15/18	
473/473 [] - 204s 431ms/step - loss: 0.0509 - accuracy: 0.9824 - val_loss: 0.0555 - val_accur	acy:
0.9845	
Epoch 16/18	
473/473 [] - 205s 432ms/step - loss: 0.0594 - accuracy: 0.9809 - val_loss: 0.0760 - val_accur	acy:
0.9845	
Epoch 17/18	
473/473 [] - 204s 431ms/step - loss: 0.0413 - accuracy: 0.9844 - val_loss: 0.0818 - val_accur	acy:
0.9897	
Epoch 18/18	
473/473 [acy:
0.9897	

Values at the end of training:

Loss: 0.0468, train accuracy: 0.9829, test loss: 0.0815, Test accuracy: 0.9897.

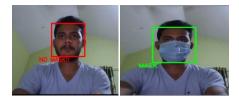


RESULT OF PROJECT

A normal CNN architecture is used for building the model and trained the model with around 8000 images. Trained model for 18 epochs and tested with real time video streaming. A good architecture is chosen by constructing different architectures and evaluating with sample dataset of smaller size. We come up with a good model to detect face mask with 98.97% test accuracy and detected faces with and without mask by real time video streaming. Also obtained a good loss percentage of 8.15% with respects to other models.







APPLICATIONS

- Face mask detector can be used along with checking temperature in public places such as supermarket, Government offices and other places where people gather that may cause to spreading of disease.
- ♣ By adding percentage that indicates proper wearing of face mask can be used to correct errors in wearing mask individually.
- ♣ This program can also be connected to the entrance gates and only people wearing face masks can come in.
- ♣ An alarm system can also be implemented to sound a beep when someone without a mask enters the area.
- ♣ Store images of the people entered the area and make dataset of people to connect them or for further researches.

[6]Paul Viola and Michael Jones in the paper, "Object Detection using Haar feature-based cascade classifiers method" in 2001

[7]https://opencv-pythontutroals.readthedocs.io/en/latest/py_tutoria ls/py_objdetect/py_face_detection/py_face_detection.html

REFERENCES:

[1]https://www.kaggle.com/datasets

[2]R. Lienhart and J. Maydt, "An extended set of haar-like features for rapid object detection," vol.1, 02 2002, pp.I–900.

[3]https://towardsdatascience.com/illustrated-10-cnn-architectures-95d78ace614d

[4]P. Viola and M. J. Jones, "Robust real-time face detection," Int. J. Comput. Vision, vol. 57, no. 2,p. 137154, May 2004. https://doi.org/10.1023/B:VISI.000001308 7.49260.fb

[5]https://towardsdatascience.com/face-detection-with-haar-cascade-727f68dafd08