



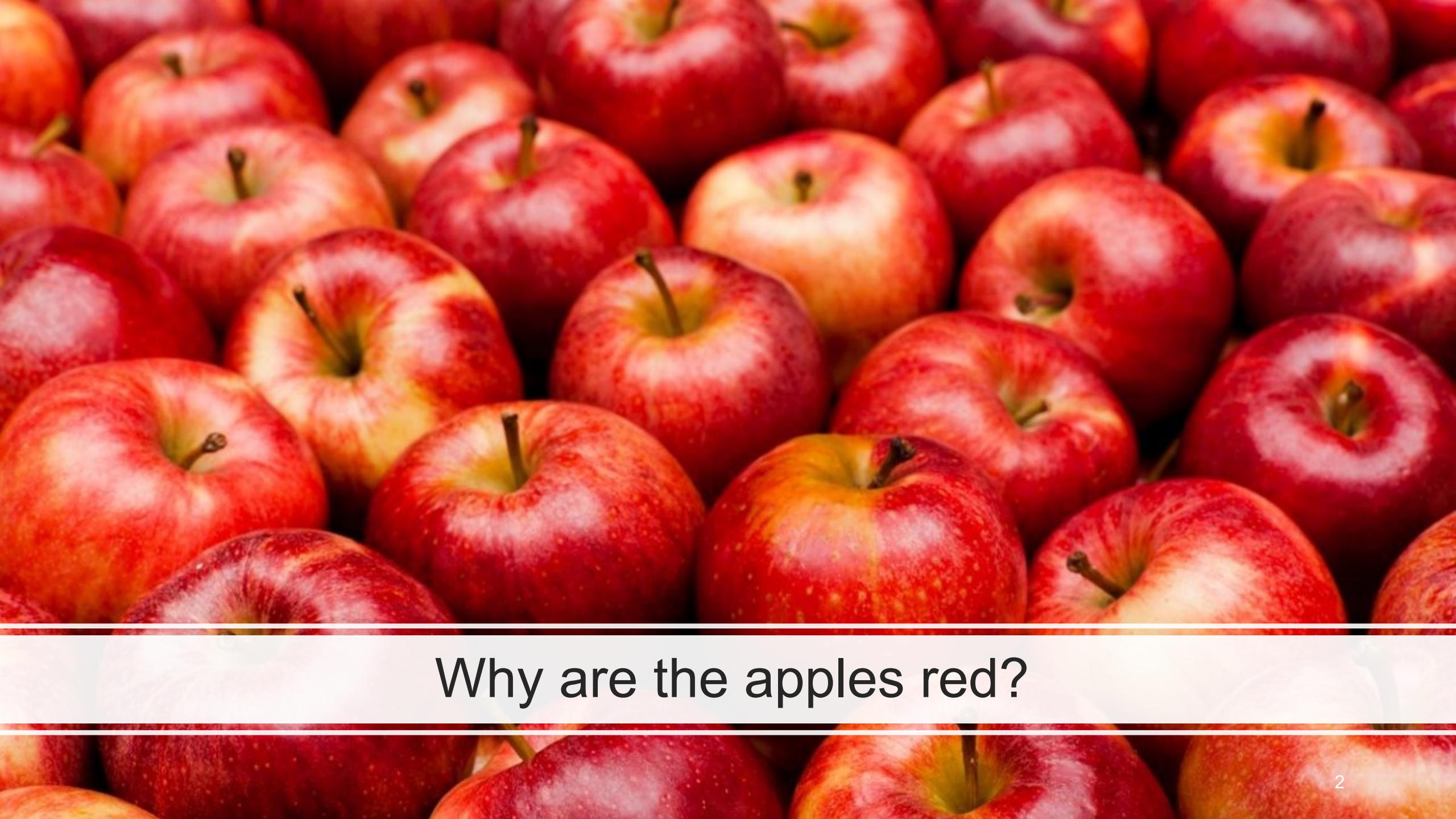
**THE UNIVERSITY OF TEXAS AT DALLAS**

# Image Formulation: Lighting and Color

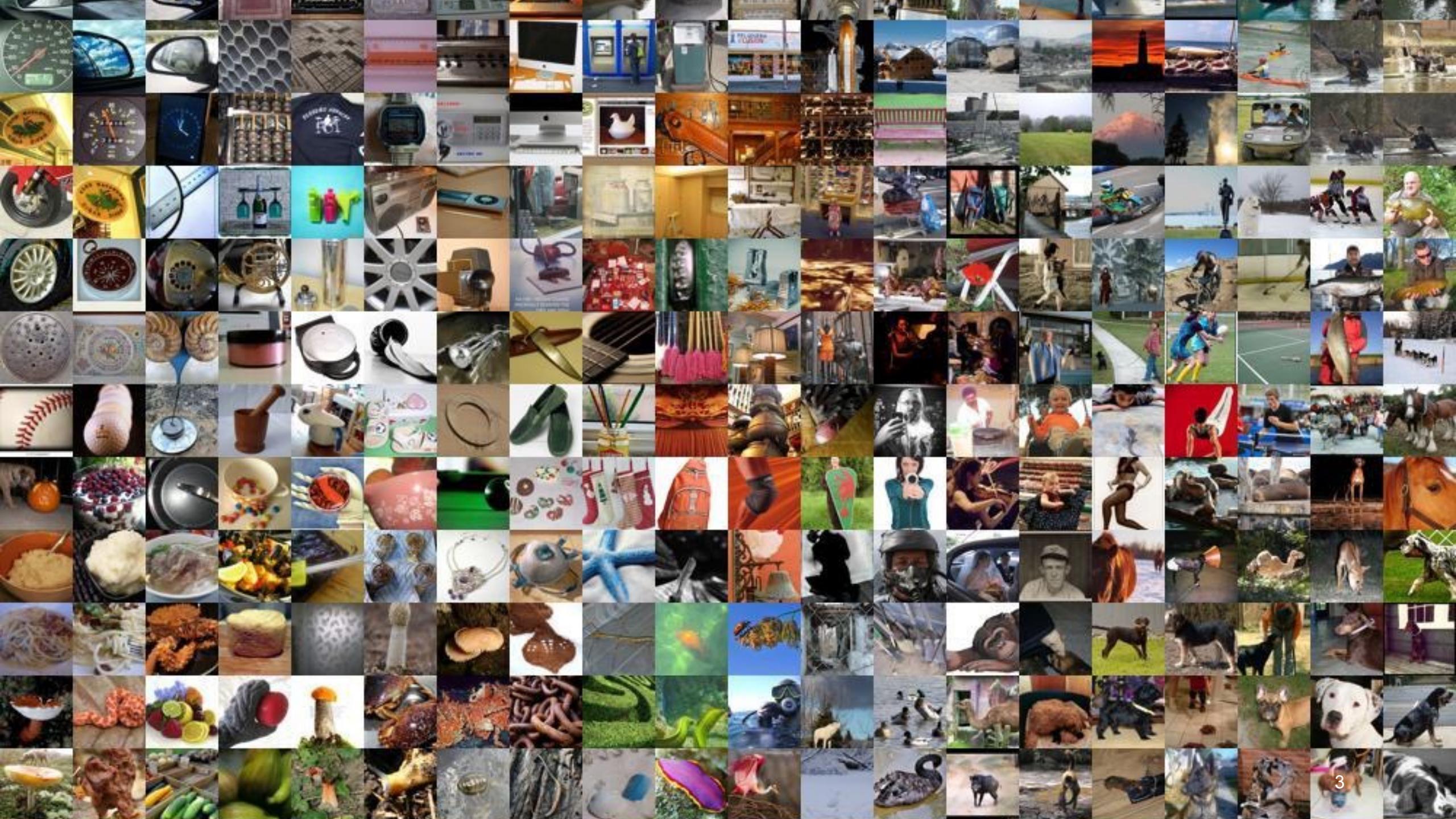
CS 6384 Computer Vision

Professor Yapeng Tian

Department of Computer Science

A close-up photograph of a large pile of ripe red apples. The apples are piled high, filling the frame. They have a vibrant red color with some yellow and green at the stems. The lighting is bright, highlighting the texture of the apple skin.

Why are the apples red?



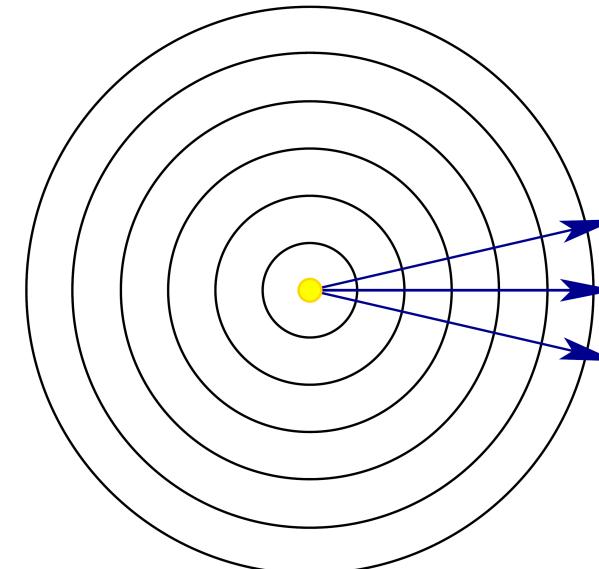
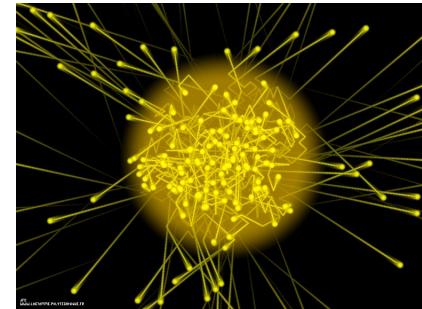
# Lighting

Images cannot exist without light. To produce an image, the scene must be illuminated with one or more light sources.

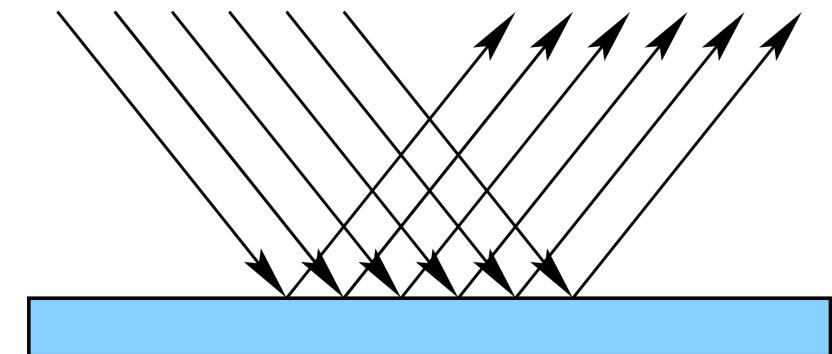
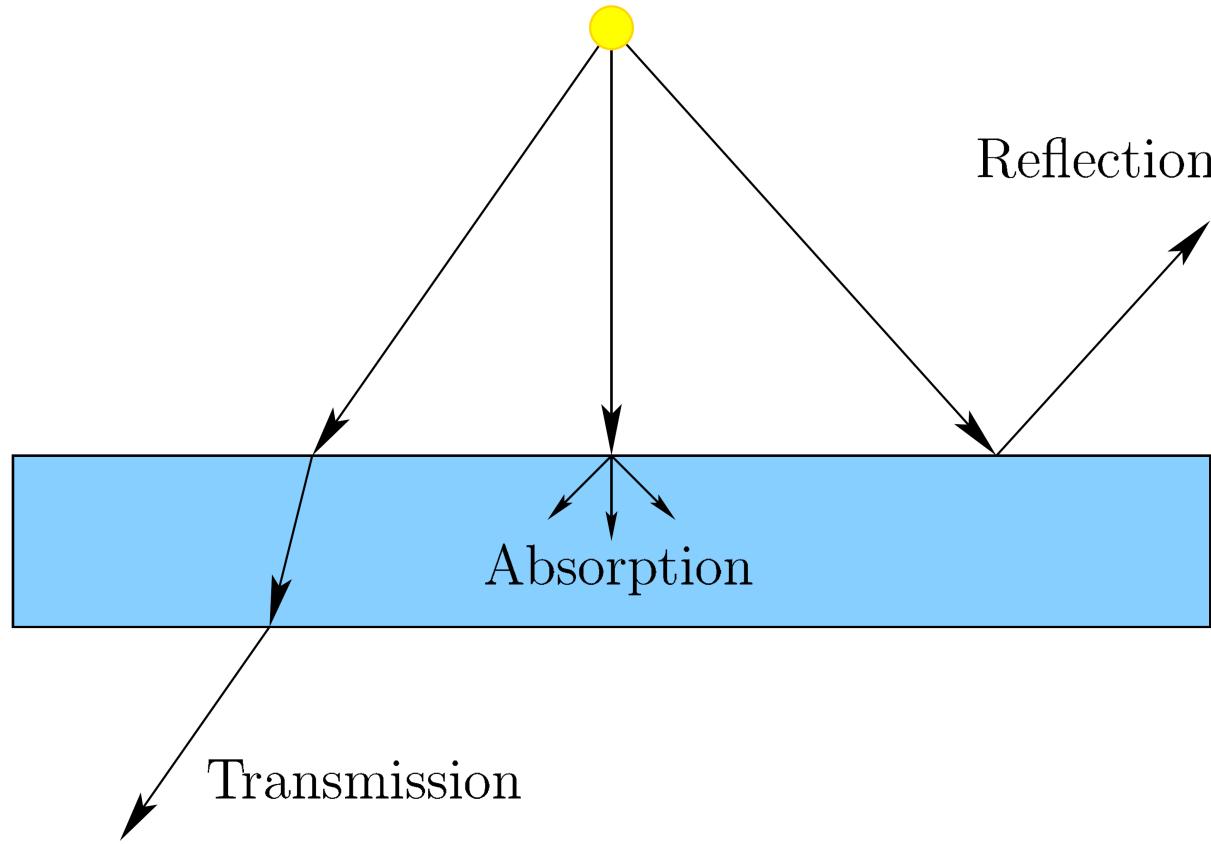
# Basic Behavior of Light

Light can be described in three ways

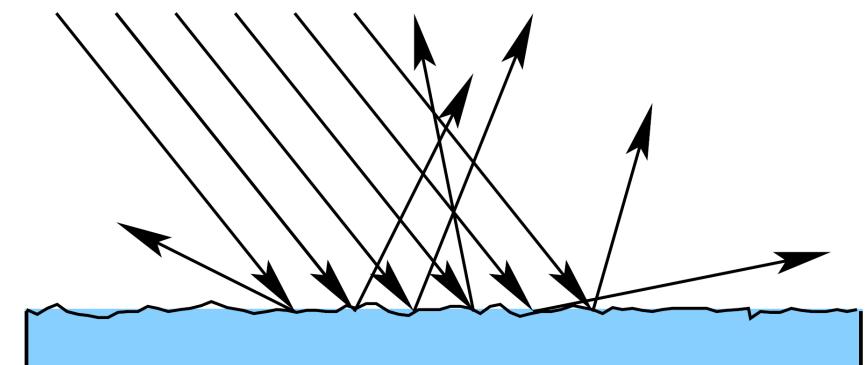
- Photons: tiny particles of energy moving through space at high speed
- Waves: ripples through space
- Rays: a ray traces the motion of a single hypothetical photon



# Interactions with Materials

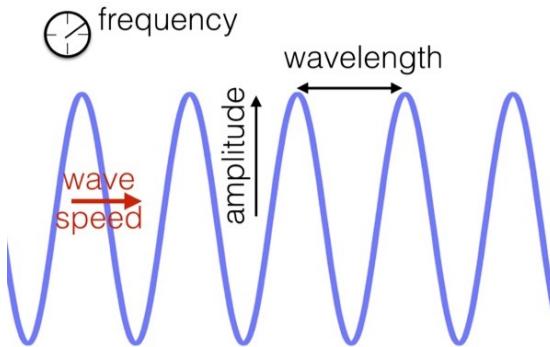


Specular



Diffuse

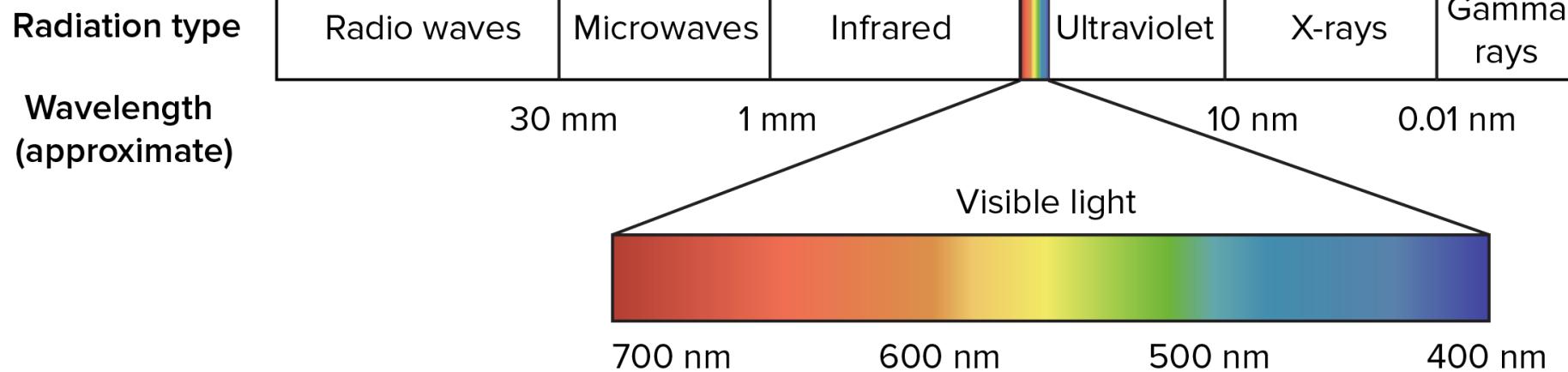
# Wavelengths and Colors



$$\text{Wavelength } \lambda = \frac{v}{f}$$

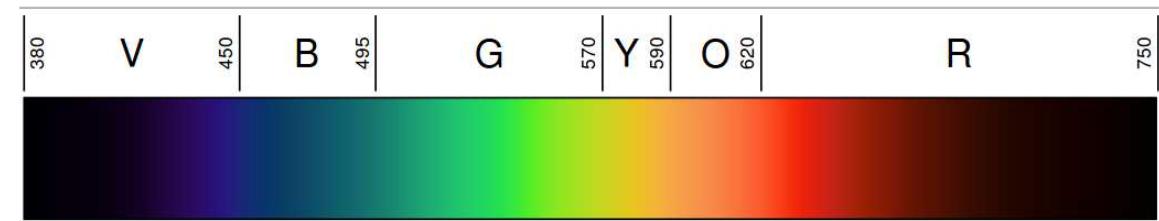
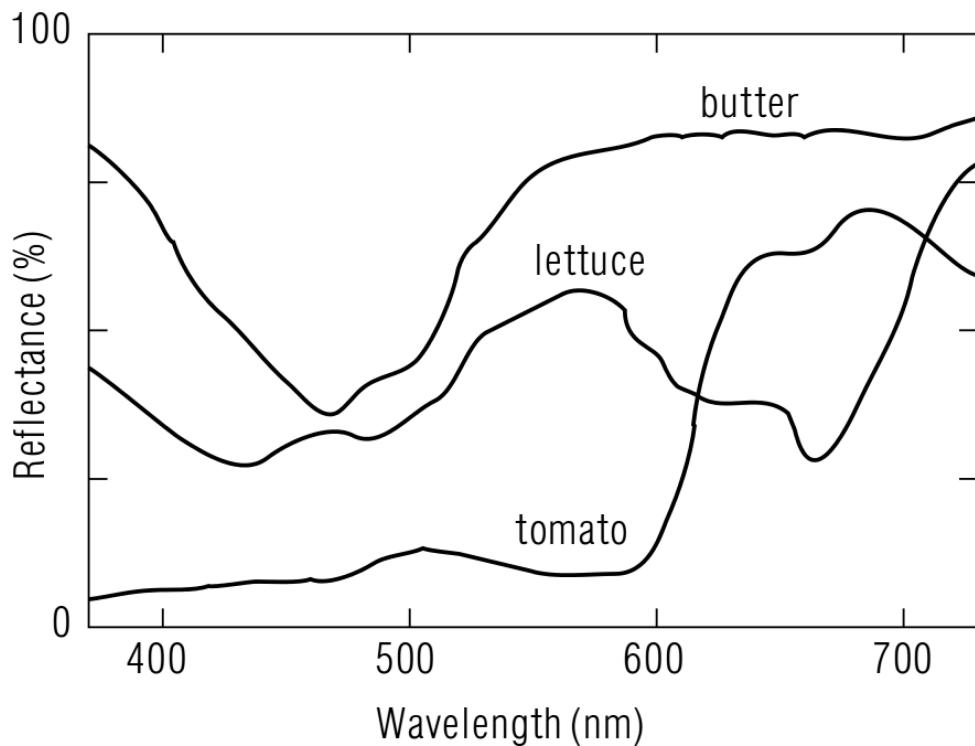
Speed  
Frequency

Electromagnetic spectrum



# Reflection of Materials

We see objects with different colors because the materials reflect specific colors differently



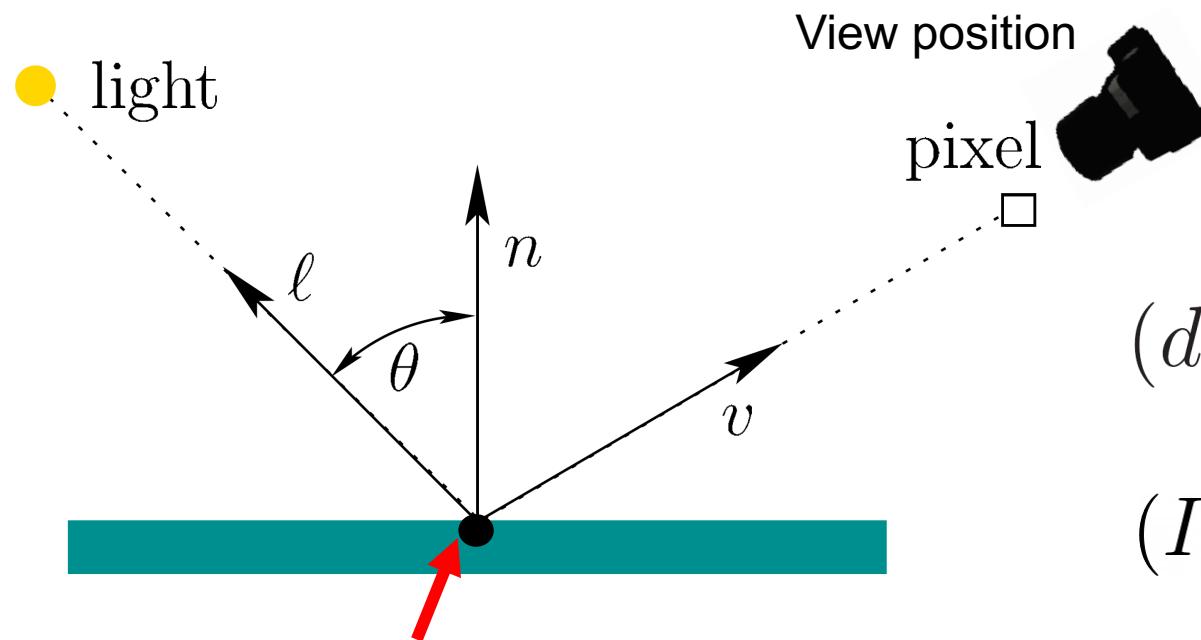
The Color of an Object Depends Upon the Light Source

# Selective Reflection



<https://www.youtube.com/watch?v=xA8MT6yhP4w>

# Lambertian Lighting



Given a 3D point, we want to compute its color on the image

$$L = dI \max(0, n \cdot \ell) \quad n \cdot \ell < 0$$

Diffuse reflection

$$R = d_R I_R \max(0, n \cdot \ell)$$

$$G = d_G I_G \max(0, n \cdot \ell)$$

$$B = d_B I_B \max(0, n \cdot \ell)$$

$$n \cdot \ell = \cos \theta$$

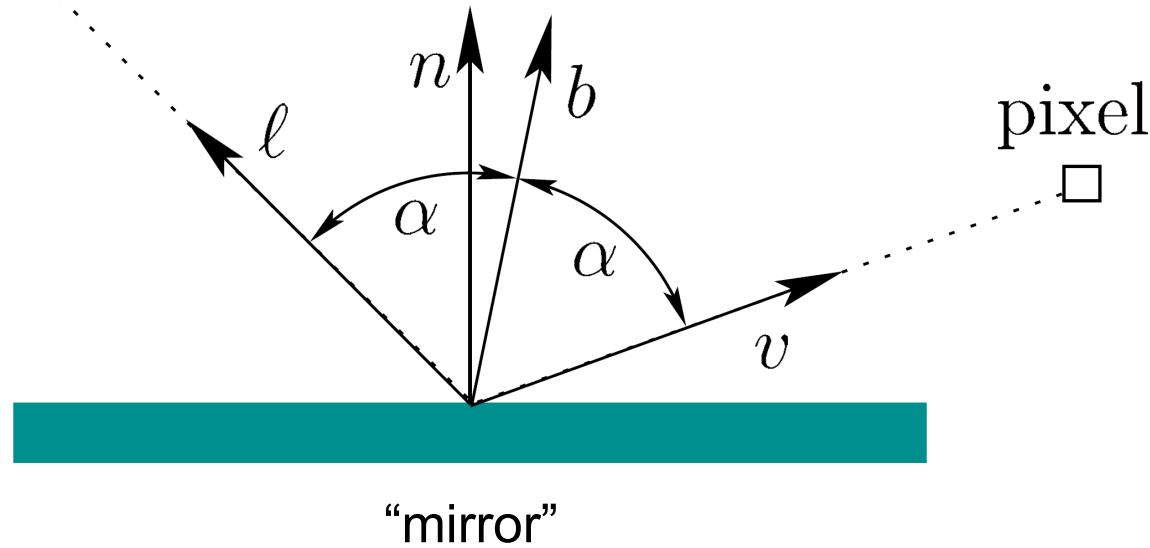
$(d_R, d_G, d_B)$  Reflectance property of the material

$(I_R, I_G, I_B)$  Spectral power distribution of the light source

Light behind surface

# Blinn-Phong Lighting

- light



Related to specular reflection

$$b = \frac{\ell + v}{\|\ell + v\|}$$

$x$  Material property that expresses the amount of surface shininess

$x=100$ , mild amount of shininess

$x=10000$ , almost like a mirror  $0.99^{10000} = 2.24^{-44}$

$s$  Specular reflectance property of the material

$$L = dI \max(0, n \cdot \ell) + sI \max(0, n \cdot b)^x$$

# Ambient Lighting

Ambient lighting provides the general illumination of an environment

Independent of light/surface position, viewer, normal

Adding some background color

$$L = dI \max(0, n \cdot \ell) + sI \max(0, n \cdot b)^x + L_a$$

Ambient light



# Multiple Light Sources and Attenuation

N light sources

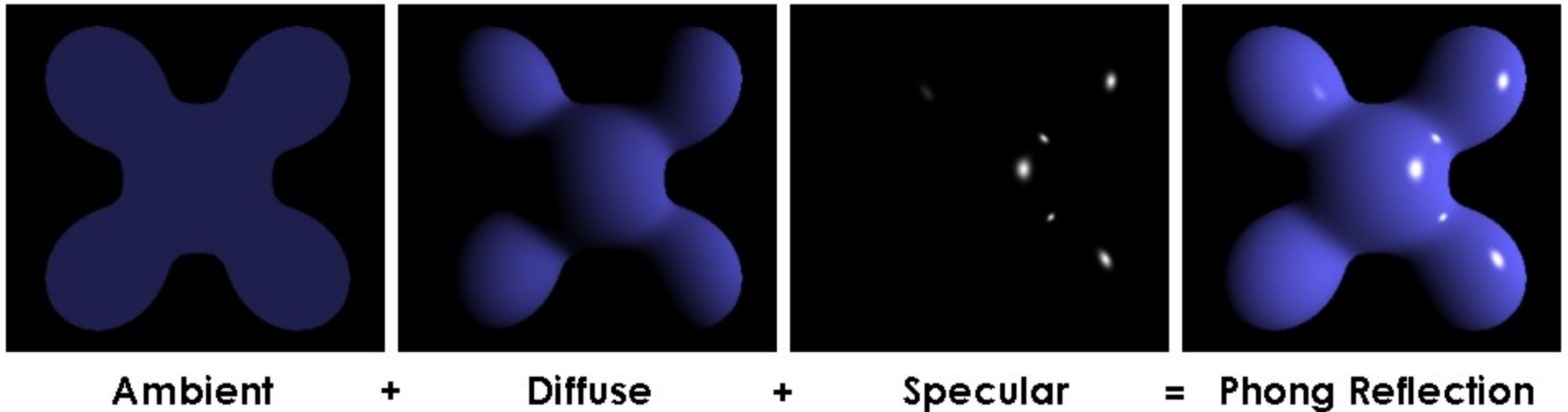
$$L = L_a + \sum_{i=1}^N dI_i \max(0, n \cdot l_i) + sI_i \max(0, n \cdot b_i)^x$$

Attenuation: the greater the distance, the low the intensity

$$L = L_a + \sum_{i=1}^N \frac{1}{k_c + k_l c + k_q c^2} \left( dI_i \max(0, n \cdot l_i) + sI_i \max(0, n \cdot b_i)^x \right)$$

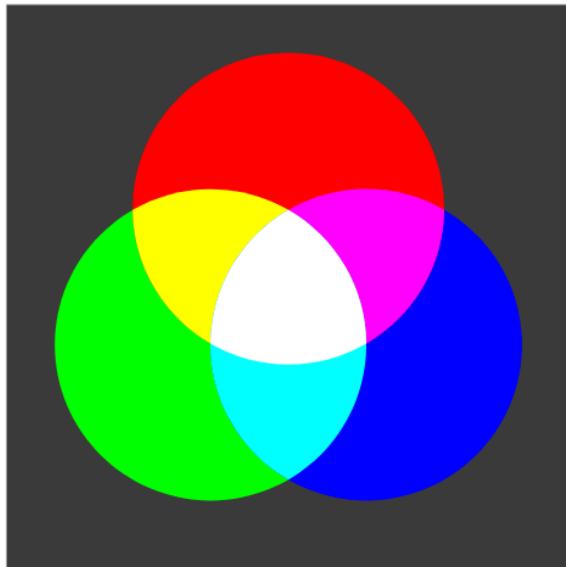
constant    linear    quadratic attenuation     $c$  Light source distance to surface    Used by OpenGL for  $\sim 25$  years

# Phong Reflection Model



# Color Formulation

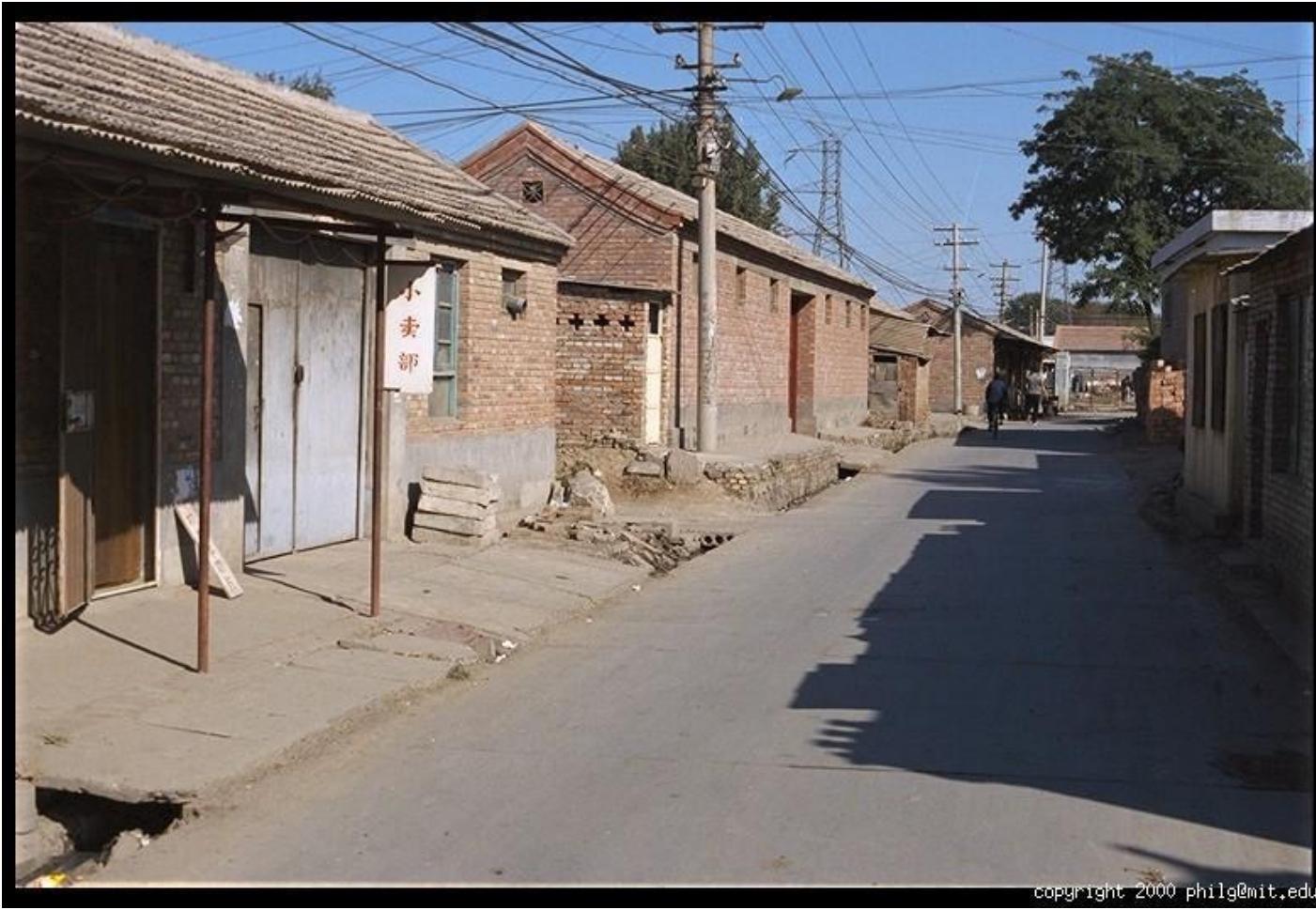
When the incoming light hits the imaging sensor, light from different parts of the spectrum is integrated into the discrete red, green, and blue (RGB) color values that we see in a digital image.



Mixing different colors can obtain a new one

- Red+green makes yellow
- Red+blue+green makes white

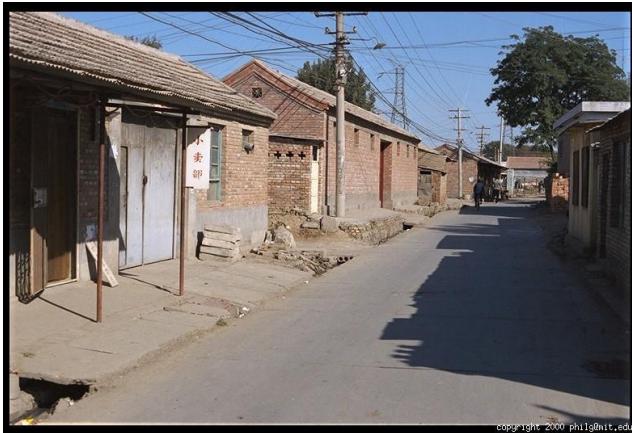
# Color Images



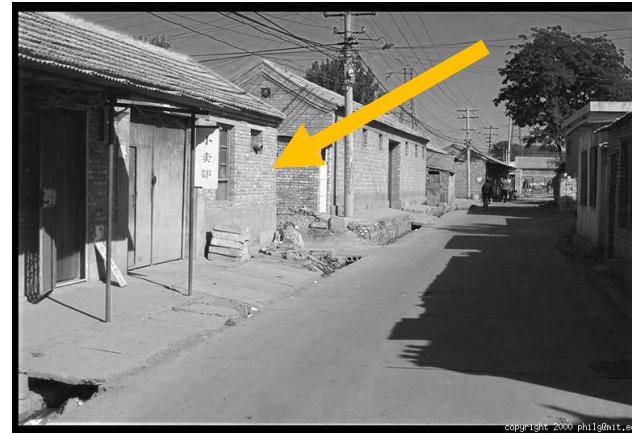
copyright 2000 philg@mit.edu

Slide Credit: J. Hays

# Color Images Combined



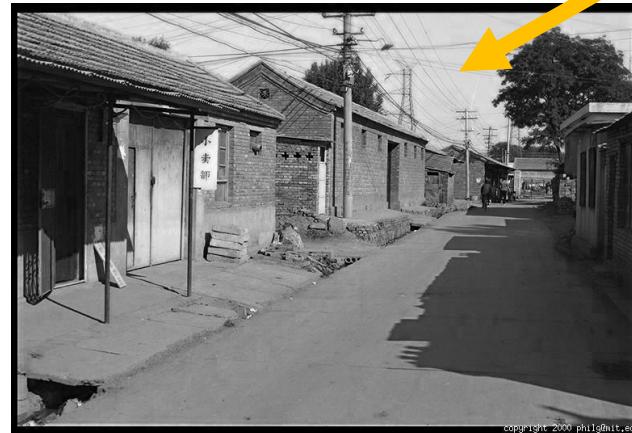
Red



Green

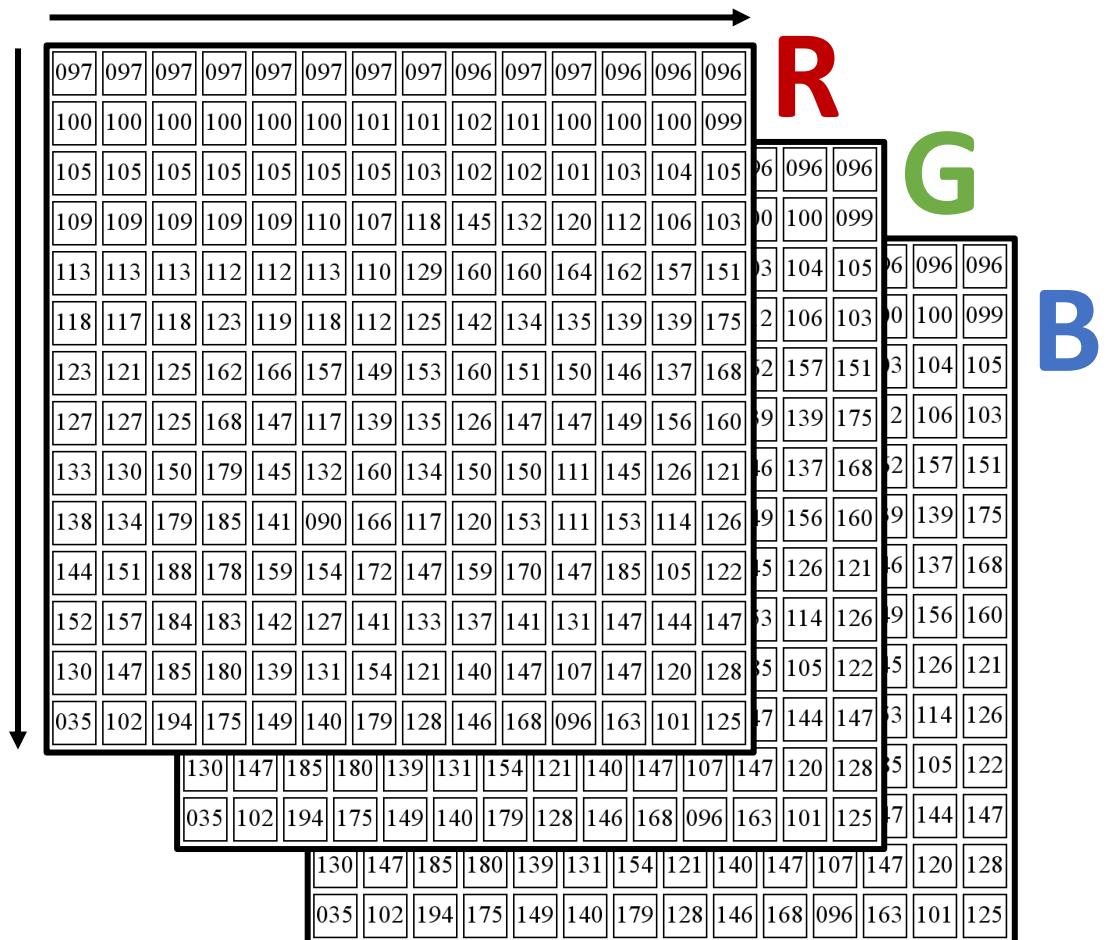


Blue



Slide Credit: J. Hays

# Images in Python



Slide Credit: D. Fouhey, J. Johnson

# Images in Python

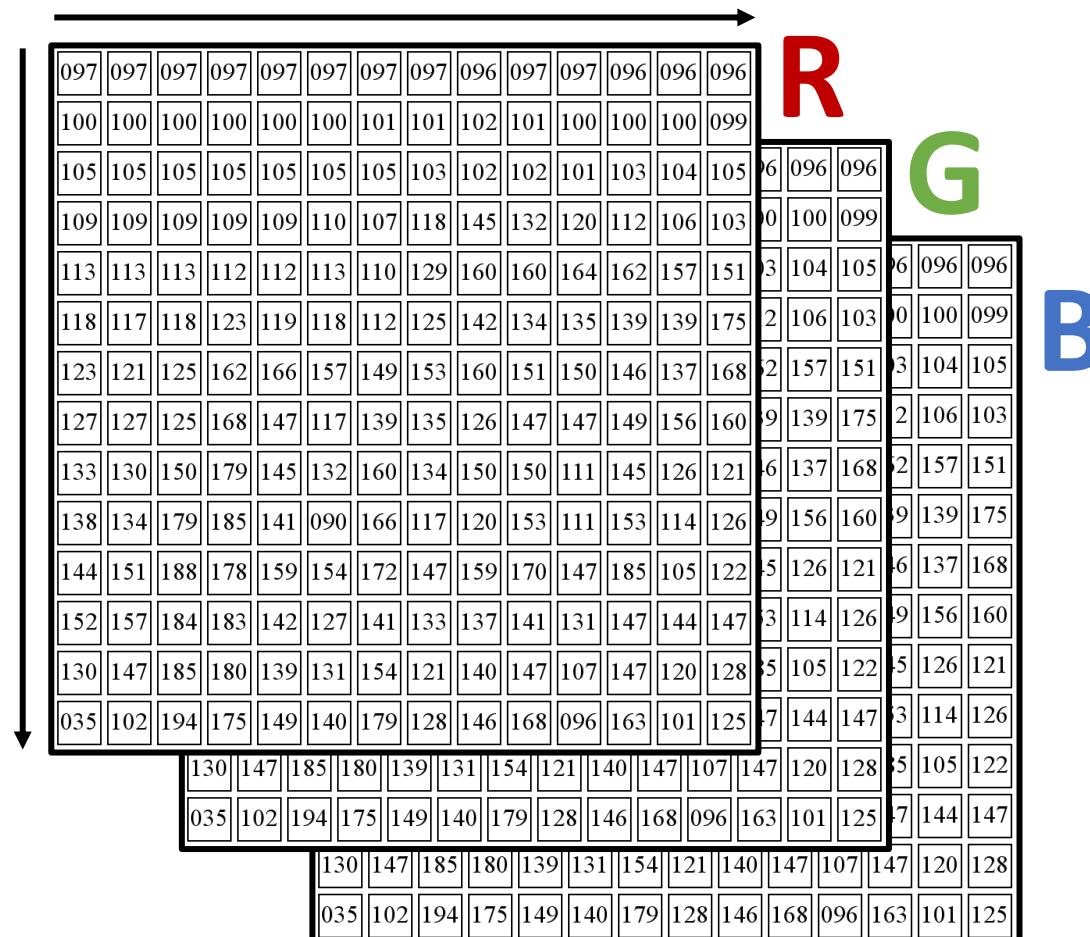
Images are matrix / tensor `im`

`im[0,0,0]`  
top, left, red

`im[y,x,c]`  
row  $y$ , column  $x$ , channel  $c$

`im[H-1,W-1,2]`  
bottom right blue

what is the index for bottom right red?



Slide Credit: D. Fouhey, J. Johnson

# Few Things to Remember

- Origin is top left
- Rows are first
- Usually referred to as HWC (Height x Width x Channel). But you'll sometimes see CHW (especially with neural networks)
- Typically stored as uint8 [0,255]

Slide Credit: D. Fouhey, J. Johnson

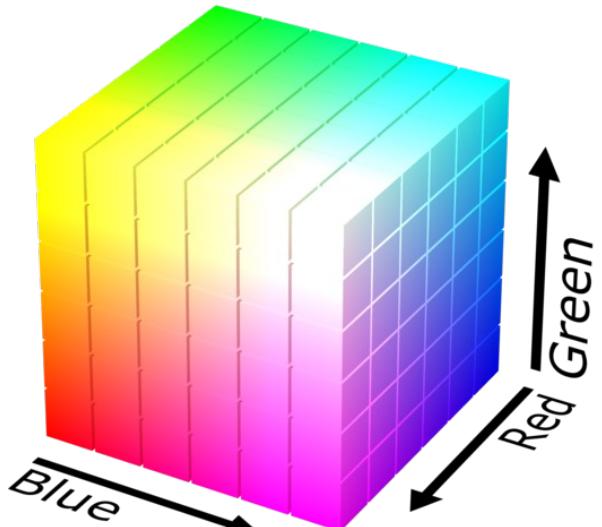
# RGB Color Space

## Pros

1. Simple
2. Common

## Cons

1. Distances don't make sense
2. Correlated



Slide Credit: J. Hays, RGB cube: [https://en.wikipedia.org/wiki/RGB\\_color\\_model](https://en.wikipedia.org/wiki/RGB_color_model)



R



G

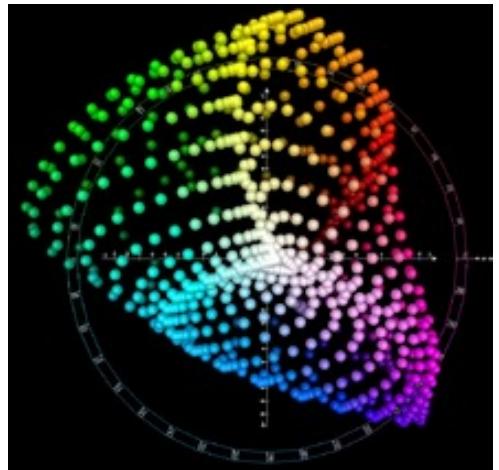


B

# LAB Color Space

## Pros

1. Distances correspond with human judgment
2. Useful for color correction



## Cons

1. Complex to calculate (don't write it yourself, lots of calculations)



**L**  
( $a=0, b=0$ )



**a**  
( $L=65, b=0$ )



**b**  
( $L=65, a=0$ )

Slide Credit: J. Hays, Lab diagram cube: [https://en.wikipedia.org/wiki/CIELAB\\_color\\_space](https://en.wikipedia.org/wiki/CIELAB_color_space)

# Different Color Spaces



R



G



B



L

( $a=0, b=0$ )



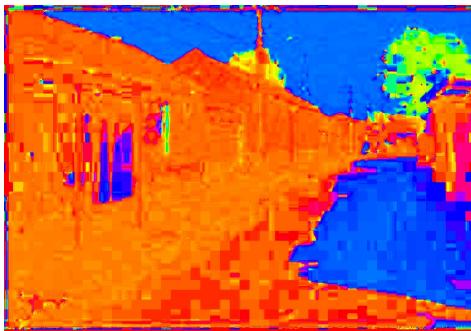
a

( $L=65, b=0$ )



b

( $L=65, a=0$ )



H

( $S=1, V=1$ )



S

( $H=1, V=1$ )



V

( $H=1, S=0$ )



Y

( $Cb=0.5, Cr=0.5$ )



Cb

( $Y=0.5, Cr=0.5$ )



Cr

( $Y=0.5, Cb=0.5$ )

# Different Color Spaces

- RGB: sort of intuitive, standard, everywhere
- HSV: good for picking specific colors, fast to compute from RGB
- YCbCr/YUV: fast to compute, great for compression
- Lab: the right(?) thing to do, but “slow” to compute

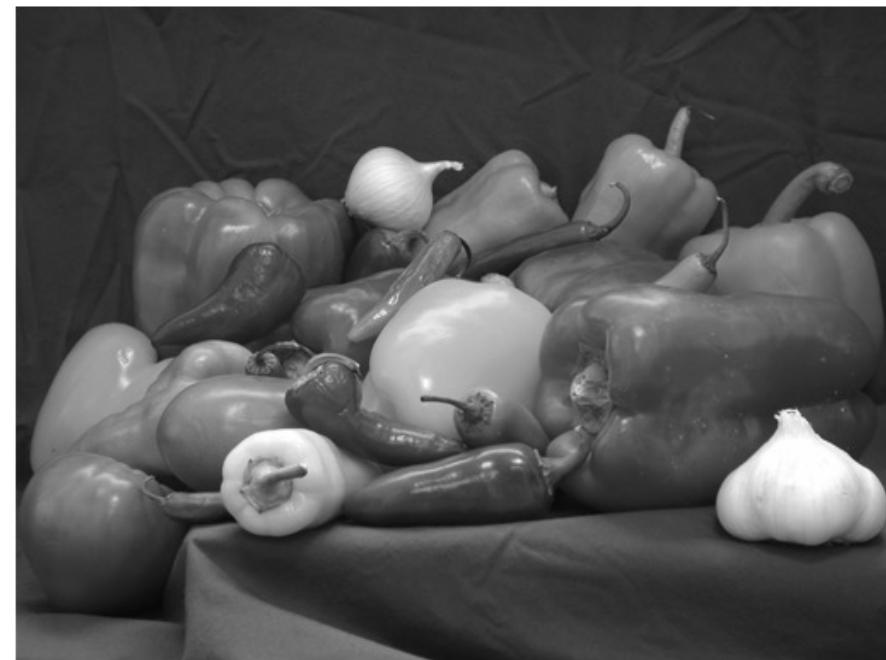
RGB space is commonly used to represent colorful images in most of our applications

# Color Conversion: One Example

Question: how to convert a RGB image to a Grayscale image?



$\text{im}[y, x, c]$



$\text{im}[y, x]$

# RGB Color to Gray Conversion

RGB2Gray function:  $I = 0.2989 * R + 0.5870 * G + 0.1140 * B$

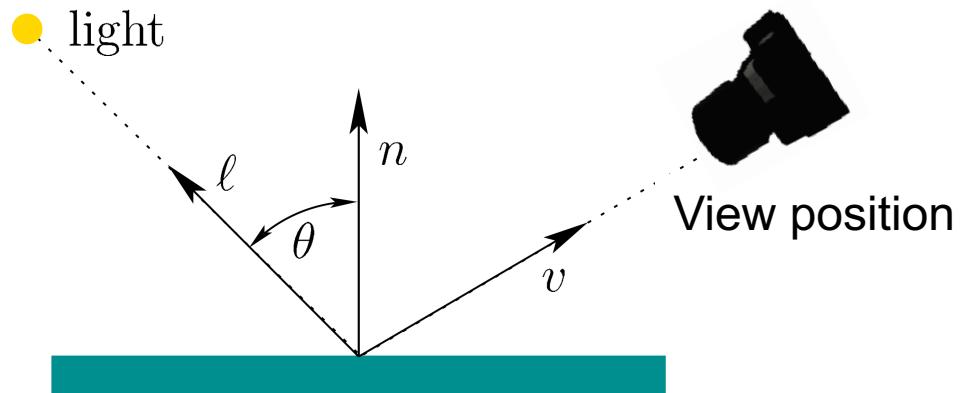
Based on research on human vision, we know that our eyes react to each color in a different manner.

Specifically, our eyes are more sensitive to green, then to red, and finally to blue.

# Summary

## Lighting Computation:

- compute color given material properties, light source color and position, normal position, view position



## Color Space:

- a color can be represented by three primaries, such as RGB
- there are different color spaces, and they can be converted to each other
- $im[y,x,c]$  – row, col, channel

# Further Reading

Chapters 2.2.1, 2.2.2, and 2.3.2, Computer Vision: Algorithms and Applications, Richard Szeliski

Chapter 7.1, Virtual Reality, Steven LaValle