**Problem 1.** There are n villages on a straight road at x-coordinates  $x_1 < x_2 < \ldots < x_n$ . You have to place k cellphone towers, each in one of the villages. Any village will connect to its nearest tower and incur a delay equal to the distance between them. The goal is to place the k towers to minimize the maximum delay of any village. Give an efficient algorithm for this.

Let V denote any vector  $x_1, x_2, \ldots, x_n$  of x-coordinates of villages. Then suppose we can efficiently solve the following decision version of our problem

**Problem 2.** Suppose we are given village locations at V and k towers. Additionally, we are given a number d. Then, is the optimum value for problem 1 at most d?

Then, we can simply binary search on d to solve our original optimization problem. More precisely, given an algorithm  $\mathtt{DECIDE}(V,k,d)$  for problem 2, the algorithm  $\mathtt{MINDELAY}(X,k)$  solves problem 1.

```
Algorithm 1 Optimization via decision version
```

```
\triangleright V is a vector x_1, x_2, \ldots, x_n of coordinates
 1: procedure MINDELAY(V, k)
         D \leftarrow x_n - x_1.
                                                                                       ▶ Maximum possible delay.
 2:
         Initialize a \leftarrow 0, b \leftarrow D.
 3:
         while b > a do
                                                \triangleright Invariant: the optimum delay lies in the interval [a, b]
 4:
             d \leftarrow |(a+b)/2|
 5:
 6:
             if DECIDE(V, k, d) then
 7:
                  b \leftarrow d
             else
 8:
                  d+1
 9:
10:
                                                                                                                 \triangleright a = b
11:
                  return a
12:
```

The correctness of algorithm 1 follows from the invariant that at the start of each iteration of the while loop, the optimum delay lies in the interval [a, b].

Time Complexity of MINDELAY Algorithm 1 makes  $O(\log_2(x_n - x_1))$  calls to DECIDE because b - a halves after each call to DECIDE and initially  $b - a = D = x_n - x_1$  (and a = b at the end).

Now to solve problem 2, it is enough to solve its following optimization version.

**Problem 3.** Given village locations at V and a number d, find the minimum number of towers needed so that maximum delay of any village is at most d.

Given an algorithm MINTOWER(V, d) to solve problem 3, DECIDE(V, k, d) simply returns whether MINTOWER(V, d) is at most k, see algorithm 2.

Hence, we now focus on solving problem 3.

## Minimizing the number of towers needed to achieve a given maximum delay

We give a natural greedy algorithm for problem 3: place a tower at the rightmost village i such that  $x_i - x_1 \leq d$ . Delete the villages whose delay by this tower is at most d, and recurse on the remaining villages. See algorithm 3 to recursively solve the problem for villages  $j, \ldots, n$ . Run this algorithm for j = 1.

```
Algorithm 3 Minimizing towers to achieve a given maximum delay for villages j, j + 1, \ldots n
 1: procedure MINTOWER(V, d, j)
                                                      \triangleright V is a vector x_1, x_2, \ldots, x_n of coordinates
        for all i = j, j + 1, ... do
 2:
           if x_i - x_i > d then
                                                                               \triangleright Place tower at i-1
 3:
 4:
               for all k = i, i + 1, \dots do
                   if x_k - x_{i-1} > d then
 5:
                       return 1 + MINTOWER(V, d, k) > k is the leftmost village not covered by
 6:
    our tower i-1
                   end if
 7:
               end for
 8:
 9:
           end if
        end for
10:
                                                                            > only one tower suffices
11:
        return 1
12: end procedure=0
```

## Proof of correctness:

*Proof.* Let us fix some feasible subset S of villages, and let G be the subset returned by the greedy algorithm. Clearly G is feasible by construction. We want to show that  $|G| \leq |S|$ . The following claim is the key to everything

Claim 1. Suppose the left most tower in G (respectively S) is at village g (resp. s). Then,  $s \leq g$  or equivalently,  $x_s \leq x_g$ .

*Proof.* First let us see why  $x_s \leq x_g$ . Since S is feasible,  $x_s - x_1 \leq d$ . Since  $x_i - x_1 > d$  for all i > g (by the greedy choice of g), it must be that  $s \leq g$ . Hence,  $x_s \leq x_g$ .

Claim 1 shows that after the choice of the left most tower, the greedy solution G is 'ahead' of any other solution S in the following sense:

Claim 2. S-s is feasible for the subset of villages not covered by g i.e. the villages  $k, k+1, \ldots, n$  in the algorithm 3. Or equivalently, any village within distance d of s is also within distance d of g.

*Proof.* It is enough to show that any village within distance d of s is within distance d of g. To see this, note first that any village to the left of  $x_g$  is within distance d of g (since this property is true for the leftmost village). Also, any village to the right of  $x_g$  is only closer to g than s (since  $x_g \ge x_s$ ). This completes the proof.

This means that one can essentially exchange s for g in S i.e.  $S-s \cup g$  is a feasible solution of the same value as S. We can now finish the proof by exchanging off all towers of S with those of G, but I prefer to do a more slick induction. We can inductively assume that greedy is optimal for any smaller subset of villages than V, hence G-g is an optimal solution for the set of villages not covered by g. Since, S-s is feasible for the set of villages not covered by g, we have that  $|S-s| \leq |G-g|$  and hence  $|S| \leq |G|$ .

Time complexity of the greedy algorithm: In algorithm 3, we look at any village at most once in the iterative loop. Hence, the time complexity is O(n).

Final time complexity There are  $O(\log(x_n - x_1))$  calls to DECIDE which makes a single call to MINTOWER. MINTOWER takes O(n) time, hence the overall running time is  $O(n \log O(x_n - x_1))$ .