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The MT3647 provides an intelligent interface between a Host and the vehicle's Electronic control units. The MT3647 is designed to act as a bridge between Heavy Duty vehicle protocol and UART interface.

Features

- · Power voltage monitoring.
- Support: J1939 and J1708 protocols.
- Configurable via AT command. Automatically searches for protocols.
- Provide ASCII and HEX CODE format output.
- Provides several formats output will be available to the integration with different applications.
- Baud Rate: 9600,19200,38400,57600,115200 are available.
- J1939 Auto Baud 500K and 250K.

(1) J1939:

CANBUS SAE-J1939 truck brands, VOLVO trucks, MACK, John Deere, Caterpillar, Detroit Diesel, Nissan Diesel, Kubota, Freightliner, Dong Feng Motor, SinoTruck, Daimler Trucks, Navistar, Chery Auto, SAIC MOTOR, SINO Truck (CNHTC), Shannxi AutoMobile, HINO

(2) According to Bus FMS-Standard Interface description Vers. 00.02 ,10.11.2010

Daimler AG ,Scania AB,Iveco SpA, MAN Nutzfahrzeuge AG , Volvo Truck Corporation,
DAF Trucks N.V.,Renault Trucks

(3) J1708:

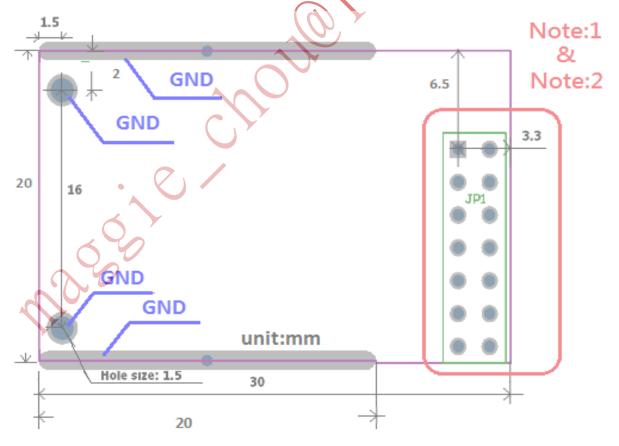
Caterpillar: CAT C-15,VOLVO: VOLVO Engine, (6 pins connector), CUMMINS ISX 475 2000, CUMMINS ISX 450 ST2 2000, Freightliner: DETROIT12.(PREMIUM SERIES), CUMMINS ISM 370, CUMMINS N14-370 ESP+, Caterpillar, Detroit Dieset, Freightliner, Renault (OBD2 connector)

1. Electrical Characteristics

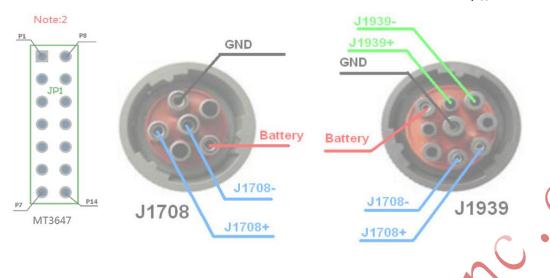
Part Name	M T 3 6 4 7
Part No	87P0U0579
Operating Voltage/ Current	5V/ 0.05A
Operating Temperature	-40~+85 °C
Dimensions	PCBA: L:30mm x W:20mm x H:5.24 mm (with Components)
Output	UART 3.3 or 5.0 V, Baud Rate : 9600 , 8 ,N, 1(Default)

2. PCB Dimensions

There are 2 fixture holes, one interface I/O.







MT3647	Definition		
Pin2	Indicate communication status.		
	DO(Digital Output):		
	Protocol Connected : High (3.3 or 5V)		
	Protocol disconnected: Low (0.0V)		
Pin3	GND		
Pin4	Wake up MT3647		
	Rising Edge(0 → 3.3 or 5V)		
Pin5	UART TX (0 ~3.3 or5 V), to your device RX		
Pin6	UART RX (0~3.3 or 5V), to your device TX		
Pin7	Power input: DC 5.0V, Max current 50mA.		

. ?	
MT3647	Definition
Pin1	Battery 24Vin
Pin8	N/A
Pin9	N/A
Pin10	Battery GND
Pin11	J1708+
Pin12	J1708-

J1939+

Pin13

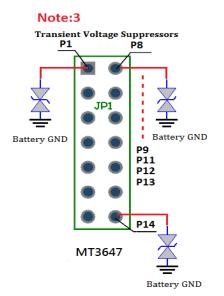
Descript

ions:

v1.2

Pin14	J1939-
	101303-

4. Application Note:



GPIO added transient voltage suppressors for surge protection. (MT3647 Pin1 \(\cdot 11 \(\cdot 12 \(\cdot 13 \) \) 14)

5.Communicating with the MT3647

The MT3647 communicate with a PO through a UART connection or virtual serial port. No matter how you physically connect to the MT3647, you need use one COM port monitor program to send and receive data. To use a terminal program, you will need to make several settings.

- 1.) Setting proper "COM' port, data rate is default 9600.
- 2.) Setting your connection for 8 data bits, no parity bits, and 1 stop bit.
- 3.) Setting 'LINE END' mode.

Properly connected and powered, the MT3647 will print interpreter information.

The '>' character that is shown on the second line is the MT3647's prompt character. It indicates that the device is in the idle state, ready to receive characters on the UART. If you did not see the identification string, you might try resetting the Interpreter again with the ATR(reset) command. Simply type the letters A T and R (spaces are optional), then press the return key:>ATR



If you type HEX code, it will be "41","54","5A","0D", as ASCII code "A", its HEX code is "41". The commands 'ATR', 'AtR' is all exactly the same to the MT3647.

If you see strange looking characters, then check your baud rate, you have likely set it incorrectly. If you send a incorrect command the MT3647 will print a single question mark ('?') to show that the input was not understood, in case it failed to communicate to BUS, MT3647 will print

PLEASE REBOOT

>

Once MT3647 connect to BUS, the power LED lit and it starts to try J1939 or J1708 protocol. Next time MT3647 only try the successful protocol unless use ATR to reset it. In case MT3647 has not connected to BUS, or wrong command AT3647 will print a

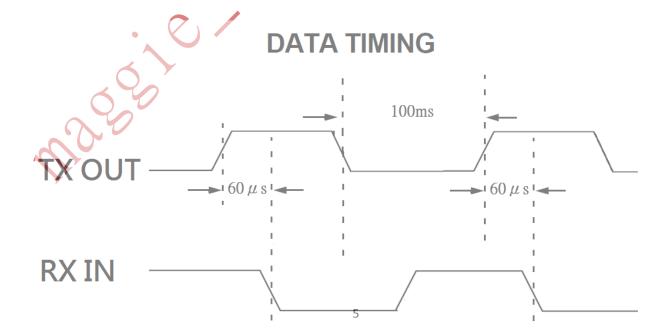
ERROR

>

After trying 180 seconds, in case the AT3647 can not find correct protocol, it will enter sleeping mode for power saving. You can restart engine to wake MT3647 up. The MT3647 provides several formats output will be available to the integration with different applications.

- 1.) Simple Data by ASCII code.
- 2.) Raw data.
- 3.) Packaged Messages by ASCII or HEX code.

Its default format is Simple Data format, MT3647 will send messages out once it communicates with vehicle successfully.



6.AT Command Summary

@1	AT@1: Display version information
	ATBS MT3647S VXX.X.XXXXXX>
BRxy	Setting RS232 baud rate. xy is baud rate parameter.
	ATBR09: 9600
	ATBR19: 19200
	ATBR38: 38400
	ATBR57: 57600
	ATBR99: 115200
Eh	ATE0: echo off(Default)
	ATE1; echo on
Т	ATT: Terminate sending. To use ATS will continue it.
1	ATI : Request vehicle ID, the length is variable.
	1.) J1708:
	Output format: ASCII code
	Byte 0:0x2A
	Byte 1: Vehicle ID byte 1
	Byte 2: Vehicle ID byte 2
	Byte N:Vehicle ID byte N
	Byte N+1: Check Sum=Byte 1+Byte2++Byte N
	Byte N+2:0x0D
	Byte N+3:0x0A
	N: Max 20
	2.)J1939
	Byte 0:0x2A
	Byte 1: Vehicle ID byte 1
_	Byte 2: Verlicle ID byte 2
•	Byte N:Vehicle ID byte N
~	Byte N+1: Check Sun= Byte1+Byte2 +ByteN
~~	Byte N+2:0x0D
	Byte N+3:0x0A
	N: Max 35
PA	ATPA: Print data by ASCII CODE format
РH	ATPH: Print data by HEX CODE format
R	ATR: Clear protocol and distance (D1 ,D2)memory, the ATR
	command clear current protocol then continue learning next
	new protocol.
RJ	ATRJ: Request J1939 FMS High Resolution Total Vehicle
	Distance #33~#36



RH	ATRH: Request Hino Truck Total vehicle distance (#33~#	
S	ATS: Continue auto-send data every 100~200ms. To use A	
	will terminal it.	
SS	ATSS: Auto- send Simple Data every 100~200 ms.	
	Refer to Simple Data format Protocol	
SP	ATSP: Auto-send Packaging Messages every 100~200 r	
	Refer to Packaging Messages protocol.	
SR	ATSR: Auto-send J1939/J1708 Raw Data,	
	Refer to Raw Data Protocol.	
Χ	ATX: Request to send data of alternate, data format as	
	ATS/ATSP command.	
	For J1939 protocol:	
	Packing1 Packing2 Packing 3	
	Packing4 Packing5 Packing6 Packing1	
	• For J1708 protocol:	
	Packing1→Packing2 →Packing3→	
	Packing4→Packing5 →Packing1	
#xy	AT#xy: The command will print designated data by ASCI	
π∧у	code. "xy" is data address, it is decimal.	
	J1708: 00~53	
	J1939: 00~99.	
	EX: AT#01, to get speed high byte.	
	EX. AT#OT, to get speed High byte.	
	• 0 /	
Q		
7		



Simple Data Protocol: (ASCII CODE)

	, , , , , , , , , , , , , , , , , , , ,
Data	Description
HEAD	@
Byte 0	,
Byte 1	Speed , (0~255) KM/HR
Byte 2	,
Byte 3	RPM High Byte (RPMHB)
Byte 4	,
Byte 5	RPM Low Byte(RPMLB) , RPM=RPMHB*256+RPMLB
Byte 6	,
Byte 7	Engine Loading, (0~100%)
Byte 8	,
Byte 9	Battery Voltage (BV), = (BV+100)/10 (v)
Byte 10	,
Byte 11	Engine Temperature(ET), =ET-40 ℃
Byte 12	,
Byte 13	Throttle position 0~100 %
Byte 14	,
Byte 15	Status , Note 2
Byte 16	,
Byte 17	MAF (0~255), MAF RATE= MAF * 3;
Byte 18	,
Byte 19	Distance : D1
Byte 20	
Byte 21	Distance: D2
Byte 22	
Byte 23	FU, Average Fuel Economy (km/L) =Fu /10
Byte 24	
Byte 25	Check sum (odd numbers)= Byte1+ Byte3+Byte5+ Byte7+
んひょ	Byte9+Byte11+ Byte13+ Byte15+Byte17+ Byte19+
	Byte21+Byte23
Byte 26	Carry return (0x0D)
Byte 27	Line feed (0x0A)

• Simple Data Protocol: (HEX CODE)

Data	Description
HEAD	@ (=0x40)
Byte 1	Speed , (0~255) KM/HR
Byte 2	RPM High Byte (RPMHB)
Byte 3	RPM Low Byte(RPMLB) , RPM=RPMHB*256+RPMLB
Byte 4	Engine Loading, (0~100%)
Byte 5	Battery Voltage (BV), = (BV+100)/10 (v)
Byte 6	Engine Temperature(ET), =ET-40 °C
Byte 7	Throttle position 0~100 %
Byte 8	Status , Note 2
Byte 9	MAF (0~255), MAF RATE= MAF * 3;
Byte 10	Distance: D1
Byte 11	Distance: D2
Byte 12	FU, Average Fuel Economy (km/L) =Fu /10
Byte 13	Check sum (odd numbers)= Byte1+ Byte2+Byte3+ Byte4+
	Byte5+Byte6+ Byte7+ Byte8+Byte9+ Byte10+ Byte11+Byte12
Byte 14	Carry return (0x0D)
Byte 15	Line feed (0x0A)

NOTE:

1.) Data format : ASCII CODE

@ , 7 8 , 0 E , 7 0 , 0 0 ,0 3 , 9 8 , 2 8 , Status ,MAF,D1,D2,Fu,CS speed=78 km/hr

rpm=0x0E70= 3696

2.) status:

Bit 7:

0: Normal

1) Emergency Braking (Acceleration < - 6 m/s2)

Bit 6:

0: Brake OFF

1: Brake ON

Bit 5:

0: Clutch OFF

1: clutch ON

Bit 4:

v1.2

0: Cruise Control OFF

1: Cruise Control ON

Bit 3:

0: Brake (ON/OFF) unavailable

1: Brake(ON/OFF) available

Bit 2:

0:Clutch (ON/OFF) unavailable

1: Clutch (ON/OFF) available

Bit 1

0: Cruise Control (ON/OFF) unavailable

1: Cruise Control (ON/OFF) available

Bit 0:

0: NORMAL

1: DTC ON

2.) Distance = D1*256+D2

3.) Average Fuel Economy =Fu /10

10



J1939 Raw Data Protocol (HEX CODE)

Support for J1939 PGN / SPN access as defined in the J1939 standards. This function will report all PGNs and their source node on the J1939 network. Each SPN under this function should be set to a size of 32 bits.

J1939	Format		
Byte 0	@ (=0x40)		
Byte 1	Bit4,3,2: Priority Bit0: Data Page Bit1,5,6,7:Reversed		
Byte 2	PDU Format (PF)	PGN	
Byte 3	PDU Specific (PS)		
Byte 4	Source Address		
Byte 5	Data1		
Byte 6	Data2		
Byte 7	Data3		
Byte 8	Data4		
Byte 9	Data5		
Byte 10	Data6		
Byte 11	Data7		
Byte 12	Data8		
Byte 13	Check Sum		
Byte 14	0x0D		
Byte 15	0x0A		

J1708 Raw Data Protocol (HEX CODE)

This function will report all MID and PID that broadcasting on the J1708 network. Its data length is not fixed, please refer to SAEJ1708.

Format	PIDs 192-253	PIDs 128-191	PIDs 0-127
Byte 0	@ (= 0x40)	@ (= 0x40)	@ (= 0x40)
Byte 1	Message identification	MID	MID
	(MID)		
Byte 2	Parameter identification	PID	PID
	(PID)		
Byte 3	Number of data bytes	Data1	Data1
Byte 4	Data 1	Data2	Check Sum
Byte 5	Data 2	Check Sum	Q0x0
Byte 6		0x0D	0x0A
Byte 7	Data N	0x0A	
Byte 8	Check Sum		
Byte 9	0x0D		
Byte 10	0x0A		

PIDs 0-127 describe data parameters that are one byte long.

PIDs 128-191 describe data parameters that consist of two bytes.

PIDs 192-253 The first byte following these PIDs will contain the number of data parameter bytes.

EX:

0x40	0x80	0x15	0x01	0x32	0xC8	0x0D	0x0A	MID=128
64	128	21	1	50	200	13	10	10110-120

PID=21 (Engine ECU temperature)

Data-50

• 1939 Packaged Messages Protocol

ATS: send packaged messages by turns.

Response HEX CODE (default) after ATPH command					
Packing 1 (#00~#17)	Packing 2 (#18~35)	Packing 3 (#36~53)			
Byte 0:" @" ,(0x40)	Byte 0: " @" ,(0x40)	Byte 0: " @" ,(0x40)			
Byte 1: "1", (0x31)	Byte 1: "2",(0x32)	Byte 1: "3",(0x33)			
Byte 2: #00	Byte 2: #18	Byte 2: #36			
Byte 3: #01	Byte 3: #19	Byte 3: #37			
Byte 19:#17	Byte 19:#35	Byte 19:#53			
Byte 20:	Byte 20:	Byte 20:			
Check sum = Byte2	Check sum = Byte2	Check sum = Byte2			
++Byte 19	++Byte 19	++Byte 19			
Byte 21: 0X0D	Byte 21: 0X0D	Byte 21: 0X0D			
Byte 22: 0X0A	Byte 22: 0X0A	Byte 22: 0X0A			
Packing 4 (#54~#71)	Packing 5 (#72~#89)	Packing 6 (#90~105)			
Byte 0:" @" ,(0x40)	Byte 0: "@" ,(0x40)	Byte 0: " @" ,(0x40)			
Byte 1: "a",(0x61)	Byte 1: "b",(0x62)	Byte 1: "c",(0x63)			
Byte 2: #54	Byte 2: #72	Byte 2: #90			
Byte 3: #55	Byte 3: #73	Byte 3: #91			
Byte 19:#71	Byte 19:#89	Byte 17:#105			
Byte 20:	Byte 20:	Byte 19:0			
Check sum = Byte2	Check sum = Byte2	Byte 20:0			
++Byte 19	++Byte 19	Check sum = Byte2			
Byte 21: 0X0D	Byte 21: 0X0D	++Byte 19			
Byte 22: 0X0A	Byte 22: 0X0A	Byte 21: 0X0D			
		Byte 22: 0X0A			

NOTE:

- 1.) AT#00 ~ AT#102 respond ASCII CODE format data.
- 2.) Packing 6, Byte15~Byte19 not defined (set to "0")
- 3.) After ATPA command, byte 21& 22 were ignored.
- 4.) This is the common J1939 measurement overview showing which measurements are available. Note: that not all measurements are supported by the individual engines.



400	0	D 1 1), D)										\neg
#00	+ -	ow Byte (S											
#01	•	igh Byte (,										
	speed=(S	SHB*256+	-SLB)/256)									
#02		1	T	1		I						ı	
	B7	B6	B5	B4		В3		B2		B1 B0			
	Clutch s	switch	Brake s	witch		NOT	US	SED		Cruise control		ol	
								activ					
	'			= pec	lat						= SV	vitche	∋ď
	released		release							off			
	01 = pedal 01			= pec	lat					01 =	= 50	vitche	∍d
	depressed depressed on												
#03											Y		
,,,,,,	B7 B6 B5 B4 B3 B2 B1 B0								1				
	B7: Emergency PTO state												
		6m/s2)B6:		00000 =	= of	f/disah	ماهما					nate	
	up (6m/s	,	ороса	00101 =				-					
	' '	ouble Em	nergency	11111 =			labl	e					
		over -12m	•		\ <u>`</u>		, a.o.	•					
	,	le, 0:Disa	,	(1)									
				1	<u> </u>								J
#04	0.4 % / B	Bit gain, Ad	ccelerator	Pedal P	osit	ion(AF	PP)	, 0 to	100) %			
	APP= Da	ata* 0.4	10										
#05	Engine T	otal Fuel	used 0,5 l	L / Bit ga	in ,	ETF1							
#06	Engine T	otal Fuel	used 0,5 I	L / Bit ga	in ,	ETF2							
#07	Engine T	otal Fuel	used 0,5 I	L / Bit ga	in ,	ETF3							
#08	Engine•T	otal Fuel	used 0,5 I	L / Bit ga	in ,	ETF4							
	Engine T	otal Fuel	used										
	=((ETF4*	256*256*	256)+(ET	F3*256*2	256)+(ET	F2*	256)+	ΕTI	F1)*0.	5		
#09	Fuel Lev	el (FL) , 0	to 100 %	, 0.4 %/b	it								
	Fuel Lev	el=FL*0.4											
#10	RPM Lov	v byte, RL	-										
#11	RPM Hig	h byte, RI	Н										
	RPM= (R	RH*256+ F	RL)* 0.125	5									



								T I			
#12	B7	B6	B5	B4	B3	B2	B1	B0			
		NOT US	ED		Engine S	Starter Mo	ode				
	B7: 1, Tot	tal Vehicle	Distance	e is provid	ed by veh	icle ECU					
	0, To	tal Vehicl	e Distanc	e is calcul	ation valu	ie					
	B3~B0:										
	0000 star	t not requ	ested					(
	0001 star	ter active,	gear not	engaged							
	0010 star	ter active,	gear eng	aged							
	0011 star	t finished;	starter no	ot active a	fter havin	g been a	ctively en	gaged?			
	(after 50m	ns mode g	goes to 00	000)?							
	0100 starter inhibited due to engine already running										
	0101 starter inhibited due to engine not ready for start (preheating)										
	0110 starter inhibited due to driveline engaged										
	0111 starter inhibited due to active immobilizer										
	1000 starter inhibited due to starter over-temp										
	1001-1011 Reserved										
	1100 starter inhibited - reason unknown										
	1101 error										
	1111 not available										
#13	Axle location The value 0xFF indicates not available.										
	B7	B6	B5	В4	B3	B2	B1	B0			
	Axle loca	ation Bit-n	napped po	sition	Tire location Bit-mapped						
	number	counting f	ront to ba	ck facing	counting left to right facing						
	forward		•		forward						
	F = not a	available			F = not available						
	· .	number, d	_		The low	The low order 4 bits represent a					
	back on	the vehicl	e. B7,B6,	B5,B4	position number, counting left to						
	Axle loca	tion Bit-n	napped po	osition	right when facing in the direction						
		counting f	ront to ba	ck facing	of norm	al vehicle	travel				
2	forward.										
#14	Axle weig	ht 0 5 kg	/ Rit gain	(Low By	te),AWL						
	Axle weig				/te), AWF	<u> </u>					
#15	J	•	J	` .	ie), Avvi	I					
#16	Weight=(/										
	Engine to		•								
#17	⊏rigine to	Engine total hours of Operation, EH2									



-	1977
#18	Engine total hours of Operation, EH3
#19	Engine total hours of Operation, EH4
	Accumulated
	time=((EH4*256*256*256)+(EH3*256*256)+(EH2*256)+EH1)*0.05
#20~	Vehicle identification number, aabbccddeeffgghh (If the Vehicle ID contains
#27	more than 8 Bytes then #20~#27 are "00", please use ATI command to
	request.
#20	aa
#21	bb
#22	cc
#23	dd
#24	ee
#25	ff
#26	gg
#27	hh
#28	Engine Percent Load At Current Speed (0~125 %)
#29~	SW-version supported for trucks, Version number in the format ab.cd
#32	where this byte represents ASCII code
	#29 : "a" , #30: 'b', #31:'c' , #32:'d'
#33~	High Resolution Total Vehicle Distance, 5 m/bit, 0 to 21,055,406 km
#36	=((D4*256*256*256)+(D3*256*256)+(D2*256)+D1)*0.005 (KM)
#33	D1
#34	D2
#35	D3
#36	D4
#37~	The distance which can be traveled by the vehicle before the next service
#38	inspection is required
	SERV=(V2*256+V1)*5-160635 (KM)
#37	V
#38	V2
1	

#39				1					_			
	E	37	B6	B5	B4		B3	B2	B1	B0		
	\	ehicle mo	tion(B7,B6): Driv	. 2 work	king st	tat	Driv. 1	l workin	g state		
		00 = Vehicl	e motion	state	e (B5,B	4,B3)	G	(B2,B1,B0):				
	r	not detecte	d	000	= Rest			000 = Rest				
		01 = vehicle	e motion	001	= Drive	r avai	ilable	001 = Driver				
		detected		010	= Work	(available				
				011	= Drive	:		010 =	Work			
			110	= Error			011 =	Drive				
					= not a	vailab	ole	110 =	Error	•		
								111 = not avaiable				
								•	\ }			
#40									Y			
		B7	B6	B5	B4	В3	B27	B1	В0]		
	Vehicle Overspeed Driver 1 card Driver 1 time related state											
	Vehicle Over speed (B7,B6). GIndicates whether the vehicle is exceeding											
										eding		
	the legal speed limit set in the tachograph.											
			over spee	d								
	<u>.</u>		er speed									
	Driv	er 1 card (I	•		V							
			rd not pres	ent								
	Det		d present	(D0 D)	0 D4 D0) Ol-	. d: t	مالا الا	luis ca u			
		er 1 time re		` '	•	,			iriver			
	арр	roaches or 0000 >		vorking	ume im	iiis (o	i otner i	imis).				
			15 min bef	15 h								
			4.5 h reach									
			15 min bef									
	Q		9 h reache									
-9	7		15 min bef									
			16h reache									
1		1110 = 1		. 								
		_	not availab	le								
L												

									псер.	// www.acbs.com					
#41															
		B7	B6	B5	B4	B3		B2	B1	B0					
		NOT	-	Drive	r 2	Driver 2	2 tim	e related sta	te (B3,B2,E	31,B0)。					
		USE	D	card		GIndica	GIndicates if the driver approaches or exceeds								
				(B5,E	34)	working time limits (or other limits).									
				00 =	Card	0000 =	0000 = normal								
				not p	resent	0001 =	15 r	min bef. 4.5 h	า						
				01=0	Card	0010 = 4.5 h reached									
				prese	ent	0011 = 15 min bef. 9 h									
						0100 =	9 h	reached							
						0101 =	15 r	min bef. 16 h	• 4						
						0110 = 16h reached									
						1110 = Error									
						1111 = not available									
#42															
#42	B7		В6		35	B4	В3	B2	B1	B0					
		ectio	_		achgra			ndling	System						
		icato			erforma			ormation	Oystern	event					
					37,B6)。	- 10									
				Forwa		100									
			01 = 1	Rever	se										
	Tacl	ngrap	h per	forma	nce (B	5,B4)									
			00 = 1	Norma	l perfor	rmance									
			01 –	Perfor	mance	analysis									
	Han	dling	infor	mation	(B3,B2	2)									
					_	nformatio	n								
	4	4			•	mation									
	System event (B1,B0)														
2	00 = no tachogr. Event														
" 1	<u> </u>	01 = tachogr. Event													
#43~	Tachogr. vehicle speed 1/256 km/h Bit gain Speed= ((VS2*256)+VS1)/256														
#44	+ -		(VS2	∠ɔɒ)+	·v51)/2	.oc									
#43 #44	VS1 VS2														
#44	v 32														



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Engine Coolant Temperature(ECT), -40 to 210 deg C
ECT=data-40 °C
Engine Turbocharger Boost Pressure(ETBP), 2 kPa/bit, 0~500 KPA ETPB=data *2 (KPA)
Engine Intake Manifold 1 Temperature(EIMT) , -40 to 210 deg C EIMT=data-40 $^\circ\!\mathbb{C}$
Bit7,6 Anti-Lock Braking (ABS) Active. G
00 - ABS passive but installed
01 - ABS active
10 – Reserved
11 - Not available
Bit5~Bit0: Resvered.
Brake Pedal Position (BPP), 0.4 %/bit, 0~100% BPP=data*0.4 (%)
Parking and/or Trailer Air Pressure(PTAP), 8 kPa/bit
PTAP=data *8 (KPA)
Service Brake Air Pressure Circuit #1 (SBAPC1), 8 kPa/bit
SBAPC1=data*8 (KPA)
Service Brake Air Pressure Circuit #2 (SBAPC2), 8 kPa/bit
SBAPC2=data*8 (KPA)
Parking Brake Switch
00 = Parking brake not set
01 = Parking brake set
Bit 1 ,Bit 0: Diagnostics supported
00 = diagnostics is not supported
01 = diagnostics is supported
10 = reserved
11 = don't care
Bit 3 ,Bit 2: Requests supported
00 = request is not supported
01= request is supported
10 = reserved
11 = don't care
Bit4~Bit7:Resvered



#55~	Ambient Air Temperature: Temperature of air surrounding vehicle.								
#56	AAT=(AATH* 256+AATL)*0.03125 -273 deg C								
	#55: AATL								
	#56: AATH								
#57	Door Control 1:								
	Bit 7,Bit6: Status 2 of doors								
	00 = all bus doors disabled								
	01 = at least 1 bus door enabled								
	10 = error								
	11 = not available								
	Bit 5, Bit4: Ramp/Wheel chairlift								
	00 = inside bus								
	01 = outside bus								
	10 = Error								
	11 = not available								
	Bit 3,2,1,0 : Position of doors								
	0000 = at least 1 door is open								
	0001 = closing last door								
	0010 = all doors closed								
	1110 = Error								
	1111 = not available								
#58~	Door Control 2, #58~#65								
#65	Lock Status:								
	locked → doors cannot be operated by the driver or a passenger								
	unlocked → door may be operated by the driver or a passenger								
	Open Status:								
	closed → door is completely closed								
	open →door is not completely closed								
	Enable Status:								
	disabled → door cannot be opened by a passenger								
2	enabled →→ door can be opened by a passenger								



							пср.,	//www.atbs.com	
#58	D.7	DC	DE	D4	DO	DO	D4	DO	
	B7	B6	B5	B4	B3	B2	B1	B0	
		t 6: Lock			•	2: Open	Bit 1,Bit		
	Status D		Enable	Status	Status E		Status D		
	00 = Un		Door 1		00 = Clo		00 = Un		
	01 = Loc		00 = Dis		01 = Op		01 = Loc		
	10 = Err		01 = En:		10 = Err		10 = Err		
	11 = No		10 = Error		11 = Not		11 = No		
	available	Э	11 = Not		available	Э	available	9	
			available						
#59							^	-	
	B7	B6	B5	B4	B3	B2	B1	B0	
	Bit 7, Bit	t 6:	Bit 5, Bit	t 4: Lock	Bit 3, Bit 2:		Bit 1, Bit 0:		
	Open St	tatus	Status Door 3		Enable Status		Open Status		
	Door 3		00 = Un	locked	Door 2	17	Door 2		
	00 = Closed		01 = Lo	cked	00 = Dis	abled	00 = Clo	sed	
	01 = Op	en	10 = Error		01 = En	abled	01 = Op	en	
	10 = Err	or	11 = Not		10 = Err	or	10 = Err	or	
	11 = No	t	available		11 = No	11 = Not		t	
	available	е			available		available		
			10						
				Y					
#60			<u>U'</u>			T			
	B7	B6	B5	B4	B3	B2	B1	B0	
	Bit 7, Bit	t 6:	Bit 5, Bit	t 4:	Bit 3, Bi	t 2: Lock	Bit 1, Bit	: 0:	
	Enable	Status	Open St	atus	Status D	Ooor 4	Enable S	Status	
	Door 4	2	Door 4		00 = Un	locked	Door 3		
	00 = Dis	abled	00 = Clc	sed	01 = Lo	cked	00 = Dis	abled	
-9	01 – En:	abled	01 = Op	en	10 = Err	or	01 = Ena	abled	
	10 = Err	or	10 = Err	or	11 = Not		10 = Err	or	
1	11 = No	t	11 = No	t	available	Э	11 = No	t	
	available	е	available	Э			available		



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#61		T		T	T	T			
	B7	B6	B5	B4	B3	B2	B1	В0	
	Bit 7, Bit	t 6: Lock	Bit 5, Bit	t 4:	Bit 3, Bit	t 2:	Bit 1, Bit	t 0: Lock	
	Status D	Door 6	Enable	Status	Open St	tatus	Status D	oor 5	
	00 = Un	locked	Door 5		Door 5		00 = Un	locked	
	01 = Lo	cked	00 = Dis	abled	00 = Clo	sed	01 = Lo	cked	
	10 = Err	or	01 = En	abled	01 = Op	en	10 = Error		
	11 = No	t	10 = Err	or	10 = Error		11 = No	t	
	available	е	11 = Not		11 = No	t	available	e	
			available		available				
#62									
	B7	B6	B5	B4	B3	B2	B1	В0	
	Bit 7, Bi	t 6:	Bit 5, Bit	t 4: Lock	Bit 3, Bit	t 2:	Bit1, Bit 0: Open		
	Open St	tatus	Status D	Ooor 7	Enable	Status	Status Door 6		
	Door 7 00 = Closed		00 = Un	locked 🔺	Door 6	Y	00 = Clo	sed	
			01 = Lo	cked	00 = Dis	abled	01 = Op	en	
	01 = Op	en	10 = Error		01 = En:	abled	10 = Error		
	10 = Err	or	11 = Not		10 = Err	or	11 = Not		
	11 = No	t	available		11 = No	t	available	Э	
	available	е			available	Э			
#63		0							
	B7 /	B6	B5	B4	B3	B2	B1	B0	
	Bit 7, Bi	t 6:	Bit 5, Bit	t 4:	Bit 3, Bit	t 2: Lock	Bit1, Bit	0:	
	Enable	Status	Open St	tatus	Status D	Door 8	Enable	Status	
C	Door 8		Door 8		00 = Un	locked	Door 7		
2	00 = Dis	sabled	00 = Clo	sed	01 = Loc	cked	00 = Dis	abled	
	01 = En	abled	01 = Op	en	10 = Err	or	01 = En	abled	
,	10 = Err	or	10 = Err	or	11 = No	t	10 = Err	or	
	11 = No	t	11 = No	t	available	Э	11 = Not		
	available	е	available	Э			available		



	1							
#64	_	l	I	I	T		Г <u>. </u>	
	B7	B6	B5	B4	B3	B2	B1	B0
		t 6: Lock			Bit 3, Bi		Bit1, Bit 0: Lock	
	Status D		Enable	Status	Open Status		Status Door 9	
	00 = Un	locked	Door 9		Door 9		00 = Unlocked	
	01 = Lo	cked	00 = Dis	abled	00 = Clo	sed	01 = Locked	
	10 = Error		01 = Enabled		01 = Open		10 = Err	or
	11 = Not		10 = Err	or	10 = Err	10 = Error		t
	available	е	11 = Not		11 = No	t	available	e
			available		available			C.
						• ^		
#65		1	1	T	T	1	Y	
	B7 B6 B5 B4				B3	B2	B1	B0
	Bit 3, Bi	t 2:	Bit1, Bit	Bit1, Bit 0: Open				
	Enable	Status	Status Door 10 00 = Closed					
	Door 10)						
	00 = Dis	sabled	01 = Op	en 🔺	(,0			
	01 = En	abled	10 = Err	or 🕟				
	10 = Err	or	11 = No	t 🕔				
	11 = No	t	available	Э				
	available	е	~					
#66	Time / Dr	ato:	CA					
#66~ #71	Time / Da		- * A 25					
#71	#66 : Sed #67 : Min							
	#68 : Hou	urs⊨data						
	#69 : Mo	nth=data						
	#70 : Day	y=data * ().25					
0	#71 : Yea	ar=data-1	985 (19	85 to 223	5 years)			



							http://	www.atbs.com	
#72	Alternato	or Status							
	B7	В6	B5	B4	В3	B2	B1	В0	
	Bit 7,	Bit6:	Bit 5, Bi	t4:	Bit 3, Bit	t 2:	Bit 1, Bi	t 0:	
	Altern	ator	Alternat	or	Alternate	or	Alternator		
	Status	s 4	Status 3	3	Status 2		Status 1		
	00 = r	not	00 = not	t	00 = not		00 = not	t	
	charg	ing	charging	9	charging	9	charging	g	
	01 = 0	charging	01 = cha	arging	01 = cha	arging	01 = cha	arging 📗	
	$10 = \epsilon$	error	10 = err	10 = error		or	10 = err	or	
	11 = r	not	11 = not	t	11 = not		11 = not		
	availa	ble	available	е	available	Э	availabl	е	
						\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \			
#73	Selected Gear – data -125negative gear are reverse gears								
#13		Selected Gear = data -125negative gear are reverse gears 00000000 = neutral							
	11111011 = park								
#74	Current Gear=data-125								
negative gear are reverse gears									
	00000000 = neutral								
	1111101	1 = park		100	/				
#75~		ressure Fr	ont Axle L	eft					
#76	Informati	ion of the p	ressure o	the air s	uspensio	n bellow a	at the left	side of the	
	front axle								
	Pressure= ((BPFAL2*256)+BPFAL1)* 0.1 ,KPA								
#75	BPFAL1								
#76	BPFAL2	, ()							
#77~	Bellow P	ressure Fr	ont Axle R	Right					
#78	Informati	ion of the p	ressure o	f the air s	uspensio	n bellow a	at the left	side of the	
	front axle	9							
	Pressure	e= ((BPFAF	R2*256)+E	3PFAR1)*	0.1 ,KPA	١			
#77	BPFAR1								
#78	BPFAR2								
#79~	Bellow P	ressure Re	ear Axle L	eft					
#80	Informati front axle		ressure o	f the air s	uspensio	n bellow a	at the left	side of the	
	Pressure	e= ((BPRAI	_2*256)+B	PRAL1)*	0.1 ,KPA				
I			·	•					



	nttp://www.atbs.com.
#79	BPRAL1
#80	BPRAL2
#81~	Bellow Pressure Rear Axle Right
#82	Information of the pressure of the air suspension bellow at the left side of the
	front axle
	Pressure= ((BPRAR2*256)+BPRAR1)* 0.1 ,KPA
#81	BPRAR1
#82	BPRAR2
#83~	Driver's Identification (Driver 1 & Driver 2 identification)
#90	#83 #84 #85 #86 #87 #88 #89 #90
	The driver ID is only available if a digital tachograph is present
#91~	Engine Fuel Rate (EFR). Amount of fuel consumed by engine per liter of hour.
#92	EFR=(EFR2*256+EFR1)* 0.05 , L/h
	Data Range: 0 to 3,212.75 L/h
#91	EFR1
#92	EFR2
#93~	Engine Instantaneous Fuel Economy(EIFE). Current fuel economy at current
#94	vehicle velocity.
	EIFE=(EIFE2*256+EIFE1) / 512, km/L
	Data Range: 0 to 125.5 km/L
#93	EIFE1
#94	EIFE2
#95~	FMS Tell Tale Status
#102	#95 #96 #97 #98 #99 #100 #101 #102
	The Tell Tale Status information is derived from information displayed to the
	driver's dashboard.
#95	Bit 3,2,1,0. Telltale Block ID
	Bit 7,6,5,4: Telltale Status 1
	000 = off
	1001 = Cond. Red
	1010 = Cond. Yellow
1	1011 = Cond. Info
	1100-1110 = Reserved
	1111 = not available

			1. //	
#96	Bit 3,2,1,0: Telltale Status 2			
	1000 = off			
	1001 = Cond. Red			
	1010 = Cond. Yellow			
	1011 = Cond. Info			
	1100-1110 = Reserved			
	1111 = not available			
	Bit 7,6,5,4: Telltale Status 3			
	1000 = off			
	1001 = Cond. Red			•
	1010 = Cond. Yellow			
	1011 = Cond. Info	• ^		
	1100-1110 = Reserved		y	
	1111 = not available			
‡ 97	Bit 3,2,1,0: Telltale Status 4			
	1000 = off			
	1001 = Cond. Red	,		
	1010 = Cond. Yellow			
	1011 = Cond. Info			
	1100–1110 = Reserved			
	1111 = not available			
	Bit 7,6,5,4: Telltale Status 5			
	1000 = off			
	1001 = Cond. Red			
	1010 = Cond. Yellow			
	1011 = Cond. Info			
	1100-1110 = Reserved			
	1111 = not available			
	60			
~				
U,				
*				

4 98	Bit 3,2,1,0: Telltale Status 6		
	1000 = off		
	1001 = Cond. Red		
	1010 = Cond. Yellow		
	1011 = Cond. Info		
	1100-1110 = Reserved		
	1111 = not available		
	Bit 7,6,5,4: Telltale Status 7		
	1000 = off		
	1001 = Cond. Red		•
	1010 = Cond. Yellow		
	1011 = Cond. Info	• ()	•
	1100-1110 = Reserved		
	1111 = not available		
<i>‡</i> 99	Bit 3,2,1,0: Telltale Status 8		
	1000 = off		
	1001 = Cond. Red	Y	
	1010 = Cond. Yellow		
	1011 = Cond. Info		
	1100–1110 = Reserved		
	1111 = not available		
	Bit 7,6,5,4: Telltale Status 9		
	1000 = off		
	1001 = Cond. Red		
	1010 = Cond. Yellow		
	1011 = Cond. Info		
	1100-1110 = Reserved		
	1111 = not available		
	00		
~			
*			

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J.D.C	
100	
100	•
10	
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	•
#102	Bit 3,2,1,0: Telltale Status 14
	1000 = off
	1001 = Cond. Red
	1010 = Cond. Yellow
	1011 = Cond. Info
	1100-1110 = Reserved
	1111 = not available
	Bit 7,6,5,4: Telltale Status 15
	1000 = off
	1001 = Cond. Red
	1010 = Cond. Yellow
	1011 = Cond. Info
	1100-1110 = Reserved
	1111 = not available
#103	Battery Voltage (BV), = (data+100)/10 (v)
#104	Engine Oil Filter Differential Pressure
	EODP= data*0.5 (kPa)
#105	YUTONG Bus, speed: 0~255 km/h
~	



J1708 Packaged Messages Protocol

Byte 17: #15

Byte 18: #16 (

Byte 19: #17

Byte 21: 0X0D

Byte 22: 0X0A

Byte 20 Check sum

= Byte2 + ..+Byte 19

S	Once AT1708 SLEEP,	it can wake it up.	
	Start to send data by 3	B packing, response HE	X CODE
	Packing 1:	Packing 2:	Packing 3:
	Byte 0: " @" , 0x40;	Byte 0: " @" , 0x40;	Byte 0: " @" , 0x40;
	Byte 1: 4	Byte 1: 5	Byte 1: 6
	Byte 2: #00	Byte 2: #18	Byte 2: #36
	Byte 3: #01	Byte 3: #19	Byte 3: #37
	Byte 4: #02	Byte 4: #20	Byte 4: #38
	Byte 5: #03	Byte 5: #21	Byte 5: #39
	Byte 6: #04	Byte 6: #22	Byte 6: #40
	Byte 7: #05	Byte 7: #23	Byte 7: #41
	Byte 8: #06	Byte 8: #24	Byte 8; #42
	Byte 9: #07	Byte 9: #25	Byte 9: #43
	Byte 10: #08	Byte 10: #26	Byte 10: #44
	Byte 11: #09	Byte 11: #27	Byte 11: #45
	Byte 12: #10	Byte 12: #28	Byte 12: #46
	Byte 13: #11	Byte 13: #29	Byte 13: #47
	Byte 14: #12	Byte 14: #30	Byte 14: #48
	Byte 15: #13	Byte 15: #31	Byte 15: #49
	Byte 16: #14	Byte 16: #32	Byte 16: #50

Byte 17: #33

Byte 18: #34

Byte 19: #35

Byte 21: 0X0D

Byte 22: 0X0A

Byte 20: Check sum

= Byte2 + ..+Byte 19

Byte 17: #51

Byte 18: #52

Byte 19: #53

Byte 21: 0X0D

Byte 22: 0X0A

Byte 20:Check sum

= Byte2 + ..+Byte 19

Packing 4:	Packing 5:	
Byte 0: " @"	Byte 0: " @"	
Byte 1: 7	Byte 1: 8	
Byte 2:a	Byte 2:a	
Byte 3:b	Byte 3:b	
Byte 4:c	Byte 4:c	
Byte 5:a	Byte 5:a	
Byte 6:b	Byte 6:b	
Byte 7:c	Byte 7:c	
Byte 8:a	Byte 8:a	
Byte 9:b	Byte 9:b	
Byte 10:c	Byte 10:c	
Byte 11:a	Byte 11:a	
Byte 12:b	Byte 12:b	
Byte 13:c	Byte 13:c	
Byte 14:a	Byte 14:a	
Byte 15:b	Byte 15:b	
Byte 16:c	Byte 16:c	
Byte 17: Check sum	Byte 17: Check sum	
= Byte2 ++Byte 21	= Byte2 ++Byte 21	
Byte 18: 0X0D	Byte 18: 0X0D	
Byte 19: 0X0A	Byte 19: 0X0A	
0.1		
a — MID		
b—SID or PID of a sta	andard diagnostic code) .
Diagnostic code o	haracter.	
	mode identifier (FMI)	
	command respond that	data are ASCII code

speed=(SHB*256+SLB)/256

Speed Low Byte (SLB)

Speed High Byte (SHB)

#00

#01



	nttp://www.atbs.cor
#02	Cruise Control Status—State of the vehicle velocity control system
	(active, not active), and system switch
	(on, off), for various system operating modes.
	Bit 8: cruise mode 1=active/0=not active
	Bit 7: clutch switch 1=on/0=off
	Bit 6: brake switch 1=on/0=off
	Bit 5: accel switch 1=on/0=off
	Bit 4: resume switch 1=on/0=off
	Bit 3: coast switch 1=on/0=off
	Bit 2: set switch 1=on/0=off
	Bit 1: cruise control switch 1=on/0=off
#03	Brake Stroke Status—Identifies the current state of the vehicle
	foundation brakes.
	Bit 8-5: Axle number 1 to 16 (represented as 0 to 15)
	Bit 4-2: Brake status/Stroke adjustment
	000 = OK
	001 = Out of adjustment
	010 = Delay brake return
	011 = Brake pads worn
	100 = Delayed brake application
	101 = Reserved
	110 = Error
	111 = Not available
	Bit 1: 1 = Left wheel, 0 = Right wheel
#04	Percent Accelerator Pedal Position(PAPP)—Ratio of actual
	accelerator pedal position to maximum pedal position.
	Maximum Range: 0.0 to 102.0%
	PAPP Data* 0.4
#5~	Total Fuel Used (Natural Gas)—Accumulated amount of fuel used
#8	during vehicle operation.
65	Maximum Range: 0.0 to 2 147 483 648 kg (0.0 to 4 724 464 025 lb)
	TFU=((ETF4*256*256*256)+(ETF3*256*256)+(ETF2*256)+ETF1)*0.4
y	73
#05	Engine Total Fuel used 0473 L / Bit gain , ETF1
#06	Engine Total Fuel used 0,473 L / Bit gain , ETF2
#07	Engine Total Fuel used 0,473 L / Bit gain , ETF3
#08	Engine Total Fuel used 0,473 L / Bit gain , ETF4



#09	Fuel Level—Ratio of volume of fuel to the total volume of the primary
	fuel storage container.
	Maximum Range: 0.0 to 127.5%
	Fuel Level=FL * 0.5 %
#10~	Engine Speed (RPM)—Rotational velocity of crankshaft.
#11	Maximum Range: 0.0 to 16383.75 rpm
	RPM= (RH*256+ RL)* 0.25
#10	RPM Low byte, RL
#11	RPM High byte, RH
#12	Engine Oil Pressure(EOP)—Gage pressure of oil in engine
	lubrication system as provided by oil pump.
	Maximum Range: 0.0 to 879.0 kPa (0.0 to 127.5 lbf/in2)
	EOP=data * 3.45 KPA
#13	Throttle Position(TP)—The position of the valve used to regulate the
	supply of a fluid, usually air or fuel/air mixture, to an engine. 0%
	represents no supply and 100% is full supply.
	Maximum Range: 0.0 to 102.0%
	TP= data * 0.4%
#14	Cargo Weight—The force of gravity of freight carried.
	Maximum Range: 0.0 to 1 166 056.9 N (0.0 to 262 140.0 lbf)
	(Low Byte),AWL
#15	(High Byte), AWH
	Weight=(AWH*256+AWL)* 17.792 N
#16	Total Engine Hours (TEH)—Accumulated time of operation of engine.
	Maximum Range: 0.0 to 214 748 364.8 h
	TEH=((EH4*256*256*256)+(EH3*256*256)+(EH2*256)+EH1)*0.05
#16	Engine total hours of Operation, EH1
#17	Engine total hours of Operation, EH2
#18	Engine total hours of Operation, EH3
#19	Engine total hours of Operation, EH4
#20~	Vehicle Identification Number—Vehicle Identification Number (VIN)
#27	as assigned by the vehicle manufacturer.
#85~	Vehicle identification number, aabbccddeeffgghh
#96	"ATI" command can show max 20 character VIN
#20	aa
#21	bb



#20
#22 cc
#23 dd
#24 ee
#25 ff
#26 gg
#27 hh
#28 PTO Engagement Control Status
PTO output status:
Bits 8-5: Reserved—all bits set to 1
Bits 4-3: PTO #2 engagement actuator status
Bits 2-1: PTO #1 engagement actuator status
NOTE—Each status will be described using the following
nomenclature:
00 Off/Not active
01 On/Active
10 Error condition
11 Not available
#29~ Average Fuel Economy
#30 AFE=((AFE2*256)+AFE1) *1.660 72 x 10-3 km/L
#29 AFE1
#30 AFE2
#31~ Mass Air Flow—Mass air flow measured at the fresh air intake
#32 MAF=((MAF2*256)+MF1)* 0.125 kg/min
#31 MAF 1
#32 MAF2
#33~ Total Vehicle Distance(TVD)—Accumulated distance travelled by
#36 vehicle during its operation.
Maximum Range: 0.0 to 691489743 km (0.0 to 429 496 729.5 mi)
Bit Resolution: 0.161 km (0.1 mi)
D=((D4*256*256*256)+(D3*256*256)+(D2*256)+D1)*0.161 (KM)
If vehicle dose not provide TVD, AT1708 replace the information with
the calculated distance, deviation is 0.5%, The first time connection
AT1708 please command ATR to clear distance memory.
#33 D1
#34 D2
#35 D3



	nttp://www.atos.col
#36	D4
#37~	Fuel Rate (Instantaneous)—Amount of fuel consumed by engine per
#38	unit of time.
	Maximum Range: 0.0 to 1.076 65 L/s
	FR=(V2*256+V1) * 16.428 x 10 6 L/s
#37	V1
#38	V2
#39~	Total Vehicle Hours(TVH)—Accumulated time of operation of
#40	vehicle.
	Maximum Range: 0.0 to 214 748 364.8 h
	TVH=((H4*256*256*256)+(H3*256*256)+(H2*256)+H1)*0.05 (H)
#39	H1
#40	H2
#41	H3
#42	H4
#43	Reserved
#44	Percent Engine Load(PEL)—Ratio of current output torque to
	maximum torque available at the current engine
	speed.
	Maximum Range: 0.0 to 127.5%
	PEL=data * 0.5%
#45	Engine Coolant Temperature(ECT) ,
	Maximum Range: 0.0 to 255.0 F
	ECT= data °F
#46	Boost Pressure (BP)—Gage pressure of air measured downstream
	on the compressor discharge side of the turbocharger.
	Maximum Range: 0.0 to 219.8 kPa (0.0 to 31.875 lbf/in2)
	PB=data * 0.862 (KPA)
#47	Intake Manifold Temperature (IMT)—Temperature of precombustion
	air found in intake manifold of engine air supply system.
0	Maximum Range: 0.0 to 255.0 F
	IMT=data°F
#48	ABS Control Status
	Bits 8-7: ABS off-road function switch
	Bits 6-5: ABS retarder control
	Bits 4-3: ABS brake control
	Bits 2-1: ABS warning lamp
	35



	IIIIp.//www.atus.c
	00 Off/Not active
	01 On/Active
	10 Error condition
	11 Not available
#40	Parties Puelo Cuitat Otatus Identifies the state (active finestics) a
#49	Parking Brake Switch Status—Identifies the state (active/inactive) of
	the parking brake switch.
	Bit 8: 1=active/0=inactive
	Bits 7-1: Undefined
#50	Brake Application Pressure (BAP)
	Maximum Range: 0.0 to 1055 kPa (0.0 to 153.0 lbf/in2)
	BAP=data *4.14 kPa
#51	Brake Primary Pressure (BPP)—Gage pressure of air in the primary
	or supply side, of the air brake system.
	Maximum Range: 0.0 to 1055 kPa (0.0 to 153.0 lbf/in2)
	BPP=data* 4.14 (KPA)
#52	Brake Secondary Pressure—Gage pressure of air in the secondary,
	or service side, of the air brake system.
	Maximum Range: 0.0 to 1055 kPa (0.0 to 153.0 lbf/in2)
	BPP=data* 4.14 (KPA)
#53	Road Speed Limit Status :State (active or not active) of the system
	used to limit maximum vehicle velocity.
	Bit 8: 1=active/0=not active
	Bits 7-1: Undefined
	. 01/
~``	

J1708 Command Example:

1.) >AT#h,

Response: "Data1" "Data2" "H0D" "H3E" by ASCII CODE.

EX1:

AT#1, to get vehicle speed, if speed is 255,

Display,

FF

>

(H46,H46, H0D,H3E).

2.) Trouble code:

40 37 80 8 CA 80 A AA 80 B AA 80 C AA 80 1 AA FC D A

Trouble code:

MID 128(H80)

PID 8(H8)

Diagnostic code character (CA), FM= A, bit4~bit1

2A	31	47	31	4A	46	32	37	57	38	47	4A	31	37	38	32	32	37	0	0	0	27	0D	0A
	1	G	1	J	F	2	7	W	8	G	ک	1	7	8	2	2	7				CS		

Country Manufactured	1	U.S.A.(1 or 4), Canada (2), Mexico (3), Japan (J), Korea (K), England (S), Germany (W), Italy (Z)
Manufacturer	G	
Vehicle Type	1	
Vehicle Features	JF27W	
Accuracy Check Digit	8	
Model Year	G	1988 (J), 1989 (K), 1990 (L), 1991 (M), 1992 (N), 1993 (P), 1994 (R), 1995 (S), 1996 (T), 1997(V), 1998 (W), 1999 (X), 2000 (Y),2001(1), 2002 (2), 2003 (3)
Production Plant	J	
Sequential Number	178227	The sequence of the vehicle for production as it rolled of the manufacturers assembly line.