Module 7: Solutions to recommended Exercises TMA4268 Statistical Learning V2021

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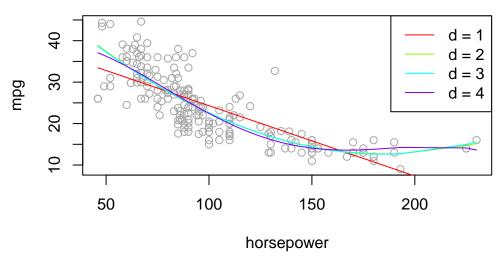
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Problem 1

The code below performs polynomial regression of degree 1, 2, 3 and 4. The function sapply() is an efficient for-loop. We iterate over all degrees to plot the fitted values and compute the test error. Finally we plot the test error for each polynomial degree.

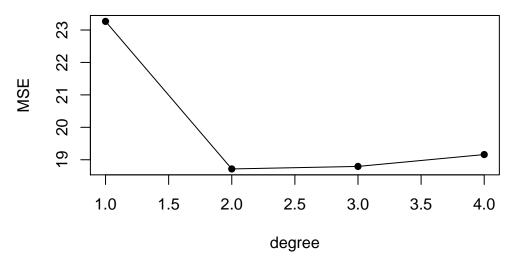
```
library(ISLR)
# extract only the two variables from Auto
ds = Auto[c("horsepower", "mpg")]
n = nrow(ds)
# which degrees we will look at
deg = 1:4
set.seed(1)
# training ids for training set
tr = sample.int(n, n/2)
# plot of training data
plot(ds[tr, ], col = "darkgrey", main = "Polynomial regression")
# which colors we will plot the lines with
co = rainbow(length(deg))
# iterate over all degrees (1:4) - could also use a for-loop here
MSE = sapply(deg, function(d) {
    # fit model with this degree
   mod = lm(mpg ~ poly(horsepower, d), ds[tr, ])
    # add lines to the plot - use fitted values (for mpg) and horsepower from
    # training set
   lines(cbind(ds[tr, 1], mod$fit)[order(ds[tr, 1]), ], col = co[d])
    # calculate mean MSE - this is returned in the MSE variable
   mean((predict(mod, ds[-tr, ]) - ds[-tr, 2])^2)
})
# add legend to see which color corresponds to which line
legend("topright", legend = paste("d =", deg), lty = 1, col = co)
```

Polynomial regression



```
# plot MSE
plot(MSE, type = "o", pch = 16, xlab = "degree", main = "Test error")
```

Test error

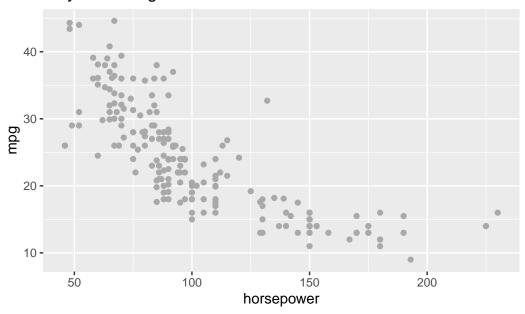


The same solution using ggplot is shown below.

```
# solution with ggplot
library(ISLR)
library(ggplot2)
# extract only the two variables from Auto
ds = Auto[c("horsepower", "mpg")]
n = nrow(ds)
# which degrees we will look at
deg = 1:4
set.seed(1)
# training ids for training set
tr = sample.int(n, n/2)
# plot of training data
ggplot(data = ds[tr, ], aes(x = horsepower, y = mpg)) + geom_point(color = "darkgrey") +
```

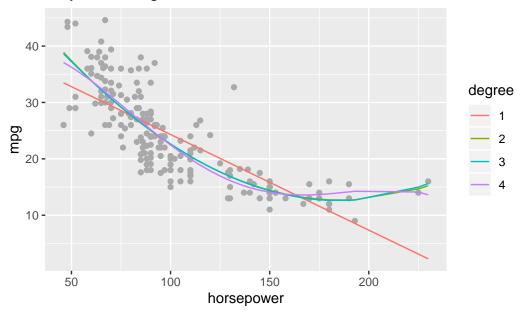
```
labs(title = "Polynomial regression")
```

Polynomial regression



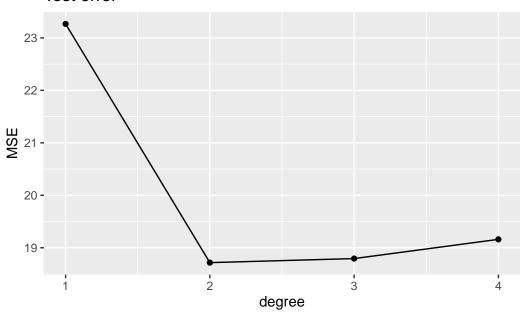
```
# iterate over all degrees (1:4) - could also use a for-loop here
dat = c() #make a empty variable to store predicted values
for (d in deg) {
    # fit model with this degree
   mod = lm(mpg ~ poly(horsepower, d), ds[tr, ])
    # dataframe of predicted values - use fitted values (for mpg) and horsepower
    # from training set and add column (factor) for degree
   dat = rbind(dat, data.frame(horsepower = ds[tr, 1], mpg = mod$fit, degree = as.factor(rep(d,
        length(mod$fit)))))
    \# calculate mean MSE - this is returned in the MSE variable
   MSE[d] = mean((predict(mod, ds[-tr, ]) - ds[-tr, 2])^2)
}
# plot fitted values for different degrees
ggplot(data = ds[tr, ], aes(x = horsepower, y = mpg)) + geom_point(color = "darkgrey") +
   labs(title = "Polynomial regression") + geom_line(data = dat, aes(x = horsepower,
   y = mpg, color = degree))
```

Polynomial regression



```
# plot MSE
MSEdata = data.frame(MSE = MSE, degree = 1:4)
ggplot(data = MSEdata, aes(x = degree, y = MSE)) + geom_line() + geom_point() +
    labs(title = "Test error")
```

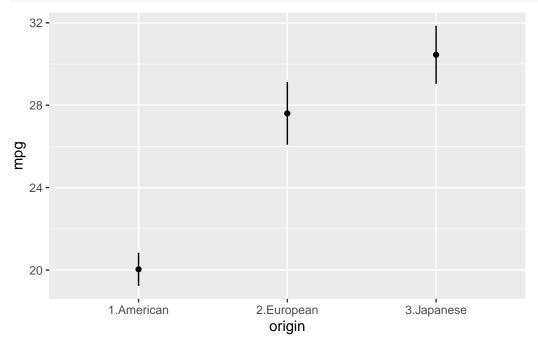
Test error



Problem 2

We use factor(origin) for conversion to a factor variable. The function predict(..., se = T) gives fitted values with standard errors.

```
attach(Auto)
# fit model
```



Problem 3

The request is a design matrix for a natural spline with X = year and one knot $c_1 = 2006$. The boundary knots be the extreme values of year, that is $c_0 = 2003$ and $c_2 = 2009$. A general basis for a natural spline is

$$b_1(x_i) = x_i$$
, $b_{k+2}(x_i) = d_k(x_i) - d_K(x_i)$, $k = 0, \dots, K - 1$,
$$d_k(x_i) = \frac{(x_i - c_k)_+^3 - (x_i - c_{K+1})_+^3}{c_{K+1} - c_k}.$$

In our case we have one internal knot, that is K = 1. Thus, k takes only the value 0. The two basis functions are

$$\begin{aligned} b_1(x_i) &= x_i, \\ b_2(x_i) &= d_0(x_i) - d_1(x_i) \\ &= \frac{(x_i - c_0)_+^3 - (x_i - c_2)_+^3}{c_2 - c_0} - \frac{(x_i - c_1)_+^3 - (x_i - c_2)_+^3}{c_2 - c_1} \\ &= \frac{1}{c_2 - c_0} (x_i - c_0)_+^3 - \frac{1}{c_2 - c_1} (x_i - c_1)_+^3 + \left(\frac{1}{c_2 - c_1} - \frac{1}{c_2 - c_0}\right) (x_i - c_2)_+^3 \\ &= \frac{1}{6} (x_i - 2003)_+^3 - \frac{1}{3} (x_i - 2006)_+^3 + \frac{1}{6} (x_i - 2009)_+^3. \end{aligned}$$

The design matrix is obtained by $\{\mathbf{X}_2\}_{ij} = b_j(x_i)$. We can simplify the second basis function more by using the fact that the boundary knots are the extreme values of x_i , that is $2003 \le x_i \le 2009$, and thus $\frac{1}{6}(x_i - 2009)_+^3 = 0$. Thus,

$$b_2(x_i) = \frac{1}{6}(x_i - 2003)^3 - \frac{1}{3}(x_i - 2006)_+^3.$$

Problem 4

The matrix X is obtained by using cbind() to join an intercept, a cubic spline, a natural cubic spline and a factor.

```
library(ISLR)
attach(Wage)
# install.packages('gam')
library(gam)
# Write a couple of functions first, which will be used to produce the
# components of the design matrix We write separate functions to generate
# X_1, X_2 and X_3 (the three components of the model) X_1: The function
# mybs() generates basis functions for the cubic spline
mybs = function(x, knots) cbind(x, x^2, x^3, sapply(knots, function(y) pmax(0,
   x - y)^3)
# X_2: The function myns() generates basis functions for the natural cubic
# spline; d() is a helper function
d = function(c, cK, x) (pmax(0, x - c)^3 - pmax(0, x - cK)^3)/(cK - c)
myns = function(x, knots) {
   kn = c(min(x), knots, max(x))
   K = length(kn)
    sub = d(kn[K - 1], kn[K], x)
    cbind(x, sapply(kn[1:(K-2)], d, kn[K], x) - sub)
}
\# X_3: The function myfactor() generates the dummy-basis functions for a
# factor covariate, building on the R-function model.matrix()
myfactor = function(x) model.matrix(~x)[, -1]
# Once these functions are prepared, we can generate the model matrix X =
# (1, X_1, X_2, X_3) as a one-liner
X = cbind(1, mybs(age, c(40, 60)), myns(year, 2006), myfactor(education))
```

We have now created a model matrix \mathbf{X} "by hand". The thing we wanted to illustrate with this exercise is

that this hand-made matrix does not correspond to the internal representation of the model matrix that we would directly get using the gam() function:

[1] TRUE

The fitted values myhat and yhat are equal. Both the design matrices \mathbf{X} and the coefficients $\hat{\beta}$ differs, but $\mathbf{X}\hat{\beta}$ are the same. How can this be? Well, just as there were several ways to represent polynomials, there are also many equivalent ways to represent splines or factor variables using different choices of basis functions.

Problem 5

Fit additive model and commenting:

```
library(gam)
# first set origin as a factor variable
Auto$origin = as.factor(Auto$origin)
# aam model
fitgam = gam(mpg ~ bs(displacement, knots = c(290)) + poly(horsepower, 2) +
    weight + s(acceleration, df = 3) + origin, data = Auto)
# plot covariates
par(mfrow = c(2, 3))
plot(fitgam, se = TRUE, col = "blue")
# summary of fitted model
summary(fitgam)
##
## Call: gam(formula = mpg ~ bs(displacement, knots = c(290)) + poly(horsepower,
       2) + weight + s(acceleration, df = 3) + origin, data = Auto)
##
## Deviance Residuals:
##
       Min
                  1Q
                      Median
                                    3Q
                                            Max
## -11.5172 -2.3774 -0.2538 1.7982 15.9994
##
## (Dispersion Parameter for gaussian family taken to be 14.1747)
##
       Null Deviance: 23818.99 on 391 degrees of freedom
## Residual Deviance: 5372.203 on 378.9999 degrees of freedom
## AIC: 2166.599
## Number of Local Scoring Iterations: 2
##
## Anova for Parametric Effects
```

```
Df Sum Sq Mean Sq F value
##
## bs(displacement, knots = c(290))
                                             4 16705.2 4176.3 294.6301 < 2.2e-16
## poly(horsepower, 2)
                                                 1283.6
                                                           641.8
                                                                    45.2786 < 2.2e-16
## weight
                                                  318.9
                                                           318.9
                                                                    22.4970 2.985e-06
                                             1
## s(acceleration, df = 3)
                                                  128.1
                                                            128.1
                                                                     9.0362 0.0028231
## origin
                                             2
                                                  213.8
                                                            106.9
                                                                     7.5422 0.0006137
## Residuals
                                           379
                                                 5372.2
                                                             14.2
##
## bs(displacement, knots = c(290)) ***
## poly(horsepower, 2)
## weight
## s(acceleration, df = 3)
                                           **
## origin
                                           ***
## Residuals
## ---
## Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Anova for Nonparametric Effects
                                           Npar Df Npar F
##
                                                               Pr(F)
## (Intercept)
## bs(displacement, knots = c(290))
## poly(horsepower, 2)
## weight
## s(acceleration, df = 3)
                                                  2 2.9111 0.05563 .
## origin
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
bs(displacement, knots = c(290))
                                         10
                                     poly(horsepower, 2)
    N
                                                                          partial for weight
    0
                                         2
                                                                               0
                                         0
                                                                               7
    4
                                         -10
    φ
                                                                               တု
         100
               200
                     300
                          400
                                              50
                                                   100
                                                         150
                                                               200
                                                                                 1500
                                                                                       2500
                                                                                             3500
                                                                                                    4500
               displacement
                                                     horsepower
                                                                                            weight
                                                             2
                                                   1
                                                                 3
s(acceleration, df = 3)
                                         ^{\circ}
                                     partial for origin
    \alpha
                                         0
    0
    7
                                         ī
    4
                                         7
          10
                 15
                        20
                                                      origin
               acceleration
```

We see displacement has two peaks, horsepower has the smallest CI for low values, the linear function in weight is very variable for small and high values, acceleration looks rather like a cubic function and there is a clear effect of origin.