

# Kyle Reppenhagen

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<https://kreppenhagen.github.io/portfolio/>

## Education

**University of Michigan - Ann Arbor**

M.S.E. Mechanical Engineering (*Specialization: Mechatronics*)

B.S.E. Mechanical Engineering

**September 2015 - May 2020**

GPA: 3.850/4.000

GPA: 3.714/4.000

## Experience

**Cold Regions Research and Engineering Laboratory**

*Robotics Engineering Intern*

**July – August 2019**

*Hanover, NH*

- Upgraded hardware and software on robotic vehicle to increase sensing capabilities for improved autonomous mobility, enabling implementation of wheel slip detection and adverse terrain avoidance
- Programmed robot's main computer using Modbus, TCP/IP Socket, and RS-232 Serial protocols to set up communication with the sensor and actuator array (wheel speed/torque sensors, radar, GPS, radio transmitters/receivers, and 3-phase BLDC motor controllers), enabling remote control of robot and expanding possibilities for feedback control and data collection

**Adient**

*Mechanical Design Engineering Intern - Automotive Seating*

**May – August 2018**

*Plymouth, MI*

- Redesigned folding headrest mechanism to increase strength and rigidity to fulfill all federal and OEM strength/stiffness requirements while reducing part cost and weight, increasing product marketability
- Performed destructive strength testing on original headrest design and performed root cause analysis of failures to identify design weaknesses as target areas for redesign efforts
- Modeled design changes in CAD and assessed strength/stiffness of mechanism using FEA, showing changes would increase load carrying capability by 1300N, exceeding the strictest OEM requirements
- Conducted study to assess how to best tolerance parts using GD&T to ensure mechanism functionality

**Michigan Baja Racing Team**

*Technical Director, Subsystem Owner – Suspension*

**September 2016 – June 2019**

*June 2018 – June 2019*

- Led multidisciplinary team on design of an off-road race car and held design reviews of each subsystem to ensure fulfillment of requirements, setting team up for success at competition
- Performed experiment to determine effects of steering kinematic changes on vehicle turn radius, enabling optimization of suspension design to achieve a 4.5 foot reduction in turn radius (37% improvement)
- Fitted rear suspension links with strain gauges and collected load data from on-car testing to derive all six forces/moments acting on the rear wheel to correct inaccurate load cases used in finite element analysis
- Used corrected load cases to redesign failed rear suspension link to withstand all driving loads without yielding, increasing component life and preventing undesirable rear wheel toe-angle changes

*Subsystem Owner – Brakes*

*June 2017 – June 2018*

- Redesigned custom hydraulic braking system to eliminate 13 seals and improve system serviceability, reducing potential for system failure through leakage and drastically shortening service time
- Reduced system part count by 50% to decrease overall complexity and cut system weight by 1 pound
- Designed brake rotors using topology optimization software to achieve a very mass-efficient design

**Capstone Project: Design of a Sprag-Type Differential Gearbox**

**September - December 2018**

- Designed a differential gearbox mechanism to implement sprag-type clutches into the driveline of an off-road vehicle, enabling a 15% reduction in the low-speed turn radius without sacrificing traction
- Performed gear sizing and bearing selection analysis to optimize gearbox packaging and mass while ensuring sufficient strength and durability for optimal vehicle performance

## Skills

*Software:* CAD (SolidWorks, CATIA, NX), Teamcenter, FEA (HyperWorks), LabVIEW, MSC Adams

*Manufacturing:* TIG welding, CNC machining, composite layups, 3D printing, waterjet, lasercut, and soldering

*Programming:* proficient with MATLAB, Simulink, Python, and Arduino; familiar with C, C++, and JavaScript