```
In [1]: import numpy as np
         import matplotlib.pyplot as plt
         import torch
         import generator
         import plotly.graph_objects as go
         from itertools import combinations
         from scipy.spatial.transform import Rotation as R
         from sklearn.decomposition import PCA
In [2]: def V(X, i, j):
             r_{ij} = X[i] - X[j]
             r = torch.norm(r_{ij}).pow(-6)
             return r.pow(2) - 2 * r
         def center(X):
            Y = X - X[0]
             return Y
         def system potential(X):
             N, _ = X.shape
             energy = 0.0
            Y = center(X)
             for i in range(N - 1):
                 for j in range(i + 1, N):
                     energy += V(Y, i, j)
             return energy
         def line_search(X, energy, g, alpha_0=1.0, factor=0.5, c=1e-4, max_iter=10, tol=1e-8):
             alpha = alpha_0
             dot = torch.sum(-g * g).item()
             for _ in range(max_iter):
                X_k = X - alpha * g
                 energy_new = system_potential(X_k)
                 if energy_new <= energy + c * alpha * dot:</pre>
                     break
                 alpha *= factor
                 if alpha < tol:</pre>
                     break
             return alpha
         def gd_solve(natoms, lr=0.008, energy_tol=1e-8, tol=1e-8, max_iter=2001, debug=True, deb
             X = gen(natoms).clone().requires_grad_().to('cuda' if torch.cuda.is_available() else
             if save_initial:
                 orig = X.clone()
             if track energy:
                 nrg_list = []
             for _iter_ in range(max_iter):
                 energy = system_potential(X)
                 if track_energy:
                     nrg_list.append(energy.detach())
                 g = torch.autograd.grad(energy, X)[0]
                 g_norm = g.norm().item()
                 if g_norm < tol:</pre>
                     if debug:
```

```
print(f"Converged on step {_iter_}, energy: {energy.item():.6f}, gradien
                     break
                with torch.no grad():
                    X -= line_search(X, energy, g) * g
                    X.requires_grad_()
                energy_new = system_potential(X)
                if abs(energy_new - energy) < energy_tol:</pre>
                     if debug:
                         print(f"Converged on step {_iter_}, energy: {energy_new.item():.6f}, gra-
                     break
                if debug and _iter_ % debug_rate == 0:
                     print(f"Step {_iter_}, energy: {energy.item():.6f}, gradient norm: {g_norm:.
            if save_initial:
                return orig.detach(), center(X.detach()), energy
            if track energy:
                return torch.tensor(nrg_list), energy
            return center(X.detach()), energy
In [3]: def plot_3d_points(points, energy):
            points_np = center(points).numpy()
            N,_ = points_np.shape
            x = points_np[:, 0]
            y = points_np[:, 1]
            z = points_np[:, 2]
            fig = go.Figure()
            for i, j in combinations(range(len(points np)), 2):
                edge_len = np.linalg.norm(points_np[i] - points_np[j])
                V_ij = V(points, i, j)
                fig.add_trace(go.Scatter3d(
                     x=[points_np[i, 0], points_np[j, 0]],
                     y=[points_np[i, 1], points_np[j, 1]],
                     z=[points_np[i, 2], points_np[j, 2]],
                    mode='lines',
                    line=dict(color='rgb(173, 216, 230, 0.4)', width=8),
                     showlegend=False,
                    hovertext=f"Length: {edge_len:.2e}, Contributes {V_ij:.2e}J",
                    hoverinfo="text",
            fig.add_trace(go.Scatter3d(
                X=X, Y=Y, Z=Z,
                mode='markers',
                hovertext=[f"Point {i + 1}" for i in range(N)],
                marker=dict(size=8, color='red'),
                showlegend=False
            fig.update layout(
                scene=dict(
                    xaxis=dict(showgrid=False, zeroline=False, showticklabels=False, title=''),
                    yaxis=dict(showgrid=False, zeroline=False, showticklabels=False, title=''),
                    zaxis=dict(showgrid=False, zeroline=False, showticklabels=False, title=''),
                ),
                title=f"{N}-Atom Configuration: {energy:.4f}J",
                width=600,
                height=400,
                 plot_bgcolor='rgba(0,0,0,0)',
```

```
paper_bgcolor='rgba(0,0,0,0)',
)
fig.update_scenes(xaxis_visible=False, yaxis_visible=False,zaxis_visible=False)
fig.show()
```

```
In [4]: for atoms in range(2,15):
    config = gd_solve(atoms, debug=False)
    plot_3d_points(*config)
```

2-Atom Configuration: -1.0000J

××

3-Atom Configuration: -3.0000J

 $\overset{\times}{\sim}$

4-Atom Configuration: -6.0000J

××

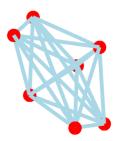
5-Atom Configuration: -9.1039J

××

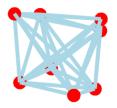
6-Atom Configuration: -12.7121J

××

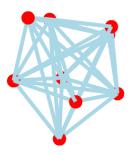
7-Atom Configuration: -16.5054J



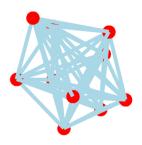
8-Atom Configuration: -19.7653J



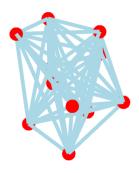
9-Atom Configuration: -23.2698J



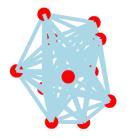
10-Atom Configuration: -26.7717J



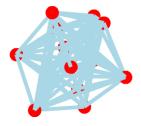
11-Atom Configuration: -32.7660J



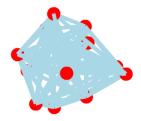
12-Atom Configuration: -34.3944J



13-Atom Configuration: -40.7585J



14-Atom Configuration: -42.5793J



```
In [5]: # Verify that line search works right
        X = generator.uniform_sphere(3).clone().requires_grad_(True)
        for i in range(20):
            E = system_potential(X)
            g = torch.autograd.grad(E, X)[0]
            p = -g.view(-1)
            a = line_search(X, E, g, alpha_0=0.1) # try 0.1 or whatever lr
            with torch.no grad():
                X = X + a * p.view_as(X)
                X = X - X[0]
            X.requires_grad_(True)
            print(f"Iter {i:2d}: E = {E.item():.6f}, ||grad|| = {g.norm().item():.2e}, a = {a:.3f}
       Iter 0: E = -0.221921, \|grad\| = 7.62e-01, a = 0.100
       Iter 1: E = -0.289849, \|grad\| = 1.04e+00, a = 0.100
       Iter 2: E = -0.424871, \|grad\| = 1.61e+00, a = 0.100
       Iter 3: E = -0.803233, \|grad\| = 3.29e+00, a = 0.100
       Iter 4: E = -1.279765, \|grad\| = 3.61e+01, a = 0.006
       Iter 5: E = -1.635842, \|grad\| = 6.56e+00, a = 0.025
       Iter 6: E = -2.858243, \|grad\| = 5.87e+00, a = 0.013
       Iter 7: E = -2.863041, \|grad\| = 9.64e+00, a = 0.006
       Iter 8: E = -2.927801, \|grad\| = 4.59e+00, a = 0.006
       Iter 9: E = -2.999994, \|grad\| = 4.41e-02, a = 0.006
       Iter 10: E = -3.000000, \|grad\| = 1.52e-02, a = 0.006
       Iter 11: E = -3.000000, \|grad\| = 5.25e-03, a = 0.006
       Iter 12: E = -3.000000, \|grad\| = 1.80e-03, a = 0.025
       Iter 13: E = -3.000000, \|grad\| = 7.38e-03, a = 0.006
       Iter 14: E = -3.000000, \|grad\| = 2.58e-03, a = 0.013
       Iter 15: E = -3.000000, \|grad\| = 4.34e-03, a = 0.006
       Iter 16: E = -3.000000, \|grad\| = 1.52e-03, a = 0.025
       Iter 17: E = -3.000000, \|grad\| = 6.68e-03, a = 0.006
       Iter 18: E = -3.000000, \|grad\| = 2.33e-03, a = 0.013
       Iter 19: E = -3.000000, \|grad\| = 3.95e-03, a = 0.006
```

```
In [6]: def strong_wolfe_line_search(X, energy, g, p,
                                      alpha0=1.0, c1=1e-4, c2=0.9,
                                      max_iter=20):
            def phi(a):
                Xt = X + a * p
                return system potential(Xt).item()
            def der phi(a):
                Xt = X + a * p
                Xt = Xt.clone().detach().requires_grad_(True)
                Et = system_potential(Xt)
                grad t = torch.autograd.grad(Et, Xt)[0]
                return (grad_t.view(-1) @ p.view(-1)).item()
            alpha_prev = 0.0
            phi0 = energy
            derphi0 = (g.view(-1) @ p.view(-1)).item()
            alpha = alpha0
            phi prev = phi0
            for i in range(max_iter):
                phi_a = phi(alpha)
                if (phi_a > phi0 + c1 * alpha * derphi0) or (i > 0 and phi_a >= phi_prev):
                    # need to zoom between alpha_prev and alpha
                     return zoom(alpha_prev, alpha, phi, der_phi, phi0, derphi0, c1, c2)
                derphi_a = der_phi(alpha)
                if abs(derphi a) <= -c2 * derphi0:</pre>
                     return alpha
                if derphi a >= 0:
                    # curvature condition violated: derivative has changed sign
                     return zoom(alpha, alpha_prev, phi, der_phi, phi0, derphi0, c1, c2)
                alpha prev, phi prev = alpha, phi a
                alpha = alpha * 2.0 # increase alpha and keep searching
            return alpha # fallback
        def zoom(a_lo, a_hi, phi, der_phi, phi0, derphi0, c1, c2):
            for j in range(20):
                # interpolate midpoint
                a_j = 0.5 * (a_lo + a_hi)
                phi_aj = phi(a_j)
                if (phi_aj > phi0 + c1 * a_j * derphi0) or (phi_aj >= phi(a_lo)):
                    a_hi = a_j
                else:
                     derphi_aj = der_phi(a_j)
                     if abs(derphi_aj) <= -c2 * derphi0:</pre>
                        return a_j
                     if derphi_aj * (a_hi - a_lo) >= 0:
                        a_hi = a_lo
                    a_lo = a_j
            return a_j
In [7]: def bfgs_step(X, energy, g, H_inv, alpha=1.0, max_iter=10, tol=1e-8):
```

```
In [7]: def bfgs_step(X, energy, g, H_inv, alpha=1.0, max_iter=10, tol=1e-8):
    N, _ = X.shape

# flatten & slice out the free variables
    g_full = g.view(-1)
    g_free = g_full[3:]
    # print("||g_full|| =", g_full.norm().item())
```

```
# print("||g_free|| =", g_free.norm().item())
# print("H_inv diag:", torch.diag(H_inv)[:6])
# print("H_inv.shape =", H_inv.shape)
# print("g_free.shape =", g_free.shape)
# descent dir in the free subspace
s_free = - H_inv @ g_free
p = torch.zeros like(g full, device=g full.device)
p[3:] = s_free
p = p.view_as(X)
# line search (still uses the full X and full g)
alpha = strong wolfe line search(X, energy, g, p)
# take a step in the free variables
x_full = X.clone().detach().view(-1)
x_{free} = x_{full[3:]}
# print("||s_free|| =", s_free.norm().item())
# print("alpha =", alpha)
# print("x_free (first 5) =", x_free[:5])
x_free_new = x_free + alpha * s_free
# print("x_free_new (first 5) =", x_free_new[:5])
\# print("s = x_free_new - x_free (first 5) =", (x_free_new - x_free)[:5])
# reassemble X_new
x \text{ full}[3:] = x \text{ free new}
X_new = x_full.view(N,3).requires_grad_(True)
# eval new energy & gradient
energy_new = system_potential(X_new)
g_new_full = torch.autograd.grad(energy_new, X_new)[0]
g_new = g_new_full.view(-1)
g_new_free = g_new[3:]
# BFGS inverse-Hessian update on the free subspace
w = alpha * s_free
y = g_new_free - g_free
# print (f"y={y}")
# print (f"s={s}")
# print (f"ys={y @ s}")
ys = (y @ w).item()
# print(f"||s|| = {w.norm().item():.2e}, ||y|| = {y.norm().item():.2e}, y^T s = {ys:
if ys <= 1e-24:
    H inv new = H inv.clone()
    valid = True
else:
    #print ("does this run")
    rho = 1.0 / ys
    I = torch.eye(H_inv.shape[0], device=H_inv.device)
    V = I - rho * torch.outer(w, y)
    with torch.no grad():
        H_inv_new = V @ H_inv @ V.T + rho * torch.outer(w, w)
    valid = True
return X_new, energy_new, g_new_full, H_inv_new, alpha, valid
```

```
def bfgs(natoms, lr=0.008, g_tol=1e-8, energy_tol=1e-8, max_iter=2001, debug=True, debug
   X = gen(natoms).clone().requires_grad_().to('cuda' if torch.cuda.is_available() else
    if save initial:
       orig = X.clone()
    N_{,} = X_{.}shape
    H_inv = torch.eye(3 * (N - 1), dtype=torch.float64).to(X.device)
   X = X.clone().detach().requires grad (True) # make sure autograd returns valid
    if track energy:
        nrg_list = [system_potential(X)]
    for _iter_ in range(max_iter):
        energy = system potential(X)
        g = torch.autograd.grad(energy, X)[0]
       X_new, energy_new, g_new, H_inv, alpha, valid = bfgs_step(X, energy, g, H_inv, a
        if track_energy and valid:
            nrg_list.append(energy_new.detach())
        if abs(energy_new - energy) < energy_tol:</pre>
            if debug:
                print(f"Converged on step {_iter_}, energy: {energy_new.item():.6f}, gra
            break
        g_norm = g.norm().item()
        if g_norm < g_tol:</pre>
            if debug:
                print(f"Converged on step {_iter_}, energy: {energy.item():.6f}, gradien
            break
        if debug and _iter_ % debug_rate == 0:
            print(f"Step {_iter_}, energy: {energy_new.item():.6f}, gradient norm: {g_no
       X, energy = X_new, energy_new
    if save_initial:
        return orig.detach(), X.detach(), energy_new
    if track_energy:
        return torch.tensor(nrg_list), energy_new
    return X.detach(), energy new
```

```
In [8]: for atoms in range(2,10):
    config = bfgs(atoms, debug=False, g_tol=1e-8, energy_tol=1e-8, debug_rate=20)
    plot_3d_points(*config)
```

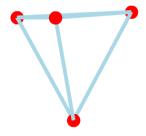
2-Atom Configuration: -1.0000J



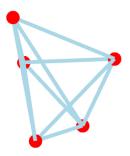
3-Atom Configuration: -3.0000J



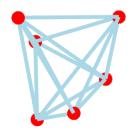
4-Atom Configuration: -6.0000J



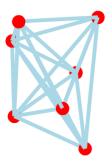
5-Atom Configuration: -9.1039J



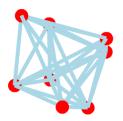
6-Atom Configuration: -12.3029J



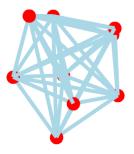
7-Atom Configuration: -15.5331J



8-Atom Configuration: -19.7653J



9-Atom Configuration: -23.2698J



```
In [9]: def plot_convergence_order(energies, final_energy, label="", show=True):
    """
    energies: 1D tensor [E0, E1, ..., E_N]
    final_energy: scalar tensor E*

    Plots (log10 e_n, log10 e_{n+1}) with a linear fit whose slope ≈ order p.
    """
    # 1) drop Last energy
    E = energies[:-1]
    # 2) absolute errors
```

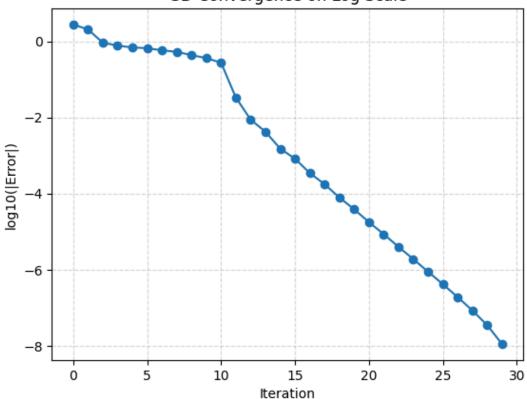
```
errs = (E - final_energy).abs()
   # 3) log10 errors, set zeros to -inf
   log_err = torch.where(errs > 0,
                          errs.log10(),
                          torch.full_like(errs, float("-inf")))
   # 4) keep only finite entries
   mask = torch.isfinite(log_err)
   log_err = log_err[mask]
   # 5) x = log err[:-1], y = log err[1:]
   x = log_err[:-1]
   y = log_err[1:]
   # 6) compute slope p and intercept a in torch
   xm = x.mean()
   ym = y.mean()
   num = ((x - xm) * (y - ym)).sum()
   den = ((x - xm)**2).sum()
   p = num / den
                               # slope
   a = ym - p * xm
                              # intercept
   # 7) convert to NumPy for plotting
   x np = x.detach().numpy()
   y_np = y.detach().numpy()
   p_val = p.item()
   a_val = a.item()
   if show:
       # 8) plot
       plt.figure()
       plt.plot(x_np, y_np, "o", label="data")
       plt.plot(x_np, p_val * x_np + a_val, "-", label=f"slope * {p_val:.2f}")
       plt.xlabel("log10(error_n)")
       plt.ylabel("log10(error_{n+1})")
       plt.title(f"Estimated {label}Convergence Order p ≈ {p_val:.2f}")
       plt.grid(True, linestyle="--", alpha=0.5)
       plt.legend()
       plt.show()
   return p_val
def plot_convergence(energies, final_energy, label=""):
   Plots the convergence of absolute errors on a log10 scale,
   ignoring the last entry in the energies tensor.
   energies: 1D torch. Tensor of computed energies [E0, E1, ..., EN]
   final_energy: scalar torch.Tensor (or float castable) E*
   # drop the last computed energy
   E = energies[:-1]
   errors = (E - final energy).abs()
   # compute log10(errors), putting -inf where error is zero
   log_errors = torch.where(
       errors > 0,
       errors.log10(),
       torch.full_like(errors, float("-inf"))
   )
   # move to CPU+NumPy for plotting
   iters = torch.arange(log_errors.size(0)).cpu().numpy()
   log_e = log_errors.detach().numpy()
```

```
plt.figure()
plt.plot(iters, log_e, marker='o')
plt.xlabel('Iteration')
plt.ylabel('log10(|Error|)')
plt.title(f'{label}Convergence on Log Scale')
plt.grid(True, linestyle='--', alpha=0.5)
plt.show()

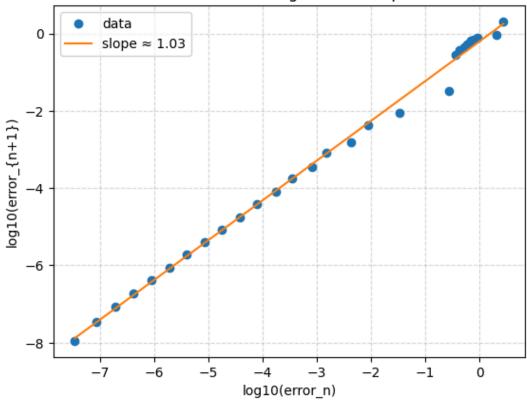
plot_convergence_order(energies, final_energy, label)
```

In [10]: plot_convergence(*(gd_solve(3, track_energy=True, debug=False, gen=generator.uniform_sph

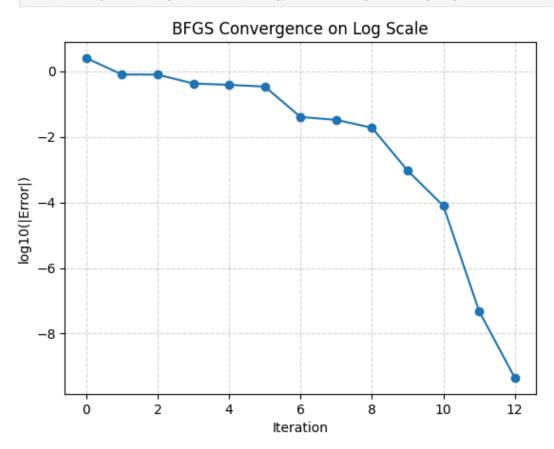




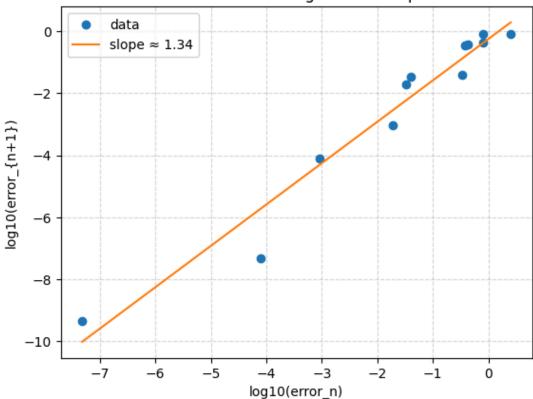
Estimated GD Convergence Order p ≈ 1.03



In [11]: plot_convergence(*(bfgs(3, track_energy=True, debug=False, gen=generator.init_pos)), lab



Estimated BFGS Convergence Order p ≈ 1.34



1.4892628612954626

```
In [13]: p_vals = []

for i in range(100):
    p_val = plot_convergence_order(*(gd_solve(3, track_energy=True, debug=False, gen=gen_p_vals.append(p_val)

print (np.nanmean(p_vals))
```

1.0548082989579861

```
In [ ]:
```