Homework 2 Report  
 (1Hz to 50MHz range signal generation and sampling)

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# Summary

Files : main.c, makefile, Homework2\_Report.docx  
 Implemented the procedures for gpio toggling and sampling:

1. Continuous generation of 50MHz ( a 3\* half cycle interleaved every 20 cycles due to the branch instruction)
2. Continuous generation of 50MHz ( a 1.5\* half cycle interleaved every 20 cycles due to the branch instruction)
3. Continuous generation of 16.667MHz signal with 50-50 duty cycle.
4. Continuous generation of user input freq in the range 0.5 MHz to 1 Hz signal with 50-50 duty cycle.
5. Sampling at 100MHz
6. Sampling at 50MHz (“”)
7. Sampling at user input freq in the range 0.5 MHz to 1 Hz signal.

All functions tested and results of few sample input frequencies are recorded in this report.

**Todo** :

Analyze the accuracy of generated signal using scope/analyzer..   
Implement functions to toggle and sample at freq. in the range 1 to 16 MHz

Fine tune to get more accurate sampling for <500,000MHz

Debug the 25MHz generation/sampling using scope.

# Learned:

1. Details of pipelining – Stalling effects of **Load,Branch**.
2. Using **inline functions** in arm
3. Adding **inline assembly** safely as follows:

First: Push all registers to be used in assembly section

Next: Add the assembly here ..

Last : Pop the registers that were push in the beginning

1. **Branch Target Forwarding :** Feature of ARM, that allows an Unconditional Branch instruction Execution cycle to be pipelined with InstructionFetch from the target address.

A simple unconditional branch like:

B offset

can have the target program counter calculated in the decode stage and start the program fetch early.

1. str - one cycle, no stall , due to the use of **Write Buffer/Store Buffer**.

STR Rx,[Ry,#imm] is always one cycle. This is because the address generation is performed

in the initial cycle, and the data store is performed at the same time as the next instruction

is executing. If the store is to the store buffer, and the store buffer is full or not enabled,

the next instruction is delayed until the store can complete.

1. ldr - takes 2 cycles. And Data Phase can be pipelined with Address Phase of next load/store, unless next instruction uses address from Data Phase of ldr.
2. Use of **SysTickTimer** to implement delay:

* wait\_us() has a +/-0.5us error and was yielding inconsistent sampling.
* SysTickTimer has a Reload register, when loaded with value 99, it will count down to 0 in 100 cpu cycles = 100 \* 10ns = 1us
* To account for the systick register loading instructions, value 91 is used to get a delay of 1 us.

# Procedures:

1. **toggle\_gpio\_50MHz()**

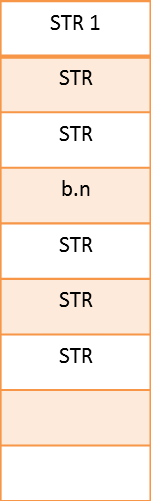
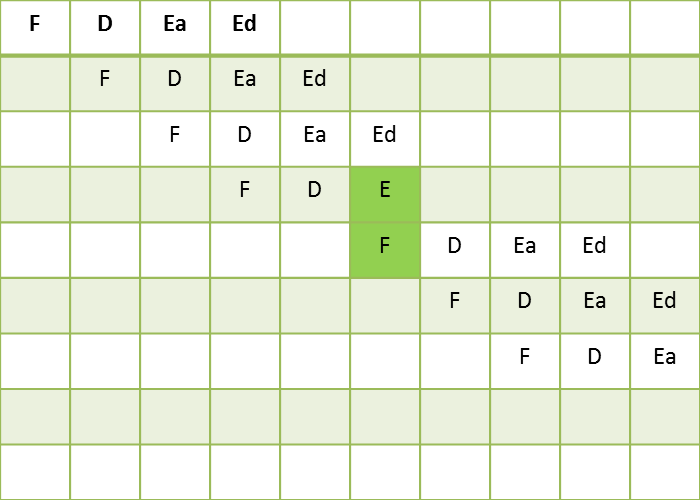
50 MHz signal generation: ( time period = 20ns) = At 96 MHz this is Max possible toggling speed.

Toggles at 50MHz for 20 cycles and then there is a 3 times long half cycle

Introduced by branch delay. Also, branch target forwarding allows Fetch of Branch target address to be pipelined with Execution of Branch.

|  |
| --- |
| while (1)  {  \*FIOSET2 = mask;  1aa: 700b strb r3, [r1, #0]  \*FIOCLR2 = mask;  1ac: 7013 strb r3, [r2, #0]  \*FIOSET2 = mask;  1ae: 700b strb r3, [r1, #0]  \*FIOCLR2 = mask;  1b0: 7013 strb r3, [r2, #0]  .  .  .  } |

30 ns



Branch target forwarding

10 ns

1. **toggle\_gpio\_25MHz()**

25 MHz signal generation:

By repeating the below code 10 times within one iteration of while loop,

generated the pattern **ten** **40ns cycles** that ends with a **30ns gap** introduced by branch instruction.

Thus generating 25MHz with a 30ns gap every ten cycles.

|  |
| --- |
| while (1)  {  // CYCLE 1  \*FIOSET2 = mask;  216: 7013 strb r3, [r2, #0]  \*FIOSET2 = mask;  218: 7013 strb r3, [r2, #0]  \*FIOCLR2 = mask;  21a: 700b strb r3, [r1, #0]  \*FIOCLR2 = mask;  21c: 700b strb r3, [r1, #0]  .  .  .  } |

1. **toggle\_gpio\_16MHz()-** At 96MHz this is Max possible freq. with 50% duty cycle

16.667 MHz signal generation:

Using the below GPIO set/clear loop,

GPIO is set for 30 ns, And clear for 10ns + 20ns by branch delay

Total 60ns time period = 16.6667 MHz frequency

|  |
| --- |
| while (1)  {  \*FIOSET2 = mask;  282: 7013 strb r3, [r2, #0]  \*FIOSET2 = mask;  284: 7013 strb r3, [r2, #0]  \*FIOSET2 = mask;  286: 7013 strb r3, [r2, #0]  \*FIOCLR2 = mask;  288: 700b strb r3, [r1, #0]  } |

.

1. **toggle\_gpio\_delay()**

Arbitrary Freq. signal generation (0.5 MHz to 1Hz)

wait\_us() function of mbed library was used to add delay between consecutive write to GPIO pin. The delay in us between toggling was computed at run time from user input freq using the simple formula:

delay\_us\_f = 1000000/(freq\*2);

delay\_us\_i = (unsigned int) delay\_us\_f;

1. **sample\_gpio\_100MHz(**), at 96MHz this is Max possible sampling freq.

100 MHz sampling – using register variables

|  |
| --- |
| 33a: 4918 ldr r1, [pc, #96] ; (39c <main+0x1b4>)  33c: f203 30ff addw r0, r3, #1023 ; 0x3ff  340: 9005 str r0, [sp, #20]  reg1 = LPC\_GPIO0->FIOPIN0;  342: f891 9014 ldrb.w r9, [r1, #20]  reg2 = LPC\_GPIO0->FIOPIN0;  346: f891 8014 ldrb.w r8, [r1, #20]  reg3 = LPC\_GPIO0->FIOPIN0;  34a: f891 c014 ldrb.w ip, [r1, #20]  reg4 = LPC\_GPIO0->FIOPIN0;  34e: f891 e014 ldrb.w lr, [r1, #20]  reg5 = LPC\_GPIO0->FIOPIN0;  352: 7d0f ldrb r7, [r1, #20]  reg6 = LPC\_GPIO0->FIOPIN0;  354: 7d0e ldrb r6, [r1, #20]  reg7 = LPC\_GPIO0->FIOPIN0;  356: 7d0d ldrb r5, [r1, #20]  reg8 = LPC\_GPIO0->FIOPIN0;  358: 7d0c ldrb r4, [r1, #20]  reg9 = LPC\_GPIO0->FIOPIN0;  35a: 7d08 ldrb r0, [r1, #20] |

ldrb takes total 4 cycles (F,D,Ea,Ed) – or 2 exec cycles.

Nth load’s Ed can be pipelined with N+1th Ea ( since address of N+1 is not based on Data Phase of N)

A sample is taken every 10ns (one clock cycle) and hence 100MHz sampling is achieved.

1. sample\_gpio\_50MHz()

50 MHz sampling – By interleaving buffer stores in between load of GPIO to register.

|  |
| --- |
| 246: 7d08 ldrb r0, [r1, #20]  248: 3308 adds r3, #8  24a: f803 0c08 strb.w r0, [r3, #-8]  reg2 = LPC\_GPIO0->FIOPIN0;  24e: 7d08 ldrb r0, [r1, #20]  buf[1] = reg2;  250: f803 0c07 strb.w r0, [r3, #-7]  reg3 = LPC\_GPIO0->FIOPIN0;  254: 7d08 ldrb r0, [r1, #20]  buf[2] = reg3;  256: f803 0c06 strb.w r0, [r3, #-6]  reg4 = LPC\_GPIO0->FIOPIN0;  25a: 7d08 ldrb r0, [r1, #20] |

1. sample\_gpio\_delay()

Arbitrary Freq. signal generation (1Hz to 500,000 Hz )

SysTickTimer is used to insert delay in multiples of microseconds. The delay in us between consecutive samples was computed at run time from user entered freq using the formula:

delay\_us\_f = 1000000/(freq);

delay\_us\_i = (unsigned int) delay\_us\_f;

1. compute\_input\_freq ()

Compute frequency from stored samples.

Sets of 10/16 samples are collected into a 1024 size buffer for 100/50MHz respectively.

For 1Hz to 500,000 range, 1024 samples are collected continuously, and **calculated delay is inserted using SysTickTimer**.

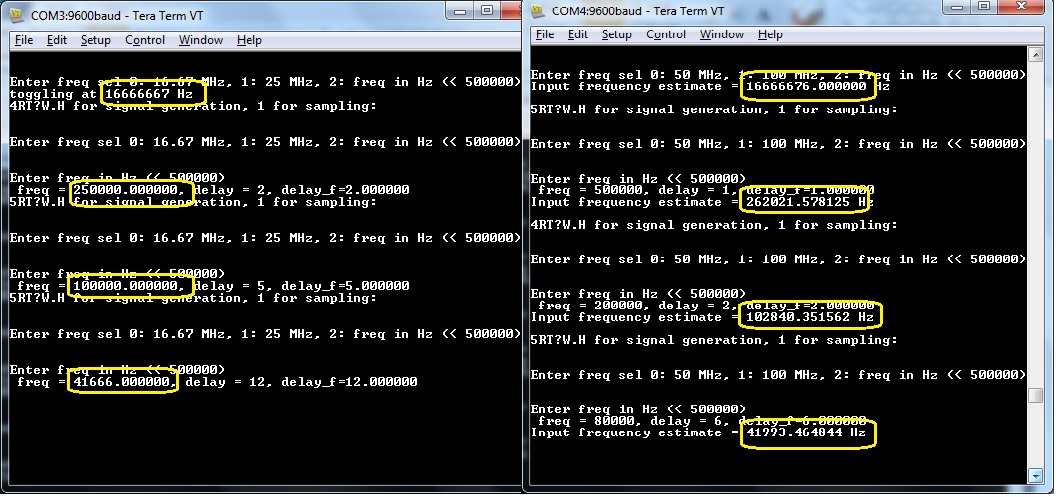
A simple **average** is performed, to compute frequency based on **sampling time period , number of valid samples and number of cycles recorded .**

**Leading bits are discarded**, and samples are counted from the first toggle onwards.

The max even number of toggles recorded are considered towards freq. estimation and **trailing bits are discarded.**

# Results – some examples:

* 16.67 MHz signal, sampled at 50MHz computed as 16,666676 Hz at sampling mbed
* 25 MHz input – giving really big error with 50MHz and 100MHz sampling
* 250,000 Hz input sampled at 500,000Hz computed as 264243.593750 at sampling mbed
* 100,000 Hz input sampled at 200,000Hz computed as 103330.062500 at sampling mbed
* 41666 Hz input sampled with 80,000 computed as 42075.964844 at sampling mbed



# Hours:

2-3 Hrs : Searching literature for pipelining of instructions, SysTick timer.  
25 : Implementing functions to toggle GPIO at different frequencies, sample at different rates and compute the frequency based on stored samples.

4-5 Hrs : Preparing the document

# References:

1. Cortex™-M3 Technical Reference Manual Revision r2p0
2. LPC17xx user manual