Optimization for Fully Connected Networks

In this notebook, we will implement different optimization rules for gradient descent. We have provided starter code; however, you will need to copy and paste your code from your implementation of the modular fully connected nets in HW #3 to build upon this.

CS231n has built a solid API for building these modular frameworks and training them, and we will use their very well implemented framework as opposed to "reinventing the wheel." This includes using their Solver, various utility functions, and their layer structure. This also includes nndl.fc_net, nndl.layers, and nndl.layer_utils. As in prior assignments, we thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu).

```
## Import and setups
import time
import numpy as np
import matplotlib.pyplot as plt
from nndl.fc net import *
from utils.data utils import get CIFAR10 data
from utils.gradient_check import eval_numerical_gradient,
eval numerical gradient array
from utils.solver import Solver
%matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'
# for auto-reloading external modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-
modules-in-ipython
%load ext autoreload
%autoreload 2
def rel error(x, y):
  """ returns relative error """
  return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) +
np.abs(y)))
# Load the (preprocessed) CIFAR10 data.
data = get CIFAR10 data()
for k in data.keys():
  print('{}: {} '.format(k, data[k].shape))
X train: (49000, 3, 32, 32)
y train: (49000,)
X val: (1000, 3, 32, 32)
```

```
y_val: (1000,)
X_test: (1000, 3, 32, 32)
y_test: (1000,)
```

Building upon your HW #3 implementation

Copy and paste the following functions from your HW #3 implementation of a modular FC net:

- affine_forward in nndl/layers.py
- affine_backward in nndl/layers.py
- relu_forward in nndl/layers.py
- relu_backward in nndl/layers.py
- affine relu forward in nndl/layer utils.py
- affine relu backwardin nndl/layer utils.py
- The FullyConnectedNet class in nndl/fc net.py

Test all functions you copy and pasted

```
from nndl.layer tests import *
affine forward test(); print('\n')
affine backward_test(); print('\n')
relu forward test(); print('\n')
relu backward test(); print('\n')
affine relu test(); print('\n')
fc net test()
If affine_forward function is working, difference should be less than
difference: 9.769849468192957e-10
If affine backward is working, error should be less than 1e-9::
dx error: 6.501491362954244e-10
dw error: 4.064162742661063e-11
db error: 7.414168664595107e-12
If relu forward function is working, difference should be around 1e-8:
difference: 4.999999798022158e-08
If relu_forward function is working, error should be less than 1e-9:
dx error: 3.275618457618382e-12
If affine relu forward and affine relu backward are working, error
should be less than 1e-9::
dx error: 1.105662793138624e-10
```

```
dw error: 7.3374048856773584e-09
db error: 4.1311479701329975e-10
Running check with reg = 0
Initial loss: 2.305869793849734
W1 relative error: 3.0804139558156004e-08
W2 relative error: 2.3778256029777398e-07
W3 relative error: 3.932763146842659e-08
bl relative error: 5.829911539522352e-09
b2 relative error: 1.8234759836310827e-09
b3 relative error: 9.364774879700393e-11
Running check with reg = 3.14
Initial loss: 6.9548560863228746
W1 relative error: 1.5041175033511533e-08
W2 relative error: 1.8533372309838707e-07
W3 relative error: 3.341534664182953e-08
b1 relative error: 2.98185923243827e-08
b2 relative error: 9.287729904632382e-09
b3 relative error: 2.092220967523909e-10
```

Training a larger model

In general, proceeding with vanilla stochastic gradient descent to optimize models may be fraught with problems and limitations, as discussed in class. Thus, we implement optimizers that improve on SGD.

SGD + momentum

In the following section, implement SGD with momentum. Read the nndl/optim.py API, which is provided by CS231n, and be sure you understand it. After, implement sgd_momentum in nndl/optim.py. Test your implementation of sgd_momentum by running the cell below.

```
11)
  [ 1.14244211,
                1.20923158, 1.27602105,
                                         1.34281053,
                                                       1.4096
expected velocity = np.asarray([
  [0.5406,
                0.55475789, 0.56891579, 0.58307368,
                                                      0.59723158],
  [ 0.61138947,
               0.62554737, 0.63970526, 0.65386316,
                                                       0.66802105],
  [ 0.68217895, 0.69633684, 0.71049474,
                                          0.72465263,
                                                       0.73881053],
  [ 0.75296842, 0.76712632, 0.78128421,
                                          0.79544211,
                                                       0.8096
                                                                 ]])
print('next w error: {}'.format(rel error(next w, expected next w)))
print('velocity error: {}'.format(rel_error(expected_velocity,
config['velocity'])))
next w error: 8.882347033505819e-09
velocity error: 4.269287743278663e-09
```

SGD + Nesterov momentum

Implement sgd_nesterov_momentum in ndl/optim.py.

```
from nndl.optim import sqd nesterov momentum
N, D = 4, 5
w = np.linspace(-0.4, 0.6, num=N*D).reshape(N, D)
dw = np.linspace(-0.6, 0.4, num=N*D).reshape(N, D)
v = np.linspace(0.6, 0.9, num=N*D).reshape(N, D)
config = {'learning_rate': 1e-3, 'velocity': v}
next_w, _ = sgd_nesterov_momentum(w, dw, config=config)
expected next w = np.asarray([
  [0.08714,
                 0.15246105,
                              0.21778211,
                                           0.28310316,
                                                        0.34842421],
                              0.54438737,
  [0.41374526,
                 0.47906632,
                                           0.60970842,
                                                        0.67502947],
  [0.74035053,
                 0.80567158,
                              0.87099263,
                                           0.93631368.
                                                        1.00163474],
  [1.06695579,
                 1.13227684,
                                                        1.32824
                                                                  ]])
                              1.19759789,
                                           1.26291895,
expected velocity = np.asarray([
  [0.5406,
                0.55475789, 0.56891579,
                                           0.58307368,
                                                        0.59723158],
  [ 0.61138947, 0.62554737, 0.63970526,
                                           0.65386316,
                                                        0.66802105],
  [ 0.68217895, 0.69633684, 0.71049474,
                                           0.72465263,
                                                        0.738810531.
  [ 0.75296842, 0.76712632, 0.78128421,
                                           0.79544211,
                                                        0.8096
                                                                  11)
print('next w error: {}'.format(rel error(next w, expected next w)))
print('velocity error: {}'.format(rel_error(expected_velocity,
config['velocity'])))
next w error: 1.0875187099974104e-08
velocity error: 4.269287743278663e-09
```

Evaluating SGD, SGD+Momentum, and SGD+NesterovMomentum

Run the following cell to train a 6 layer FC net with SGD, SGD+momentum, and SGD+Nesterov momentum. You should see that SGD+momentum achieves a better loss than SGD, and that SGD+Nesterov momentum achieves a slightly better loss (and training accuracy) than SGD+momentum.

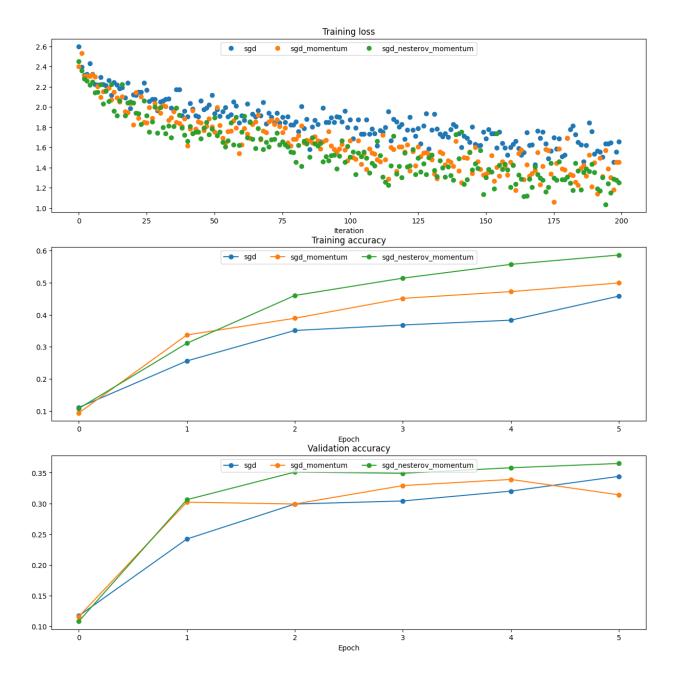
```
num train = 4000
small data = {
  'X train': data['X train'][:num train],
  'y_train': data['y_train'][:num_train],
  'X val': data['X val'],
  'y_val': data['y_val'],
solvers = {}
for update rule in ['sqd', 'sqd momentum', 'sqd nesterov momentum']:
  print('Optimizing with {}'.format(update rule))
  model = FullyConnectedNet([100, 100, 100, 100, 100],
weight scale=5e-2)
  solver = Solver(model, small data,
                  num epochs=5, batch size=100,
                  update rule=update rule,
                  optim config={
                    'learning rate': 1e-2,
                  },
                  verbose=False)
  solvers[update rule] = solver
  solver.train()
  print
plt.subplot(3, 1, 1)
plt.title('Training loss')
plt.xlabel('Iteration')
plt.subplot(3, 1, 2)
plt.title('Training accuracy')
plt.xlabel('Epoch')
plt.subplot(3, 1, 3)
plt.title('Validation accuracy')
plt.xlabel('Epoch')
for update_rule, solver in solvers.items():
  plt.subplot(3, 1, 1)
  plt.plot(solver.loss history, 'o', label=update rule)
```

```
plt.subplot(3, 1, 2)
plt.plot(solver.train_acc_history, '-o', label=update_rule)

plt.subplot(3, 1, 3)
plt.plot(solver.val_acc_history, '-o', label=update_rule)

for i in [1, 2, 3]:
   plt.subplot(3, 1, i)
   plt.legend(loc='upper center', ncol=4)
plt.gcf().set_size_inches(15, 15)
plt.show()

Optimizing with sgd
Optimizing with sgd_momentum
Optimizing with sgd_nesterov_momentum
```



RMSProp

Now we go to techniques that adapt the gradient. Implement rmsprop in nndl/optim.py. Test your implementation by running the cell below.

```
from nndl.optim import rmsprop

N, D = 4, 5
w = np.linspace(-0.4, 0.6, num=N*D).reshape(N, D)
dw = np.linspace(-0.6, 0.4, num=N*D).reshape(N, D)
a = np.linspace(0.6, 0.9, num=N*D).reshape(N, D)
```

```
config = {'learning rate': le-2, 'a': a}
next_w, _ = rmsprop(w, dw, config=config)
expected next w = np.asarray([
  [-0.39223849, -0.34037513, -0.28849239, -0.23659121, -0.18467247],
  [-0.132737,
                -0.08078555, -0.02881884,
                                           0.02316247,
                                                        0.07515774],
  [ 0.12716641, 0.17918792, 0.23122175,
                                           0.28326742,
                                                        0.33532447],
  [ 0.38739248, 0.43947102,
                              0.49155973,
                                           0.54365823,
                                                       0.59576619]])
expected cache = np.asarray([
  [ 0.5976,
                0.6126277,
                             0.6277108,
                                           0.64284931,
                                                        0.65804321],
  [ 0.67329252,
               0.68859723, 0.70395734,
                                                        0.73484377],
                                           0.71937285,
  [ 0.75037008, 0.7659518,
                                           0.79728144,
                             0.78158892,
                                                        0.81302936],
                            0.86060554,
                                                                  11)
  [ 0.82883269, 0.84469141,
                                           0.87657507, 0.8926
print('next w error: {}'.format(rel error(expected next w, next w)))
print('cache error: {}'.format(rel_error(expected_cache,
config['a'])))
next w error: 9.524687511038133e-08
cache error: 2.6477955807156126e-09
```

Adaptive moments

Now, implement adam in nndl/optim.py. Test your implementation by running the cell below.

```
# Test Adam implementation; you should see errors around 1e-7 or less
from nndl.optim import adam
N, D = 4, 5
w = np.linspace(-0.4, 0.6, num=N*D).reshape(N, D)
dw = np.linspace(-0.6, 0.4, num=N*D).reshape(N, D)
v = np.linspace(0.6, 0.9, num=N*D).reshape(N, D)
a = np.linspace(0.7, 0.5, num=N*D).reshape(N, D)
config = {'learning rate': 1e-2, 'v': v, 'a': a, 't': 5}
next_w, _ = adam(w, dw, config=config)
expected next w = np.asarray([
  [-0.40094747, -0.34836187, -0.29577703, -0.24319299, -0.19060977],
                                           0.01971428,
  [-0.1380274, -0.08544591, -0.03286534,
                                                        0.07229291,
  [ 0.1248705,
               0.17744702, 0.23002243,
                                           0.28259667,
                                                        0.33516969],
  [ 0.38774145,
               0.44031188.
                             0.49288093,
                                           0.54544852,
                                                       0.59801459]])
expected a = np.asarray([
  [0.69966,
                 0.68908382, 0.67851319,
                                           0.66794809,
                                                        0.65738853,],
                                           0.61520571,
  [ 0.64683452, 0.63628604, 0.6257431,
                                                        0.60467385,],
  [ 0.59414753, 0.58362676, 0.57311152,
                                           0.56260183,
                                                        0.55209767,],
  [ 0.54159906, 0.53110598,
                             0.52061845,
                                           0.51013645,
                                                        0.49966,
                                                                   ]])
```

```
expected v = np.asarray([
             0.49947368, 0.51894737,
  0.48,
                                          0.53842105, 0.55789474],
  [ 0.57736842, 0.59684211,
                             0.61631579,
                                          0.63578947, 0.65526316],
  [ 0.67473684, 0.69421053, 0.71368421,
                                          0.73315789.
                                                       0.752631581.
  [ 0.77210526, 0.79157895,
                             0.81105263,
                                          0.83052632, 0.85
                                                                 11)
print('next_w error: {}'.format(rel_error(expected_next_w, next_w)))
print('a error: {}'.format(rel error(expected a, config['a'])))
print('v error: {}'.format(rel_error(expected_v, config['v'])))
next w error: 1.1395691798535431e-07
a error: 4.208314038113071e-09
v error: 4.214963193114416e-09
```

Comparing SGD, SGD+NesterovMomentum, RMSProp, and Adam

The following code will compare optimization with SGD, Momentum, Nesterov Momentum, RMSProp and Adam. In our code, we find that RMSProp, Adam, and SGD + Nesterov Momentum achieve approximately the same training error after a few training epochs.

```
learning rates = {'rmsprop': 2e-4, 'adam': 1e-3}
for update rule in ['adam', 'rmsprop']:
  print('Optimizing with {}'.format(update rule))
  model = FullyConnectedNet([100, 100, 100, 100, 100],
weight scale=5e-2)
  solver = Solver(model, small data,
                  num epochs=5, batch size=100,
                  update rule=update rule,
                  optim config={
                    'learning rate': learning rates[update rule]
                  verbose=False)
  solvers[update rule] = solver
  solver.train()
  print
plt.subplot(3, 1, 1)
plt.title('Training loss')
plt.xlabel('Iteration')
plt.subplot(3, 1, 2)
plt.title('Training accuracy')
plt.xlabel('Epoch')
plt.subplot(3, 1, 3)
plt.title('Validation accuracy')
```

```
plt.xlabel('Epoch')

for update_rule, solver in solvers.items():
    plt.subplot(3, 1, 1)
    plt.plot(solver.loss_history, 'o', label=update_rule)

plt.subplot(3, 1, 2)
    plt.plot(solver.train_acc_history, '-o', label=update_rule)

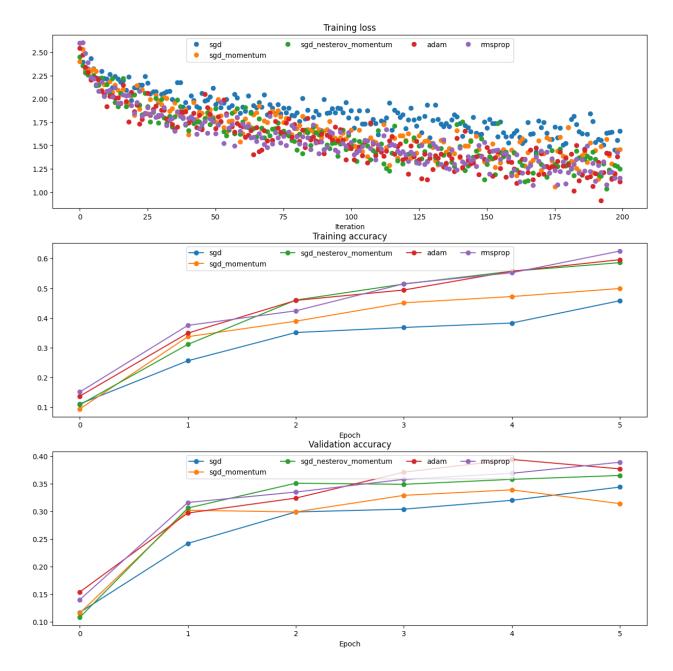
plt.subplot(3, 1, 3)
    plt.plot(solver.val_acc_history, '-o', label=update_rule)

for i in [1, 2, 3]:
    plt.subplot(3, 1, i)
    plt.legend(loc='upper center', ncol=4)

plt.gcf().set_size_inches(15, 15)

plt.show()

Optimizing with adam
Optimizing with rmsprop
```



Easier optimization

In the following cell, we'll train a 4 layer neural network having 500 units in each hidden layer with the different optimizers, and find that it is far easier to get up to 50+% performance on CIFAR-10. After we implement batchnorm and dropout, we'll ask you to get 55+% on CIFAR-10.

```
optimizer = 'adam'
best_model = None

layer_dims = [500, 500, 500]
weight_scale = 0.01
```

```
learning rate = 1e-3
lr decay = 0.9
model = FullyConnectedNet(layer dims, weight scale=weight scale,
                          use batchnorm=True)
solver = Solver(model, data,
                num epochs=10, batch size=100,
                update rule=optimizer,
                optim config={
                  'learning rate': learning rate,
                lr decay=lr decay,
                verbose=True, print every=50)
solver.train()
(Iteration 1 / 4900) loss: 2.320216
(Epoch 0 / 10) train acc: 0.201000; val acc: 0.215000
(Iteration 51 / 4900) loss: 1.802697
(Iteration 101 / 4900) loss: 1.839267
(Iteration 151 / 4900) loss: 1.642738
(Iteration 201 / 4900) loss: 1.675290
(Iteration 251 / 4900) loss: 1.674492
(Iteration 301 / 4900) loss: 1.422024
(Iteration 351 / 4900) loss: 1.485432
(Iteration 401 / 4900) loss: 1.482620
(Iteration 451 / 4900) loss: 1.431989
(Epoch 1 / 10) train acc: 0.482000; val acc: 0.478000
(Iteration 501 / 4900) loss: 1.520223
(Iteration 551 / 4900) loss: 1.412681
(Iteration 601 / 4900) loss: 1.211547
(Iteration 651 / 4900) loss: 1.431844
(Iteration 701 / 4900) loss: 1.455634
(Iteration 751 / 4900) loss: 1.300787
(Iteration 801 / 4900) loss: 1.336608
(Iteration 851 / 4900) loss: 1.292135
(Iteration 901 / 4900) loss: 1.313295
(Iteration 951 / 4900) loss: 1.579138
(Epoch 2 / 10) train acc: 0.580000; val_acc: 0.515000
(Iteration 1001 / 4900) loss: 1.260819
(Iteration 1051 / 4900) loss: 1.107324
(Iteration 1101 / 4900) loss: 0.995973
(Iteration 1151 / 4900) loss: 1.258211
(Iteration 1201 / 4900) loss: 1.495768
(Iteration 1251 / 4900) loss: 1.232023
(Iteration 1301 / 4900) loss: 1.316851
(Iteration 1351 / 4900) loss: 1.124855
(Iteration 1401 / 4900) loss: 1.227120
(Iteration 1451 / 4900) loss: 1.224893
(Epoch 3 / 10) train acc: 0.625000; val acc: 0.547000
```

```
(Iteration 1501 / 4900) loss: 1.331305
(Iteration 1551 / 4900) loss: 1.248914
(Iteration 1601 / 4900) loss: 1.115145
(Iteration 1651 / 4900) loss: 1.183321
(Iteration 1701 / 4900) loss: 1.126724
(Iteration 1751 / 4900) loss: 1.120186
(Iteration 1801 / 4900) loss: 1.080077
(Iteration 1851 / 4900) loss: 0.958713
(Iteration 1901 / 4900) loss: 1.149974
(Iteration 1951 / 4900) loss: 1.206972
(Epoch 4 / 10) train acc: 0.646000; val acc: 0.540000
(Iteration 2001 / 4900) loss: 0.950351
(Iteration 2051 / 4900) loss: 0.785877
(Iteration 2101 / 4900) loss: 0.930028
(Iteration 2151 / 4900) loss: 1.078887
(Iteration 2201 / 4900) loss: 0.922855
(Iteration 2251 / 4900) loss: 1.203087
(Iteration 2301 / 4900) loss: 1.115383
(Iteration 2351 / 4900) loss: 1.043127
(Iteration 2401 / 4900) loss: 1.017699
(Epoch 5 / 10) train acc: 0.666000; val acc: 0.564000
(Iteration 2451 / 4900) loss: 1.208598
(Iteration 2501 / 4900) loss: 0.836278
(Iteration 2551 / 4900) loss: 0.963328
(Iteration 2601 / 4900) loss: 0.937147
(Iteration 2651 / 4900) loss: 0.813613
(Iteration 2701 / 4900) loss: 0.865801
(Iteration 2751 / 4900) loss: 1.139042
(Iteration 2801 / 4900) loss: 0.806744
(Iteration 2851 / 4900) loss: 0.726715
(Iteration 2901 / 4900) loss: 0.810212
(Epoch 6 / 10) train acc: 0.701000; val acc: 0.561000
(Iteration 2951 / 4900) loss: 0.848263
(Iteration 3001 / 4900) loss: 0.917435
(Iteration 3051 / 4900) loss: 0.701462
(Iteration 3101 / 4900) loss: 0.700631
(Iteration 3151 / 4900) loss: 0.718690
(Iteration 3201 / 4900) loss: 0.787667
(Iteration 3251 / 4900) loss: 0.761422
(Iteration 3301 / 4900) loss: 0.931597
(Iteration 3351 / 4900) loss: 0.949510
(Iteration 3401 / 4900) loss: 0.740956
(Epoch 7 / 10) train acc: 0.710000; val acc: 0.566000
(Iteration 3451 / 4900) loss: 0.817906
(Iteration 3501 / 4900) loss: 0.721976
(Iteration 3551 / 4900) loss: 0.736508
(Iteration 3601 / 4900) loss: 0.807700
(Iteration 3651 / 4900) loss: 0.784453
(Iteration 3701 / 4900) loss: 0.837618
```

```
(Iteration 3751 / 4900) loss: 0.610160
(Iteration 3801 / 4900) loss: 0.734950
(Iteration 3851 / 4900) loss: 0.926549
(Iteration 3901 / 4900) loss: 0.755103
(Epoch 8 / 10) train acc: 0.765000; val acc: 0.555000
(Iteration 3951 / 4900) loss: 0.592995
(Iteration 4001 / 4900) loss: 0.686560
(Iteration 4051 / 4900) loss: 0.656597
(Iteration 4101 / 4900) loss: 0.545963
(Iteration 4151 / 4900) loss: 0.672857
(Iteration 4201 / 4900) loss: 0.576171
(Iteration 4251 / 4900) loss: 0.433184
(Iteration 4301 / 4900) loss: 0.544410
(Iteration 4351 / 4900) loss: 0.595788
(Iteration 4401 / 4900) loss: 0.534230
(Epoch 9 / 10) train acc: 0.784000; val acc: 0.550000
(Iteration 4451 / 4900) loss: 0.659326
(Iteration 4501 / 4900) loss: 0.381986
(Iteration 4551 / 4900) loss: 0.709688
(Iteration 4601 / 4900) loss: 0.592681
(Iteration 4651 / 4900) loss: 0.470972
(Iteration 4701 / 4900) loss: 0.468080
(Iteration 4751 / 4900) loss: 0.854547
(Iteration 4801 / 4900) loss: 0.510759
(Iteration 4851 / 4900) loss: 0.718478
(Epoch 10 / 10) train acc: 0.783000; val acc: 0.563000
y test pred = np.argmax(model.loss(data['X test']), axis=1)
y val pred = np.argmax(model.loss(data['X val']), axis=1)
print('Validation set accuracy: {}'.format(np.mean(y val pred ==
data['y val'])))
print('Test set accuracy: {}'.format(np.mean(y test pred ==
data['y test'])))
Validation set accuracy: 0.575
Test set accuracy: 0.598
```