Computer Architecture Cheatsheet

Module 16 – System

System Overview

Components Beyond CPU and Memory:

- Input/Output (I/O) Devices: Interfaces for data exchange between the computer and the external environment.
- Secondary/Tertiary Storage: Flash drives, HDDs, SSDs, tapes.
- Network Interfaces: Ethernet, WiFi, Bluetooth, LTE.
- Human-Machine Interfaces (HMIs): Keyboards, mice, touchscreens, displays, audio systems.
- **Printers and Sensors:** Various types including 3D printers, GPS sensors, heart rate monitors.
- Actuators: Valves, robotic arms, automotive brakes.

I/O Communication Methods

Direct Channels/Register-Based I/O:

- Use specific registers or channels for communication.
- Common in microcontrollers and simple embedded systems.

Memory-Mapped I/O (MMIO):

- Reserve a portion of the address space for I/O devices.
- I/O operations are performed using standard memory instructions (load/store).
- Typically "uncached" memory addresses (using page tables).
- Virtual Address considerations.

Communication Technologies and Protocols

- Time-Multiplexed, Shared, and Slow: PCI, IDE.
- Shared but Faster: Ethernet, SATA.
- Dedicated Channels: PCIe.
- Handshaking Protocols: Asynchronous communication using arbiter, initiator, and target.
- Fixed Timing Protocols: Synchronous communication with predefined timing.

Direct Memory Access (DMA)

Overview:

 DMA allows peripherals to read/write memory without CPU intervention.

- Offloads data transfer tasks from the CPU, improving performance.
- Typically managed by a DMA controller or engine.

DMA Operation:

- 1. CPU initializes DMA transfer by setting up DMA registers.
- 2. DMA controller handles the data transfer between I/O device and memory.
- 3. Upon completion, DMA controller sends an interrupt to notify the CPU.

Benefits and Drawbacks: Benefits:

- Reduces CPU overhead for data transfers.
- Enables simultaneous data transfers and CPU processing.

Drawbacks:

- Complexity in managing multiple DMA channels.
- Potential for bus contention and performance bottlenecks.

Network-on-Chip (NoC)

Overview:

- NoC is an on-chip communication subsystem that connects multiple cores, memory controllers, GPUs, and I/O devices.
- Facilitates efficient data exchange and scalability in multicore processors.

Design Challenges:

- Performance Optimization: Ensuring low latency and high throughput.
- Scalability: Supporting increasing numbers of cores and devices.
- **Energy Efficiency:** Minimizing power consumption.
- **Security:** Protecting against data breaches and unauthorized access.
- Integration with Emerging Paradigms: Adapting to new computing models and technologies.

Design Ingredients:

- **Topology:** Network structure (mesh, torus, star, etc.).
- Routing Logic: Algorithms for data packet traversal.
- Router Design: Handling data packets, buffering, and flow control.
- Bandwidth and Latency: Ensuring sufficient data transfer rates and minimal delays.

Interrupts, Exceptions, and Traps

Definitions:

- Exception: An unusual condition occurring at runtime associated with an instruction (e.g., division by zero).
- **Trap:** A synchronous transfer of control to a handler due to an exceptional condition within a thread.
- Interrupt: An external event that occurs asynchronously to the current thread (e.g., I/O events).

Handling Mechanisms: Interrupt Handling:

- Interrupt Exception: Occurs to handle the interrupt.
- Trap Execution: Transfers control to the interrupt handler.
- **Priority Management:** Determines when to trap based on interrupt priority.

Exception Handling:

- Precise Exceptions: Ensure all states are maintained for accurate recovery.
- Examples: Branch mispredictions, unknown instructions, hardware failures.

Trap Handling:

- System Calls: Transition to OS handlers with specific service parameters.
- Handler Tables: Use tables to jump to appropriate subroutines based on trap parameters.

Interrupt vs. Polling vs. Hybrid

Interrupt:

- Pros: Low CPU overhead until event occurs.
- Cons: Can occur unpredictably, causing contextswitch overhead.

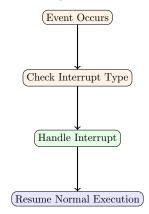
Polling:

- Pros: Can be fully scheduled, predictable.
- Cons: High CPU overhead, difficult to implement efficiently.

Hybrid Approach:

• Use interrupts initially, switch to polling after the first event, and revert to interrupts after a certain period.

Interrupt Handling Flowchart



Module 15 – Memory Consistency

Consistency Problem Example

Initially:
$$M[Z] = M[Y] = 0$$
, $x3 = 100$, $x4 = 200$
Core1: lw x1, Z(x0)
...
sw Y, x3(x0)
Core2: lw x2, Y(x0)
...
sw Z, x4(x0)

Potential Values for x1 **and** x2**:** Depending on the order of memory operations, x1 and x2 can take values 0 or 200 and 0 or 100, respectively.

Memory Consistency vs. Coherency

- Consistency: Ordering of parallel accesses between different addresses.
- Coherency: Ordering of parallel accesses to the same address.

Memory Model

Definition: Interactions between threads and the shared memory. In other words, what are the possible values for a load?

Sequential Consistency (SC)

- 1. Processors see their own loads and stores in program order.
- 2. Processors see others' loads and stores in program order.
- 3. All processors see the same global load/store ordering.

Characteristics:

- Simplest memory model.
- Makes multicore systems indistinguishable from multi-programmed in-order uniprocessors.
- Too slow due to strict ordering constraints.

Memory Operation Ordering

Four Types of Memory Operation Orderings:

- W→R: Write must complete before subsequent read.
- **R**→**R**: Read must complete before subsequent read.
- W→W: Write must complete before subsequent write.

Sequential Consistency: Maintains all four orderings. Relaxed Memory Consistency Models: Allow certain orderings to be violated for performance gains.

Total Store Order (TSO) Model

Definition: A relaxed memory consistency model where processors can reorder certain memory operations to improve performance.

Key Points:

- Processors can move their own reads in front of their own writes.
- Read by other processors cannot return the new value of a write until the write is visible to all processors.

Example Scenario:

 $a=0,\ flag=0$ Thread 1: store $1\to a$ store $1\to flag$ Thread 2: loop: if (flag == 0) goto loop load a

Question: Can the load in Thread 2 read 0? TSO vs. SC:

Initially: M[Z] = M[Y] = 0Core1: lw x1, Z Core2: lw x2, Y ... Core1: sw Y, 100 Core2: sw Z, 200

Potential Values for x1 **and** x2**:** Depending on the visibility and ordering of writes, x1 and x2 can take 0 or the updated values.

Weak Consistency

- Relaxed memory ordering allows certain memory operation orderings to be violated.
- Performance vs. complexity trade-off.
- Different architectures use different weak consistency models.

RISC-V Weak Memory Ordering (RVWMO)

- Loads are optimistically fired to memory on arrival to the Load-Store Unit (LSU) for performance.
- Load instructions compare their address with all dependent store addresses:
 - If a match is found, the memory request is either:
 - * Killed: If the store data is not present, the load goes to sleep and retries later.
 - * Forwarded: If the store data is present, forward the data to the load and mark it as succeeded.

• Behavior:

- Write → Read Constraint: Relaxes the ordering, allowing newer loads to execute before older stores.
- Read → Read Constraint: Maintains ordering; loads to the same address appear in order.
- Own Writes Early: A thread can read its own writes early.

Writing Correct Programs

Approaches:

• Race-Free Programming: Ensure that there are no data races in the program.

• Synchronization Primitives: Use fences, mutexes, semaphores, etc., to enforce ordering and visibility.

Synchronization Mechanisms

Fences:

- **Definition:** An instruction that enforces all memory operations before it to complete before the fence is executed. All memory operations after the fence must wait until the fence is completed.
- Usage in RISC-V:

```
fence rwio
fence r, r
```

Semaphores and Barriers: Semaphores:

- Used to synchronize access to shared resources.
- Implemented using flags or counters.
- Typically implemented in software.

Barriers:

- Synchronize all processors at a certain point in the program.
- Implemented using hardware flags or software synchronization.

Mutexes and Locks:

- Mutual Exclusiveness: Ensures only one thread accesses a shared resource at a time.
- Implementation:

```
acquire(lock) {
    while (lock != 0) { /* busy
        wait */ }
    lock = 1; // Acquire the lock
}

release(lock) {
    lock = 0; // Release the lock
}
```

Atomic Instructions:

- Hardware primitives that guarantee instructions are executed in-order and without interruption.
- Examples:
 - Test-and-Set:

- Compare-and-Swap (CAS)
- Fetch-and-Add

$\begin{array}{ccc} {\rm Load\text{-}Reserved} & {\rm and} & {\rm Store\text{-}Conditional} \\ {\rm (LR/SC):} & \end{array}$

- Load-Reserved: Processor remembers the address.
- Store-Conditional: Attempts to store only if no write has occurred to the address since the last load-reserved.
- Example in RISC-V:

```
loop:
    lr.w x2, 0(x1)
    addi x2, x0, 1
    sc.w x2, 0(x1)
    bnez x2, loop // Retry if
    store-conditional failed
```

- MESI Protocol Integration:
 - Load-Reserved: Ensures the cache line is in Exclusive or Modified state.
 - Store-Conditional: Succeeds only if the cache line remains in Exclusive or Modified state.

Synchronization Example: Producer-Consumer Model

Example Code:

```
thread1:
    sw Y, 100
    fence
    sw X, 1

thread2:
    lw X, 0
    if (X == 1) {
        lw Y, 0
    }
}
```

Explanation:

- Thread1: Stores to Y and then to X with a memory fence to ensure ordering.
- Thread2: Loads X first and, if X is 1, then loads Y, ensuring Y is updated before X.

Optimizations in Synchronization

Test-Test-and-Set (TTAS):

```
TTS(int x) {
    oldval = x; // Read the lock
    if (oldval == 0) {
        oldval = SWAP(x, 1); // Attempt to
            acquire lock
    }
    return oldval;
}
// Usage
while (TTS(lock) == 1) { /* busy wait */ }
```

Benefits:

• Reduces the number of atomic operations by first testing the lock before attempting to set it.

Other Optimizations:

- Queue-Based Locks: Ensures fairness by queuing lock acquisition requests.
- Multiple/Parallel Locks: Allows multiple locks to be acquired concurrently for different resources.

Final Recap and Bottom-Line

Memory Consistency Models:

- Range from Sequential Consistency (strong) to Weak Consistency (relaxed).
- Balance between performance and correctness.

Synchronization:

- Essential for ensuring correctness in parallel programs.
- Achieved using fences, mutexes, semaphores, and atomic operations.

Cache Coherency:

- Critical for maintaining consistency across multicore processors.
- Implemented using protocols like MESI, MOESI, and MOESIF.

TLB and Address Translation:

- TLBs speed up virtual to physical address translation.
- Critical for performance in systems with virtual memory.

I/O and DMA:

- Efficient I/O handling is crucial for overall system performance.
- DMA offloads data transfer tasks from the CPU, enhancing efficiency.

Network-on-Chip (NoC):

- Facilitates efficient communication in multicore systems.
- Essential for scalability and performance in modern processors.

Module 14 – Cache Coherency

Cache Coherency Basics

Definition: Uniformity of shared resource data that ends up stored in multiple local caches.

Coherency vs. Consistency

- Coherency: Ensures that multiple caches reflect the same value for a shared data item.
- Consistency: Refers to the order in which memory operations appear to execute across multiple processors.

Cache Coherence Problem

Example Scenario:

```
M[Z] = 0 (Z is an address, e.g., 0x200), x5 = 10 Core1: lw x1, 0(Z) ...

Core2: lw x3, 0(Z) ...

Core1: sw x5, 0(Z) Core2: lw x6, 0(Z)
```

Problem: Ensuring that Core2's load after Core1's store gets the updated value.

Coherence Protocols

Snooping Protocols:

- **Definition:** Caches monitor (snoop) the shared bus for memory operations to maintain coherence.
- Write Miss: The address is invalidated in all other caches before the write is performed.
- Read Miss: If a dirty copy is found in another cache, a write-back is performed before the memory is read. Otherwise, read from memory.

Coherence States

Basic States (MI Protocol):

- Modified (M): The cache line is dirty and has the only valid copy.
- Invalid (I): The cache line is invalid.

Enhanced States:

- Shared (S): The cache line is clean and can be shared among multiple caches.
- Exclusive (E): The cache line is clean and is only present in one cache.
- Owned (O): The cache line is dirty but shared; one cache owns the dirty copy.
- Forwarding (F): The cache line is shared and one cache acts as a forwarder.

MSI Coherence Protocol

States:

- Modified (M)
- Shared (S)
- Invalid (I)

State Transitions:

- Read Miss: Transition from I to S or E.
- Write Miss: Transition from I to M.
- Write to S: Transition from S to M (with invalidation).

MESI Coherence Protocol

States:

- Modified (M)
- Exclusive (E)
- Shared (S)
- Invalid (I)

Enhancements:

- Exclusive (E): Allows silent upgrades to M without broadcasting.
- Transition Rules:
 - **I** \rightarrow **E**: On read miss if no other cache has the line.
 - $\mathbf{E} \to \mathbf{M}$: On write, silently upgrade to M.
 - $-\mathbf{E} \to \mathbf{S}$: If another cache requests the line, transition to S.

MOSI Coherence Protocol

States:

- Modified (M)
- Owned (O)
- Shared (S)
- Invalid (I)

Enhancements:

- Owned (O): Allows one cache to own the dirty copy while others have shared clean copies.
- State Transitions:
 - $-\mathbf{M} \to \mathbf{O}$: On read request from another cache.
 - **O** \rightarrow **I**: On write request from another cache.

MOESI Coherence Protocol

States:

- Modified (M)
- Owned (O)
- Exclusive (E)
- Shared (S)
- Invalid (I)

Enhancements:

- Exclusive (E) and Owned (O) States: Combine benefits of E and O.
- State Transitions:
 - $I \rightarrow E$: On read miss with no other copies.
 - $-\mathbf{E} \to \mathbf{M}$: On write.
 - $\mathbf{E} \rightarrow \mathbf{S}$: On read by another cache.
 - $-\mathbf{M} \to \mathbf{O}$: On read by another cache.
 - **O** \rightarrow **I**: On write by another cache.

MOESIF Coherence Protocol

States:

- Modified (M)
- Owned (O)
- Exclusive (E)
- Shared (S)
- Invalid (I)
- Forwarder (F)

Enhancements:

- Forwarder (F): Acts as a source for data to other caches, reducing the need for multiple cache-to-cache transfers.
- State Transitions:
 - $-\mathbf{S} \to \mathbf{F}$: When a cache acts as a forwarder.
 - **F** \rightarrow **I:** When another cache modifies the data.

False Sharing

Definition: Occurs when multiple processors cache the same cache line containing different variables, leading to unnecessary invalidations.

Impact: Causes coherence misses and reduces cache efficiency.

Directory-Based Coherence Protocol

- Definition: Uses a centralized directory to keep track of which caches have copies of each cache line
- Advantages: Scales better than snooping protocols, reduces bus traffic.
- Operation:
 - On a cache miss, the directory is consulted to determine which caches have the line.
 - Coherence actions are directed only to those caches, avoiding unnecessary broadcasts.

Coherence Example

```
\begin{split} M[Z] &= 0 \quad \text{(Z is an address, e.g., } 0x200\text{)}, \ x5 = 10\\ \text{Core1: lw x1, } 0(\text{Z})\\ & \dots\\ \text{Core2: lw x3, } 0(\text{Z})\\ & \dots\\ \text{Core1: sw x5, } 0(\text{Z})\\ \text{Core2: lw x6, } 0(\text{Z}) \end{split}
```

Goal: Ensure Core2's load after Core1's store gets the updated value.

Module 15 – Memory Consistency (Continued)

Consistency Problems

- Reordering Issues: SW and LW (to different addresses) within one core can be reordered, disrupting assumptions in other cores.
- **Timing Issues:** The timing between cores might be off, even without reordering.

Solutions to Consistency Problems

Synchronization Strategies:

- Fences: Enforce ordering constraints.
- Mutexes/Locks: Ensure mutual exclusiveness for shared resources.
- Semaphores and Barriers: Coordinate actions among multiple threads or cores.

Synchronization Using Semaphores

Example:

Core1: lw x1, Z
...
Core1: sw Y, 100
Core2: lw x3, Y
...
Core2: sw Z, 200

Implementation in Hardware:

- Use one-hot encoding to set a flag when a core reaches the barrier.
- Wait until all flags are set.

Mutual Exclusiveness

Definition: Ensures only one process accesses a shared region at any given time.

Implementation Using Mutexes/Locks:

```
acquire(lock) {
   while (lock != 0) { /* busy wait */ }
   lock = 1; // Acquire the lock
}

release(lock) {
   lock = 0; // Release the lock
}
```

Assembly Version:

```
loop:
    lw ra, 0(x1)
    bnez ra, loop
    addi ra, x0, 1
    sw ra, 0(x1)

release:
    sw x0, 0(x1)
```

Atomic Instructions:

• Test-and-Set (TS):

• Load-Reserved and Store-Conditional (LR/SC):

Release Consistency

- Guarantees that all reads and writes within acquire/release blocks are completed and visible to all cores upon releasing the lock.
- Allows for reordering of memory operations outside synchronization blocks.

Recap

- Locks: Test-and-set, Atomic operations, LR/SC.
- Optimizations: Test-Test-and-Set (TTAS), Queue-based locks, Multiple/Parallel Locks.
- **Synchronization:** Essential for maintaining consistency and correctness in multicore systems.

Module 14 – Cache Coherency (Continued)

False Sharing

• **Definition:** Occurs when multiple processors cache the same cache line containing different variables, leading to unnecessary invalidations.

• Impact: Causes coherence misses and reduces cache efficiency.

Optimizing MSI Coherence Protocol

- **Issue:** Unnecessary broadcasts and write-backs when a core with an exclusive cache line wants to write.
- Solution: Introduce the Exclusive (E) state to allow silent upgrades from S to M without broadcasting.

Coherence States and Transitions

MSI Protocol:

• States: Modified (M), Shared (S), Invalid (I).

• Transitions:

– Read Miss: $I \rightarrow S$ or E.

– Write Miss: $I \rightarrow M$.

- Write to S: $S \to M$ (with invalidation).

MESI Protocol:

- States: Modified (M), Exclusive (E), Shared (S), Invalid (I).
- Enhancements: Allows silent upgrades from E to M, transitions between E and S.

MOSI Protocol:

- States: Modified (M), Owned (O), Shared (S), Invalid (I).
- Enhancements: Owned state allows a cache to supply data to others without write-back.

MOESI Protocol:

- States: Modified (M), Owned (O), Exclusive (E), Shared (S), Invalid (I).
- Enhancements: Combines Exclusive and Owned states for better efficiency.

MOESIF Protocol:

- States: Modified (M), Owned (O), Exclusive (E), Shared (S), Invalid (I), Forwarder (F).
- Enhancements: Forwarder state allows one cache to supply data to multiple caches, reducing cacheto-cache transfers.

Optimizing MSI and MESI

- Silently Upgrade to M from E: Avoid unnecessary broadcasts.
- Forwarding (F) State in MOESIF: Reduces cache-to-cache traffic by designating a forwarder.
- Directory-Based Coherence: Scales better by using a centralized directory to track cache line states.

Coherence Example with MOESI

Mem[Z] = 0, Z = address 0x200, x5 = 10 Core1: lw x1, 0(Z) ... Core2: lw x3, 0(Z) ... Core1: sw x5, 0(Z) Core2: lw x6, 0(Z)

Goal: Ensure Core2's load after Core1's store gets the updated value using the MOESI protocol.

Directory-Based Coherence Protocol

- Central Directory: Keeps track of which caches have copies of each cache line.
- Operation:
 - On a cache miss, consult the directory to determine which caches have the line.
 - Send coherence messages only to those caches, avoiding unnecessary broadcasts.
- Advantages: Scales better than snooping protocols, reduces bus traffic.

Module 14 – Cache Coherency (Continued)

Cache Coherency States and Transitions

States:

- Shared (S): Multiple caches have the line in a clean state.
- Modified (M): Only one cache has the line in a dirty state.
- Exclusive (E): Only one cache has the line, and it is clean.
- Owned (O): One cache has the dirty line, and others may have shared clean copies.
- Invalid (I): The cache line is invalid.
- Forwarder (F): A cache acts as the forwarder for the line.

State Transitions:

• Read Miss: $I \to S$ or E.

• Write Miss: $I \to M$.

 Read Hit: S, E, O → Remain or transition based on access.

• Write Hit: S, E, $O \rightarrow M$.

False Sharing

Definition: Occurs when multiple processors cache the same cache line containing different variables, leading to unnecessary invalidations.

Impact: Causes coherence misses and reduces cache efficiency.

Directory-Based Coherence Protocol

- Central Directory: Maintains a record of which caches have copies of each cache line.
- Operation:
 - On a cache miss, the requesting cache queries the directory.
 - The directory responds with the list of caches that have the line.
 - Coherence actions (e.g., invalidations, data forwarding) are directed only to those caches.
- Advantages:
 - Scales better than snooping protocols.
 - Reduces unnecessary bus traffic.

Coherence Protocol Example: MOESIF

States:

- Modified (M)
- Owned (O)
- Exclusive (E)
- Shared (S)
- Invalid (I)
- Forwarder (F)

State Transitions:

- $\mathbf{I} \to \mathbf{E}$: On a read miss if no other cache has the line
- $\mathbf{E} \to \mathbf{M}$: On a write, silently upgrade to M.
- M → O: On a read by another cache, transition to O
- O → I: On a write by another cache, transition to I after writing back.
- $S \to F$: When acting as a forwarder.

Benefits:

- Reduces unnecessary data traffic.
- Improves cache line utilization.
- Enhances performance by minimizing cache-to-cache transfers.

Cache Coherency Example with MOESIF

M[Z] = 0, Z = address 0x200, x5 = 10

Core1: lw x1, 0(Z) (S)

. . .

Core2: lw x3, 0(Z) (S)

. . .

Core1: sw x5, 0(Z) (M)

Core2: lw x6, 0(Z) (F)

Goal: Ensure Core2's load after Core1's store gets the updated value efficiently using MOESIF protocol.

Key Metrics and Formulas

Cache Metrics

Average Memory Access Time (AMAT):

 $AMAT = Hit Time + (Miss Rate \times Miss Penalty)$

Cache Access Time:

Total Access Time = L1 Access Time+L2 Access Time+L3 Acc

Performance Metrics

Clock Cycles per Instruction (CPI):

$$\text{CPI} = \frac{\text{Total Clock Cycles}}{\text{Total Instructions}}$$

Execution Time:

Execution Time = CPI×Clock Period×Number of Instructions

Address Translation Metrics

Page Offset Bits:

Page Offset Bits = $log_2(Page Size)$

VPN Bits:

VPN Bits = Virtual Address Size - Page Offset Bits

PPN Calculation:

Physical Page Number (PPN) =
$$\left\lfloor \frac{\text{Physical Address}}{\text{Page Size}} \right\rfloor$$

Tables and Figures

Cache Performance Metrics

Cache Level	Hit Time (ns)	Miss Penalty (ns)
L1	1	10
L2	5	50
L3	10	100
Main Memory	100	-

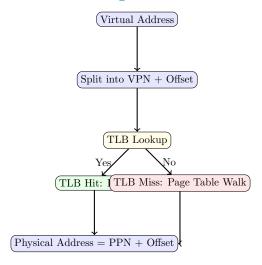
Table 1: Cache Performance Metrics

Cache Mapping Schemes Comparison

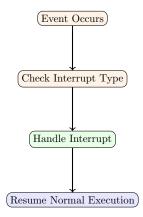
Mapping Scheme	Flexibility	Complexity	Speed
Direct-Mapped Set-Associative	Low Medium	Low Medium	Fast Moderate
Fully Associative	High	High	Slow

Table 2: Comparison of Cache Mapping Schemes

TLB Workflow Diagram



Interrupt Handling Flowchart



Multi-Core Systems

Introduction to Multi-Core Systems

- Leverage multiple cores to improve performance.
- Design choices include how to share memory, cache hierarchies, and interconnects.
- Challenges include cache coherency, memory consistency, and efficient inter-core communication.

SMT vs. Multitasking

Simultaneous Multithreading (SMT):

- Execute multiple threads on the same pipeline.
- Utilizes pipeline resources more efficiently.
- Each thread requires its own:
 - Program Counter (PC)
 - Register file
 - Logic for virtual address translation
 - Exception handling mechanism

Multitasking:

- Running different processes/tasks on the same core.
- Managed by the operating system through thread scheduling and context switching.
- Creates the illusion of concurrent execution on single-core systems.

Multicore Design Choices

Shared vs. Private Caches:

- Shared Caches: Multiple cores share a common cache level (e.g., L3).
- Private Caches: Each core has its own dedicated cache levels (e.g., L1, L2).
- **Hybrid Approach:** Combines shared and private caches to balance performance and scalability.

Interconnects:

- Network-on-Chip (NoC) used to connect multiple cores and shared resources.
- Ensures efficient data transfer and communication between cores.

Cache Coherency in Multicore Systems

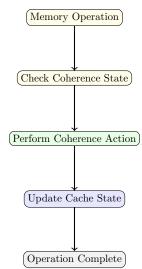
- Ensures that all caches reflect the most recent write to any shared data.
- Implemented using coherence protocols like MESI, MOESI, and MOESIF.
- Can use snooping or directory-based approaches.

Cache Coherency Example

Mem[Z] = 0, Z = address 0x200, x5 = 10 Core1: lw x1, 0(Z) (S) ... Core2: lw x3, 0(Z) (S) ... Core1: sw x5, 0(Z) (M) Core2: lw x6, 0(Z) (F)

Goal: Ensure Core2's load after Core1's store gets the updated value efficiently using the MOESIF protocol.

Cache Coherence Flowchart



Additional Tables

Coherence Protocols Overview

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Protocol	States	Key Feature	Benefit
MSI	M, S, I	Simple state model	Low complexity
MESI	M, E, S, I	Adds Exclusive state	Reduces invalidations
MOSI	M, O, S, I	Adds Owned state	Efficient cache-to-cache transfers
MOESI	M, O, E, S, I	Combines Exclusive and Owned	Enhanced performance
MOESIF	M, O, E, S, I, F	Adds Forwarder state	Reduces cache-to-cache traffic

Table 3: Overview of Coherence Protocols