Vermicompost Monitoring & Management System - Arduino Code

```
#include <Wire.h>
#include <LiquidCrystal_I2C.h>
#define DHTPIN 2
                      // Pin connected to DHT11 data pin
#define MAX_TIMINGS 85
#define DHTTYPE DHT11 // DHT11 sensor type
#define moisturePin A0 // Analog pin A0 for the soil moisture sensor
#define PUMP_PIN P2_2 // Pin connected to the pump control
#define FAN_PIN P2_0
                          // Pin connected to the fan control
#define LED GREEN P1 4
#define LED RED P1 5
                         // Pin connected to Red LED (for temperature indication)
int dht11_dat[5] = \{0, 0, 0, 0, 0\}; // Array to hold the data from DHT11
int moisture Threshold = 40;
                                // Threshold for moisture level (in percentage)
float temperatureThreshold = 30+.0; // Threshold for fan activation (in Celsius)
LiquidCrystal_I2C lcd(0x27, 16, 2); // Create LCD object for I2C Display
unsigned long lastReadingTime = 0; // To track time for sensor readings
const unsigned long interval = 2000; // 2-second interval
bool showTemperatureHumidity = true; // Toggle between temp/humidity and moisture
int dryValue = 4095; // Analog reading when the soil is completely dry
int wetValue = 1500; // Analog reading when the soil is completely wet
void setup() {
  Serial.begin(9600);
  pinMode(DHTPIN, OUTPUT);
  digitalWrite(DHTPIN, HIGH);
  pinMode(PUMP_PIN, OUTPUT);
  digitalWrite(PUMP_PIN, HIGH);
  pinMode(FAN_PIN, OUTPUT);
  digitalWrite(FAN_PIN, HIGH);
  pinMode(LED_GREEN, OUTPUT);
  digitalWrite(LED_GREEN, HIGH);
  pinMode(LED_RED, OUTPUT);
  digitalWrite(LED_RED, HIGH);
  lcd.begin();
  lcd.backlight();
  lcd.setCursor(0, 0);
  lcd.print("Initializing...");
  delay(2000);
}
void loop() {
  unsigned long currentMillis = millis();
  if (currentMillis - lastReadingTime >= interval) {
    lastReadingTime = currentMillis;
    showTemperatureHumidity = !showTemperatureHumidity;
```

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```
if (showTemperatureHumidity) {
  int chk = readDHT11();
  if (chk == 0) {
    float temperature = dht11_dat[2] + dht11_dat[3] / 10.0;
    if (temperature > temperatureThreshold) {
       digitalWrite(FAN_PIN, LOW);
       Serial.println("Fan: ON");
       digitalWrite(LED_GREEN, LOW);
       Serial.println("GREEN LED: ON");
     } else {
       digitalWrite(FAN_PIN, HIGH);
       Serial.println("Fan: OFF");
       digitalWrite(LED_GREEN, HIGH);
       Serial.println("GREEN LED: OFF");
    }
    lcd.clear();
    lcd.setCursor(0, 0);
    lcd.print("Temp: ");
    lcd.print(temperature);
    lcd.print(" C");
    lcd.setCursor(0, 1);
    lcd.print("Hum: ");
    lcd.print(dht11 dat[0]);
    lcd.print(" %");
    displayError("DHT11 Error");
} else {
  int moistureLevel = analogRead(moisturePin);
  int moisturePercent = map(moistureLevel, dryValue, wetValue, 0, 100);
  moisturePercent = constrain(moisturePercent, 0, 100);
  if (moisturePercent < moistureThreshold) {</pre>
    digitalWrite(PUMP_PIN, LOW);
    Serial.println("Pump: ON");
    digitalWrite(LED_RED, LOW);
    Serial.println("RED LED: ON");
  } else {
    digitalWrite(PUMP_PIN, HIGH);
    Serial.println("Pump: OFF");
    digitalWrite(LED_RED, HIGH);
    Serial.println("RED LED: OFF");
  Serial.print("Soil Moisture Level: ");
  Serial.print(moisturePercent);
  Serial.println(" %");
  lcd.clear();
  lcd.setCursor(0, 0);
  lcd.print("Moisture Level:");
  lcd.setCursor(0, 1);
  lcd.print(moisturePercent);
  lcd.print(" %");
```

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```
}
       delay(2000);
int readDHT11() {
       uint8_t laststate = HIGH;
       uint8_t counter = 0;
       uint8_t j = 0, i;
       dht11_dat[0] = dht11_dat[1] = dht11_dat[2] = dht11_dat[3] = dht11_dat[4] = 0;
       pinMode(DHTPIN, OUTPUT);
       digitalWrite(DHTPIN, LOW);
       delay(18);
       digitalWrite(DHTPIN, HIGH);
       delayMicroseconds(40);
       pinMode(DHTPIN, INPUT);
       for (i = 0; i < MAX\_TIMINGS; i++) {
               counter = 0;
               while (digitalRead(DHTPIN) == laststate) {
                       counter++;
                       delayMicroseconds(1);
                      if (counter == 255) break;
               laststate = digitalRead(DHTPIN);
               if (counter == 255) break;
               if ((i >= 4) \&\& (i \% 2 == 0)) {
                        dht11_dat[j / 8] <<= 1;
                      if (counter > 16)
                               dht11_dat[j / 8] = 1;
                      j++;
                }
       if \ ((j>=40) \ \&\& \ (dht11\_dat[4] == ((dht11\_dat[0] + dht11\_dat[1] + dht11\_dat[2] + dht11\_dat[3]) \ \& \ 0xFF))) \ \{delta(f) = ((dht11\_dat[4] + dht11\_dat[4] + dht11\_dat[4]) \ \& \ (dht11\_dat[4] = ((dht11\_dat[0] + dht11\_dat[1] + dht11\_dat[2] + dht11\_dat[3]) \ \& \ (dht11\_dat[4] = ((dht11\_dat[0] + dht11\_dat[1] + dht11\_dat[2] + dht11\_dat[3]) \ \& \ (dht11\_dat[4] = ((dht11\_dat[4] + dht11\_dat[4] + dht11\_dat[4] + dht11\_dat[4]) \ \& \ (dht11\_dat[4] = ((dht11\_dat[4] + dht11\_dat[4] + dht11\_dat[4] + dht11\_dat[4]) \ \& \ (dht11\_dat[4] = ((dht11\_dat[4] + dht11\_dat[4] + 
               return 0;
        }
       return 1;
 }
void displayError(const char* message) {
       Serial.println(message);
       digitalWrite(LED_RED, LOW);
       lcd.clear();
       lcd.setCursor(0, 0);
       lcd.print(message);
       delay(2000);
```