
Theory

1 Vector

◆ Definition

A vector is an ordered list of numbers that represents magnitude and direction in space.

◆ Mathematical Form

$$v = (x_1, x_2, x_3, \dots, x_n)$$

◆ In Your Project

Each student is represented as a 6-dimensional vector:

$$v = (\textit{Math}, \textit{Physics}, \textit{Chemistry}, \textit{English}, \textit{Computer}, \textit{Statistics})$$

Vectors allow us to perform mathematical operations on student performance.

2 Norms (Vector Length)

Norm measures the magnitude of a vector.

◆ L1 Norm (Manhattan Norm)

$$\|v\|_1 = |x_1| + |x_2| + \dots + |x_n|$$

Used to measure total absolute performance.

◆ L2 Norm (Euclidean Norm)

$$\|v\|_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

Represents actual geometric length of vector.

3 Dot Product

◆ Definition

Dot product measures similarity between two vectors.

◆ Formula

$$v \cdot w = x_1y_1 + x_2y_2 + \dots + x_ny_n$$

◆ Interpretation

- Large value → Similar performance
- Zero → Independent (orthogonal)

4 Cross Product (3D Only)

◆ **Definition**

Produces a vector perpendicular to two 3D vectors.

◆ **Formula**

$$v \times w = \begin{vmatrix} i & j & k \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

Used in geometric interpretation.

5 Projection of Vector

◆ **Definition**

Projection measures component of one vector in direction of another.

◆ **Formula**

$$proj_w(v) = \frac{v \cdot w}{w \cdot w} w$$

Used in regression and dimensionality reduction.

6 Matrix

◆ **Definition**

A matrix is a rectangular arrangement of numbers in rows and columns.

◆ **In Your Project**

Your dataset is a 250×6 matrix:

- Rows \rightarrow Students
- Columns \rightarrow Subjects

Matrix representation allows advanced operations.

7 Determinant

◆ **Definition**

Determinant is a scalar value that indicates whether matrix is invertible.

If:

$$\det(A) \neq 0$$

\rightarrow Inverse exists.

8 Inverse Matrix

◆ **Definition**

Inverse matrix reverses transformation of original matrix.

$$AA^{-1} = I$$

Used in solving linear systems.

9 Covariance Matrix

◆ Definition

Covariance measures how two variables vary together.

$$\text{Cov}(X, Y) = E[(X - \bar{X})(Y - \bar{Y})]$$

Covariance matrix shows relationship between all subjects.

10 Eigenvalues & Eigenvectors

◆ Definition

Eigenvectors represent directions of maximum variance.

Eigenvalues represent magnitude of variance.

◆ Formula

$$Av = \lambda v$$

Very important in PCA.

1 1 LU Decomposition

◆ Definition

Factorizes matrix into lower and upper triangular matrices.

$$A = LU$$

Used to simplify solving linear equations.

1 2 Singular Value Decomposition (SVD)

◆ Definition

Decomposes matrix into three matrices.

$$A = USV^T$$

Used in dimensionality reduction and pattern extraction.

1 3 Principal Component Analysis (PCA)

◆ Definition

PCA reduces dimensionality by projecting data onto new orthogonal axes that maximize variance.

◆ Steps:

1. Compute covariance matrix
2. Find eigenvalues and eigenvectors
3. Select top components

1 4 Linear Discriminant Analysis (LDA)

◆ Definition

LDA finds a hyperplane that maximizes separation between classes.

◆ Formula

$$w^T x + b = 0$$

Used for classification.

1 5 Line, Plane, Hyperplane

◆ Line (2D)

$$y = mx + c$$

◆ Plane (3D)

$$z = ax + by + d$$

◆ Hyperplane (n-Dimension)

$$w_1 x_1 + w_2 x_2 + \dots + w_n x_n + b = 0$$

Used as decision boundary in ML models.

1 6 Dimensionality Concept

As number of features increases:

- 2 features → 2D space
- 3 features → 3D space
- n features → n-dimensional space

Higher dimensions require reduction techniques like PCA.