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## Theory

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### 1 Vector

- ◆ **Definition**

A vector is an ordered list of numbers that represents magnitude and direction in space.

- ◆ **Mathematical Form**

$$v = (x_1, x_2, x_3, \dots, x_n)$$

- ◆ **In Your Project**

Each student is represented as a 6-dimensional vector:

$$v = (Math, Physics, Chemistry, English, Computer, Statistics)$$

Vectors allow us to perform mathematical operations on student performance.

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### 2 Norms (Vector Length)

Norm measures the magnitude of a vector.

- ◆ **L1 Norm (Manhattan Norm)**

$$\| v \|_1 = |x_1| + |x_2| + \dots + |x_n|$$

Used to measure total absolute performance.

- ◆ **L2 Norm (Euclidean Norm)**

$$\| v \|_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

Represents actual geometric length of vector.

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### 3 Dot Product

- ◆ **Definition**

Dot product measures similarity between two vectors.

- ◆ **Formula**

$$v \cdot w = x_1y_1 + x_2y_2 + \dots + x_ny_n$$

- ◆ **Interpretation**

- Large value → Similar performance
  - Zero → Independent (orthogonal)
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### 4 Cross Product (3D Only)

#### ◆ Definition

Produces a vector perpendicular to two 3D vectors.

#### ◆ Formula

$$v \times w = \begin{vmatrix} i & j & k \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

Used in geometric interpretation.

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## 5 Projection of Vector

#### ◆ Definition

Projection measures component of one vector in direction of another.

#### ◆ Formula

$$\text{proj}_w(v) = \frac{v \cdot w}{w \cdot w} w$$

Used in regression and dimensionality reduction.

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## 6 Matrix

#### ◆ Definition

A matrix is a rectangular arrangement of numbers in rows and columns.

#### ◆ In Your Project

Your dataset is a  $250 \times 6$  matrix:

- Rows  $\rightarrow$  Students
- Columns  $\rightarrow$  Subjects

Matrix representation allows advanced operations.

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## 7 Determinant

#### ◆ Definition

Determinant is a scalar value that indicates whether matrix is invertible.

If:

$$\det(A) \neq 0$$

$\rightarrow$  Inverse exists.

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## 8 Inverse Matrix

#### ◆ Definition

Inverse matrix reverses transformation of original matrix.

$$AA^{-1} = I$$

Used in solving linear systems.

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## 9 Covariance Matrix

### ◆ Definition

Covariance measures how two variables vary together.

$$\text{Cov}(X, Y) = E[(X - \bar{X})(Y - \bar{Y})]$$

Covariance matrix shows relationship between all subjects.

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## 10 Eigenvalues & Eigenvectors

### ◆ Definition

Eigenvectors represent directions of maximum variance.

Eigenvalues represent magnitude of variance.

### ◆ Formula

$$A\mathbf{v} = \lambda\mathbf{v}$$

Very important in PCA.

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## 1 1 LU Decomposition

### ◆ Definition

Factorizes matrix into lower and upper triangular matrices.

$$A = LU$$

Used to simplify solving linear equations.

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## 1 2 Singular Value Decomposition (SVD)

### ◆ Definition

Decomposes matrix into three matrices.

$$A = USV^T$$

Used in dimensionality reduction and pattern extraction.

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## 1 3 Principal Component Analysis (PCA)

### ◆ Definition

PCA reduces dimensionality by projecting data onto new orthogonal axes that maximize variance.

### ◆ Steps:

1. Compute covariance matrix
2. Find eigenvalues and eigenvectors
3. Select top components

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## 1 4 Linear Discriminant Analysis (LDA)

- ◆ **Definition**

LDA finds a hyperplane that maximizes separation between classes.

- ◆ **Formula**

$$w^T x + b = 0$$

Used for classification.

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## 1 5 Line, Plane, Hyperplane

- ◆ **Line (2D)**

$$y = mx + c$$

- ◆ **Plane (3D)**

$$z = ax + by + d$$

- ◆ **Hyperplane (n-Dimension)**

$$w_1x_1 + w_2x_2 + \dots + w_nx_n + b = 0$$

Used as decision boundary in ML models.

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## 1 6 Dimensionality Concept

As number of features increases:

- 2 features → 2D space
- 3 features → 3D space
- n features → n-dimensional space

Higher dimensions require reduction techniques like PCA.