Strps	to	solve	problem	s on	Rout	locus
0,40	. •					,

Step. (1) from a(s) H(s), find out no of open loop poles,
zens & no. of branches

@ P > Z N = P

6 Z7P, N=Z

(C) P=Z, N=P=Z

P-Z Z-P branches approaches to co

2) Druw pole-zero plot Identify sections of real axis for RL & NRL

Predict for no. of branches breakaway points.

RL > It no co open loop polen 4 open loop zerus
to R'H'S is ODD

3 Calculate angle of asymptotes

No.06 asymptotes = P-Z/Z-P

Q = C2 q + 1) 180° q = 0,1,2, - - -

(4) Calculate Centroid

6= ERP of Poles - ERP. Zems P-Z

Sketch for controld & asymptotes

(\$)	Calculate breakaway breakin point
	1) Find 1+ acs)+(s) = 0
	(1) K=f(s) [sepercula terms of K45]
	① dk = 0 .
1	ds
	(1) Find mots of eq. dk => break away point
1	ds .
	(V) Check for their validity
i.	U.
1	Substitute value in eq. k=f(s)
8	I/k is +ve > Valid
	K is -ve ≥ Invalid
(C)	Calculate intersection with Imaginary axis
- 11	() find 1+Ges) HU)=0
- !!	(i) consmict Robeth array
	(11) Determine Kmar
	· W
~	Value of k for with one of the ruw
	of Rowth array becomes zero excepts
A	(1) Construct auxillian eg' Acs= a by cosing
The same and the s	coefficients of new whitch is just above
	nuce de zeno.
	' lange tim
	Roots of ACS) for k= kmax are intersection
	points

1	
4	Calculate angle of departure or arrivals
	if applicable
•	: [Use only if pules/zero an complex
	(Conjugate)
	\$d = 180° - \$\psi\$ whex \$\phi = \xi \phi_P - \xi \phi_Z\
,	
	= 1 = do 1 h
,	5 dp = dp1 + dp2+
	$\sum \Phi z = \Phi z_1 + \Phi z_2 +$
·	[a= 180°+6]
	Combine Steps 1 to 7 & draw final sketch
4	of not locus.
<u> </u>	Predict for stability
	for OKK < kmar > stable system
	for K= Kmar > marginally stable
	for kmar < K < 00 > unstable stable
nie.	
-sks	
-	