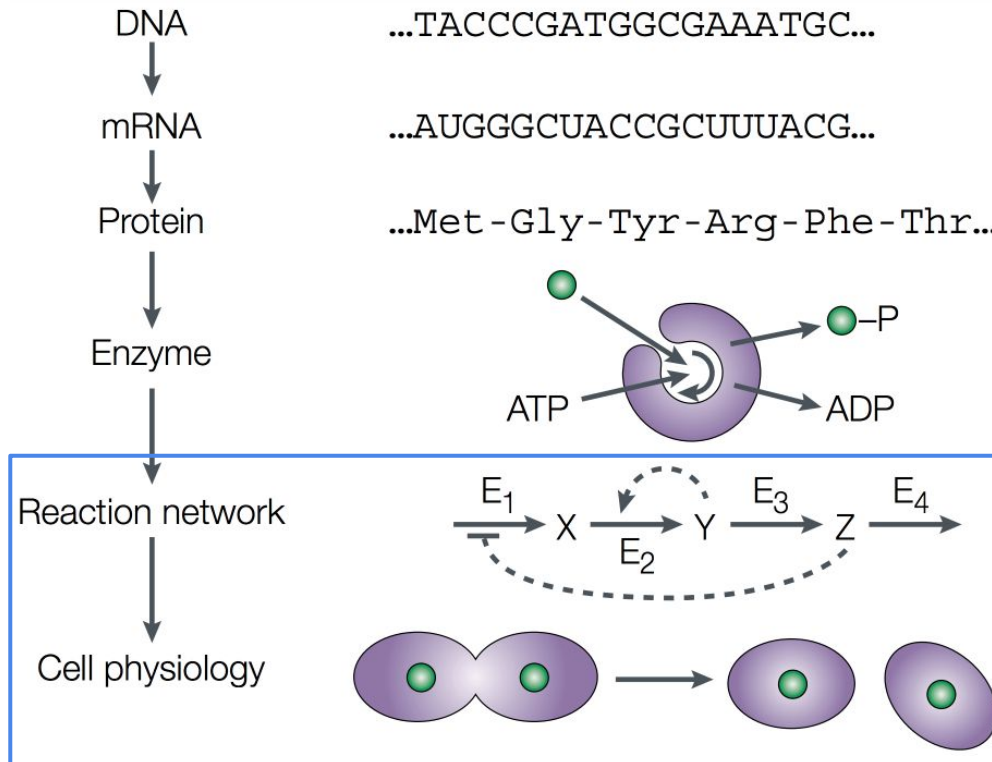


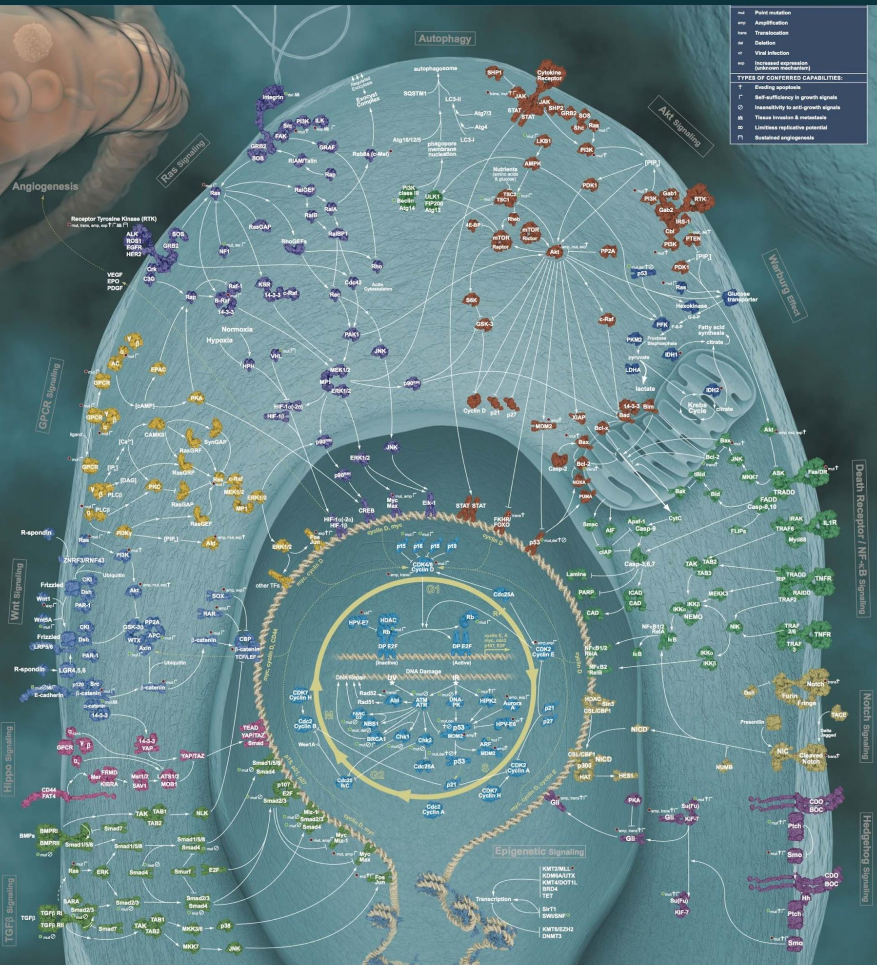
# Modeling cellular pathways

- Modeling simple motifs
- State spaces, vector fields, and bifurcations
- Application to modeling the cell cycle

# Next level of hierarchy



# Cellular signaling and regulatory pathways



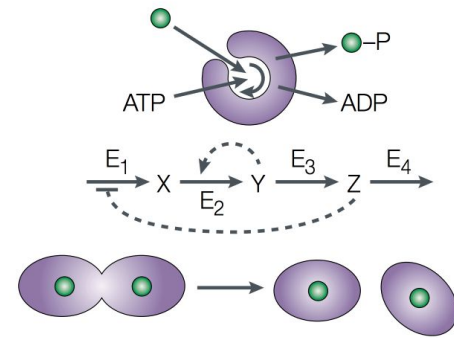
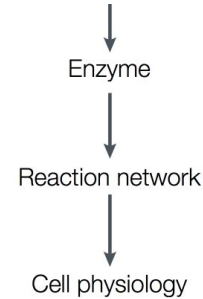
Cell physiology is governed by complex assemblies of interacting proteins carrying out most of the interesting jobs in a cell, such as metabolism, DNA synthesis, movement and information processing.

These processes are orchestrated by signaling and regulatory networks.

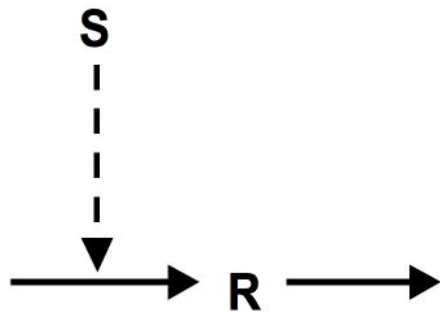
# Computational molecular biology

Take a cellular process and...

1. Draw a **wiring diagram** representing the signaling and regulatory interactions between underlying proteins...
2. Convert the diagram to a **system of** (differential/difference/Boolean) **equations**...
3. **Simulate the system** (along with **finding optimal parameters**) to understand its temporal/spatial properties and how they relate to the process being modelled...
4. **Make predictions** about molecular and process-level behavior in unobserved scenarios including the effect of mutations.



# Linear response

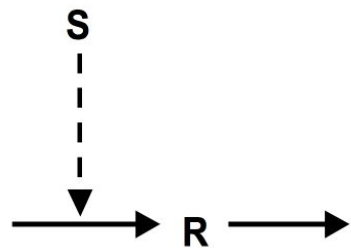


$$\frac{dR}{dt} = k_0 + k_1 S - k_2 R$$

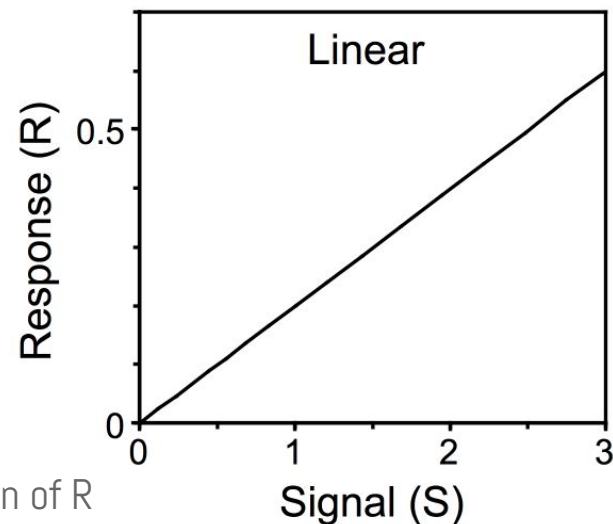
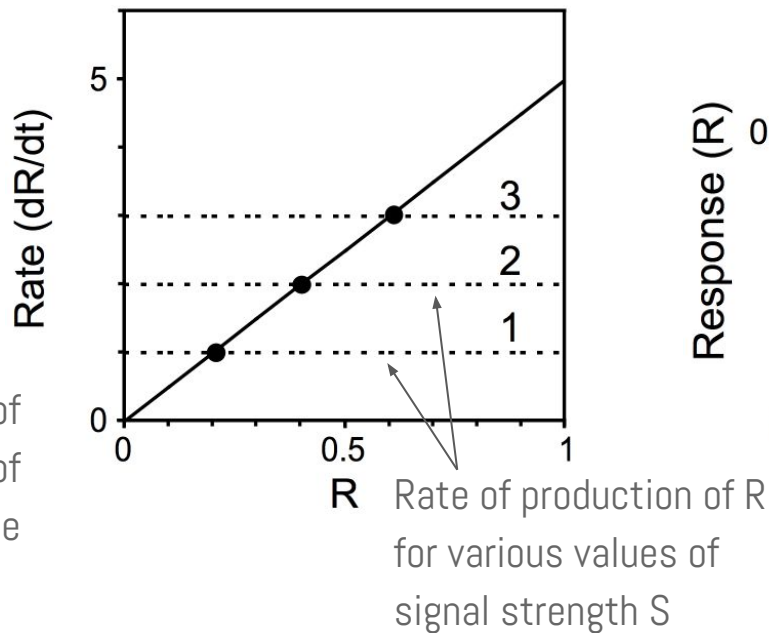
Steady-state  
solution

$$R_{ss} = \frac{k_0 + k_1 S}{k_2}$$

# Linear response



Rate of  
removal of  
response

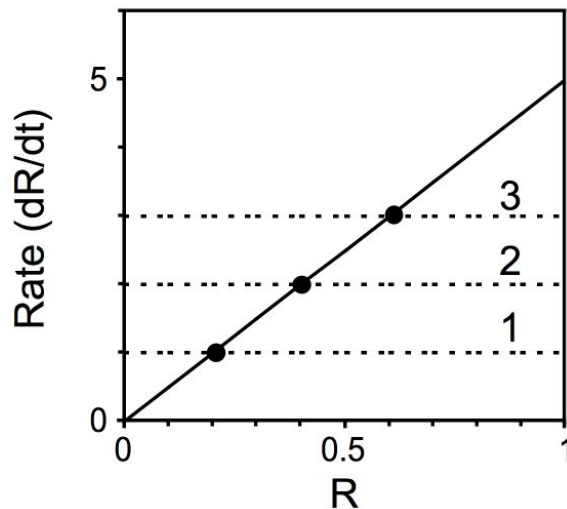
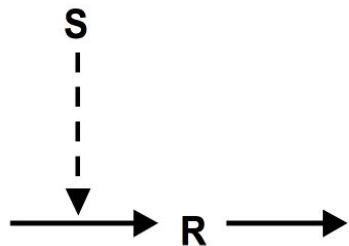


$$\frac{dR}{dt} = k_0 + k_1 S - k_2 R$$

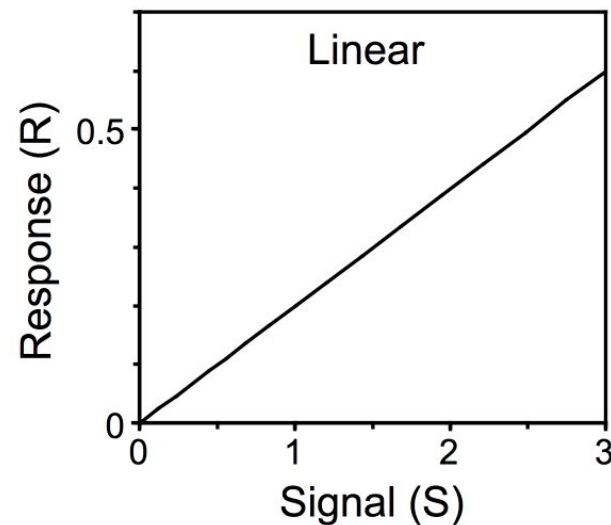
Steady-state  
solution

$$R_{ss} = \frac{k_0 + k_1 S}{k_2}$$

# Linear response



Rate curve



Signal-response curve

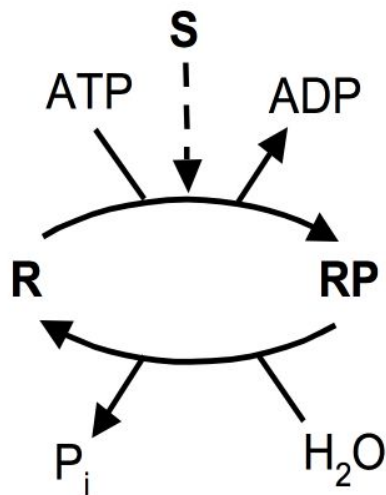
$$\frac{dR}{dt} = k_0 + k_1 S - k_2 R$$

Steady-state solution

$$R_{ss} = \frac{k_0 + k_1 S}{k_2}$$

# Hyperbolic response

$$R_T = R + R_P$$



$$\frac{dR_P}{dt} = k_1 S R - k_2 R_P$$

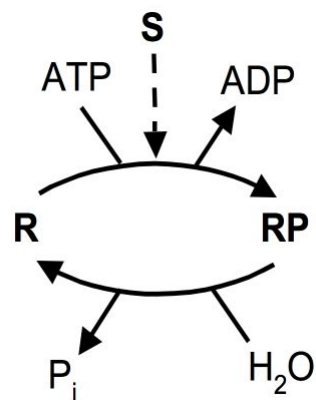
$$= k_1 S (R_T - R_P) - k_2 R_P$$

Steady-state  
solution

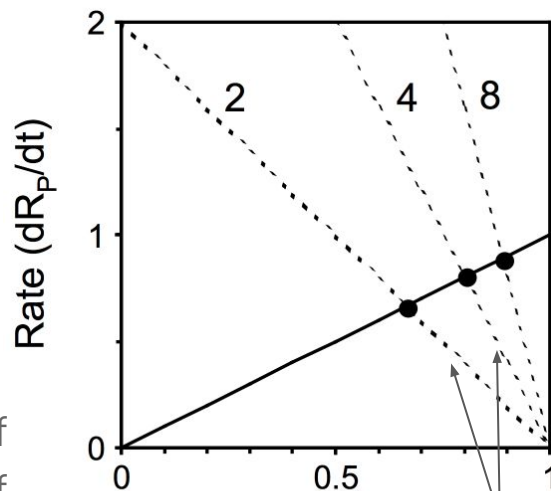
$$R_{P,ss} = \frac{R_T S}{(k_2/k_1) + S}$$



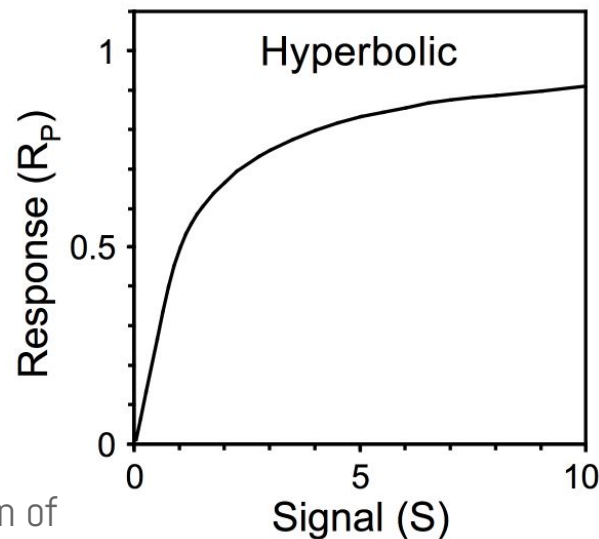
# Hyperbolic response



Rate of  
removal of  
response  $R_p$



Rate of production of  
response  $R_p$  for various  
values of signal strength  $S$



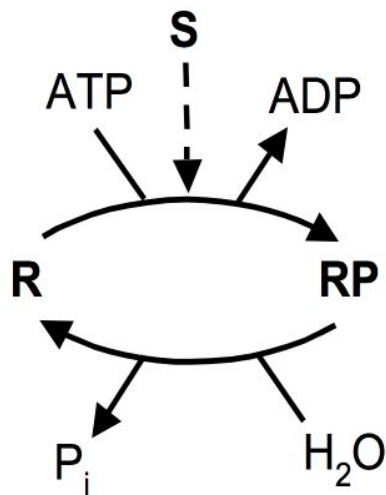
$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = k_1 S (R_T - R_P) - k_2 R_P$$

Steady-state  
solution

$$R_{P,ss} = \frac{R_T S}{(k_2/k_1) + S}$$

# Hyperbolic response



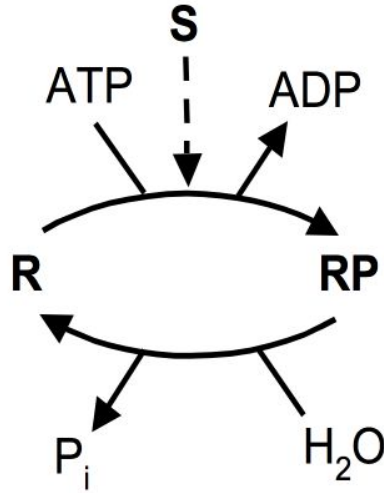
$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = k_1 S (R_T - R_P) - k_2 R_P$$

Steady-state  
solution

$$R_{P,ss} = \frac{R_T S}{(k_2/k_1) + S}$$

# Sigmoidal response



$$R_T = R + R_P$$

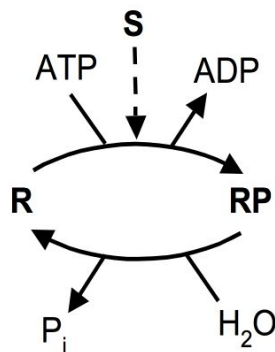
$$\frac{dR_P}{dt} = \frac{k_1 S (R_T - R_P)}{K_{m1} + R_T - R_P} - \frac{k_2 R_P}{k_{m2} + R_P}$$

## Michaelis-Menten kinetics:

- One of the best-known models for enzyme kinetics
- Assumes that enzyme concentration is much less than the substrate concentration.



# Sigmoidal response



$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = \frac{k_1 S (R_T - R_P)}{K_{m1} + R_T - R_P} - \frac{k_2 R_P}{K_{m2} + R_P}$$

Steady-state  
solution

$$k_1 S (R_T - R_P) (K_{m2} + R_P) = k_2 R_P (K_{m1} + R_T - R_P)$$

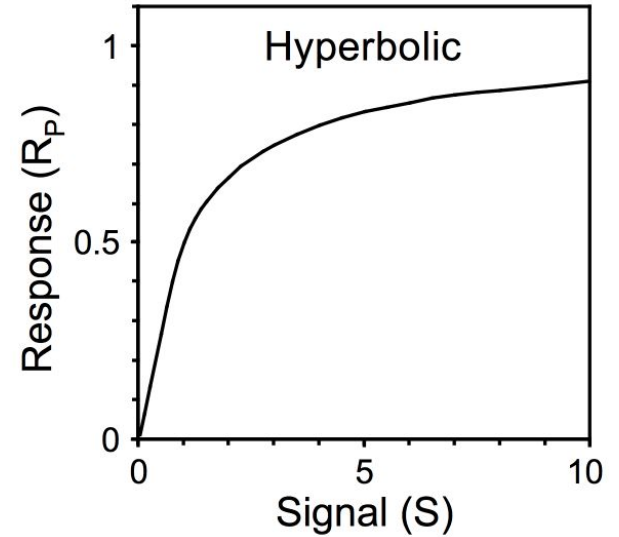
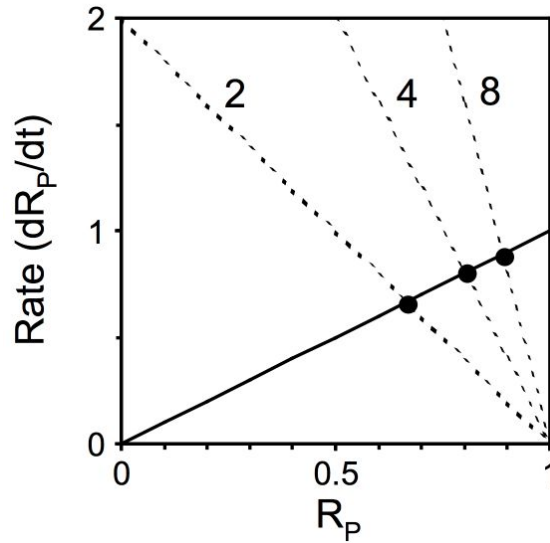
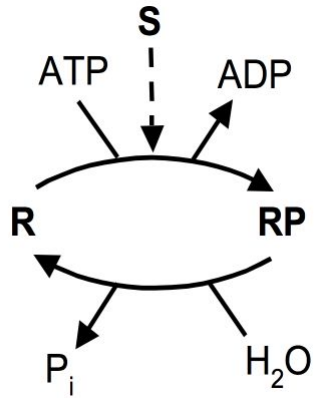
$$\frac{R_{P,ss}}{R_T} = G\left(k_1 S, k_2, \frac{K_{m1}}{R_T}, \frac{K_{m2}}{R_T}\right)$$

Physiologically meaningful  
solution w/  $0 < R_P < R_T$

Goldbeter-Koshland  
function: graded &  
reversible

$$G(u, v, J, K) = \frac{2uK}{v - u + vJ + uK + \sqrt{(v - u + vJ + uK)^2 - 4(v - u)uK}}$$

# Hyperbolic response



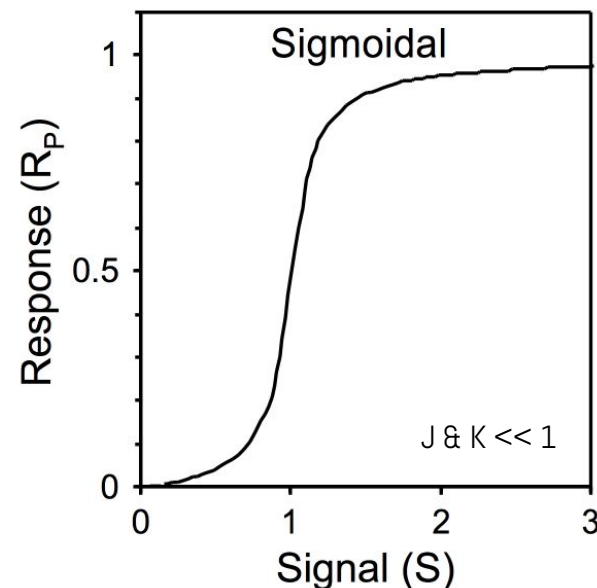
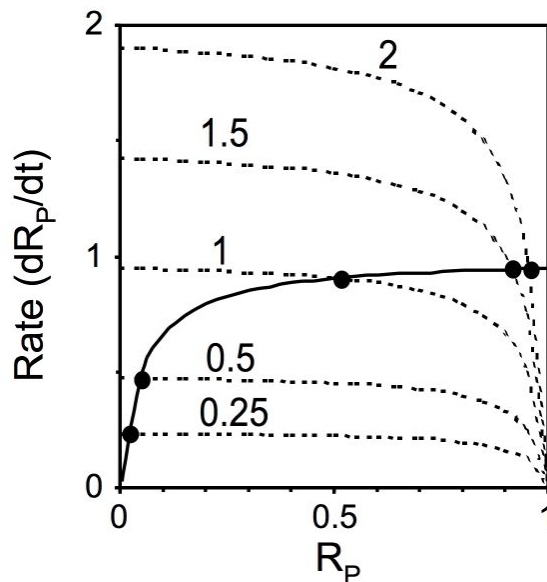
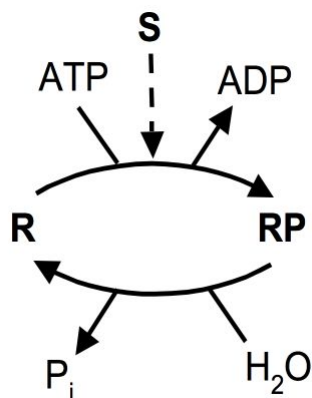
$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = k_1 S (R_T - R_P) - k_2 R_P$$

Steady-state solution

$$R_{P,ss} = \frac{R_T S}{(k_2/k_1) + S}$$

# Sigmoidal response



Zero-order ultrasensitivity

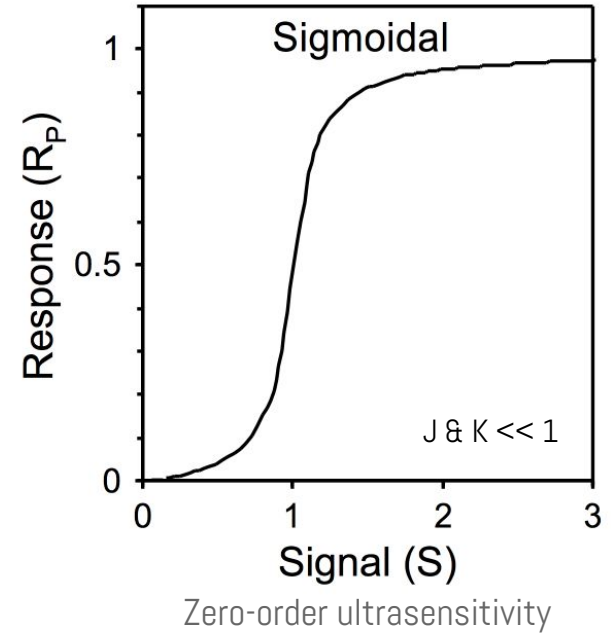
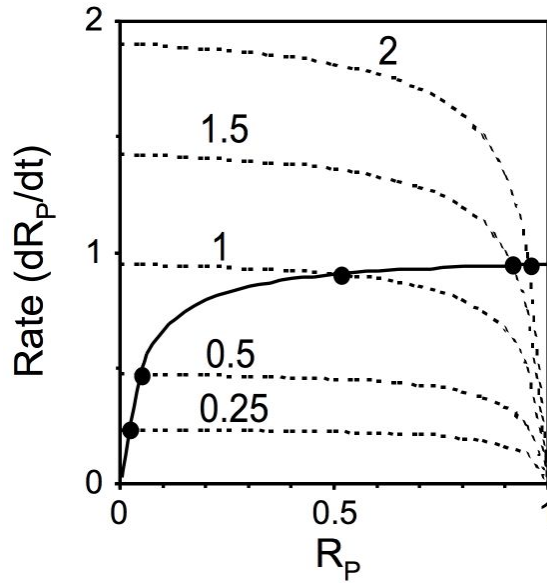
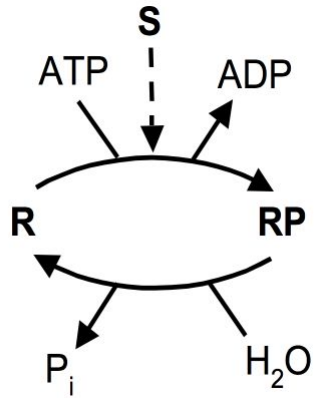
$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = \frac{k_1 S (R_T - R_P)}{K_{m1} + R_T - R_P} - \frac{k_2 R_P}{k_{m2} + R_P}$$

Steady-state solution

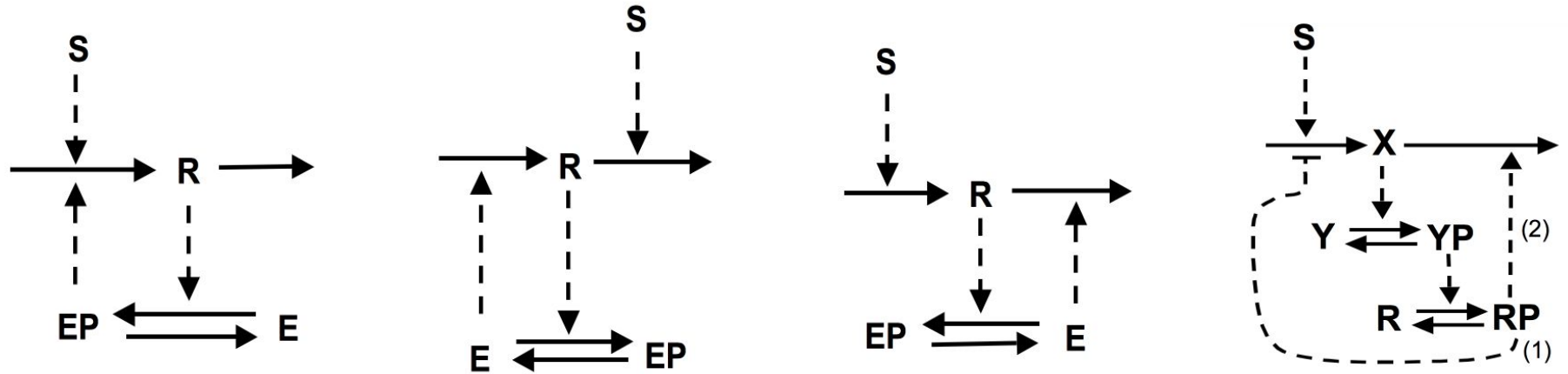
$$\frac{R_{P,ss}}{R_T} = G(k_1, S, k_2, \frac{K_{m1}}{R_T}, \frac{K_{m2}}{R_T})$$

# Sigmoidal response



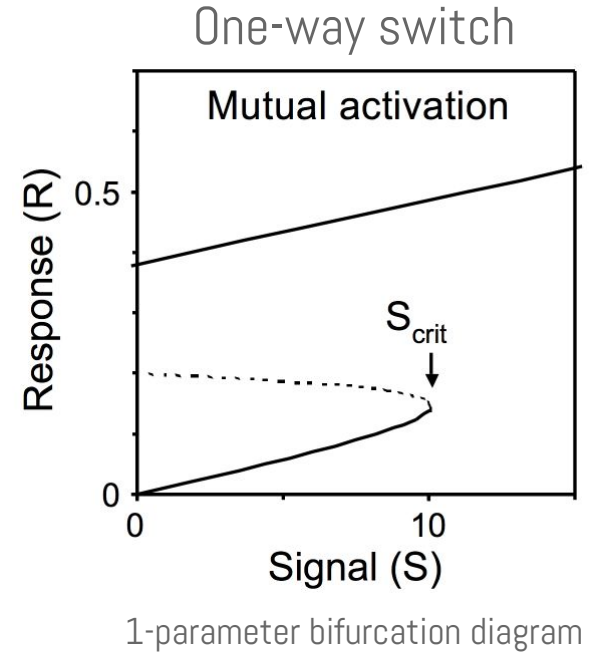
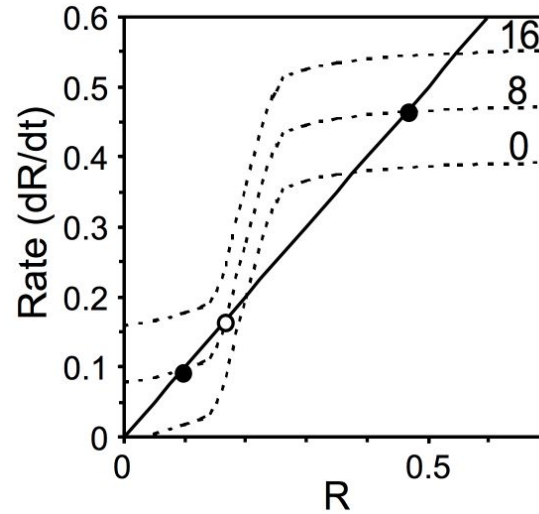
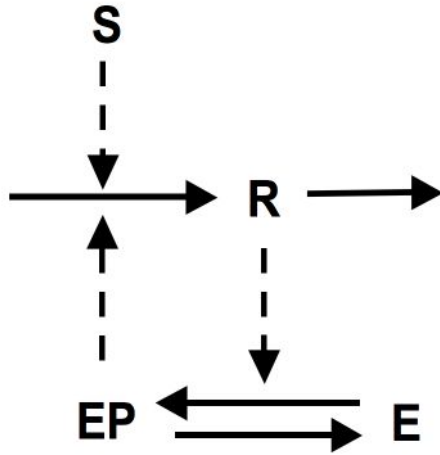
Just like the linear and hyperbolic responses, the sigmoid response is **graded & reversible**, but, unlike the other two, it is also **abrupt**.

# Feedback loops



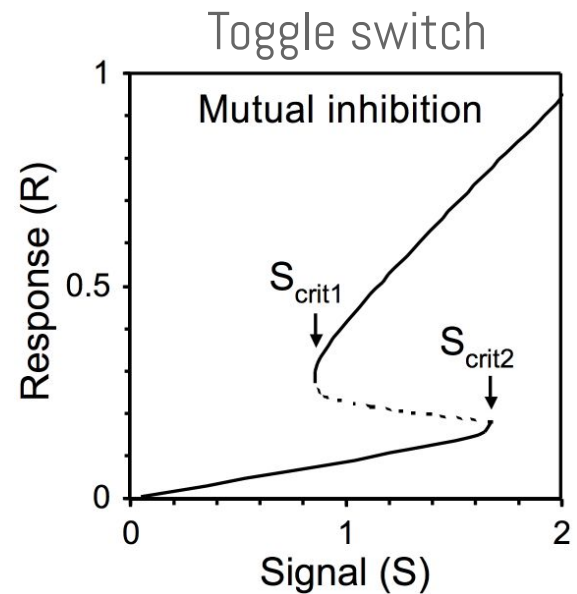
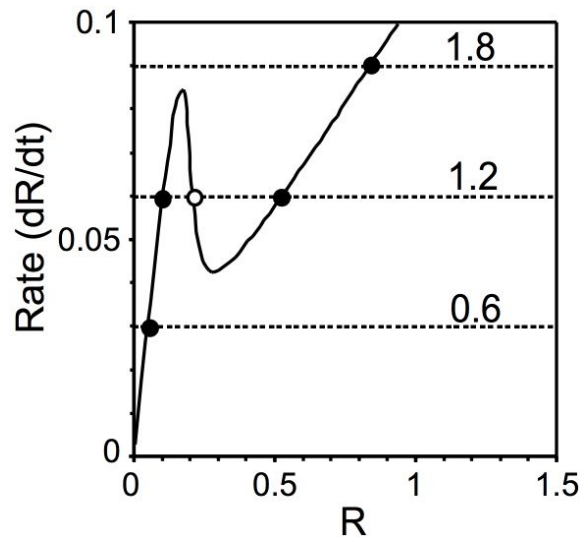
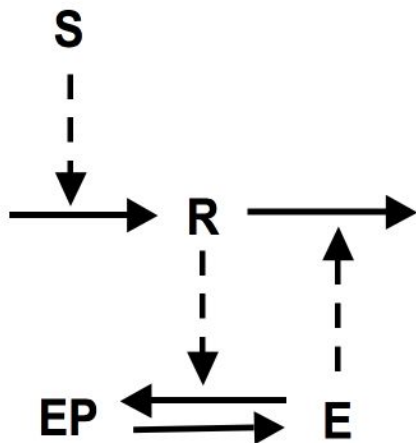


# Positive feedback loop



**Bifurcation:** A sudden 'qualitative' change in the behavior of a dynamical system caused by a small smooth change made to the parameter values.

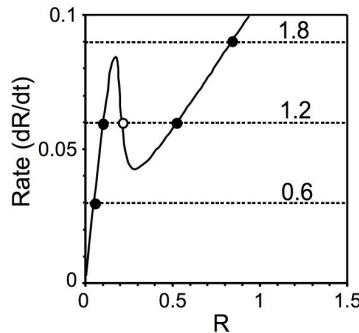
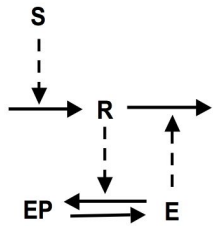
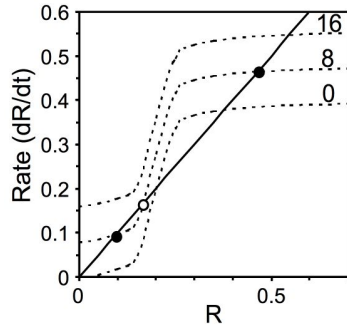
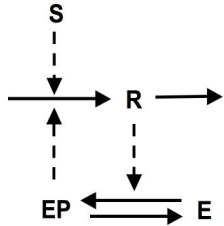
# Positive feedback loop



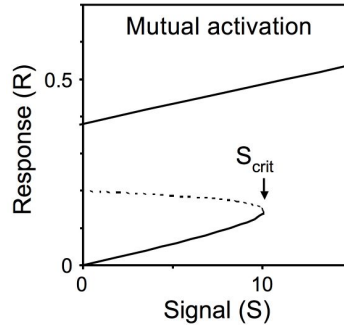
1-parameter bifurcation diagram

**Bifurcation:** A sudden 'qualitative' change in the behavior of a dynamical system caused by a small smooth change made to the parameter values.

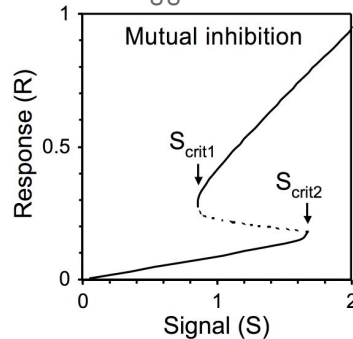
# Positive feedback loop



One-way switch

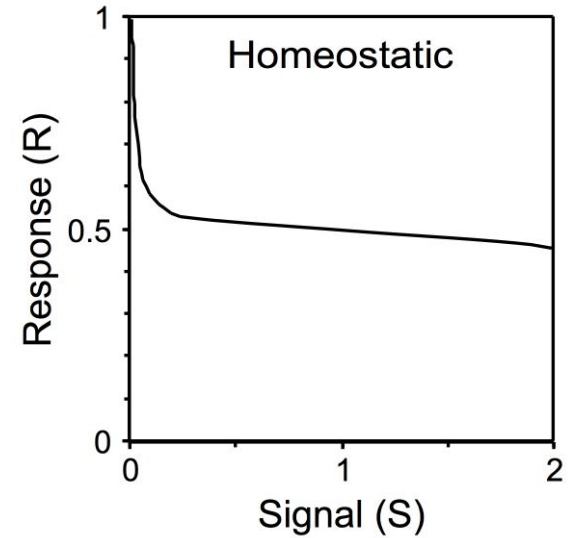
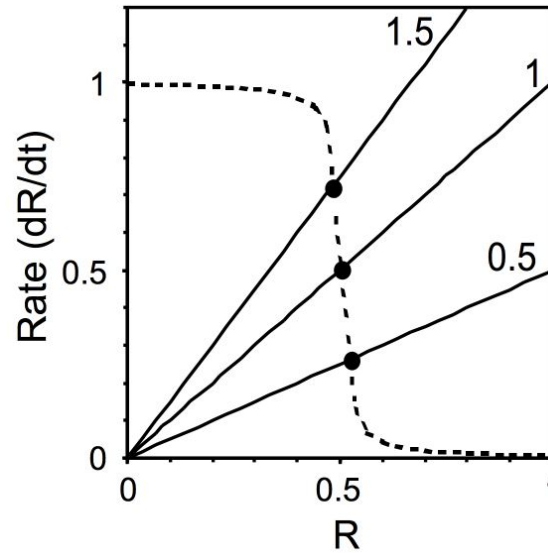
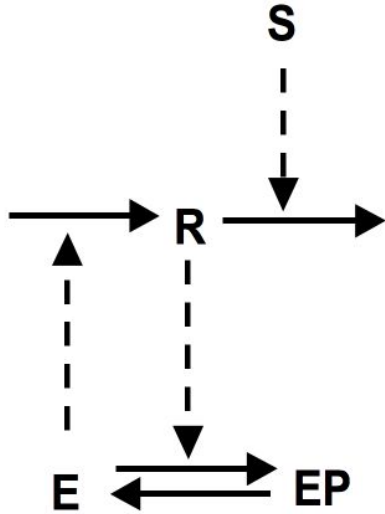


Toggle switch

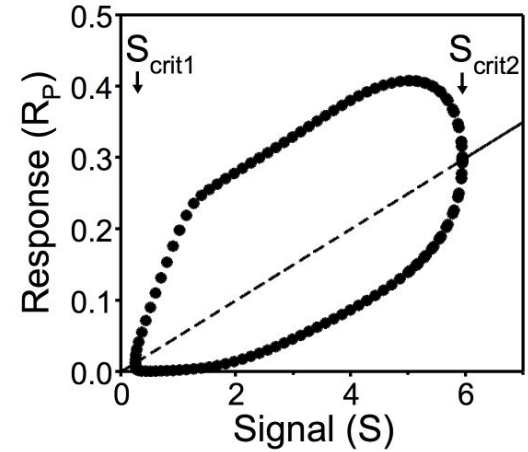
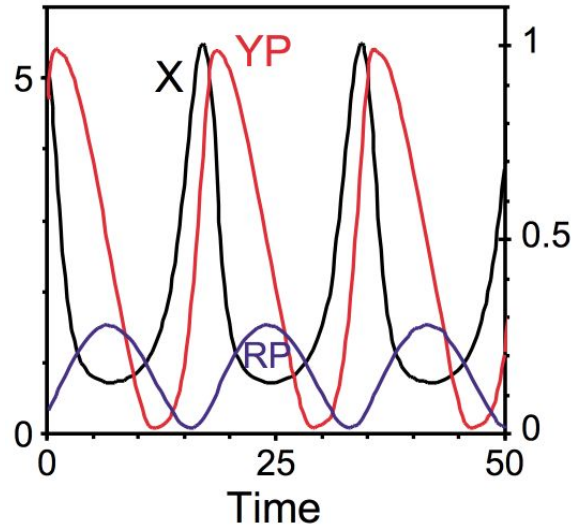
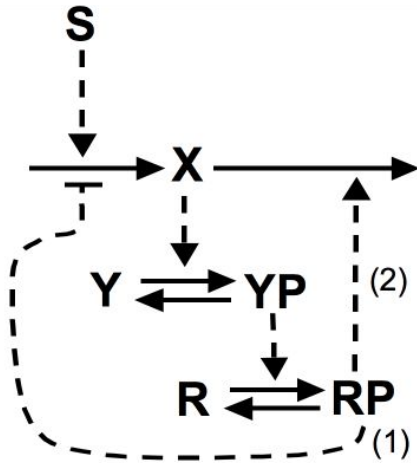


- Irreversible
- Bistable
  - Between 0 &  $S_{crit}$  (bifurcation point) and
  - Between  $S_{crit1}$  &  $S_{crit2}$
- Undergoes a bifurcation:
  - In this case, a saddle-node bifurcation.

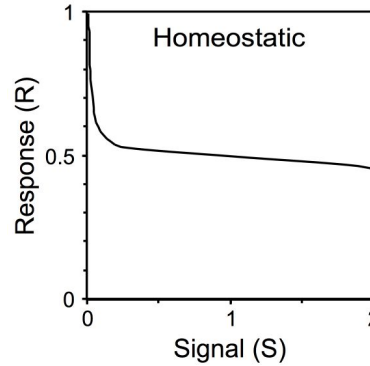
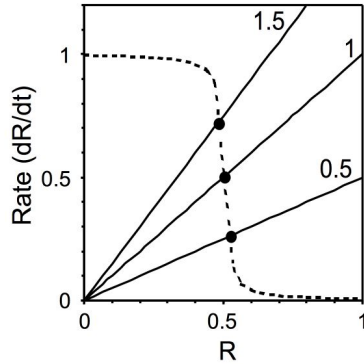
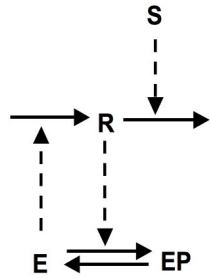
# Negative feedback loop



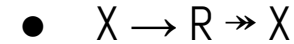
# Negative feedback loop



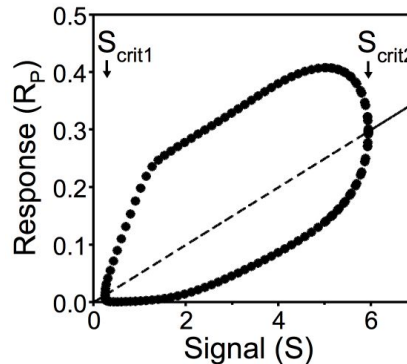
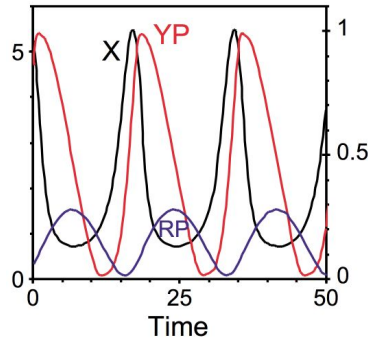
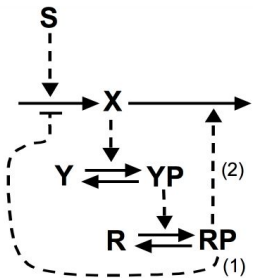
# Negative feedback loop



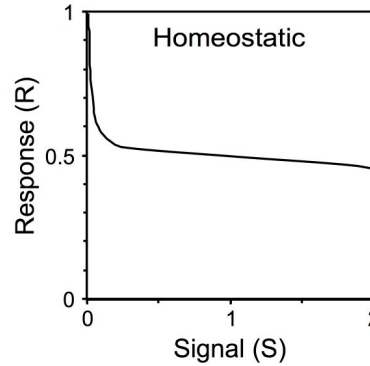
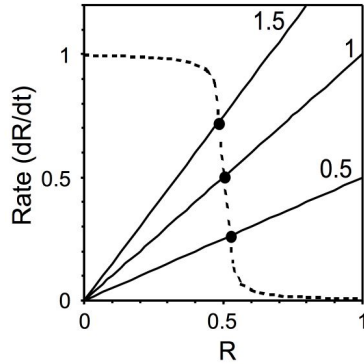
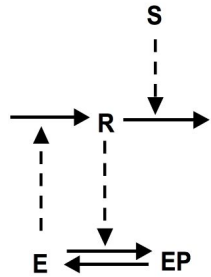
Negative feedback can also create an oscillatory response.



This results in **damped oscillations** to a stable steady state.



# Negative feedback loop



**Sustained oscillations** require at least three components:



Third component (Y) introduces a time delay in the feedback loop, causing the system to repeatedly over- & undershoot its steady state.

