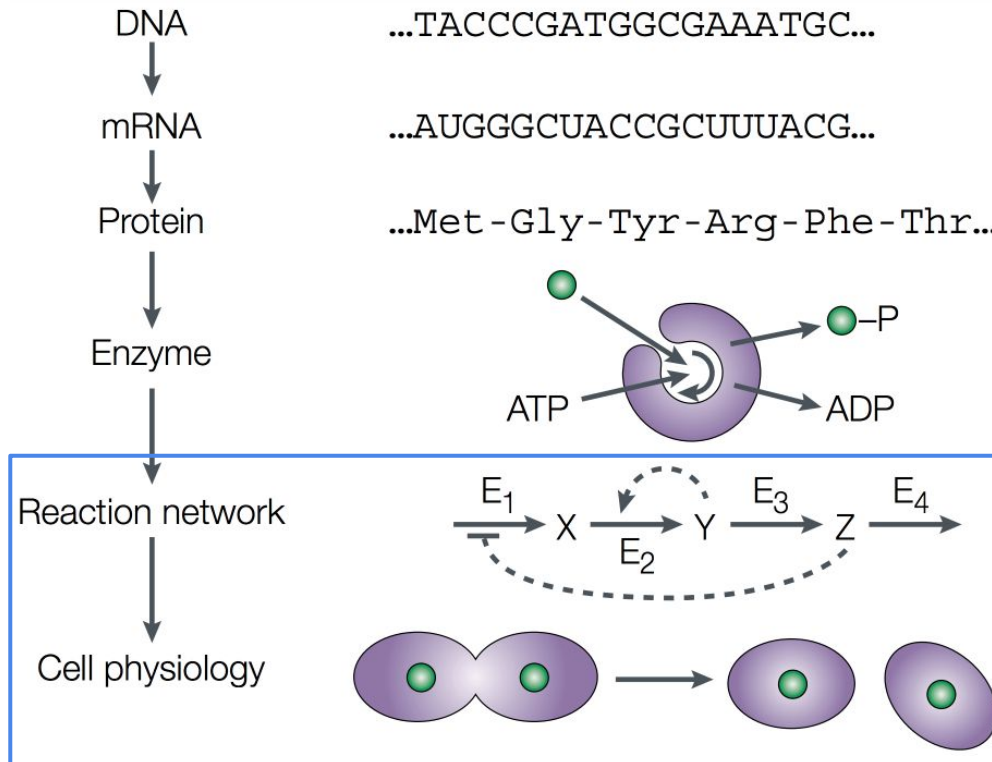


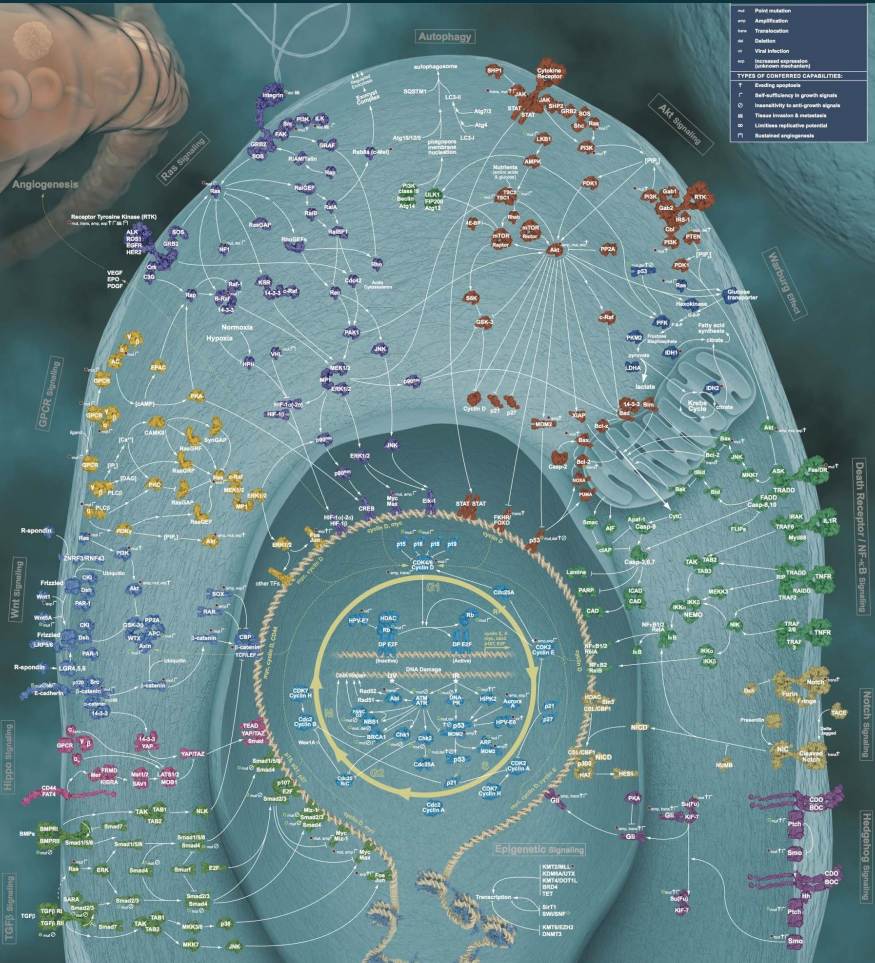
Modeling cellular pathways

- Modeling simple motifs
- State spaces, vector fields, and bifurcations
- Application to modeling the cell cycle

Next level of hierarchy



Cellular signaling and regulatory pathways



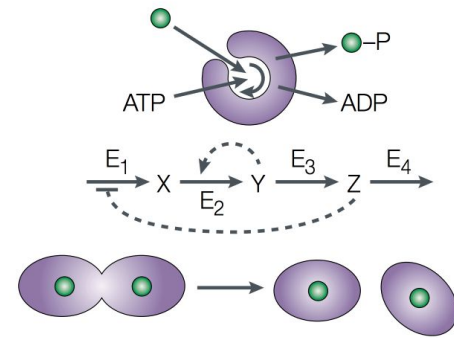
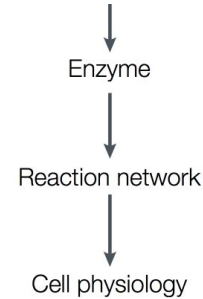
Cell physiology is governed by complex assemblies of interacting proteins carrying out most of the interesting jobs in a cell, such as metabolism, DNA synthesis, movement and information processing.

These processes are orchestrated by signaling and regulatory networks.

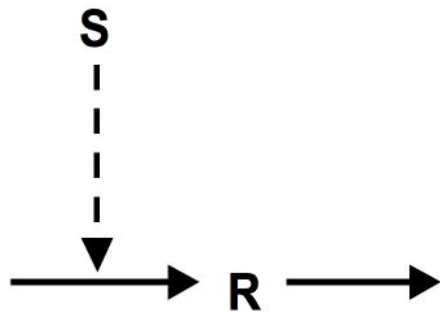
Computational molecular biology

Take a cellular process and...

1. Draw a **wiring diagram** representing the signaling and regulatory interactions between underlying proteins...
2. Convert the diagram to a **system of** (differential/difference/Boolean) **equations**...
3. **Simulate the system** (along with **finding optimal parameters**) to understand its temporal/spatial properties and how they relate to the process being modelled...
4. **Make predictions** about molecular and process-level behavior in unobserved scenarios including the effect of mutations.



Linear response

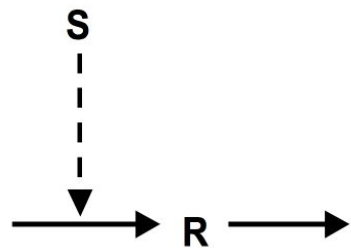


$$\frac{dR}{dt} = k_0 + k_1 S - k_2 R$$

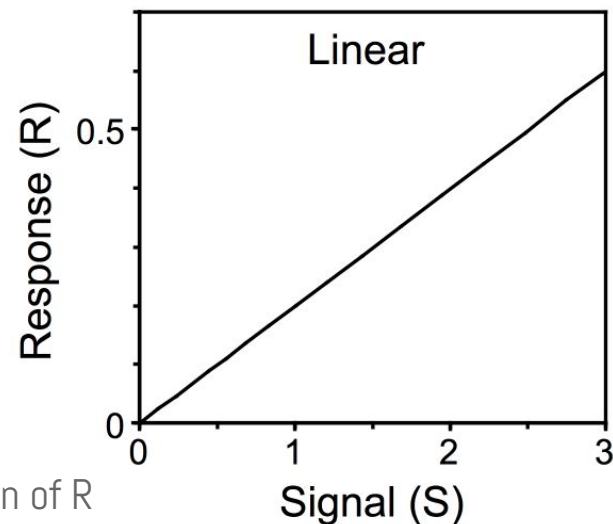
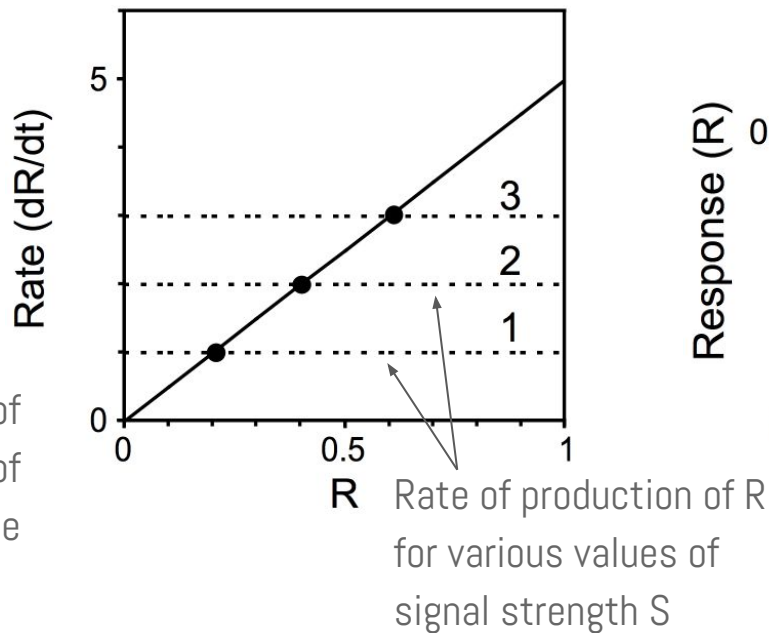
Steady-state
solution

$$R_{ss} = \frac{k_0 + k_1 S}{k_2}$$

Linear response



Rate of
removal of
response

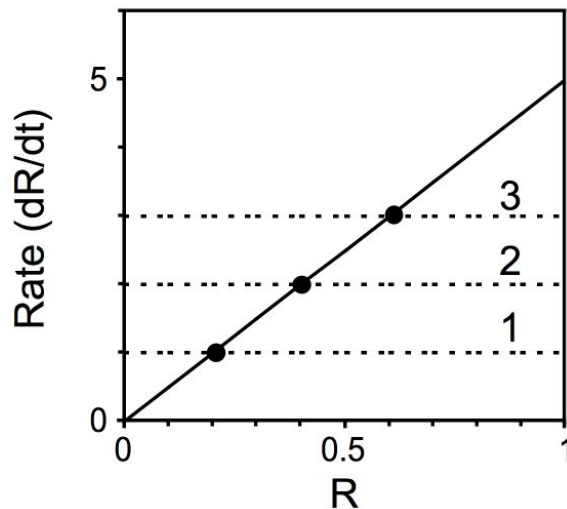
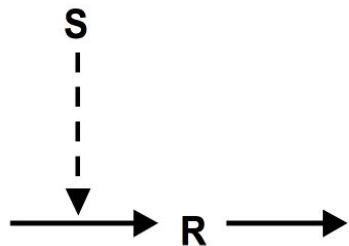


$$\frac{dR}{dt} = k_0 + k_1 S - k_2 R$$

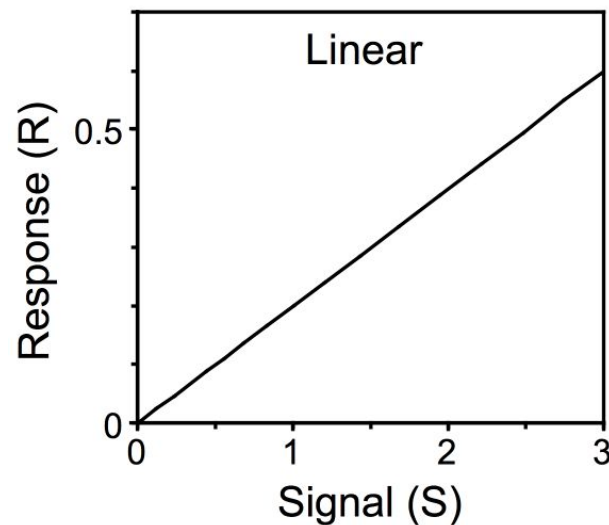
Steady-state
solution

$$R_{ss} = \frac{k_0 + k_1 S}{k_2}$$

Linear response



Rate curve



Signal-response curve

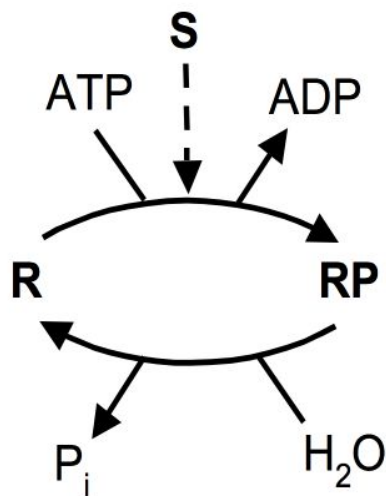
$$\frac{dR}{dt} = k_0 + k_1 S - k_2 R$$

Steady-state
solution

$$R_{ss} = \frac{k_0 + k_1 S}{k_2}$$

Hyperbolic response

$$R_T = R + R_P$$



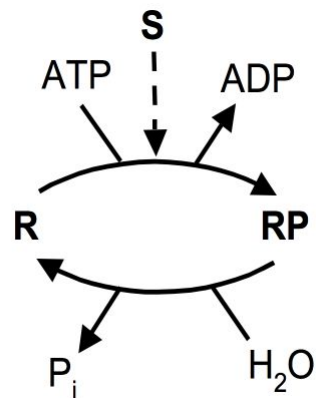
$$\frac{dR_P}{dt} = k_1 S R - k_2 R_P$$

$$= k_1 S (R_T - R_P) - k_2 R_P$$

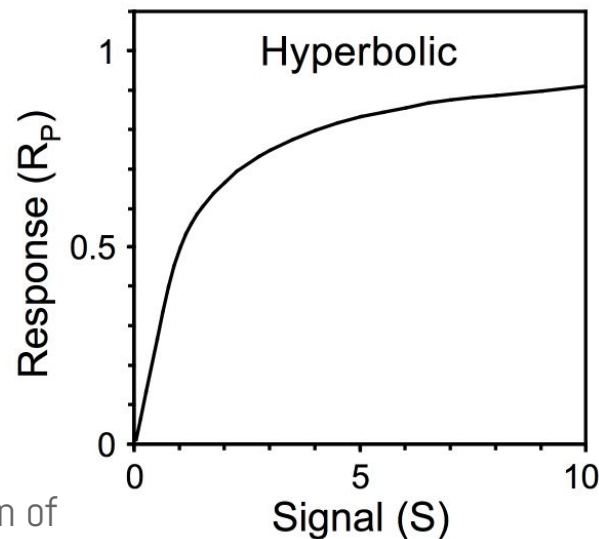
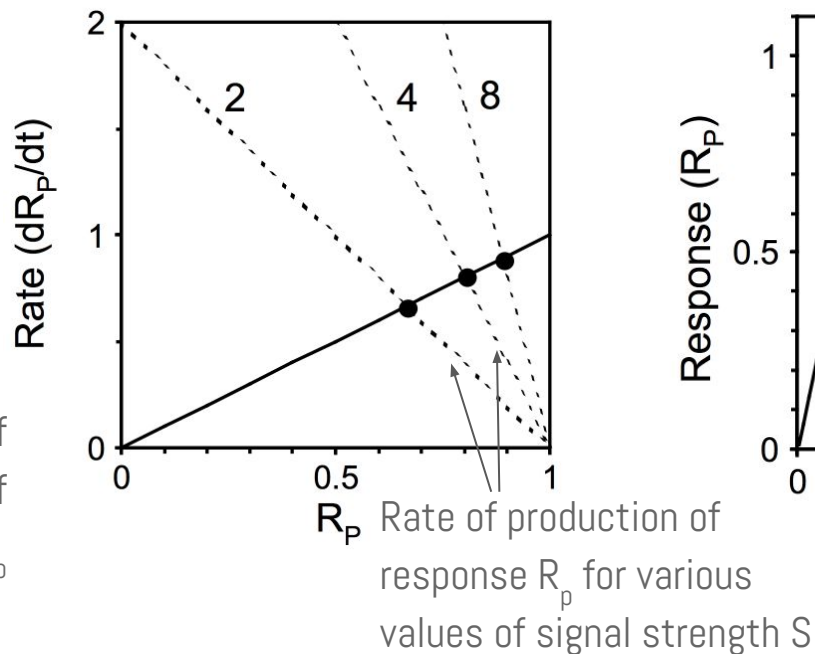
Steady-state
solution

$$R_{P,ss} = \frac{R_T S}{(k_2/k_1) + S}$$

Hyperbolic response



Rate of
removal of
response R_p



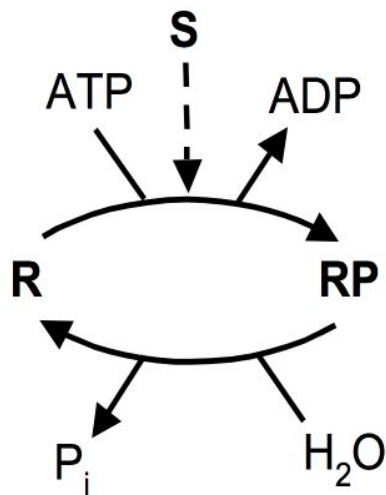
$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = k_1 S (R_T - R_P) - k_2 R_P$$

Steady-state
solution

$$R_{P,ss} = \frac{R_T S}{(k_2/k_1) + S}$$

Hyperbolic response



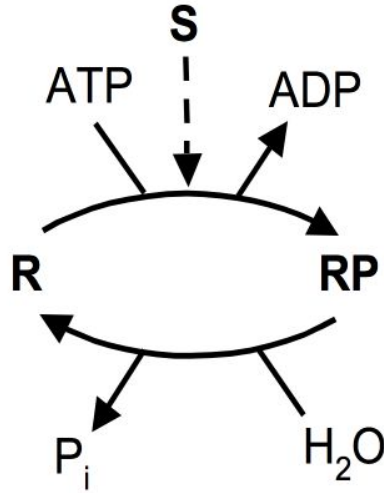
Steady-state
solution

$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = k_1 S (R_T - R_P) - k_2 R_P$$

$$R_{P,ss} = \frac{R_T S}{(k_2/k_1) + S}$$

Sigmoidal response



$$R_T = R + R_P$$

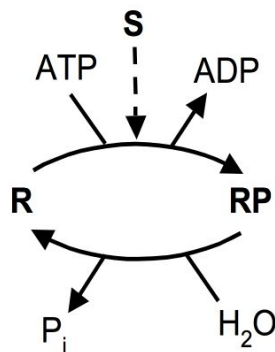
$$\frac{dR_P}{dt} = \frac{k_1 S (R_T - R_P)}{K_{m1} + R_T - R_P} - \frac{k_2 R_P}{k_{m2} + R_P}$$

Michaelis-Menten kinetics:

- One of the best-known models for enzyme kinetics
- Assumes that enzyme concentration is much less than the substrate concentration.



Sigmoidal response



$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = \frac{k_1 S (R_T - R_P)}{K_{m1} + R_T - R_P} - \frac{k_2 R_P}{K_{m2} + R_P}$$

Steady-state
solution

$$k_1 S (R_T - R_P) (K_{m2} + R_P) = k_2 R_P (K_{m1} + R_T - R_P)$$

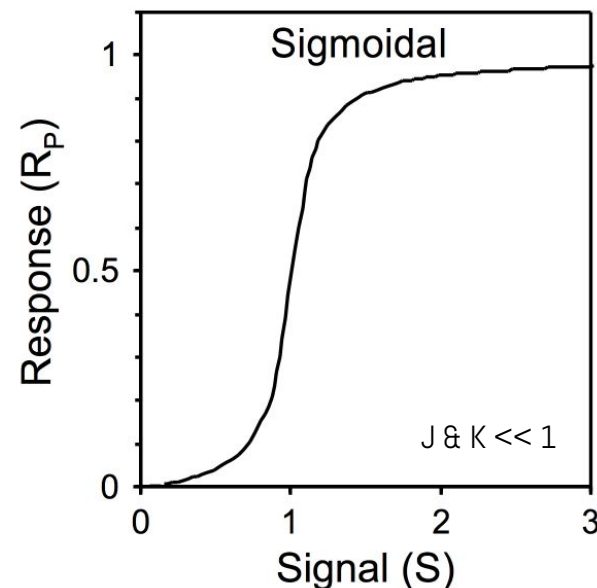
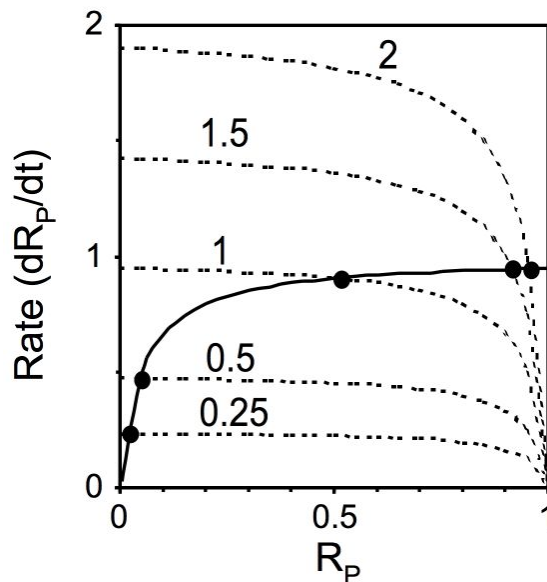
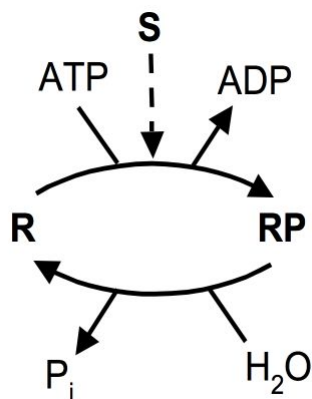
$$\frac{R_{P,ss}}{R_T} = G\left(k_1 S, k_2, \frac{K_{m1}}{R_T}, \frac{K_{m2}}{R_T}\right)$$

Physiologically meaningful
solution w/ $0 < R_P < R_T$

Goldbeter-Koshland
function: graded &
reversible

$$G(u, v, J, K) = \frac{2uK}{v - u + vJ + uK + \sqrt{(v - u + vJ + uK)^2 - 4(v - u)uK}}$$

Sigmoidal response



Zero-order ultrasensitivity

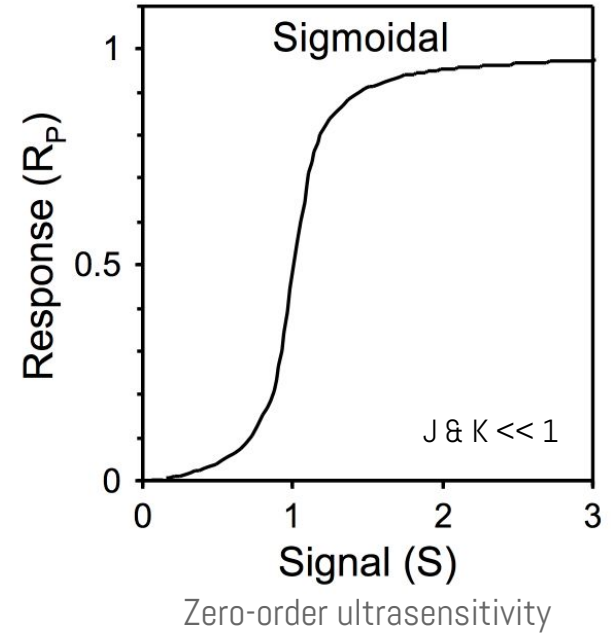
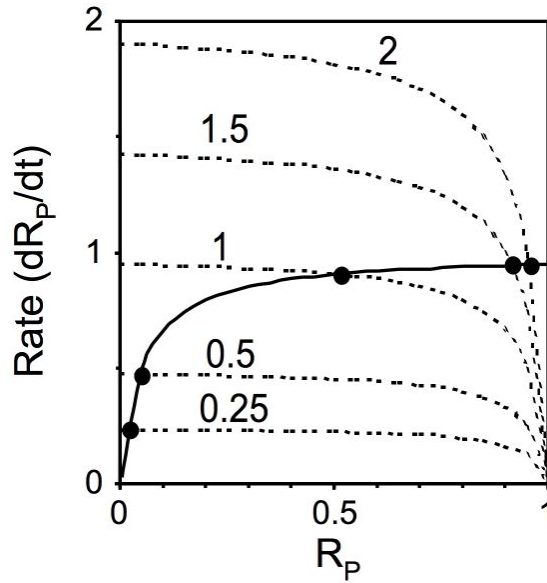
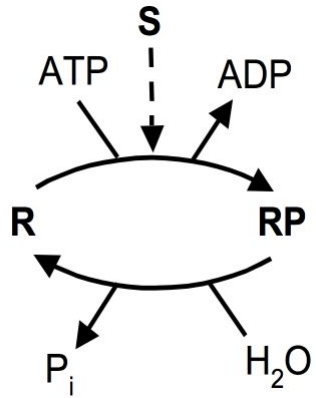
$$R_T = R + R_P$$

$$\frac{dR_P}{dt} = \frac{k_1 S (R_T - R_P)}{K_{m1} + R_T - R_P} - \frac{k_2 R_P}{k_{m2} + R_P}$$

Steady-state solution

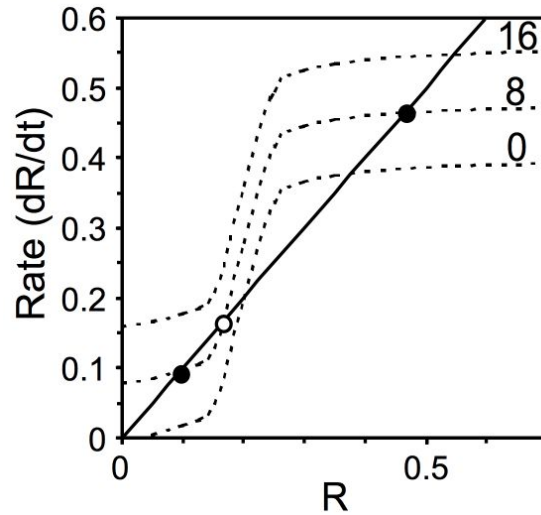
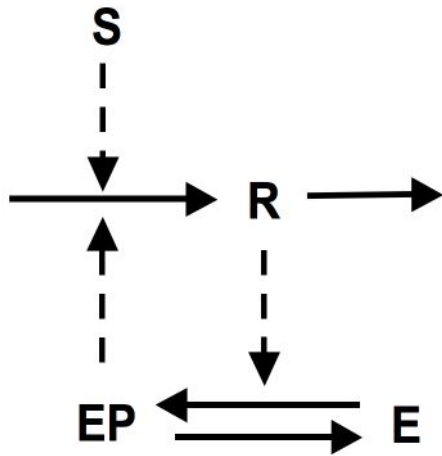
$$\frac{R_{P,ss}}{R_T} = G(k_1, S, k_2, \frac{K_{m1}}{R_T}, \frac{K_{m2}}{R_T})$$

Sigmoidal response

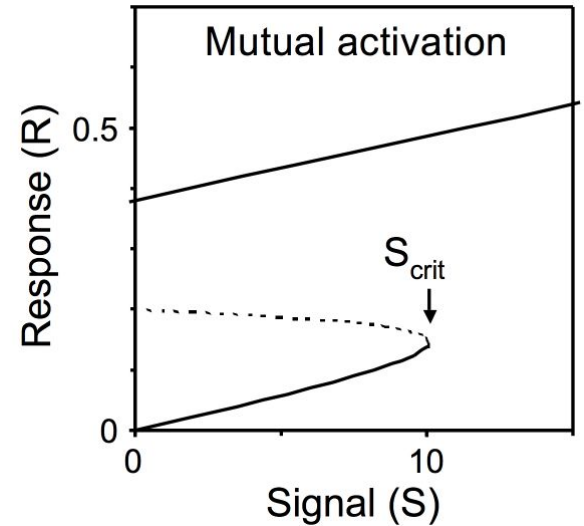


Just like the linear and hyperbolic responses, the sigmoid response is graded & reversible, but, unlike the other two, it is also abrupt.

Positive feedback loop

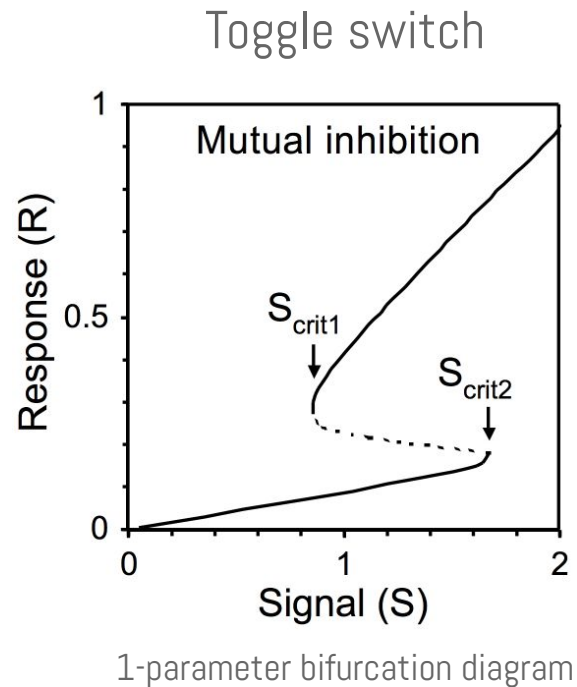
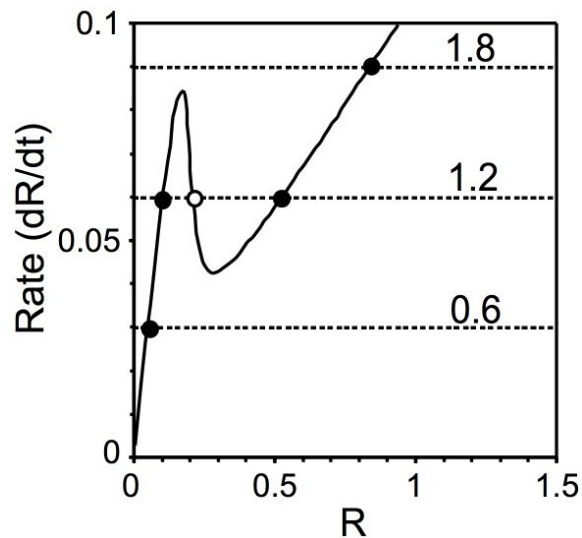
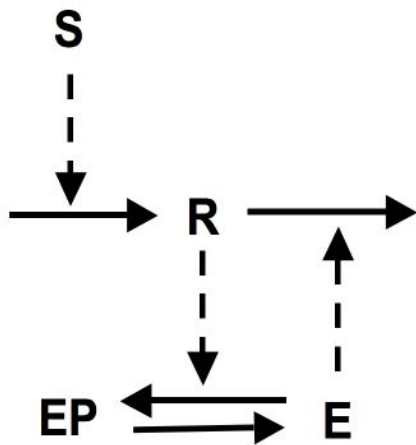


One-way switch

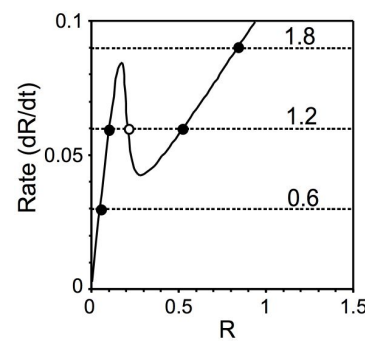
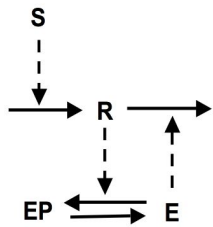
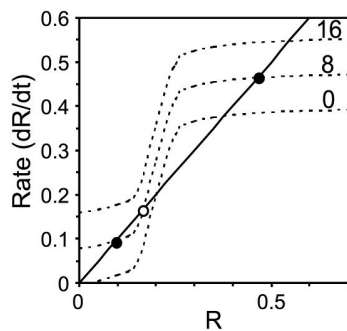
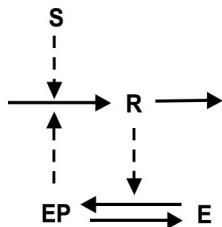


1-parameter bifurcation diagram

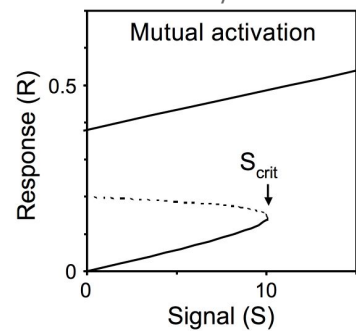
Positive feedback loop



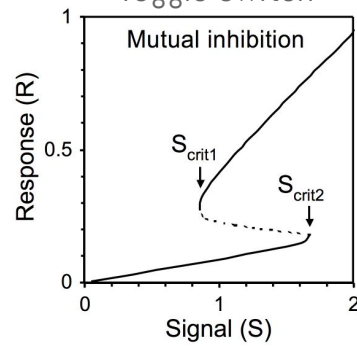
Positive feedback loop



One-way switch

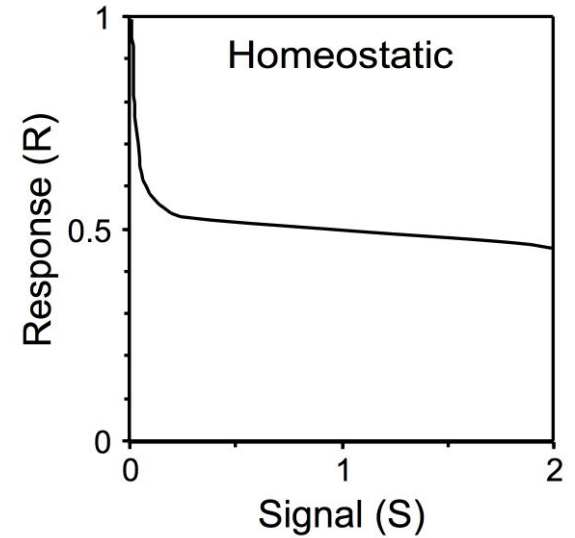
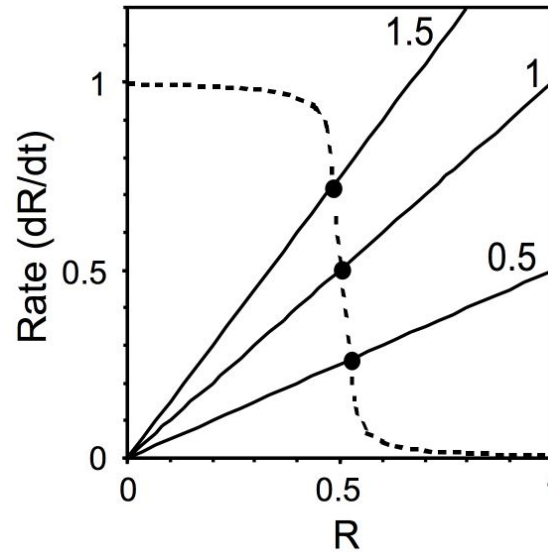
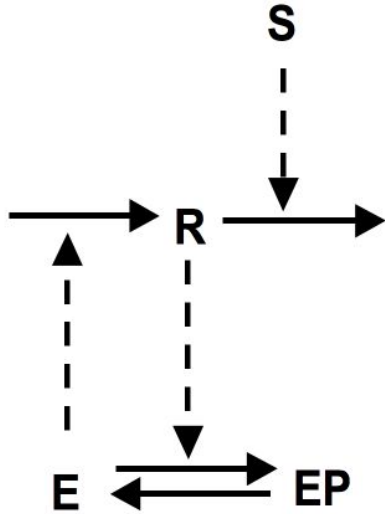


Toggle switch

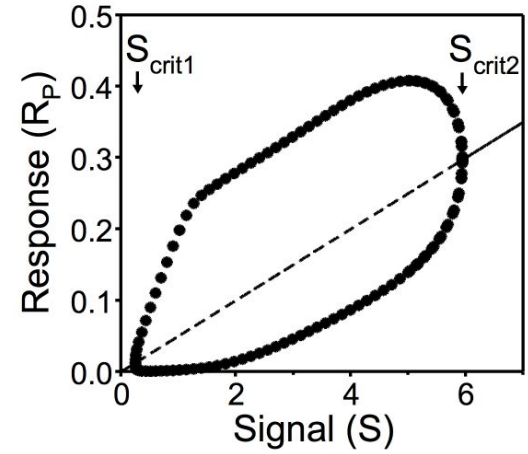
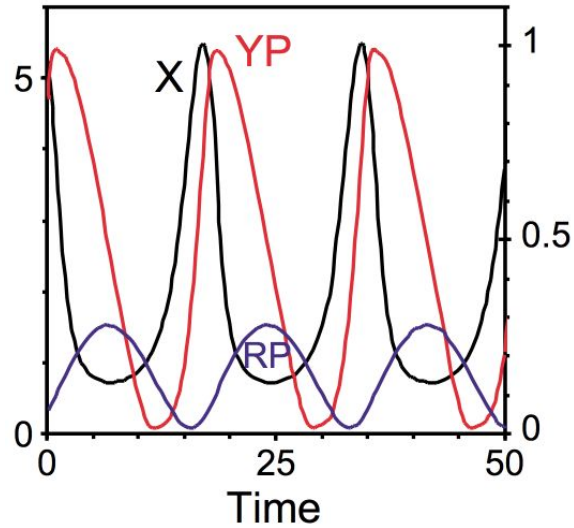
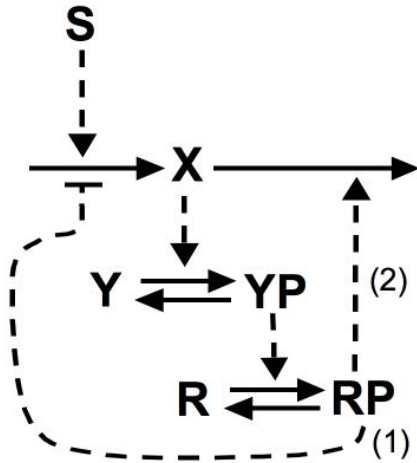


- Irreversible
- Bistable
 - Between 0 & S_{crit} (bifurcation point) and
 - Between S_{crit1} & S_{crit2}
- Undergoes a bifurcation:
 - In this case, a saddle-node bifurcation.

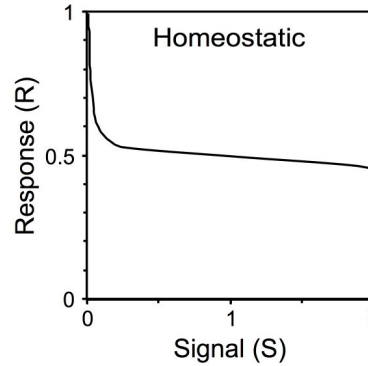
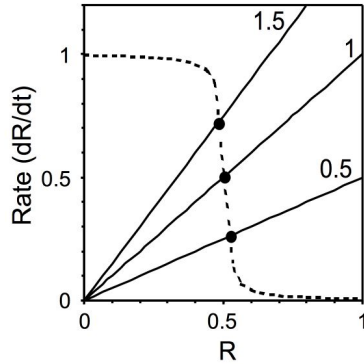
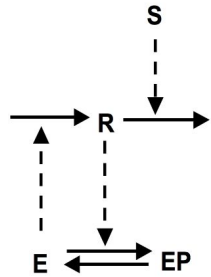
Negative feedback loop



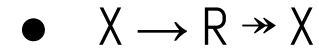
Negative feedback loop



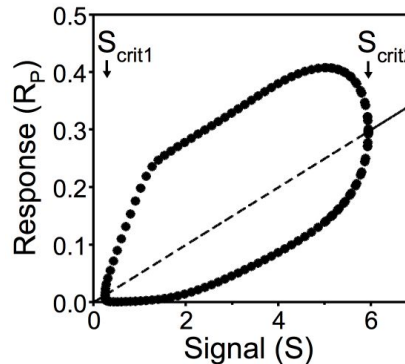
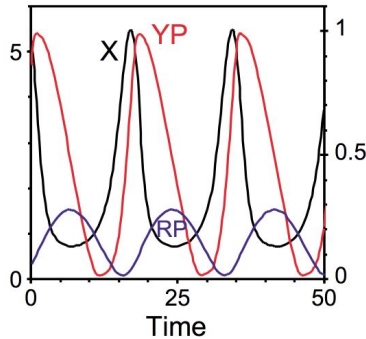
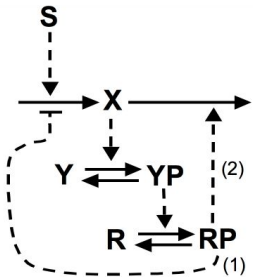
Negative feedback loop



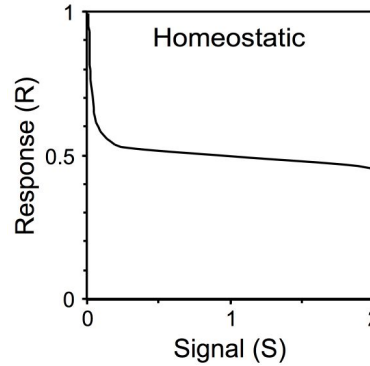
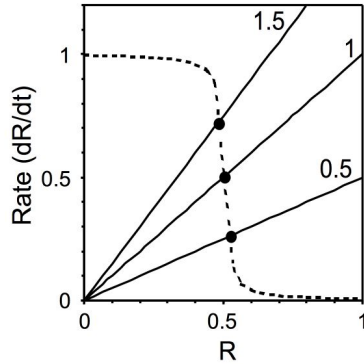
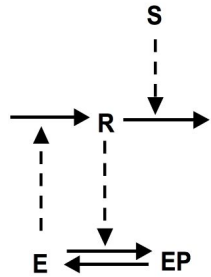
Negative feedback can also create an oscillatory response.



This results in **damped oscillations** to a stable steady state.



Negative feedback loop



Sustained oscillations require at least three components:



Third component (Y) introduces a time delay in the feedback loop, causing the system to repeatedly over- & undershoot its steady state.

