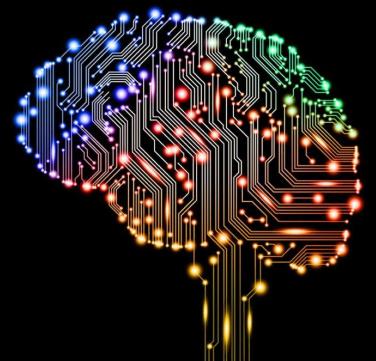




# Real-time Autonomous Vehicle

Krishna Teja Chitty  
11/08/18

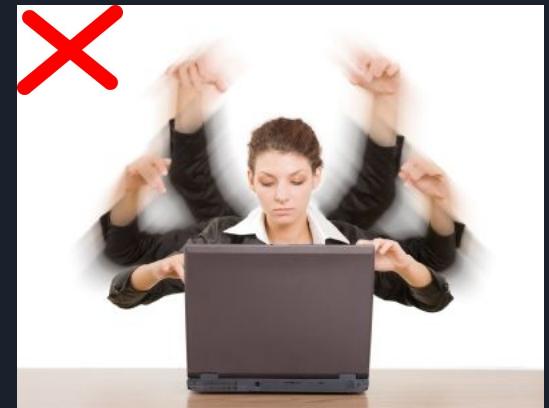


# *What is Real-time performance ??*

*Meeting the deadline*



*Not fast execution*



Source: Google Images

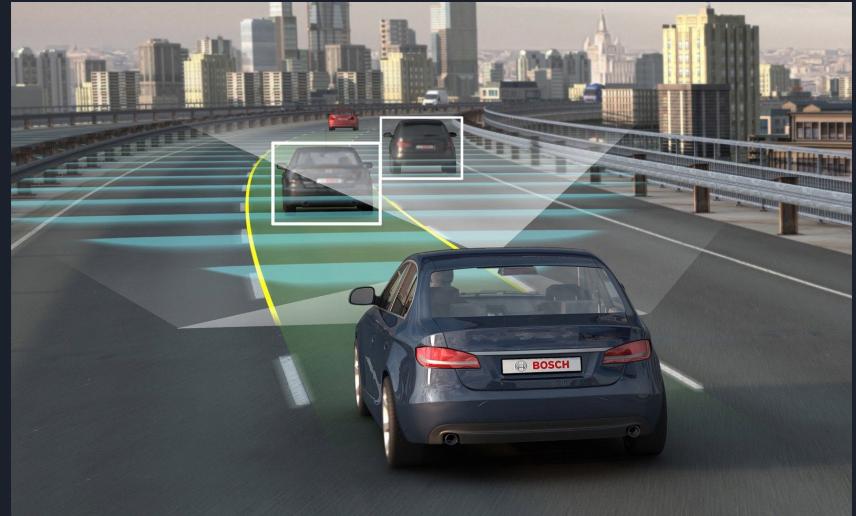


# Review

- Real-Time Monitoring: Reporting the state of an environment within a very small duration, ensuring that the reported state of the environment matches the actual state at the time of the report's delivery.
- Real-Time Data Processing: Collecting and responding to data from the environment before the environment conditions change

# Autonomous Car

Autonomous car, commonly known as driverless car, self-driving car is a vehicle which is capable of detecting its environment and navigating without human interference



Source:  
[https://medium.com/the-mission/the-road-ahead-autonomous-vehicle  
s-startup-ecosystem-3c91d546673d](https://medium.com/the-mission/the-road-ahead-autonomous-vehicle-s-startup-ecosystem-3c91d546673d)

# Google



# Uber



Source: Google, Uber

## **GPS (global positioning system)**

combined with readings from tachometers, altimeters and gyroscopes to provide the most accurate positioning

**Cost:** \$80-\$6,000

## **Lidar (light detection and ranging)**

monitor the vehicle's surroundings (road, vehicles, pedestrians, etc.)

**Cost:** \$90-\$8,000

## **Ultrasonic sensors**

to measure the position of objects very close to the vehicle

**Cost:** \$15-\$20

## **Video cameras**

monitor the vehicle's surroundings (road, vehicles, pedestrians, etc.) and read traffic lights

**Cost (Mono):** \$125-\$150

**Cost (Stereo):** \$150-\$200

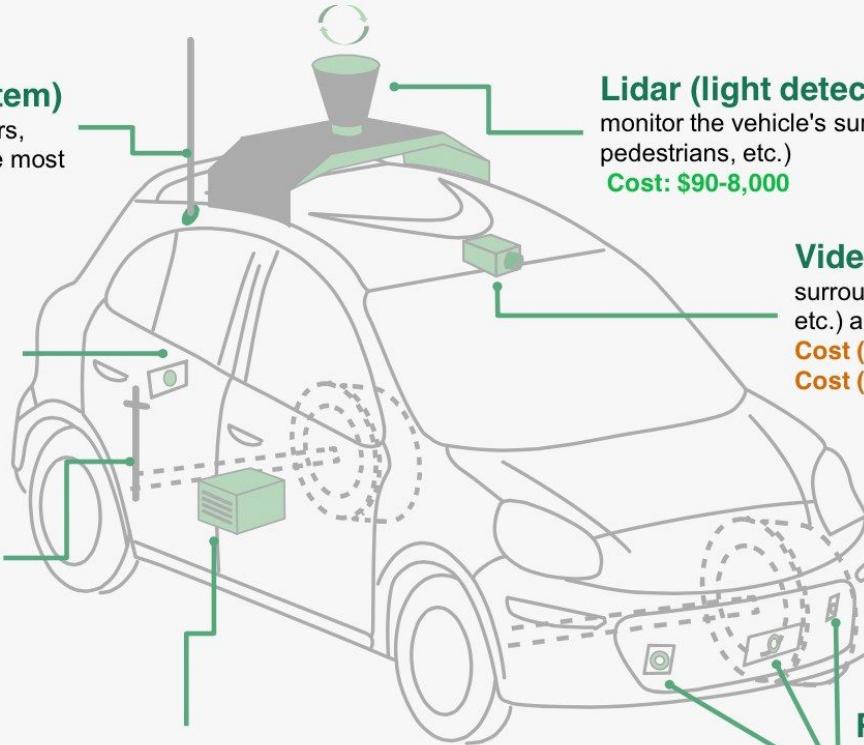
## **Odometry sensors**

complement and improve GPS information

**Cost:** \$80-\$120

**Central computer** analyzes all sensor input, applies rules of the road and operates the steering, accelerator and brakes

**Cost:** ~50-200% of sensor costs



**Radar sensors** monitor the vehicle's surroundings (road, vehicles, pedestrians, etc.)

**Cost (Long Range):** \$125-\$150

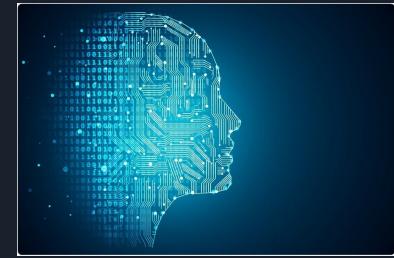
**Cost (Short Range):** \$50-\$100

# What is Real-time performance in Autonomous Car ?

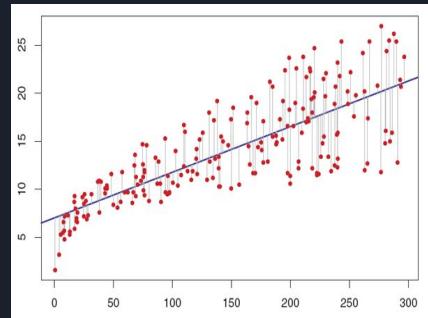
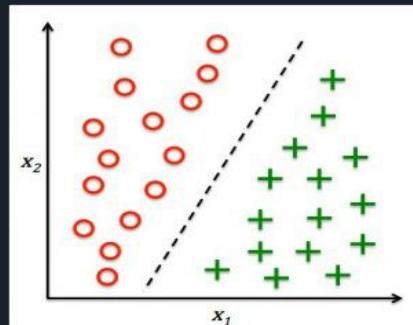
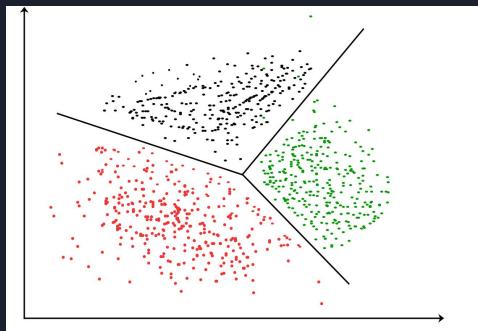
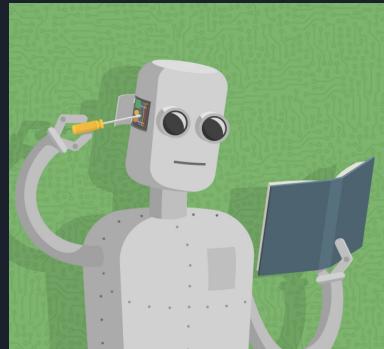
- Navigating through the environment vehicle properly
- Avoiding accidents



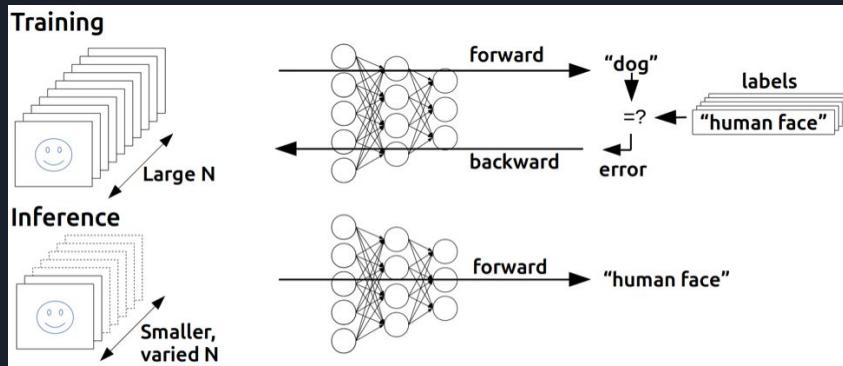
# What is Artificial Intelligence ??



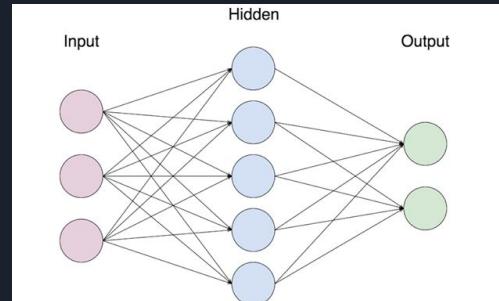
- A technique which enables computers to emulate human behavior in terms of sensing, acting, adapting etc.
- Machine Learning: The subset of Artificial Intelligence where the accuracy of algorithm is improved when they are exposed to more data over time

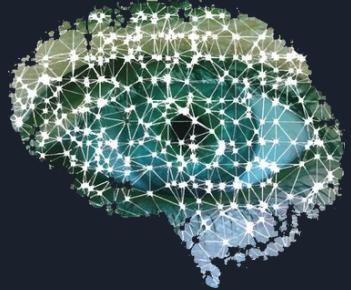


# Training vs Inference



- Deep Learning: The subset of Machine Learning which Neural networks to learn the patterns in data

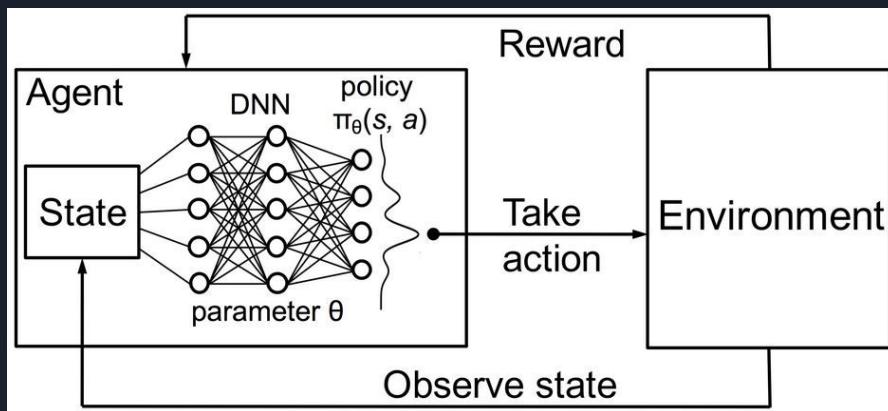




# Reinforcement Learning

- Interacting with the environment and learning from it to achieve the goal

Example: AlphaGo

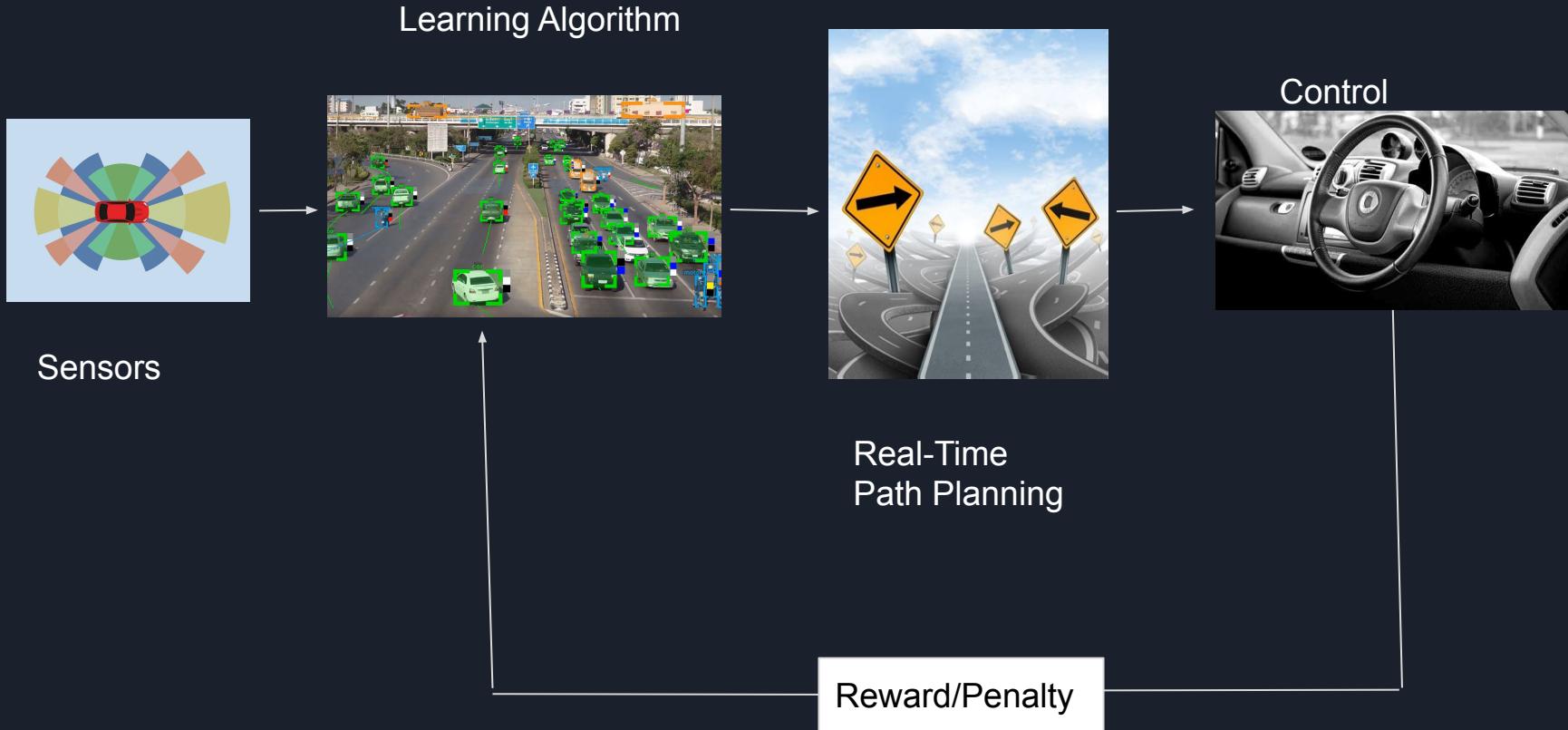


Source: <http://amid.fish/reproducing-deep-rl>



Activity: Try to come up with a feedback mechanism which has sensors, actuators that uses “Reinforcement Learning” Technique

# Feedback Mechanism



# Recent Incident



Source: <https://www.theverge.com/2018/6/22/17492320/safety-driver-self-driving-uber-crash-hulu-police-report>

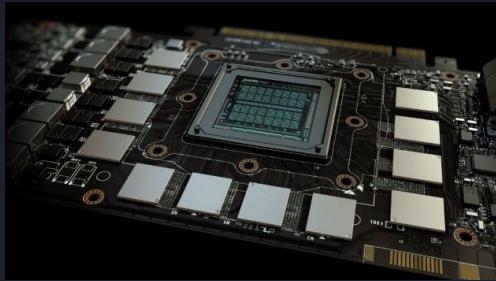
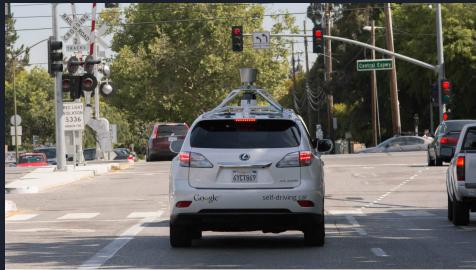
# Reasons for accidents ??

- Low accuracy of the Algorithm
- High accuracy, but couldn't deliver in time



# Parameters w.r.t Real Time System

- Accuracy: Predicting to take proper actions at the right moment
- Computational Power: Amount of work done to get the result
- Latency: Delivered the accuracy before the deadline



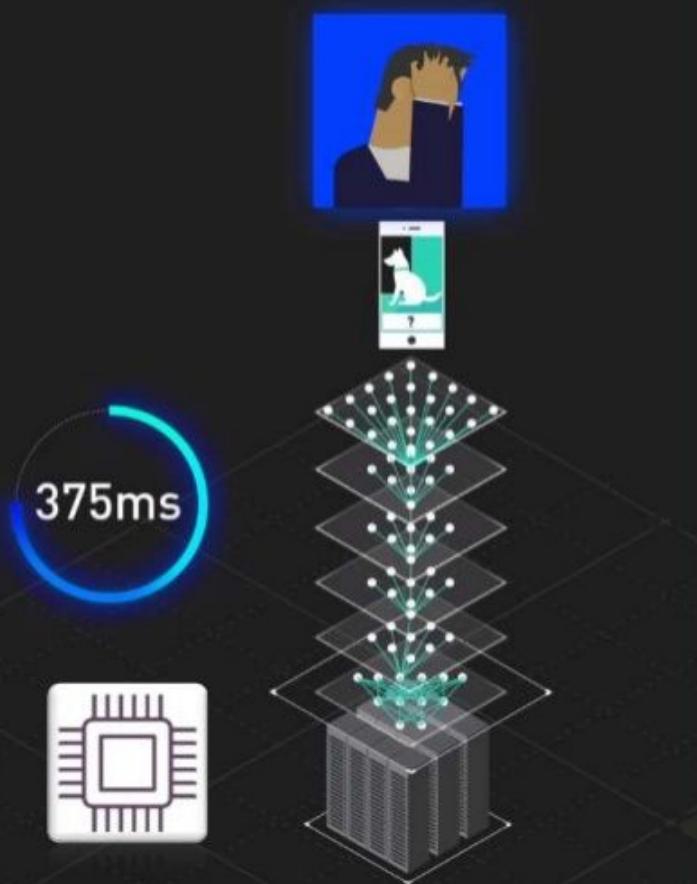


# Accuracy

# Computation Cost

Low	High
Low	Low
High	High
High	Low

Which is more desirable ??





# Conclusion

Artificial Intelligence + Efficient hardware =>  
Real-Time Autonomous Vehicle



# *References*

- <https://selfdrivingcars.mit.edu/>
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- <https://www.theverge.com/2018/6/22/17492320/safety-driver-self-driving-uber-crash-hulu-police-report>
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