ICS-OS Lab 01: Building and Booting ICS-OS

Task 1: Install Docker and Docker-Compose

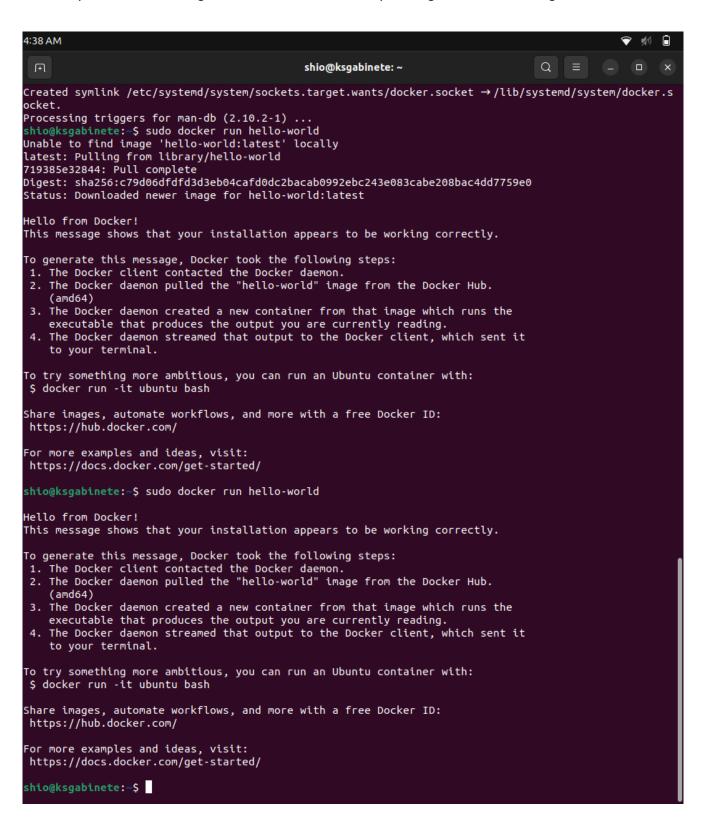
- I. Install Docker Engine on Ubuntu. https://docs.docker.com/engine/install/ubuntu/
- a. Uninstall all conflicting packages before installing docker (if there's any).

```
shio@ksgabinete: ~
                                                                             Q
shio@ksgabinete:~$ for pkg in docker.io docker-doc docker-compose docker-compose-v2 podman-docker
containerd runc; do sudo apt-get remove $pkg; done
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
Package 'docker.io' is not installed, so not removed
0 upgraded, 0 newly installed, 0 to remove and 3 not upgraded.
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
Package 'docker-doc' is not installed, so not removed
0 upgraded, 0 newly installed, 0 to remove and 3 not upgraded.
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
Package 'docker-compose' is not installed, so not removed
0 upgraded, 0 newly installed, 0 to remove and 3 not upgraded.
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
Package 'docker-compose-v2' is not installed, so not removed
0 upgraded, 0 newly installed, 0 to remove and 3 not upgraded.
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
Package 'podman-docker' is not installed, so not removed
0 upgraded, 0 newly installed, 0 to remove and 3 not upgraded.
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
Package 'containerd' is not installed, so not removed
0 upgraded, 0 newly installed, 0 to remove and 3 not upgraded.
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
Package 'runc' is not installed, so not removed
0 upgraded, 0 newly installed, 0 to remove and 3 not upgraded.
shio@ksgabinete:~$
```

b. Set up Docker's apt repository.

```
4:34 AM
                                              shio@ksgabinete: ~
                                                                                    Q ≡
shio@ksgabinete:~$ # Add Docker's official GPG key:
sudo apt-get update
sudo apt-get install ca-certificates curl gnupg
sudo install -m 0755 -d /etc/apt/keyrings
curl -fsSL https://download.docker.com/linux/ubuntu/gpg | sudo gpg --dearmor -o /etc/apt/keyrings/doc
ker.gpg
sudo chmod a+r /etc/apt/keyrings/docker.gpg
# Add the repository to Apt sources:
  "deb [arch="$(dpkg --print-architecture)" signed-by=/etc/apt/keyrings/docker.gpg] https://download.
docker.com/linux/ubuntu \
  "$(. /etc/os-release && echo "$VERSION_CODENAME")" stable" | \
  sudo tee /etc/apt/sources.list.d/docker.list > /dev/null
sudo apt-get update
Hit:1 http://ph.archive.ubuntu.com/ubuntu jammy InRelease
Hit:2 http://ph.archive.ubuntu.com/ubuntu jammy-updates InRelease
Hit:3 http://ph.archive.ubuntu.com/ubuntu jammy-backports InRelease
Hit:4 http://security.ubuntu.com/ubuntu jammy-security InRelease
Hit:5 https://dl.winehq.org/wine-builds/ubuntu jammy InRelease
Hit:6 https://ppa.launchpadcontent.net/yannubuntu/boot-repair/ubuntu jammy InRelease
Reading package lists... Done Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
ca-certificates is already the newest version (20230311ubuntu0.22.04.1).
ca-certificates set to manually installed.
gnupg is already the newest version (2.2.27-3ubuntu2.1).
gnupg set to manually installed.
The following NEW packages will be installed:
 curl
O upgraded, 1 newly installed, O to remove and 3 not upgraded.
Need to get 194 kB of archives.
After this operation, 454 kB of additional disk space will be used.
Do you want to continue? [Y/n] Y
Get:1 http://ph.archive.ubuntu.com/ubuntu jammy-updates/main amd64 curl amd64 7.81.0-1ubuntu1.14 [194
kB]
Fetched 194 kB in 1s (361 kB/s)
Selecting previously unselected package curl.
(Reading database ... 212403 files and directories currently installed.)
Preparing to unpack .../curl_7.81.0-1ubuntu1.14_amd64.deb ...
Unpacking curl (7.81.0-1ubuntu1.14) ...
Setting up curl (7.81.0-1ubuntu1.14) ...
Processing triggers for man-db (2.10.2-1) ...
Hit:1 http://ph.archive.ubuntu.com/ubuntu jammy InRelease
Hit:2 http://ph.archive.ubuntu.com/ubuntu jammy-updates InRelease
Hit:3 http://ph.archive.ubuntu.com/ubuntu jammy-backports InRelease
Get:4 https://download.docker.com/linux/ubuntu jammy InRelease [48.8 kB]
Hit:5 http://security.ubuntu.com/ubuntu jammy-security InRelease
Get:6 https://download.docker.com/linux/ubuntu jammy/stable amd64 Packages [22.7 kB]
Hit:7 https://ppa.launchpadcontent.net/yannubuntu/boot-repair/ubuntu jammy InRelease
Hit:8 https://dl.winehq.org/wine-builds/ubuntu jammy InRelease
Fetched 71.5 kB in 1s (53.9 kB/s)
Reading package lists... Done
shio@ksgabinete:~$
```

c. Verify that the Docker Engine installation is successful by running the hello-world image.



- II. Install the Docker's Compose plugin. https://docs.docker.com/compose/install/linux/#install-using-the-repository
- a. Set up the repository. (already did in the previous section)
- b. Update the package index, and install the latest version of Docker Compose.

```
shio@ksgabinete:~ Q = - - ×

shio@ksgabinete:~ Sudo apt-get update
Hit:1 http://ph.archive.ubuntu.com/ubuntu jammy InRelease
Hit:2 http://ph.archive.ubuntu.com/ubuntu jammy-updates InRelease
Hit:3 http://ph.archive.ubuntu.com/ubuntu jammy-backports InRelease
Hit:4 https://download.docker.com/linux/ubuntu jammy InRelease
Hit:5 http://security.ubuntu.com/ubuntu jammy-security InRelease
Hit:6 https://dl.winehq.org/wine-builds/ubuntu jammy InRelease
Hit:7 https://ppa.launchpadcontent.net/yannubuntu/boot-repair/ubuntu jammy InRelease
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
docker-compose-plugin is already the newest version (2.21.0-1~ubuntu.22.04~jammy).
0 upgraded, 0 newly installed, 0 to remove and 3 not upgraded.
```

c. Verify that Docker Compose is installed correctly by checking the version.

```
shio@ksgabinete:~$ docker compose version
Docker Compose version v2.21.0
shio@ksgabinete:~$
```

- III. Linux post-installation steps for Docker Engine (Manage Docker as a non-root user)
- a. Create the docker group.



b. Add your user to the docker group.

```
shio@ksgabinete:~$ sudo usermod -aG docker $USER
shio@ksgabinete:~$
```

c. Log out and log back in so that your group membership is re-evaluated. (did off Cam)

activate the changes to groups:



d. Verify that you can run docker commands without sudo.

```
shio@ksgabinete:~$ docker run hello-world
Hello from Docker!
This message shows that your installation appears to be working correctly.
To generate this message, Docker took the following steps:
1. The Docker client contacted the Docker daemon.
2. The Docker daemon pulled the "hello-world" image from the Docker Hub.
    (amd64)
3. The Docker daemon created a new container from that image which runs the
    executable that produces the output you are currently reading.
 4. The Docker daemon streamed that output to the Docker client, which sent it
   to your terminal.
To try something more ambitious, you can run an Ubuntu container with:
$ docker run -it ubuntu bash
Share images, automate workflows, and more with a free Docker ID:
https://hub.docker.com/
For more examples and ideas, visit:
https://docs.docker.com/get-started/
shio@ksgabinete:~$
```

Additional: Configure Docker to start on boot with system

```
shio@ksgabinete:~$ sudo systemctl enable docker.service
Synchronizing state of docker.service with SysV service script with /lib/systemd/systemd-sysv-install
.
Executing: /lib/systemd/systemd-sysv-install enable docker
shio@ksgabinete:~$ sudo systemctl enable containerd.service
shio@ksgabinete:~$
```

Task 2: Clone the repository and explore the source tree

I. Checkout the source code and explore the source tree. (clone https://github.com/srg-ics-uplb/ics-os.git into a local directory)

```
shio@ksgabinete:~

shio@ksgabinete:~

shio@ksgabinete:-$ git clone https://github.com/srg-ics-uplb/ics-os.git ics-os-ksgabinete

Cloning into 'ics-os-ksgabinete'...
remote: Enumerating objects: 3547, done.
remote: Counting objects: 100% (398/398), done.
remote: Compressing objects: 100% (188/188), done.
remote: Total 3547 (delta 212), reused 396 (delta 210), pack-reused 3149

Receiving objects: 100% (3547/3547), 25.76 MiB | 503.00 KiB/s, done.

Resolving deltas: 100% (2364/2364), done.
```

Note: 'ics-os-ksgabinete' was renamed to 'ics-os-kgsg' (can be seen in the succeeding screenshots)

II. Create a branch for lab01 to make code management easier.

```
shio@ksgabinete:~$ cd ics-os-kgsg/
shio@ksgabinete:~/ics-os-kgsg$ git checkout -b lab01
Switched to a new branch 'lab01'
shio@ksgabinete:~/ics-os-kgsg$ git branch
* lab01
   master
shio@ksgabinete:~/ics-os-kgsg$
```

Task 3: Build ICS-OS kernel

I. Open a new terminal. Start and enter the container.

I. Build the kernel image.

```
root@b2a85ef0597e:/# /#cd /home/ics-os
bash: /#cd: No such file or directory
root@b2a85ef0597e:/# cd /home/ics-os
root@b2a85ef0597e:/home/ics-os# make clean
rm -f vmdex
rm -f ics-os-livecd.iso
rm -fr tmp/*
make -C kernel/ clean
rmake[1]: Entering directory '/home/ics-os/kernel'
rm -f *.o
rm -f Kernel32.bin
rm -f Kernel32.sym
rm -f vmdex
make[1]: Leaving directory '/home/ics-os/kernel'
root@b2a85ef0597e:/home/ics-os# make
make -C kernel/
make[1]: Entering directory '/home/ics-os/kernel'
gcc -fno-stack-protector -fgnu89-inline -m32 -w -nostdlib -fno-builtin -ffreestanding -c -g -o sched
uler.o process/scheduler.c
gcc -fno-stack-protector -fgnu89-inline -m32 -w -nostdlib -fno-builtin -ffreestanding -c -g -o fat.o
 filesystem/fat12.c
qcc -fno-stack-protector -fqnu89-inline -m32 -w -nostdlib -fno-builtin -ffreestanding -c -g -o iso96
60.o filesystem/iso9660.c
gcc -fno-stack-protector -fgnu89-inline -m32 -w -nostdlib -fno-builtin -ffreestanding -c -g -o devfs
.o filesystem/devfs.c
gcc -fno-stack-protector -fgnu89-inline -m32 -w -nostdlib -fno-builtin -ffreestanding -c -g -o iomgr
.o iomgr/iosched.c
gcc -fno-stack-protector -fgnu89-inline -m32 -w -nostdlib -fno-builtin -ffreestanding -c -g -o devmg
gcc -fno-stack-protector -fgnu89-inline -m32 -w -nostdlib -fno-builtin -ffreestanding -c -g -o kerne
132.o kernel32.c
nasm -f elf32 -o startup.o startup/startup.asm
nasm -f elf32 -o asmlib.o startup/asmlib.asm
startup/asmlib.asm:321: warning: label alone on a line without a colon might be in error
nasm -f elf32 -o irqwrap.o irqwrap.asm
**strip --strip-debug *.o
ld -melf_i386 -T lscript.ld -Map mapfile.txt
objcopy --only-keep-debug Kernel32.bin Kernel32.sym
objcopy --strip-debug Kernel32.bin
gzip -c -9 Kernel32.bin > vmdex
cp vmdex .
make[1]: Leaving directory '/home/ics-os/kernel'
root@b2a85ef0597e:/home/ics-os#
```

Task 4: Create the disk and boot ICS-OS

I. Build the boot floppy then start Qemu with the floppy image as boot device.

```
shio@ksgabinete: ~/ics-os-kgsg/ics-os
shio@ksgabinete:~/ics-os-kgsg$ cd ics-os/
shio@ksgabinete:~/ics-os-kgsg/ics-os$ sudo make floppy
[sudo] password for shio:
rm -fr tmp
mkdir tmp
cp -r vmdex tmp
scripts/gen-help.sh
cp base/* tmp
mkdir -p tmp/apps
mkdir -p tmp/tcc1
mkdir -p tmp/lib1
cp apps/* tmp/apps/
cp sdk/* tmp/tcc1/
cp lib/* tmp/lib1/
cp grub.img ics-os-floppy.img
                                                        #copy an image with grub
sudo rm -fr mnt
sudo mkdir mnt
sudo mount ics-os-floppy.img mnt -tmsdos -oloop
sudo cp -r tmp/* mnt/
sudo umount mnt
sudo chmod 666 ics-os-floppy.img
rm -fr tmp/
shio@ksgabinete:~/ics-os-kgsg/ics-os$ make boot-floppy
qemu-system-i386 -net nic,model=rtl8139 -soundhw pcspk -fda ics-os-floppy.img -boot a -m 64M
WARNING: Image format was not specified for 'ics-os-floppy.img' and probing guessed raw.
           Automatically detecting the format is dangerous for raw images, write operations on block 0
will be restricted.
           Specify the 'raw' format explicitly to remove the restrictions.
qemu-system-i386: warning: '-soundhw pcspk' is deprecated, please set a backend using '-machine pcspk
-audiodev=<name>' instead
qemu-system-i386: warning: hub 0 is not connected to host network
5:09 AM
                                                                                                                       ♥ 蚴 🚛
                                              shio@ksgabinete: ~/ics-os-kgsg/ics-os
shio@ksgabinete:~/ics-os-kgsg$ cd ics-os/
shio@ksgabinete:~/ics-os-kgsg/ics-os$ sudo make floppy
[sudo] password for shio:
rm -fr tmp
mkdir tmp
                                                             QEMU
cp -r vmdex
scripts/ger Machine View
cp base/*
mkdir -p tr
mkdir -p tr
mkdir -p tr
                  GRUB version 0.92 (639K lower / 64384K upper memory)
cp apps/* t
cp sdk/* tr
                ICS Operating System
cp lib/* tr
cp grub.imo
sudo rm -fr
sudo mkdir
sudo mount
sudo cp -r
sudo umount
sudo chmod
 rm -fr tmp/
                     Use the 1 and 4 keys to select which entry is highlighted. Press enter to boot the selected OS, 'e' to edit the commands before booting, or 'c' for a command-line.
qemu-syster
WARNING: Ir
                                                                                                                    n block 0
          Au
will be res
           Sp
qemu-syster
                                                                                                                    hine pcspk
 -audiodev=<
qemu-system-i386: warning: hub 0 is not connected to host network
```

Task 5: Run ICS-OS commands

- I. Once the ICS-OS command prompt (%) appears, type help. Examine the list of commands and run two of these commands.
- I. typing "help"

- II. running two commands
- a. "cpuid"

b. "Isdev"

```
/icsos/ %lsdev
I D
            Device Name
                                                                              Description
                                             Type
                                            Kernel Service Standard Library Interface
memory manager DEX low-level memory manager
Kernel Extension University of California, Berkeley malloc
            stdlib
           mem_mgr
bsd_malloc
                                            Kernel Extension Doug Lea's dlmalloc VERSION 2.7.2
Kernel Extension malloc for debugging
port manager Hardware port manager
character device Default generic keyboard driver 1.00
character device Default mouse driver 1.00
Kernel Extension Default Round-Robin Scheduler
            dl_malloc
           dex_malloc
hwportmgr
            keyb
            mouse
            default_sched
                                                                              ATA s master CD/DVD-ROM (READ-ONLY)
VGA graphics driver
DEX default I/O scheduler and manager
            cds0
                                            Block device
12
            vga
default_iomgr
                                            Unknown
13
14
15
                                            I/O manager
Block device
            nu l l
                                                                              null block device
                                                                              Device Filesystem
MS-DOS FATFs driver
DEX ISO 9660∕Joliet CD-ROM filesystem
            devfs
                                            Filesystem
16
                                             Filesystem
                                            Filesystem
17
            cdfs
```

Task 6: Cleanup

I. Exit the build container by typing the command "exit".

```
QEMU-Press Ctrl+Alt+G to release grab

Marning: 6. Cannot resolve 'Sleep'
Warning: 7. Cannot resolve 'MaitForSingleObject'
Warning: 8. Cannot resolve '__dllonexit'
Warning: 9. Cannot resolve 'abort'
Number of Data directories: 16
examining export directory.
bobtaining DEX specific entrypoints..
Number of exports - 1
fxn names address = 0xe0016030
fxn addresses = 0xe0016034
function name: dex32_libmain
Calling dex32 compatible library entrypoint located at e000d420..
DEX Randisk Driver 1.03
10000 blocks alloated
Identifying FAT type..
Identifying FAT type..
Using FAT16..
allocating FAT..
uriting to FAT..formatting..
done.
Installing Randisk as randisk
Initialization successful!
Driver was assigned handle 18
Call successful.
```

II. Go back to the master branch of the source code.

```
shio@ksgabinete: ~/ics-os-kgsg/ics-os
shio@ksgabinete:~/ics-os-kgsg$ cd ics-os/
shio@ksgabinete:~/ics-os-kgsg/ics-os$ sudo make floppy
[sudo] password for shio:
rm -fr tmp
mkdir tmp
cp -r vmdex tmp
scripts/gen-help.sh
cp base/* tmp
mkdir -p tmp/apps
mkdir -p tmp/tcc1
mkdir -p tmp/lib1
cp apps/* tmp/apps/
cp sdk/* tmp/tcc1/
cp lib/* tmp/lib1/
cp grub.img ics-os-floppy.img
                                                  #copy an image with grub
sudo rm -fr mnt
sudo mkdir mnt
sudo mount ics-os-floppy.img mnt -tmsdos -oloop
sudo cp -r tmp/* mnt/
sudo umount mnt
sudo chmod 666 ics-os-floppy.img
rm -fr tmp/
shio@ksgabinete:~/ics-os-kgsg/ics-os$ make boot-floppy
qemu-system-i386 -net nic,model=rtl8139 -soundhw pcspk -fda ics-os-floppy.img -boot a -m 64M
WARNING: Image format was not specified for 'ics-os-floppy.img' and probing guessed raw.
         Automatically detecting the format is dangerous for raw images, write operations on block 0
will be restricted.
         Specify the 'raw' format explicitly to remove the restrictions.
qemu-system-i386: warning: '-soundhw pcspk' is deprecated, please set a backend using '-machine pcspk
-audiodev=<name>' instead
qemu-system-i386: warning: hub 0 is not connected to host network
                           -kgsg/ics-os$ git checkout master
        ics-os/ics-os-floppy.img
Switched to branch 'master'
Your branch is up to date with 'origin/master'.
shio@ksgabinete:~/ics-os-kgsg/ics-os$ git branch
 lab01
shio@ksgabinete:~/ics-os-kgsg/ics-os$
```

Reflection: Write some realizations and questions that crossed your mind while doing this lab.

While doing this lab, I came to realize that ICS-OS is also a Linux distribution (distro), similar to Ubuntu. I noticed that most, if not all, of the commands in ICS-OS are based on Linux built-in commands, named and functioning exactly like their Linux counterparts. One question that comes to mind, though, is why do we need to use Docker to run the ICS operating system? What are containers exactly for? And can we run ICS-OS without these containers?

A few other questions that crossed my mind while doing this lab are: "Can I install the ICS operating system as a stand-alone package in an empty disk drive?" "Wouldn't I encounter problems running the ICS-OS on my device due to some missing drivers or driver incompatibility?" "Do I have to write drivers for each specific component that makes up my device, or can I use the already-existing drivers from other operating systems?"

Obviously, I still have much to learn about how operating systems work and are built. So, for now, I believe further research on my part is necessary.