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Part 1:

1. Find the B-matrix for the transformation $\mathbf{x} \mapsto \mathbf{Ax}$ when is given by the indicated vectors \mathbf{b}_i .

a. $A = \begin{bmatrix} 3 & 4 \\ -1 & -1 \end{bmatrix}$ with $\mathbf{b}_1 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$ and $\mathbf{b}_2 = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$

b. $A = \begin{bmatrix} -14 & 4 & -14 \\ -33 & 9 & -31 \\ 11 & -4 & 11 \end{bmatrix}$ with $\mathbf{b}_1 = \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}$, $\mathbf{b}_2 = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix}$, and $\mathbf{b}_3 = \begin{bmatrix} -1 \\ -2 \\ 0 \end{bmatrix}$

2. Let $B = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$ be a basis for a vector space V . Let $T: V \rightarrow V$ be a linear transformation for

which $[T]_B = \begin{bmatrix} 0 & -6 & 1 \\ 0 & 5 & -1 \\ 1 & -2 & 7 \end{bmatrix}$. Find $T(3\mathbf{b}_1 - 4\mathbf{b}_2)$.

3. Prove that if \mathbf{u} and \mathbf{v} are two vectors in \mathbb{R}^n of the same length, then $\mathbf{u} + \mathbf{v}$ is orthogonal to $\mathbf{u} - \mathbf{v}$.

4. For $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$, verify that

$$\|\mathbf{u} + \mathbf{v}\|^2 + \|\mathbf{u} - \mathbf{v}\|^2 = 2\|\mathbf{u}\|^2 + 2\|\mathbf{v}\|^2$$

Describe geometrically what this equation means.

5. Suppose vector \mathbf{x} is orthogonal to vectors \mathbf{v}_1 and \mathbf{v}_2 . Show that \mathbf{x} is orthogonal to every $\mathbf{v} \in \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

Part 2:

1. For any $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$, the angle between \mathbf{u} and \mathbf{v} is any angle θ satisfying $\frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\|\|\mathbf{v}\|} = \cos \theta$

Let $\mathbf{u} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ and $\mathbf{v} = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$

- Find the cosine of the angle between \mathbf{u} and \mathbf{v} .
 - Find unit vectors in the directions of \mathbf{u} and \mathbf{v} .
 - Find the projection of \mathbf{u} onto \mathbf{v} .
2. Let V be a nonzero subspace of \mathbb{R}^n with an orthogonal basis $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ and let $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be defined by $T(\mathbf{x}) = \text{proj}_V \mathbf{x}$. Show that T is a linear transformation.
3. Let U and V be orthogonal matrices.

- a. Prove that the product UV is also orthogonal.
- b. Find examples U and V for which $U+V$ is not orthogonal.

4. Find the closest point to $\mathbf{x} = \begin{bmatrix} 3 \\ 1 \\ 5 \\ 1 \end{bmatrix}$ in the subspace spanned by $\mathbf{w}_1 = \begin{bmatrix} 3 \\ 1 \\ -1 \\ 1 \end{bmatrix}$ and $\mathbf{w}_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}$

5. Let A be an $m \times n$ matrix. Prove that $\mathbf{x} \in \mathbb{R}^n$ can be written in the form $\mathbf{p} + \mathbf{u}$, where $\mathbf{p} \in \text{Row } A$ and $\mathbf{u} \in \text{Nul } A$. Further, show that if the equation $A\mathbf{x} = \mathbf{b}$ is consistent, then there is a unique $\mathbf{p} \in \text{Row } A$ such that $A\mathbf{p} = \mathbf{b}$.

6. Apply the Gram-Schmidt process to produce an orthonormal basis for the subspace W spanned by the indicate vectors.

a. $\mathbf{w}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \mathbf{w}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \mathbf{w}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix},$

b. $\mathbf{w}_1 = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}, \mathbf{w}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \mathbf{w}_3 = \begin{bmatrix} 2 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \mathbf{w}_4 = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 1 \end{bmatrix}$

7. For cases when the equation $A\mathbf{x} = \mathbf{b}$ is inconsistent, there may still be a need to find an “approximate” solution. In that case, $A\mathbf{x} \neq \mathbf{b}$, but the smaller the distance $\|A\mathbf{x} - \mathbf{b}\|$ is, the better the approximation is. The general least squares problem seeks to find a solution \mathbf{x} that makes $\|A\mathbf{x} - \mathbf{b}\|$ as small as possible.

One method to find a least-squares solution is to solve the equation

$$A^T A \mathbf{x} = A^T \mathbf{b}$$

Verify that $A\mathbf{x} = \mathbf{b}$ is an inconsistent system; then using the method just described, find a least squares solution of $A\mathbf{x} = \mathbf{b}$ when

$$A = \begin{bmatrix} 1 & 3 \\ 1 & -1 \\ 1 & 1 \end{bmatrix} \text{ and } \mathbf{b} = \begin{bmatrix} 5 \\ 1 \\ 0 \end{bmatrix}$$