

# Einführung in Visual Computing

186.822

## Textures

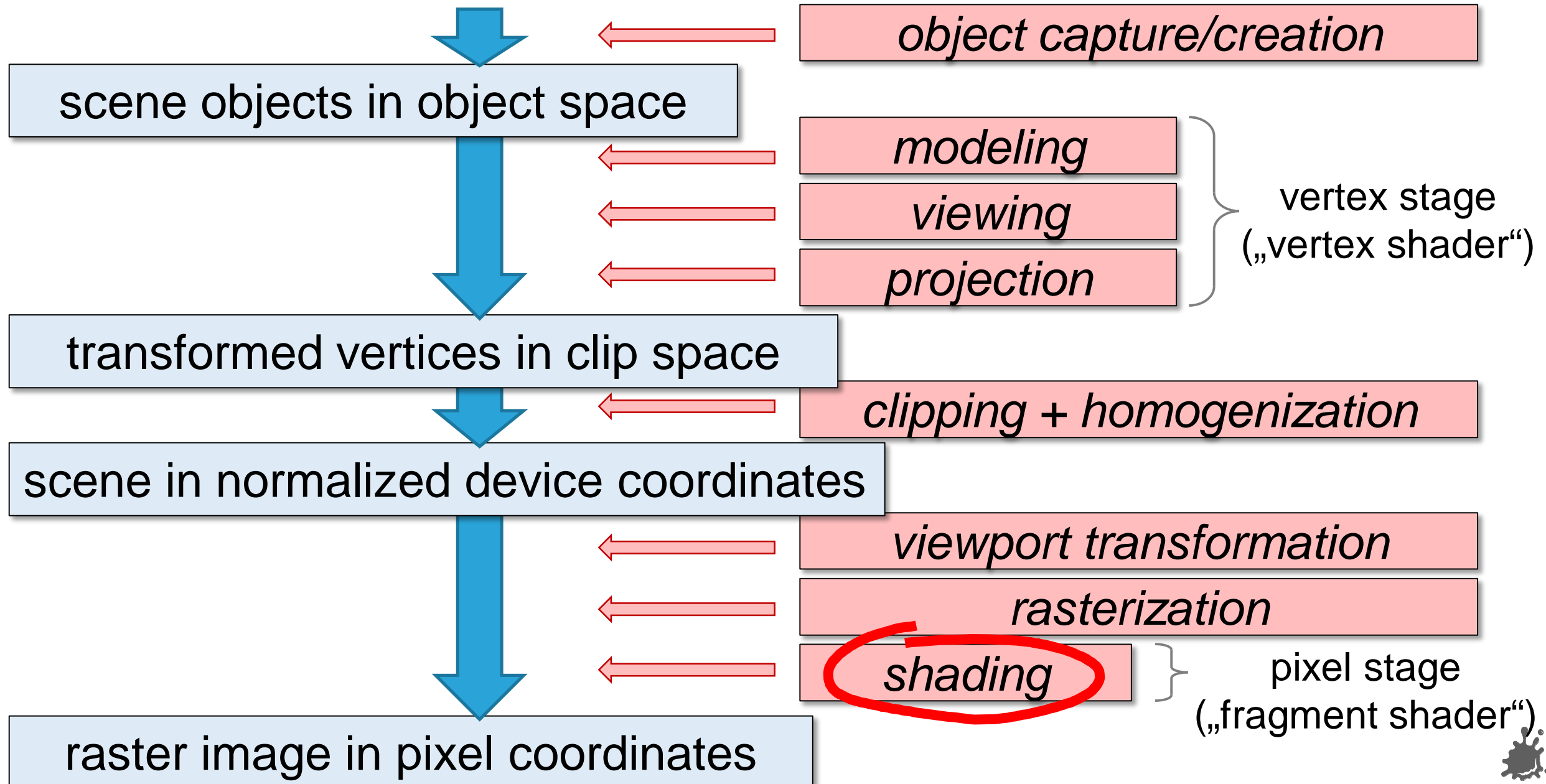
Werner Purgathofer



- polygon rendering methods
- ray tracing
- global illumination
- environment mapping
- texture mapping
- bump mapping

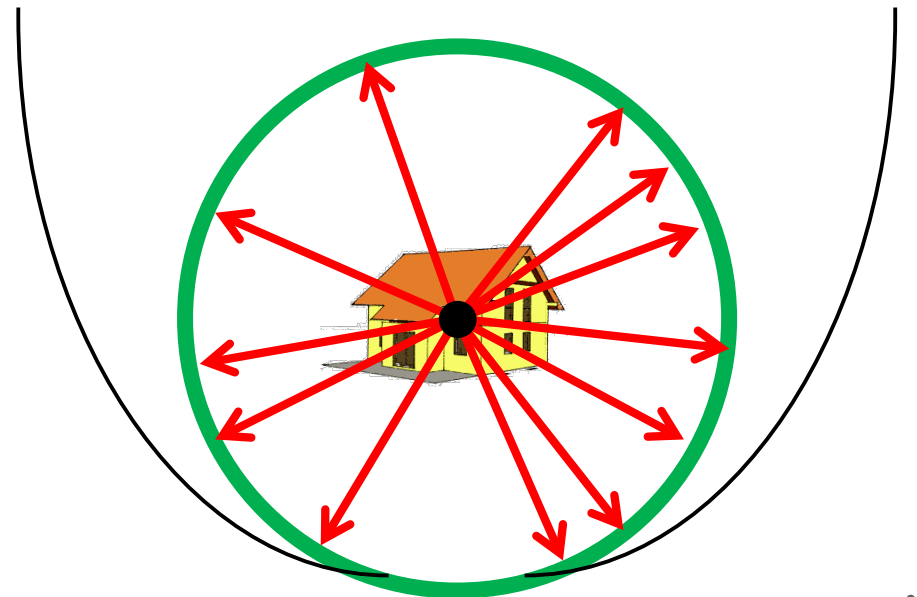
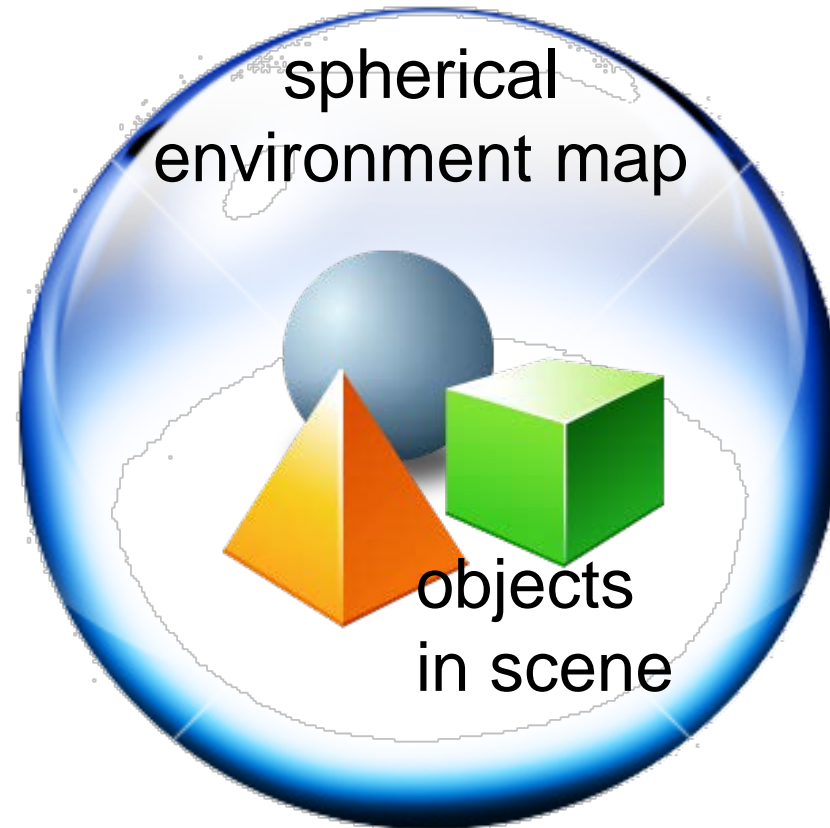
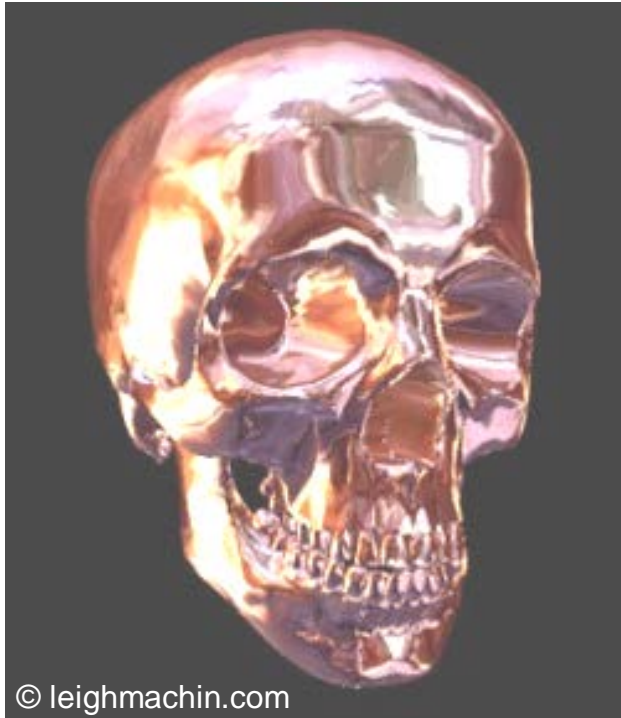


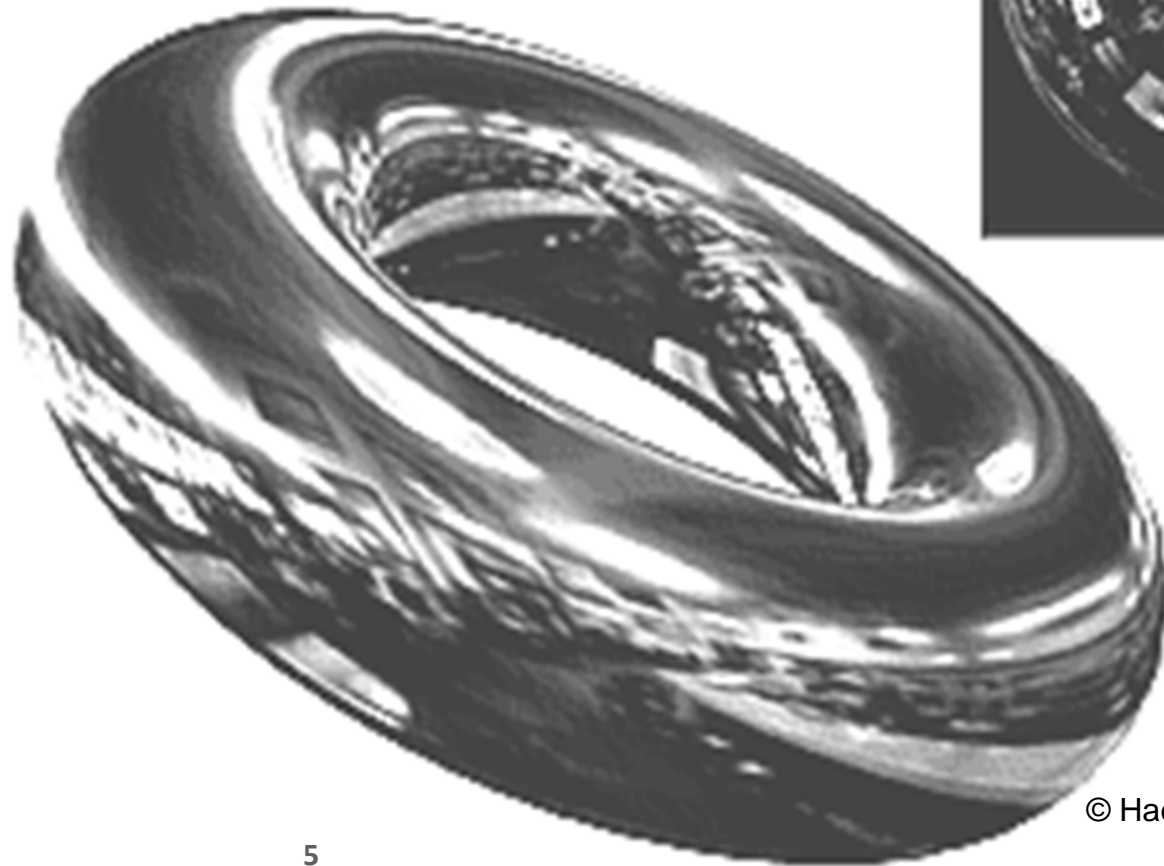
# Textures in the Rendering Pipeline



= reflection mapping

defined over surface of an enclosing universe (sphere, cube, cylinder)



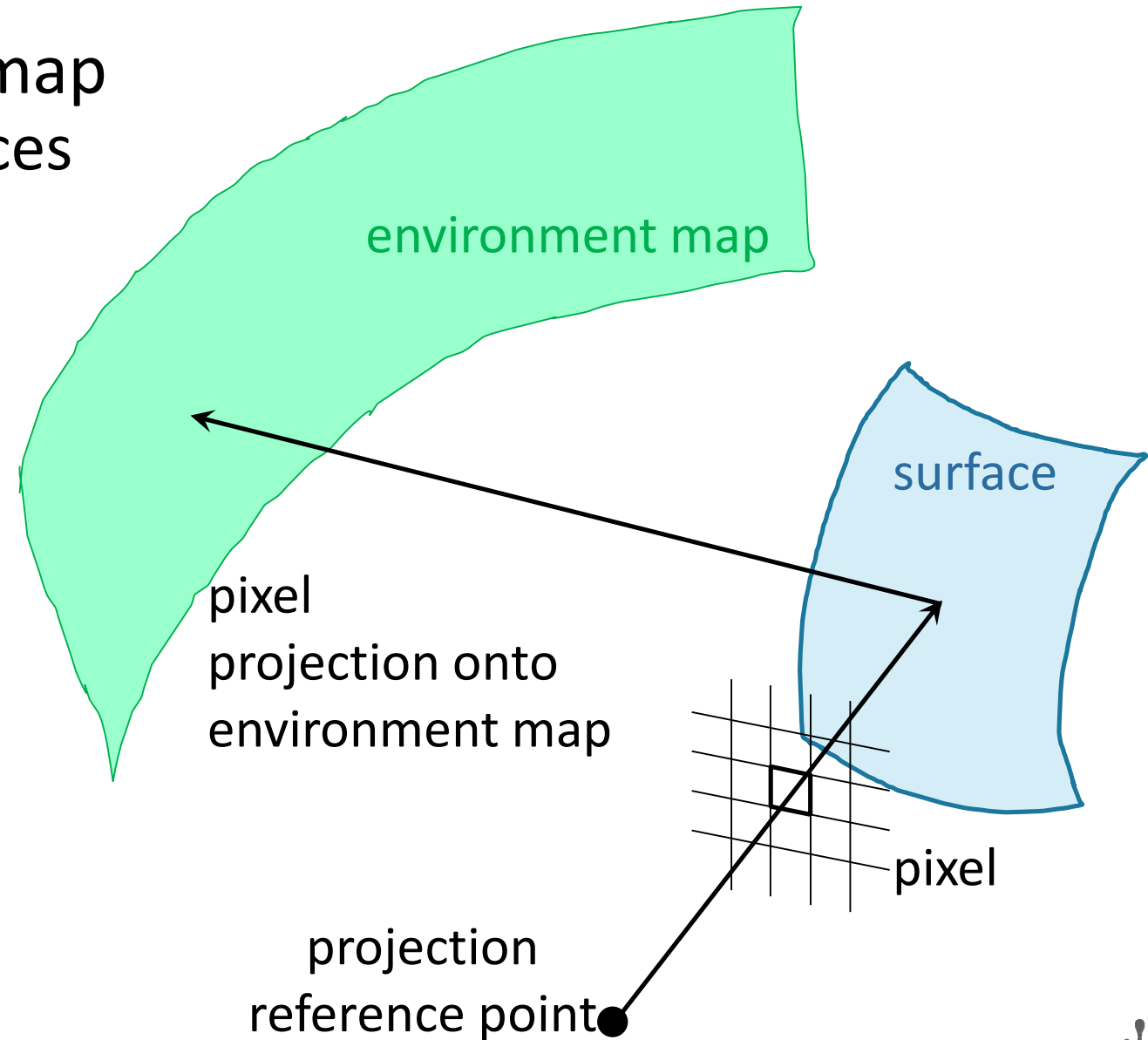


information in the environment map

- intensity values for light sources
- sky
- background objects

pixel:

- projected onto surface
- reflected onto environment map

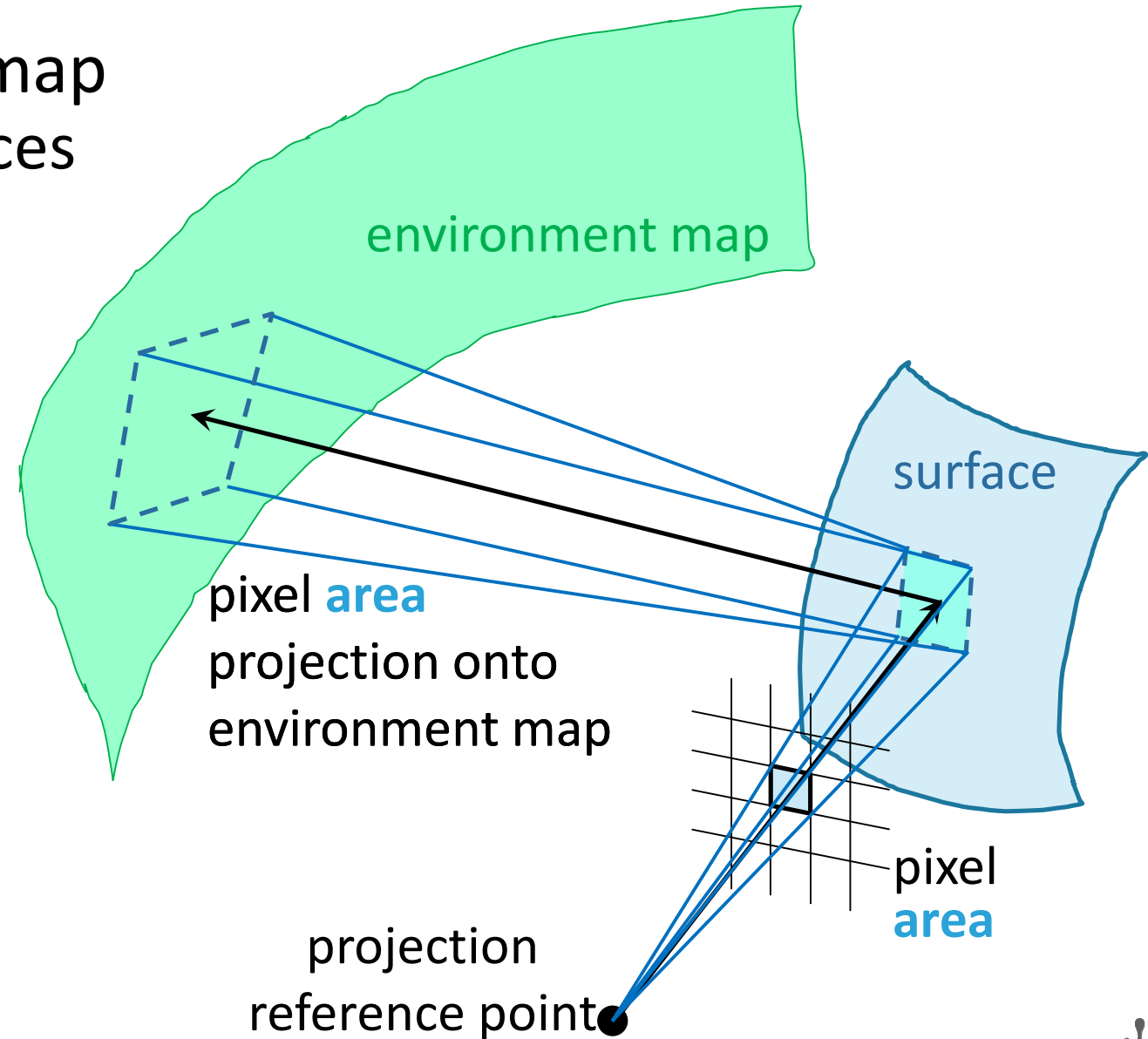


information in the environment map

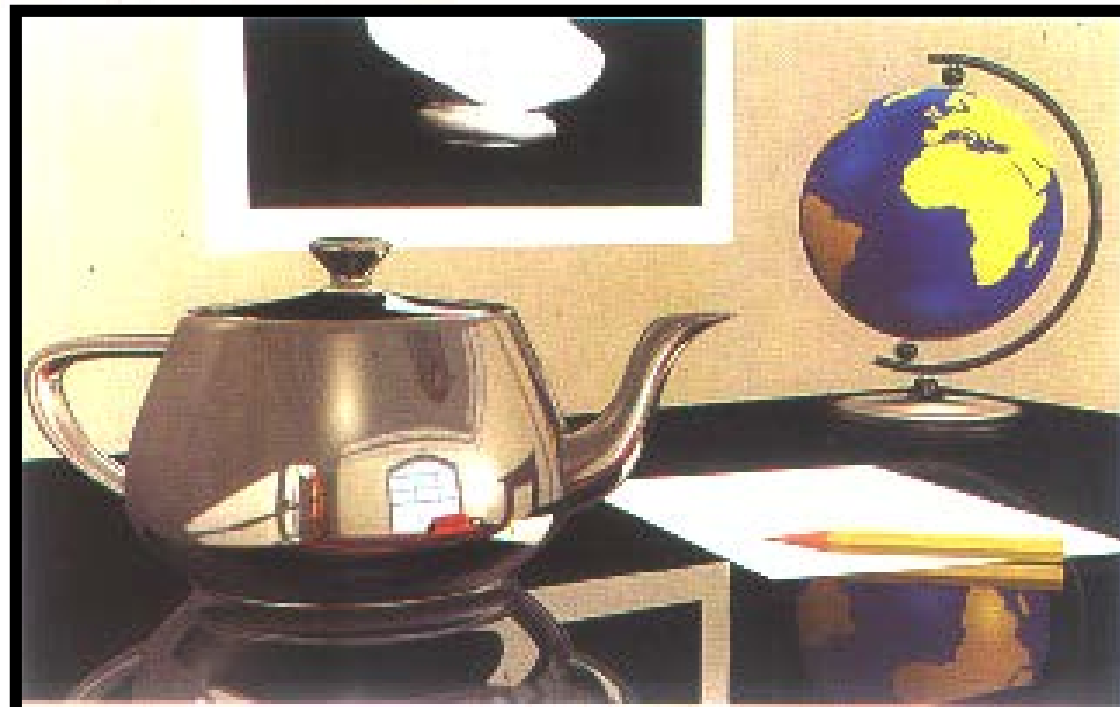
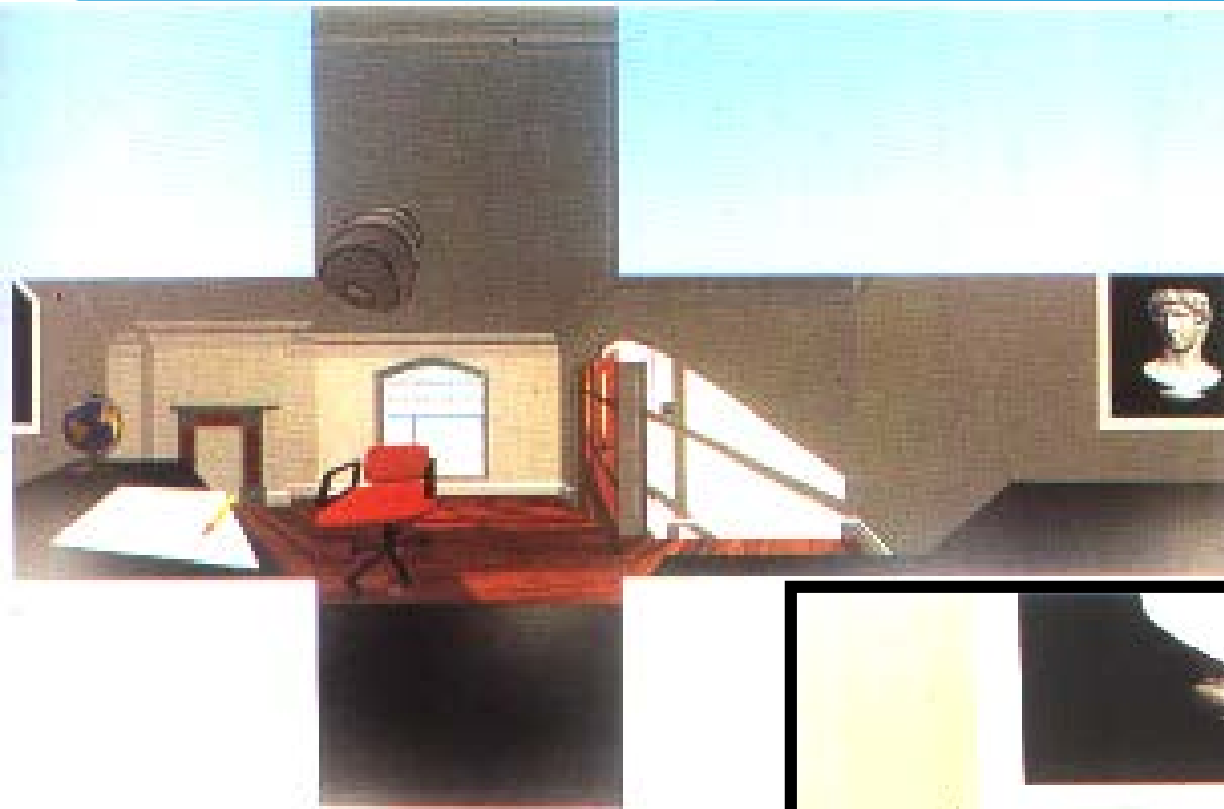
- intensity values for light sources
- sky
- background objects

pixel **area**:

- projected onto surface
- reflected onto environment map

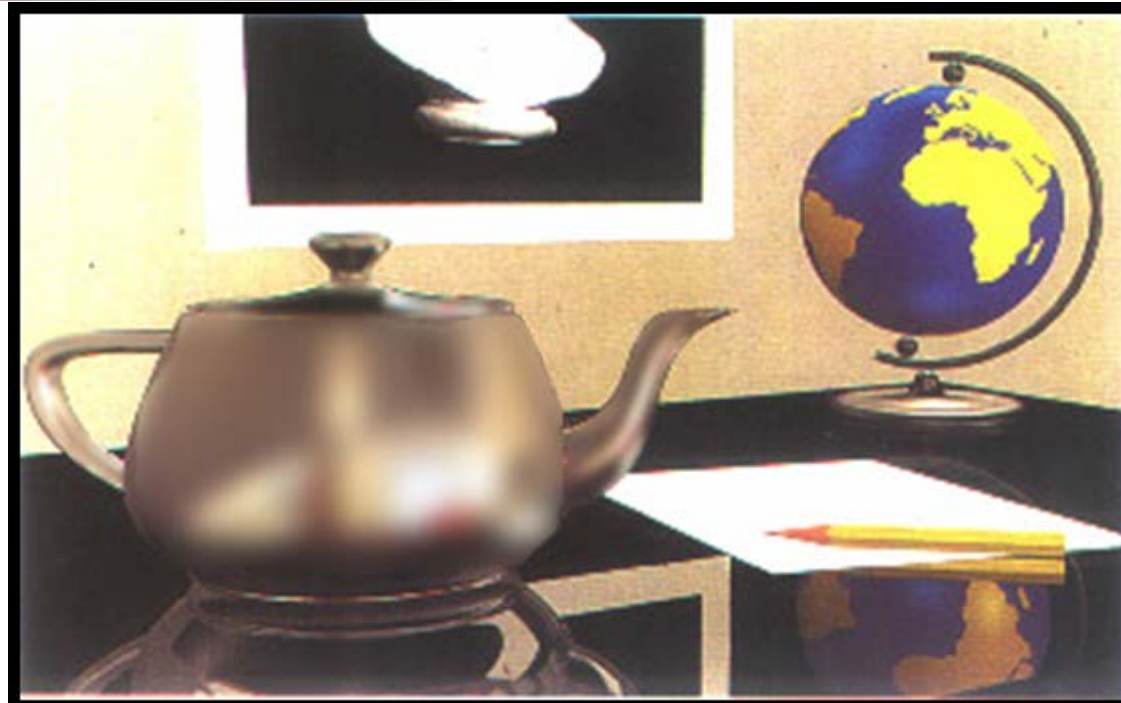
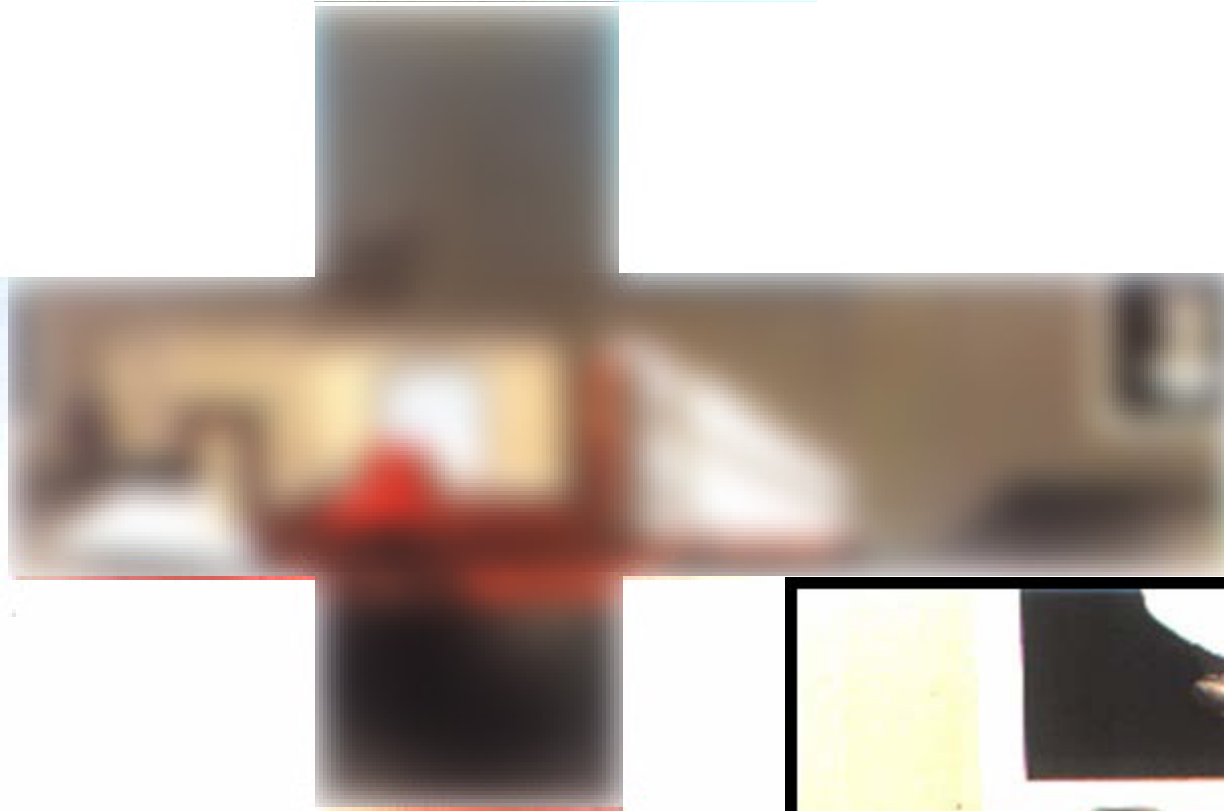


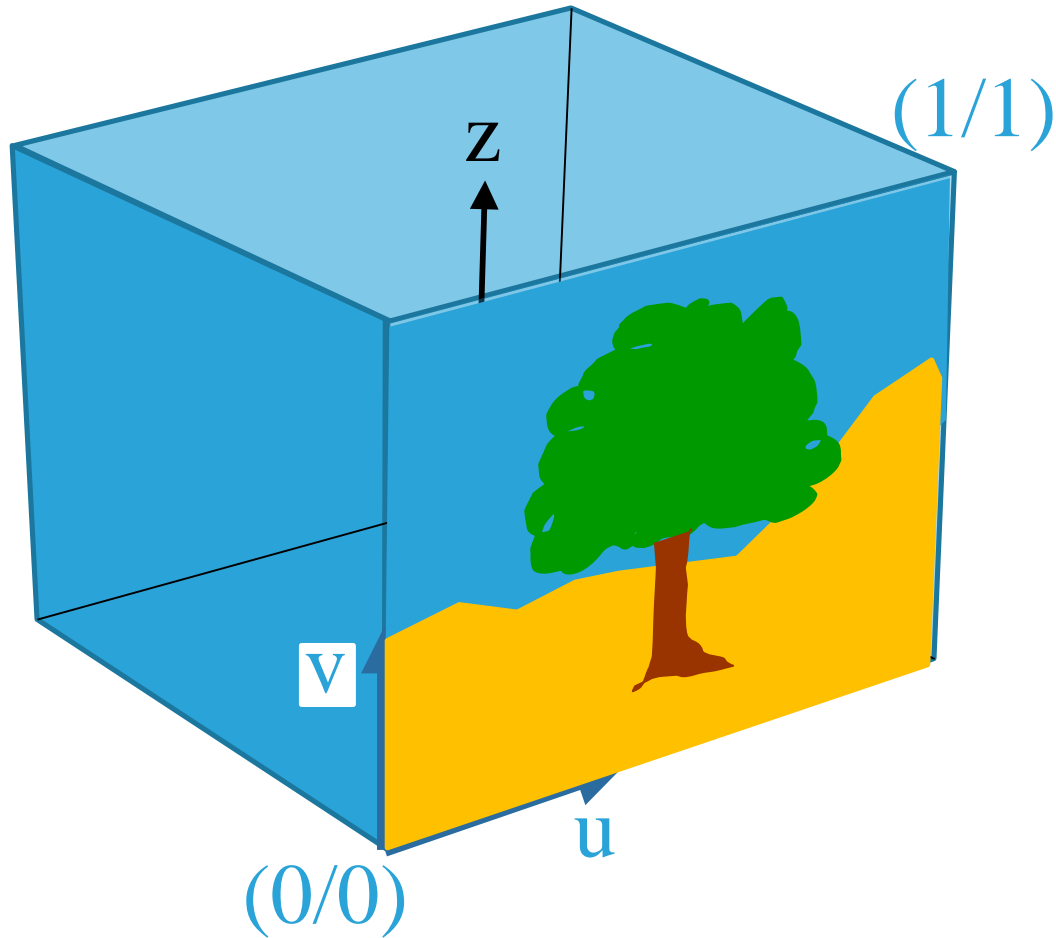
# Environment Mapping Example





environment maps may be filtered  
for not so reflective surfaces

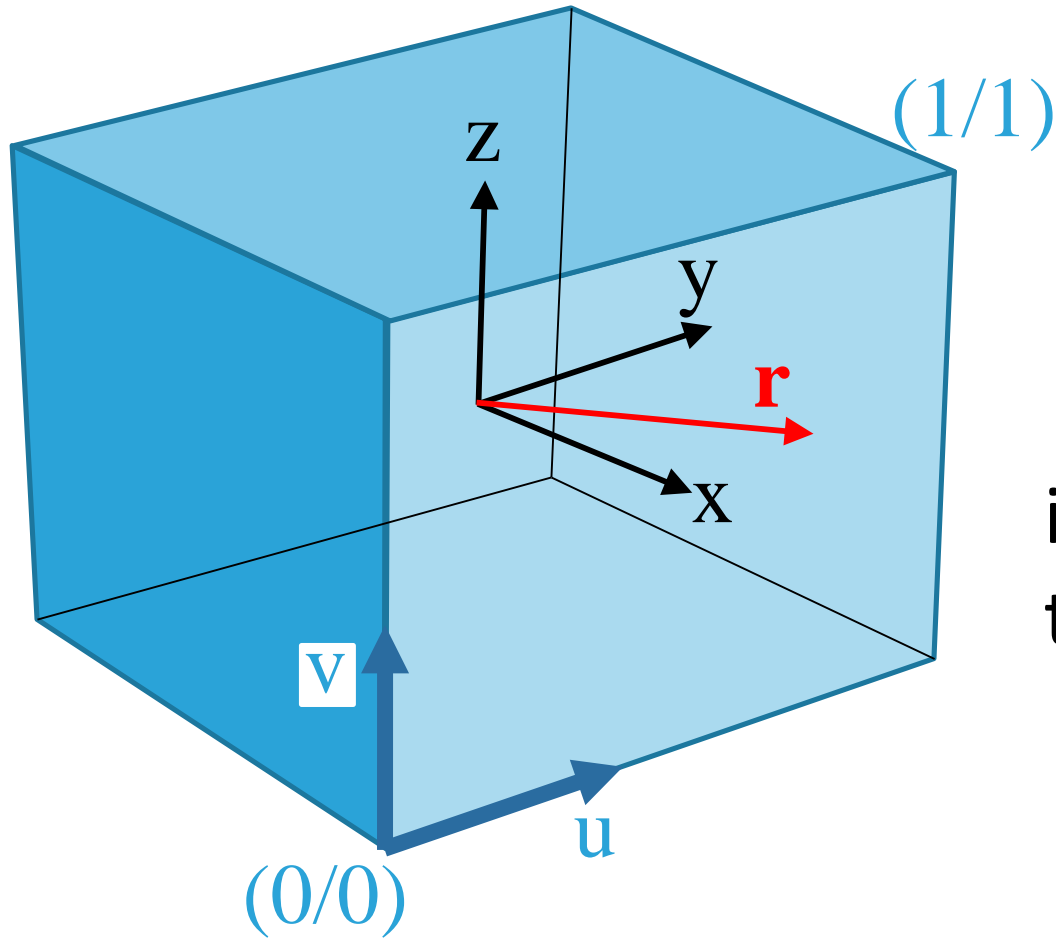




define textures on 6 sides of a cube,  
each parameterized in  $(u,v)$

direction vector  $\mathbf{r}$  starts at  $(0,0,0)$



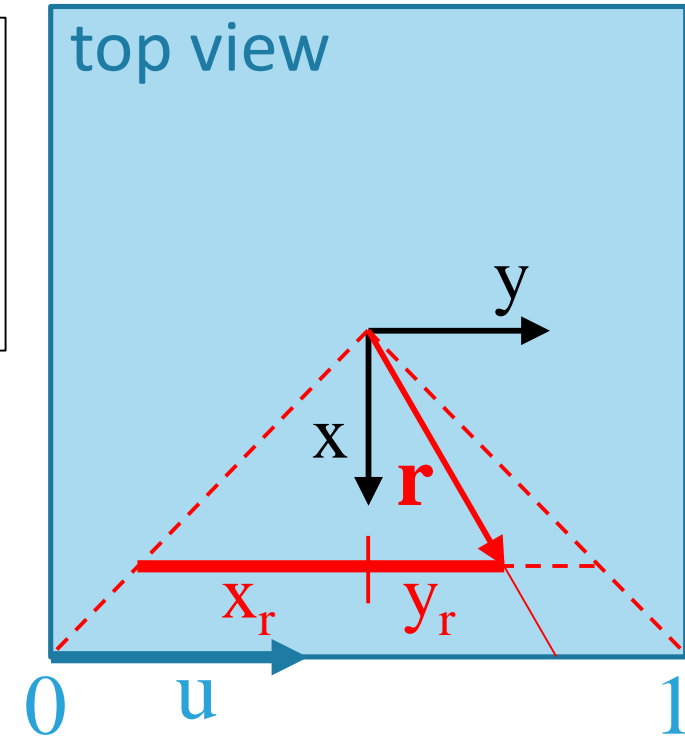


find  $(u,v)$  from  
the direction  
vector  $\mathbf{r}(x_r, y_r, z_r)$ :

if  $x_r > |y_r|$  and  $x_r > |z_r|$   
then “front face”

$$u = (y_r + x_r) / 2x_r$$

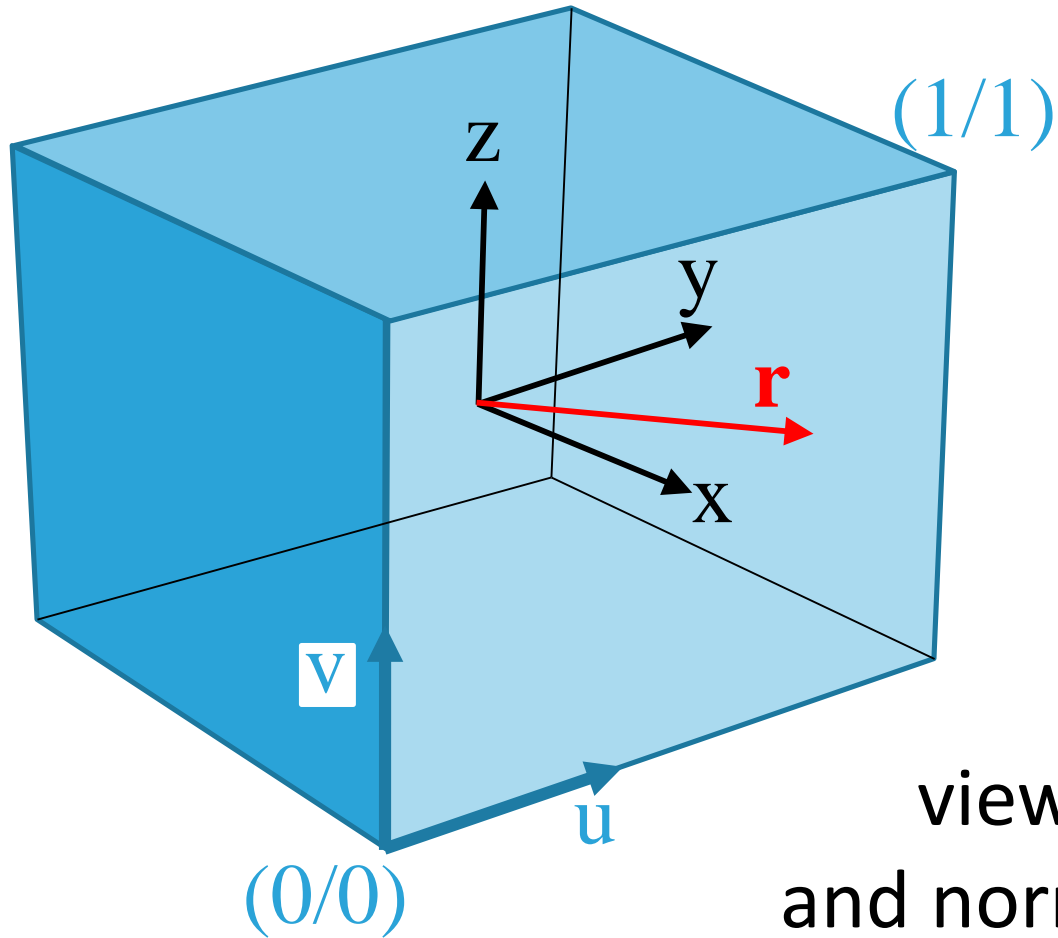
$$v = (z_r + x_r) / 2x_r$$



analogous formulas for the other 5 faces

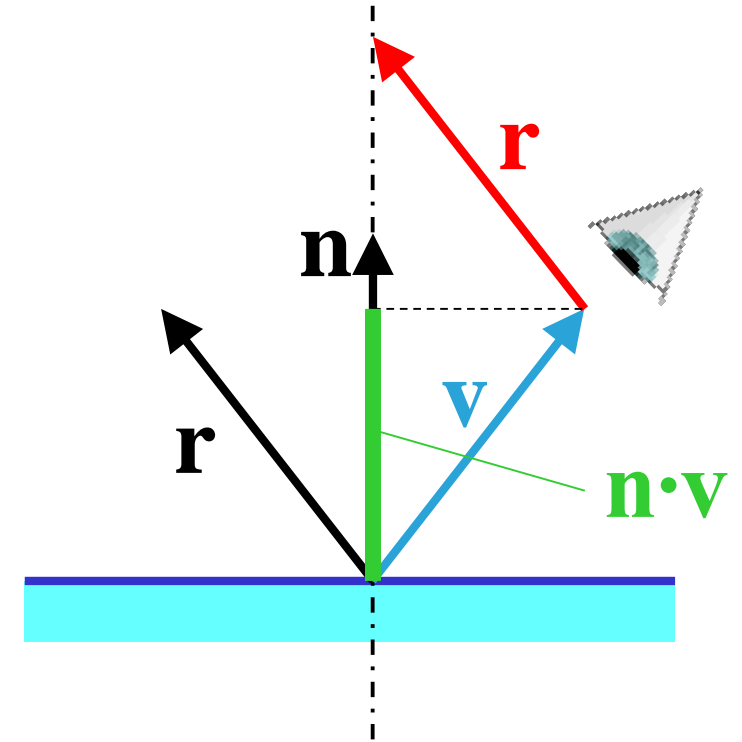
$$(-x > |y| \wedge -x > |z|, \quad y > |x| \wedge y > |z|, \quad -y > |x| \wedge -y > |z|, \quad z > |x| \wedge z > |y|, \quad -z > |x| \wedge -z > |y|)$$





calculation of  
the direction  
vector  $\mathbf{r}$ :

at a pixel:  
viewing direction  $\mathbf{v}$   
and normal vector  $\mathbf{n} \Rightarrow$

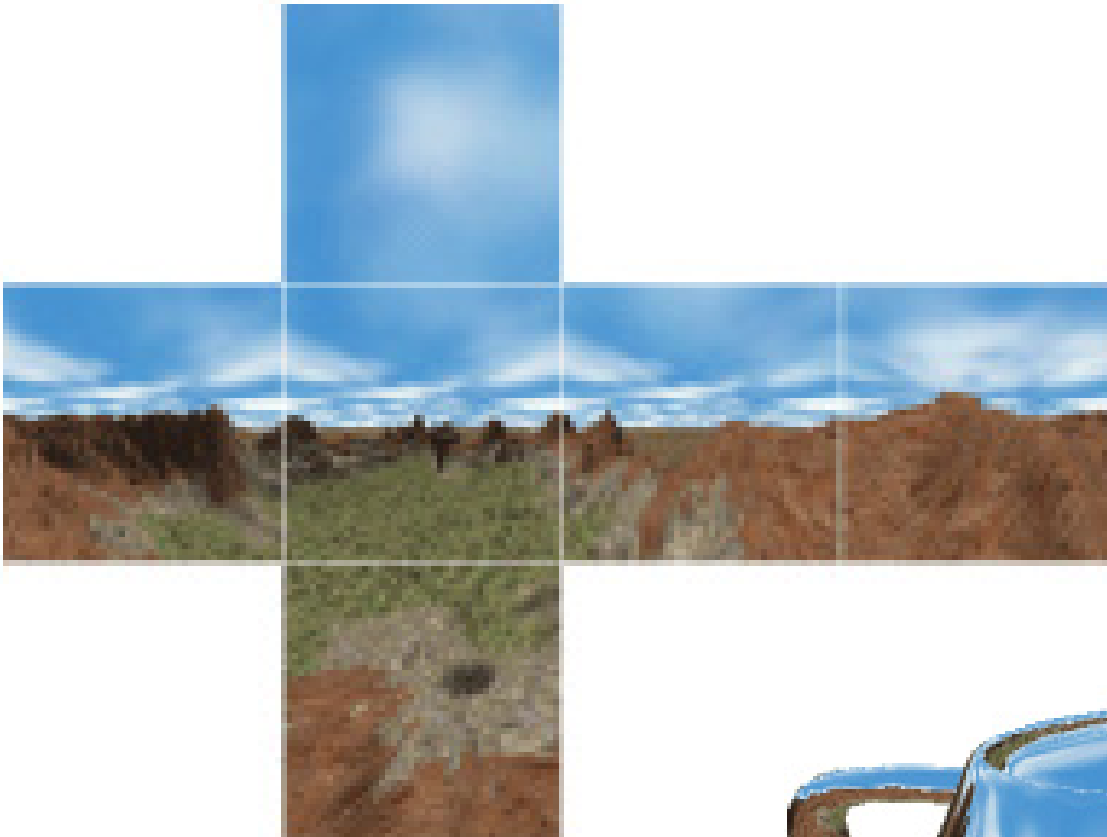


$$\mathbf{r} + \mathbf{v} = (2\mathbf{n} \cdot \mathbf{v})\mathbf{n}$$

$$\mathbf{r} = (2\mathbf{n} \cdot \mathbf{v})\mathbf{n} - \mathbf{v}$$



# Environment Mapping Example





# Adding Surface Detail

most objects do not have smooth surfaces

- brick walls
- gravel roads
- carpets

→ surface texture required



## modeling surface detail with polygons

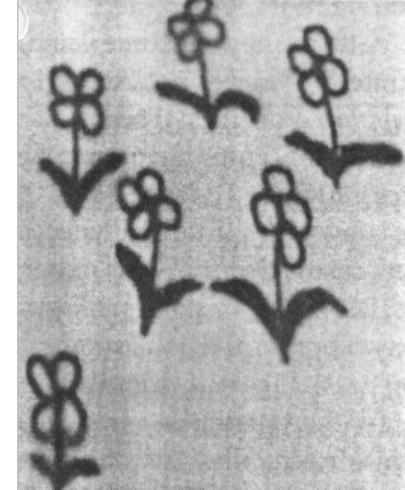
- small polygon facets (e.g., checkerboard squares)
- facets overlaid on surface polygon (parent)
- parent surface used for visibility calculations
- facets used for illumination calculations
- impractical for complicated surface structure



texture patterns are mapped onto surfaces

texture pattern can be:

- raster image
- or procedure  
(modifies surface intensities)



**texture space**

texture-surface  
transformation

**object space**

viewing  
& projection  
transformation

**image space**

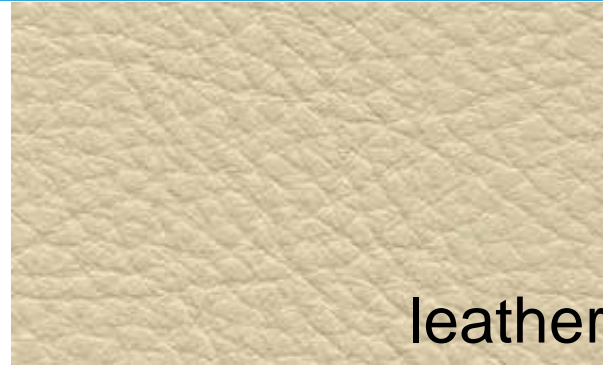




# Texture Mapping: Samples



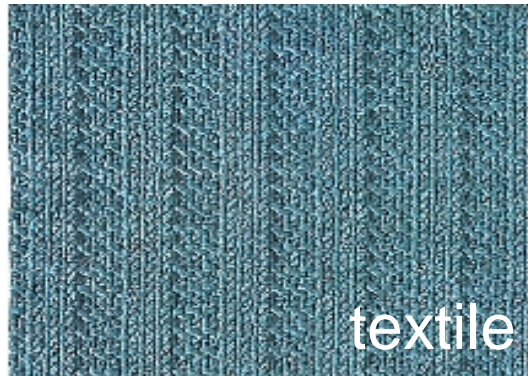
marble



leather



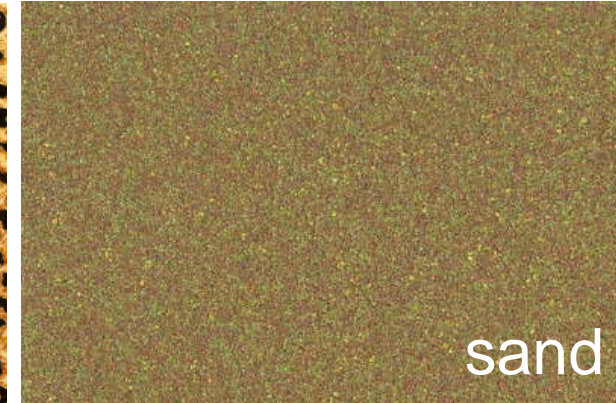
cobblestones



textile



fur



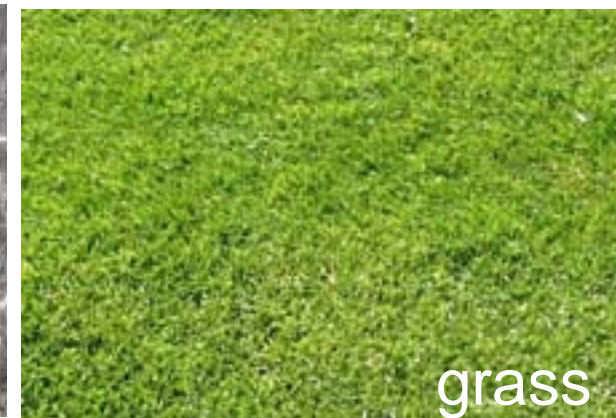
sand



wood



stone

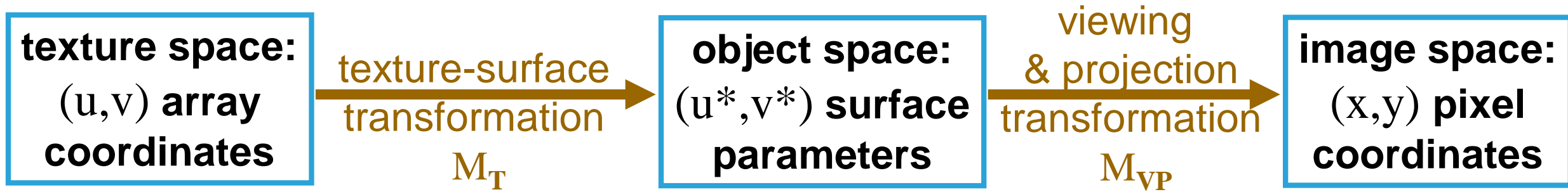


grass



texture mapping options:

- texture scanning  $(u,v) \rightarrow (x,y)$
- inverse scanning  $(x,y) \rightarrow (u,v)$

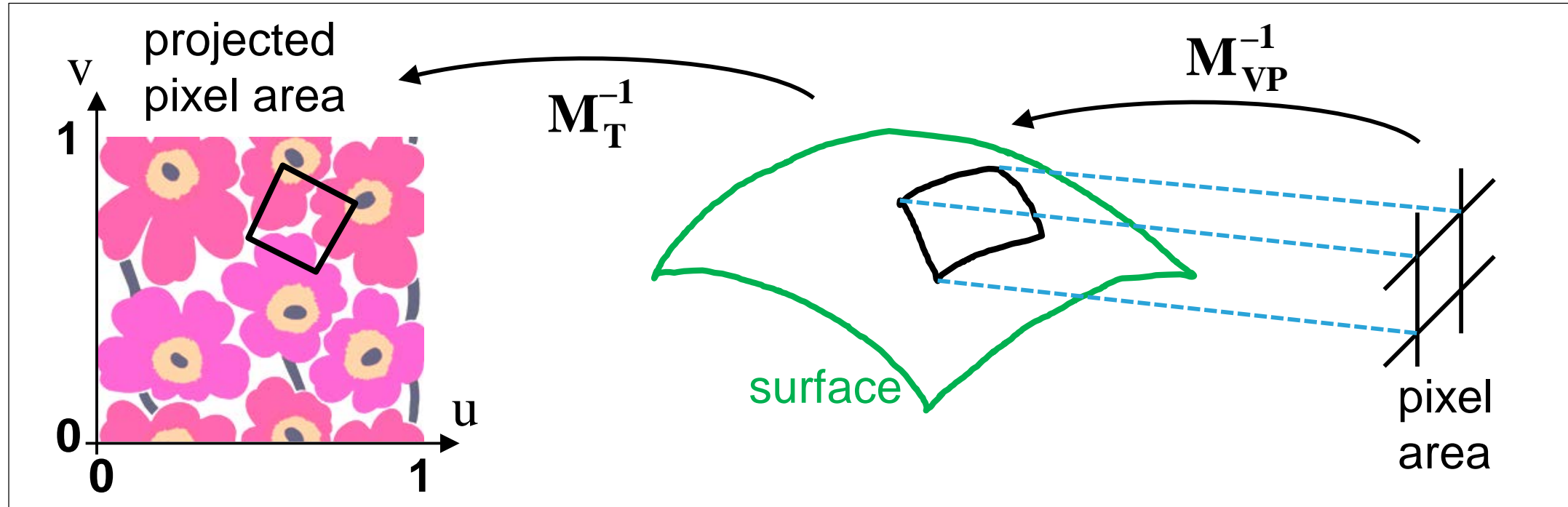


texture-surface transformation:

$$u^* = u^*(u,v) = a_{u^*}u + b_{u^*}v + c_{u^*}$$
$$v^* = v^*(u,v) = a_{v^*}u + b_{v^*}v + c_{v^*}$$



projecting pixel areas to texture space = inverse scanning  $(x,y) \rightarrow (u,v)$



- calculation of  $M_{VP}^{-1}$  and  $M_T^{-1}$
- anti-aliasing with filter operations



■  $M_{VP}$

$$x^2 + y^2 = r^2 \quad x, y \geq 0 \quad 0 \leq z \leq h$$

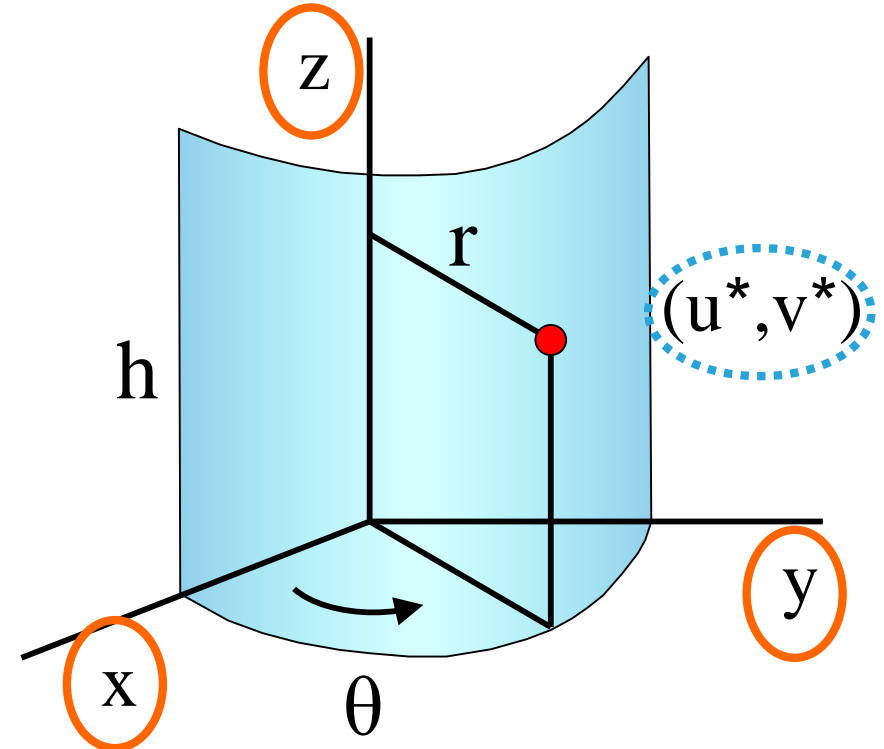
$$u^* = \theta, \text{ with } 0 \leq \theta \leq \pi/2$$

$$v^* = z \text{ with } 0 \leq z \leq h$$

$$x = r \cdot \cos u^*$$

$$y = r \cdot \sin u^*$$

$$z = v^*$$



■  $M_{VP}^{-1}$

pixel  $\rightarrow$  surface point  $(x, y, z)$

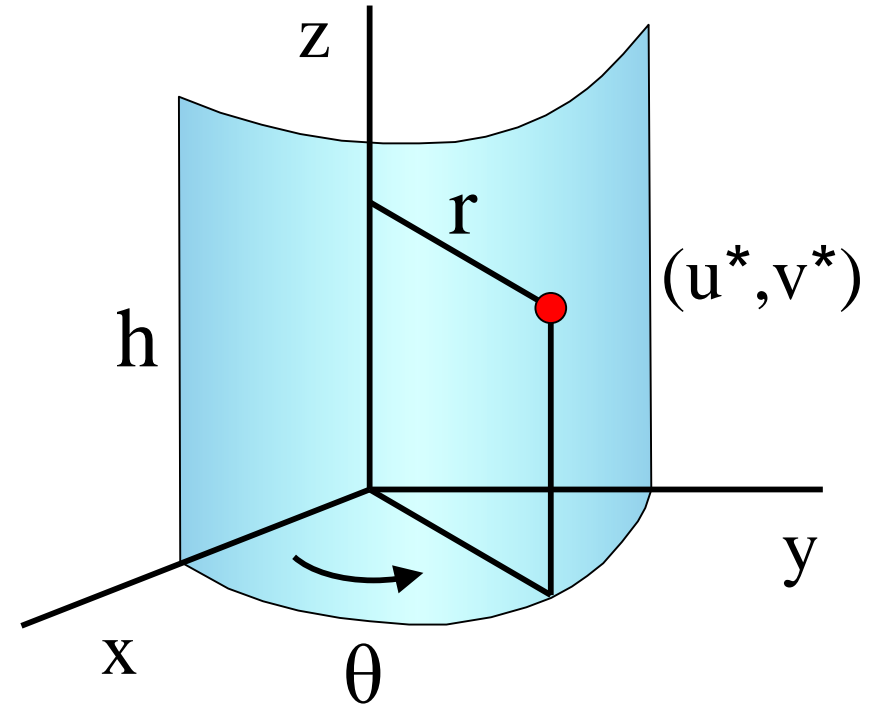
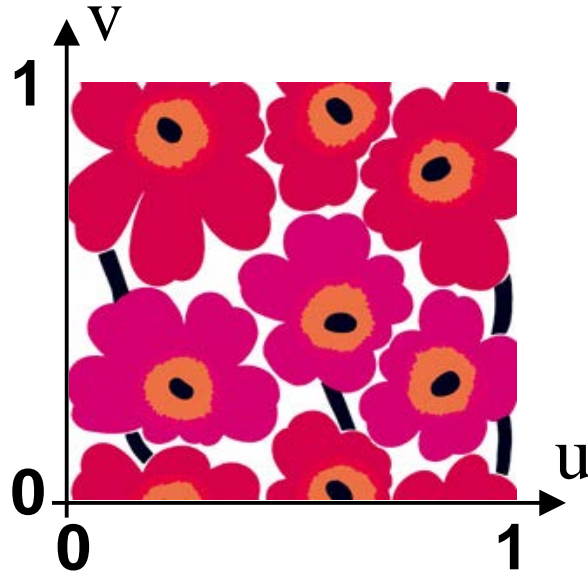
$(x, y, z) \rightarrow (u^*, v^*)$ :

$$u^* = \cos^{-1}(x/r), \quad v^* = z$$





■  $M_T$        $u^* = u \cdot \pi/2, \quad v^* = v \cdot h$



■  $M_T^{-1}$        $u = 2u^*/\pi, \quad v = v^*/h$

$(u^* = \cos^{-1}(x/r), \quad v^* = z)$

$u = 2\cos^{-1}(x/r)/\pi, \quad v = z/h$

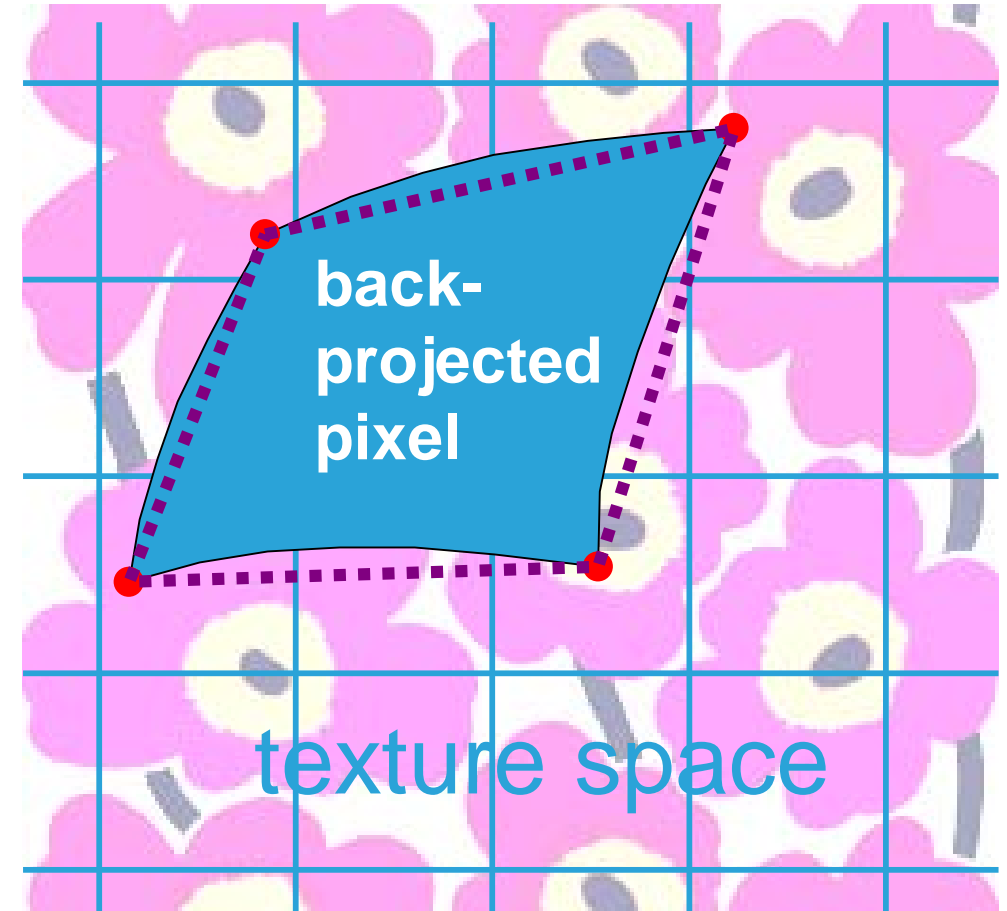


anti-aliasing with filter operations:

project pixel area into texture space  
and take average texture value

speed ups:

- mip-mapping
- summed-area table method

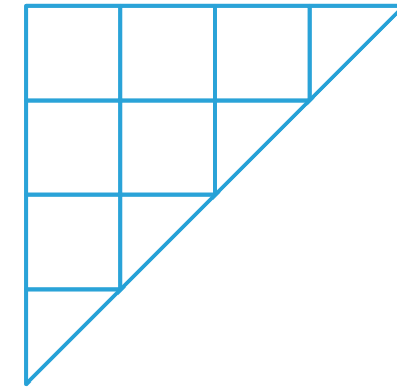


mapping a texture on a triangle with barycentric coordinates:

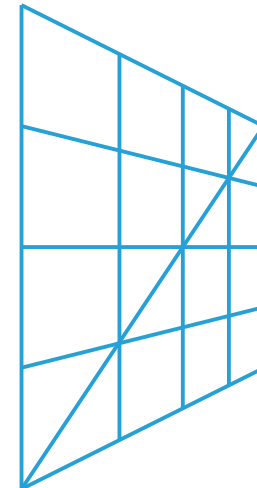
$$\mathbf{p}(\alpha, \beta, \gamma) = \alpha \cdot \mathbf{a} + \beta \cdot \mathbf{b} + \gamma \cdot \mathbf{c}$$

$$\text{color}(x, y) = \alpha \cdot t_0 + \beta \cdot t_1 + \gamma \cdot t_2$$

fails after perspective transform!



correct:



**solution:** keep homogeneous weights  $h_0, h_1, h_2$  of **a, b, c**  
and correct the barycentric values

$$d = h_1 h_2 + h_2 \beta (h_0 - h_1) + h_1 \gamma (h_0 - h_2)$$

$$\beta_w = h_0 h_2 \beta / d \quad \gamma_w = h_0 h_1 \gamma / d \quad \alpha_w = 1 - \beta_w - \gamma_w$$

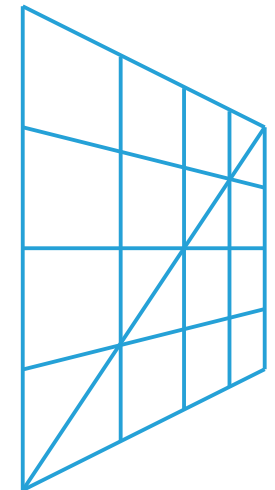
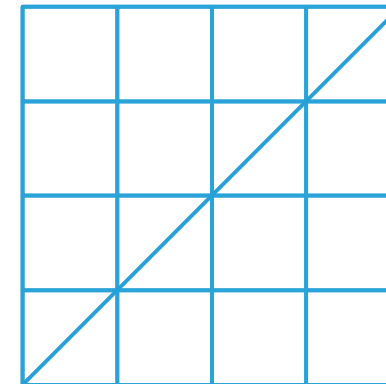
$$u = \alpha_w u_0 + \beta_w u_1 + \gamma_w u_2 \quad v = \alpha_w v_0 + \beta_w v_1 + \gamma_w v_2$$

$$\text{color}(x, y) = t(u, v)$$

instead of

$$u = \alpha u_0 + \beta u_1 + \gamma u_2 \quad v = \alpha v_0 + \beta v_1 + \gamma v_2$$

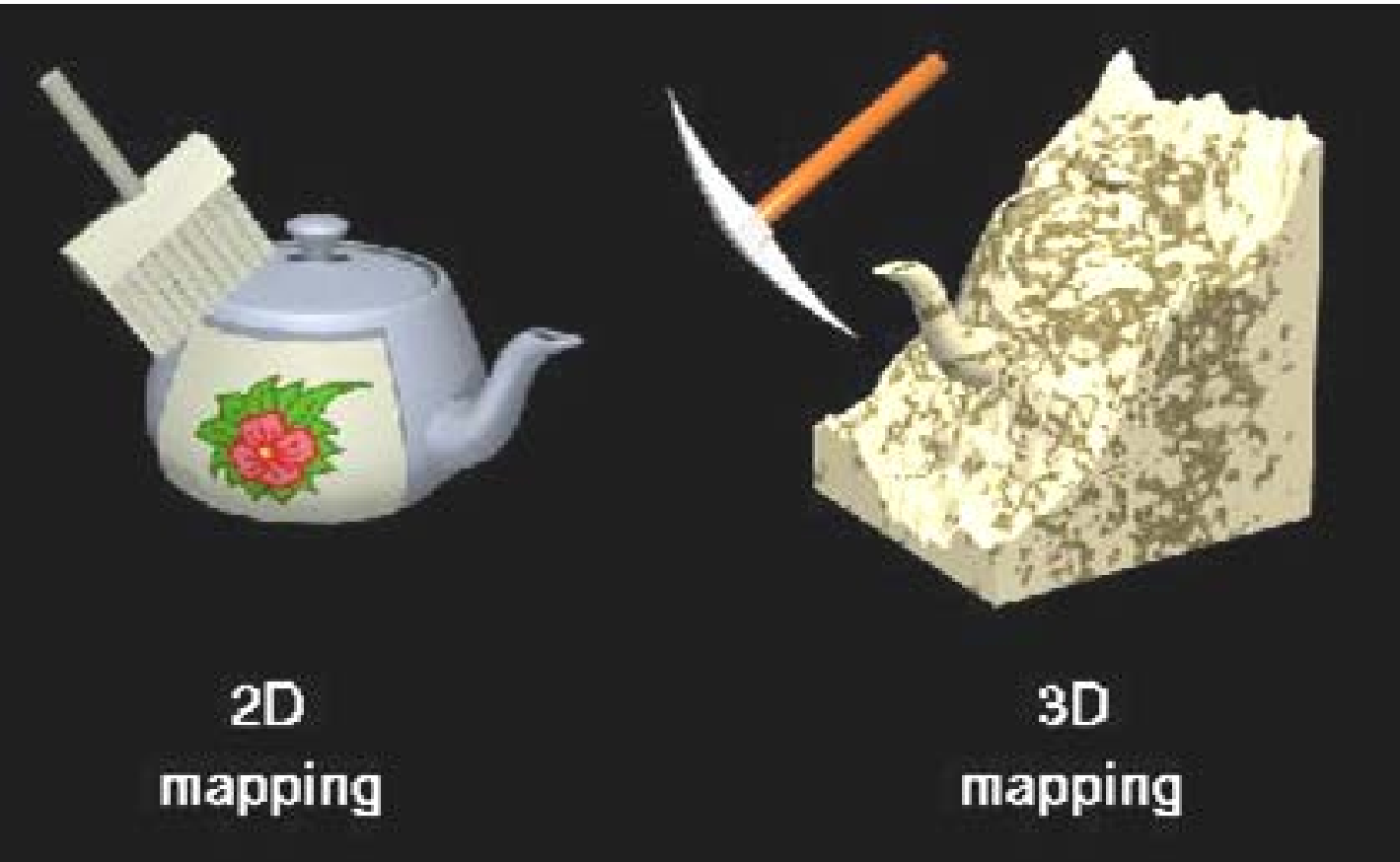
$$\text{color}(x, y) = t(u, v)$$



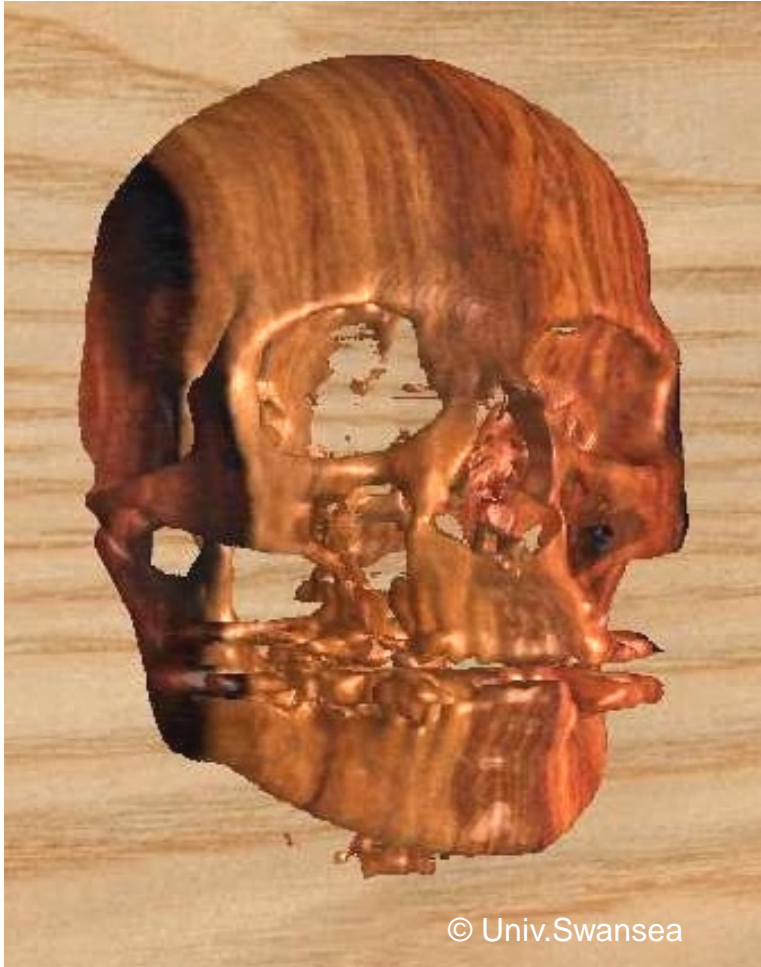


= texture defined in 3D

- every position in space has a color
- coherent textures across corners



*examples for application of 3D textures on a skull and a face*



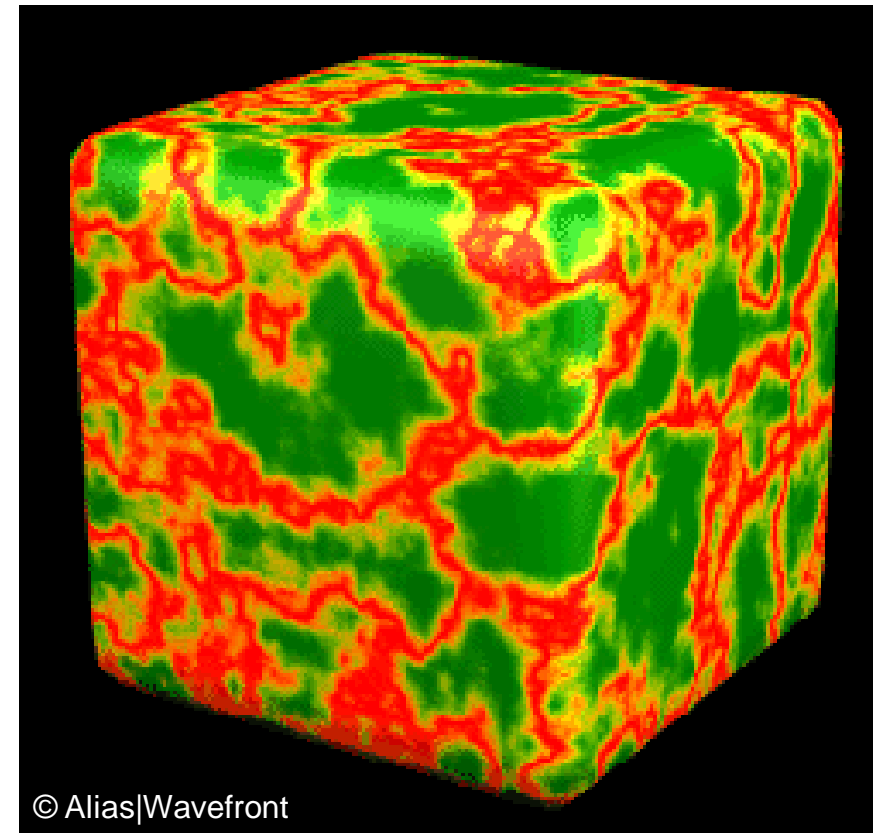
procedural texture definition

- texture-function  $t(x,y,z)$  returns intensity
- avoid  $M_T$

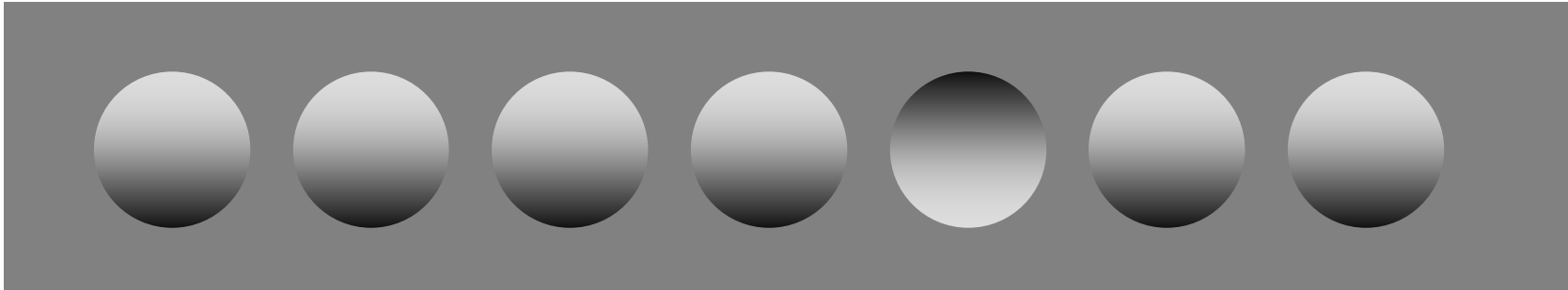
2D (surface texturing) or 3D (solid texturing)

stochastic variations (noise function)

examples: wood grains, marble, foam

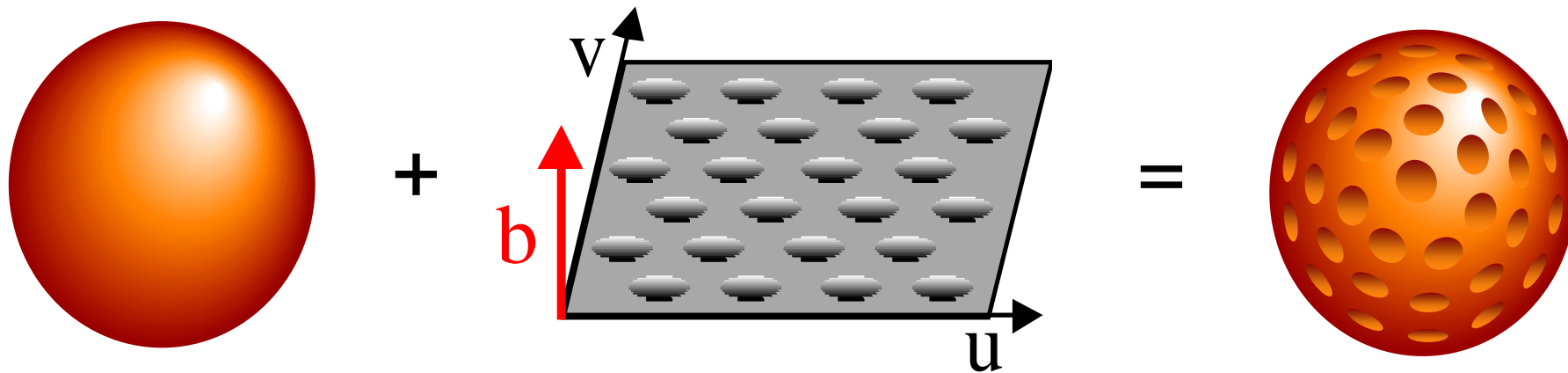


bumps are visible because of shading



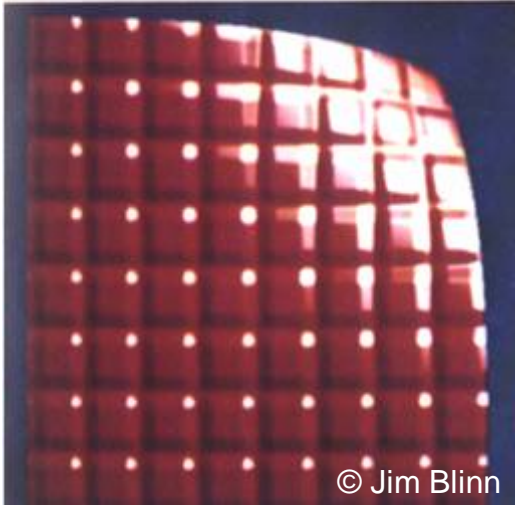
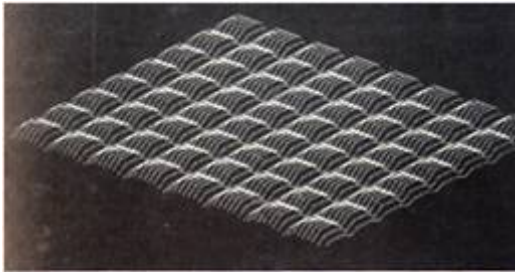
modeling of bumps is very costly.

*trick: insert a detail structure  $b$ :*

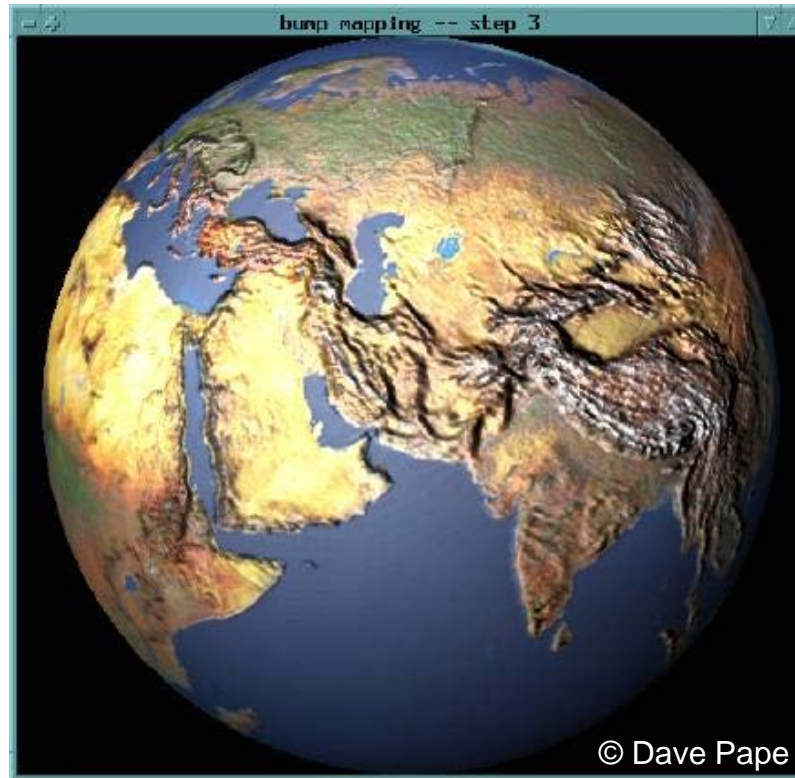




# Bump Mapping Examples



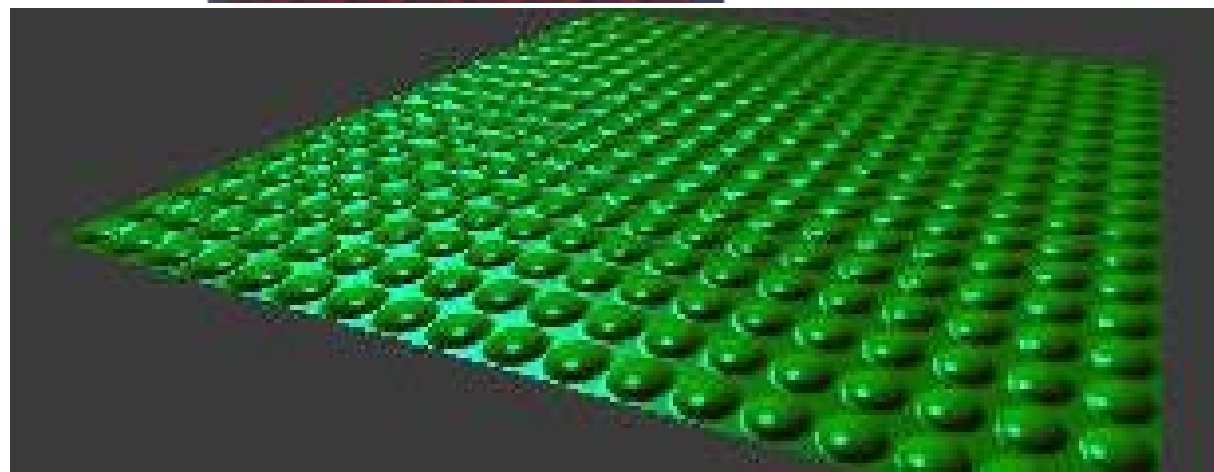
© Jim Blinn



© Dave Pape

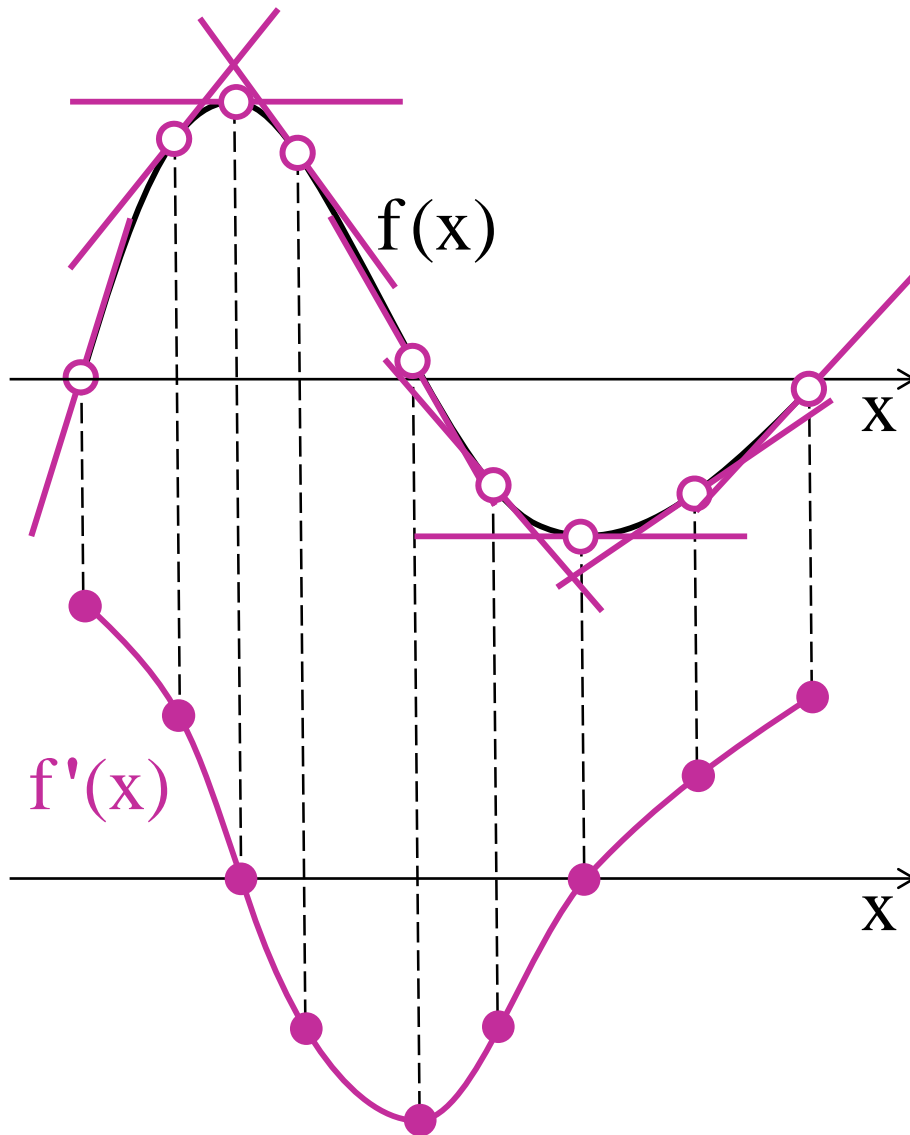


© Gamestar



© Stanford

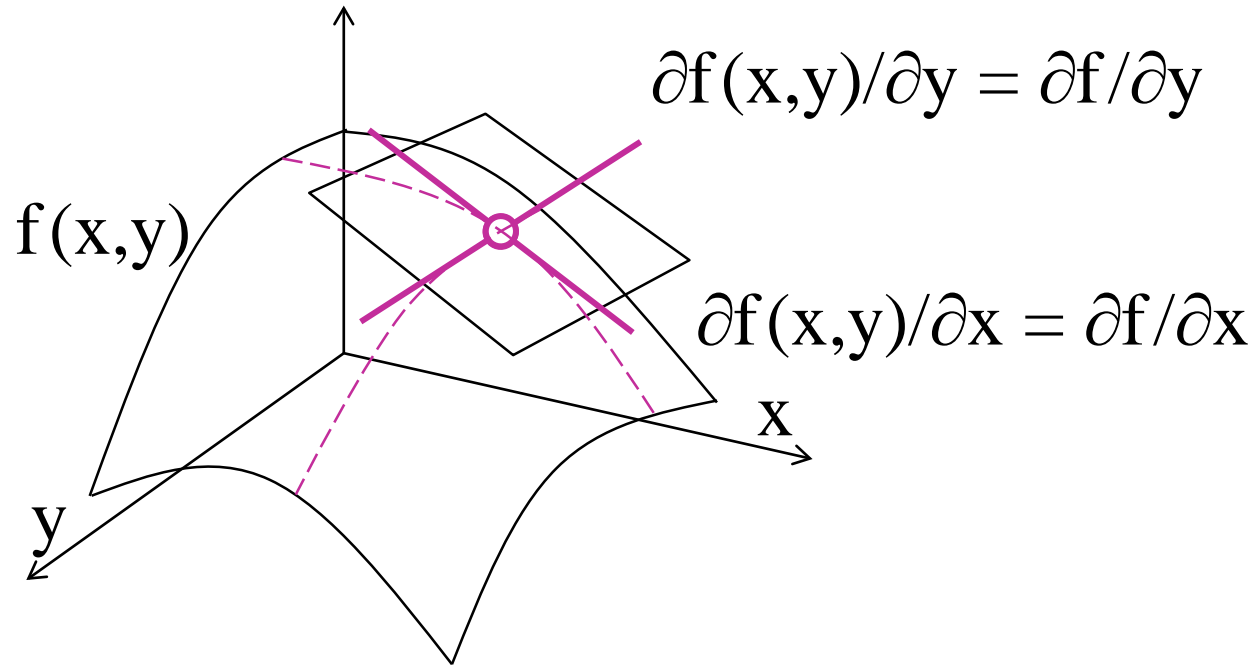




derivation of a function in  
one variable is the  
*slope of the function*

$$f'(x) = df(x)/dx = df/dx$$





partial derivations of a function in two variables are the slopes of the functions when you keep one of the variables fixed, they are slopes of tangents



surface roughness simulated:

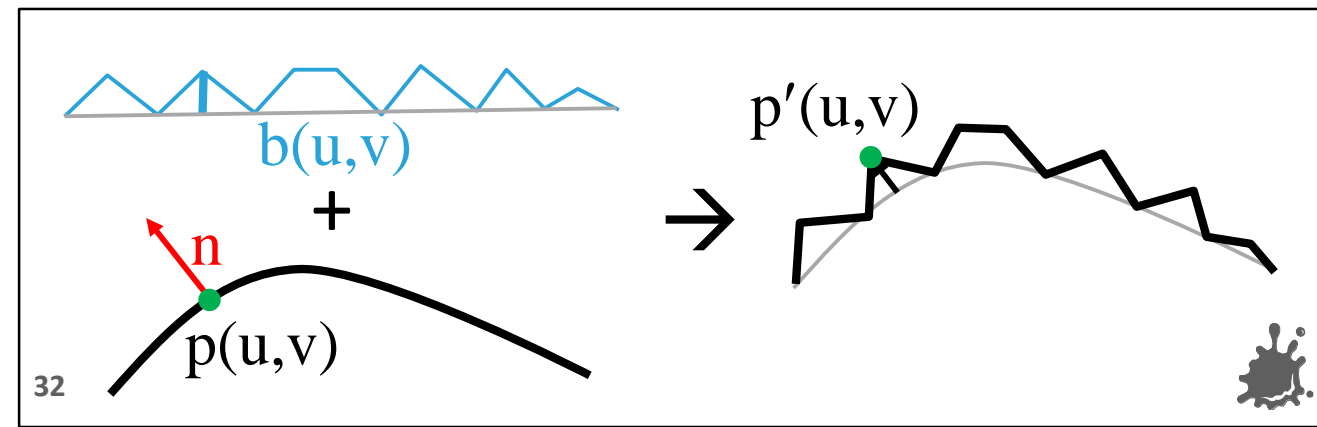
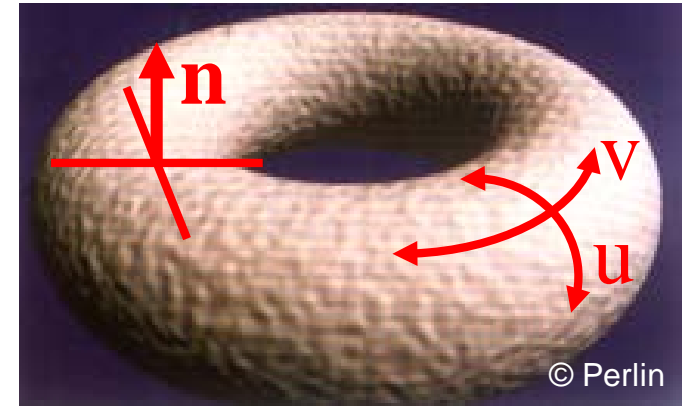
perturbation function varies surface normal locally

= "bump map"  $b(u,v)$

$\mathbf{p}(u,v)$  surface point

$\mathbf{n}^* = \mathbf{p}_u \times \mathbf{p}_v$        $\mathbf{n} = \mathbf{n}^* / |\mathbf{n}^*|$       surface normal

$\mathbf{p}'(u,v) = \mathbf{p}(u,v) + b(u,v) \cdot \mathbf{n}$   
= modified surface point





$$\mathbf{p}'(u,v) = \mathbf{p}(u,v) + b(u,v) \cdot \mathbf{n}$$

$$\mathbf{n}' = (\mathbf{p}_u' \times \mathbf{p}_v')$$

$$\mathbf{p}_u' = \partial(\mathbf{p} + b\mathbf{n}) / \partial u = \mathbf{p}_u + b_u \mathbf{n} + b \mathbf{n}_u$$

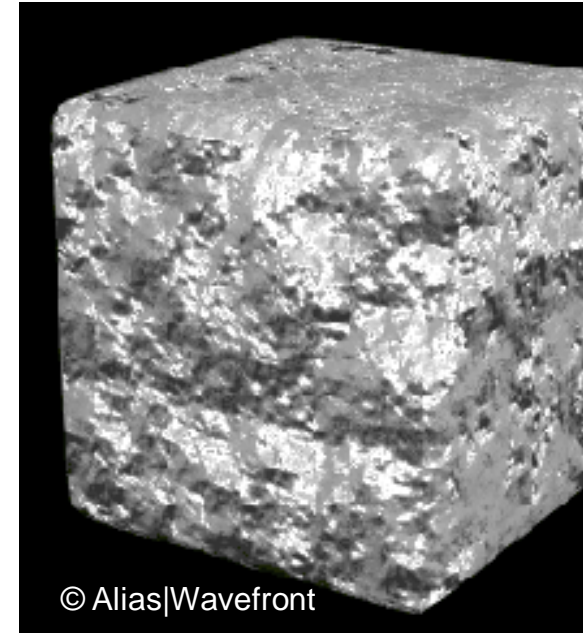
$$\mathbf{p}_u' \approx \mathbf{p}_u + b_u \mathbf{n} \quad \mathbf{p}_v' \approx \mathbf{p}_v + b_v \mathbf{n}$$

because  
b is very small

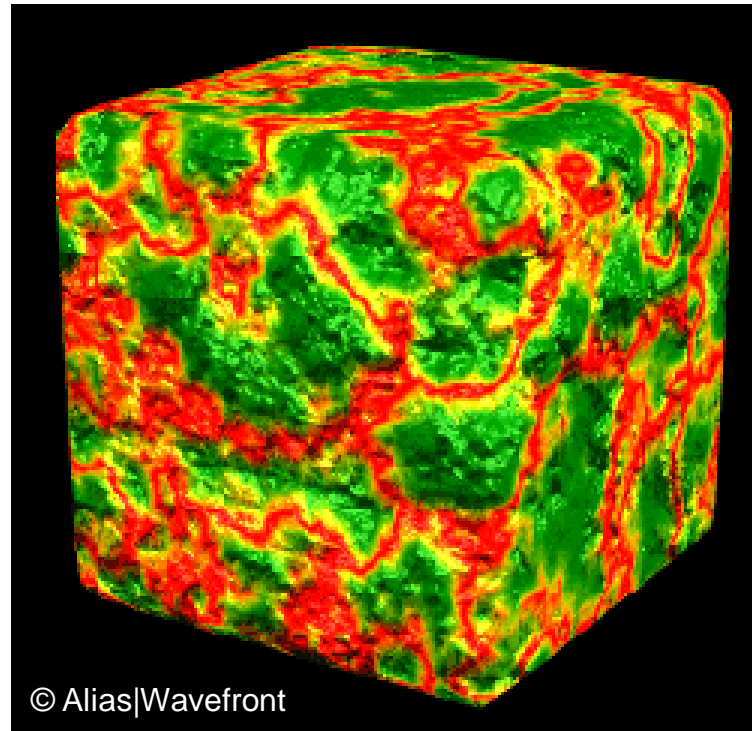
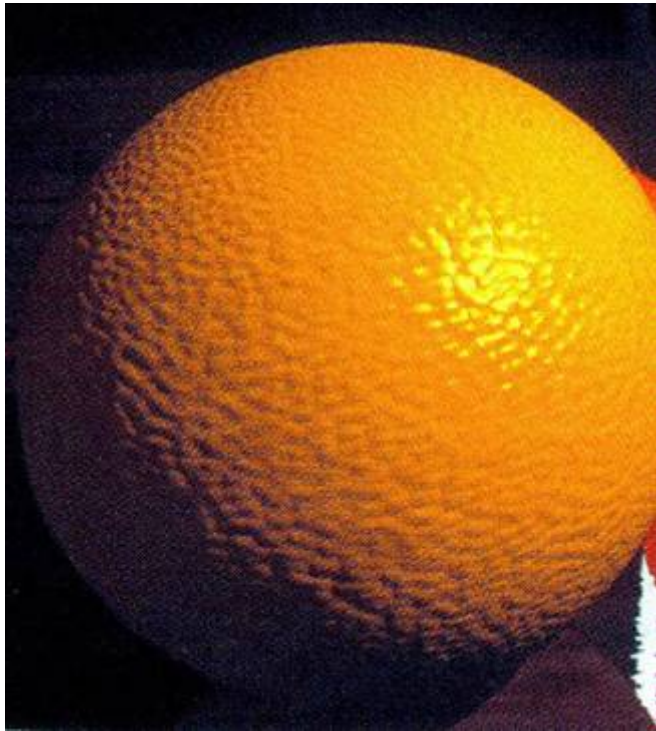
$$\mathbf{n}' = (\mathbf{p}_u + b_u \mathbf{n}) \times (\mathbf{p}_v + b_v \mathbf{n})$$

$$\mathbf{n}' = \mathbf{p}_u \times \mathbf{p}_v + b_v (\mathbf{p}_u \times \mathbf{n}) + b_u (\mathbf{n} \times \mathbf{p}_v) + b_u b_v (\mathbf{n} \times \mathbf{n}) \quad \mathbf{n} \times \mathbf{n} = 0$$

$$\mathbf{n}' = \mathbf{n}^* + b_v (\mathbf{p}_u \times \mathbf{n}) + b_u (\mathbf{n} \times \mathbf{p}_v)$$



bump map  $b(u,v)$  can be defined as raster image  
 $b_u$ ,  $b_v$ : approximated with finite differences

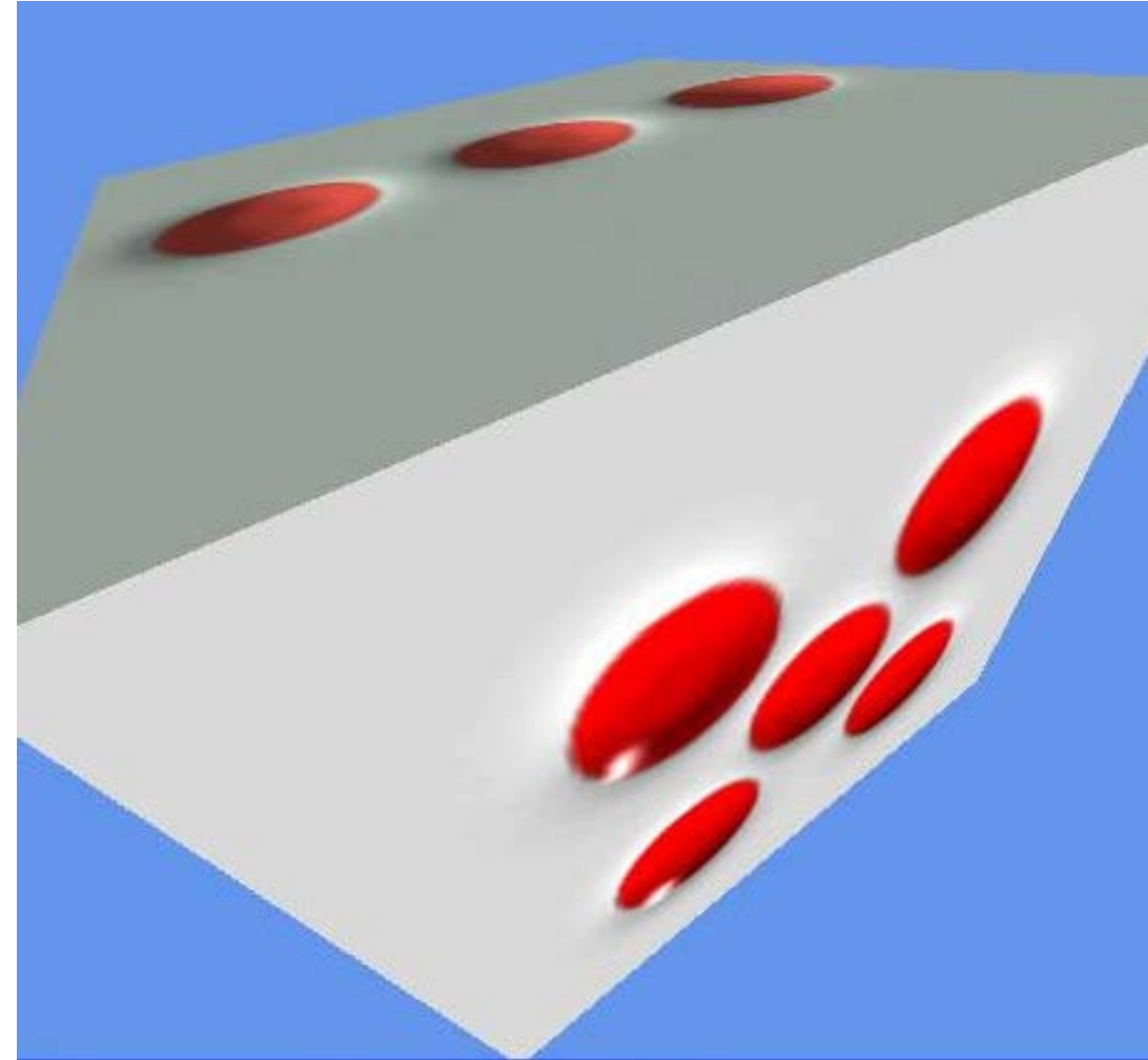


sources of error:

- **distortions at grazing angles**
- wrong silhouette (geometry is not changed!)
- wrong shadows
- missing bump shadows
- light effects on back side



red buttons appear too flat,  
although they are shaded in 3D



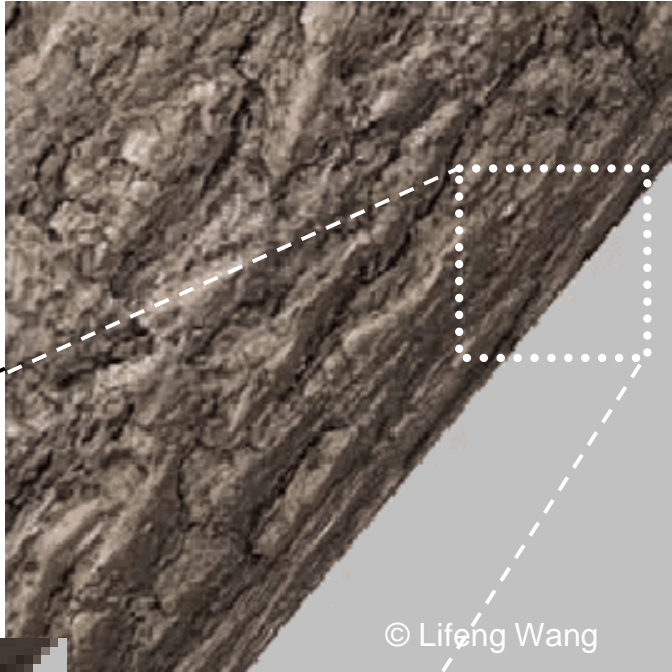
## sources of error

- distortions at grazing angles
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- light effects on back side

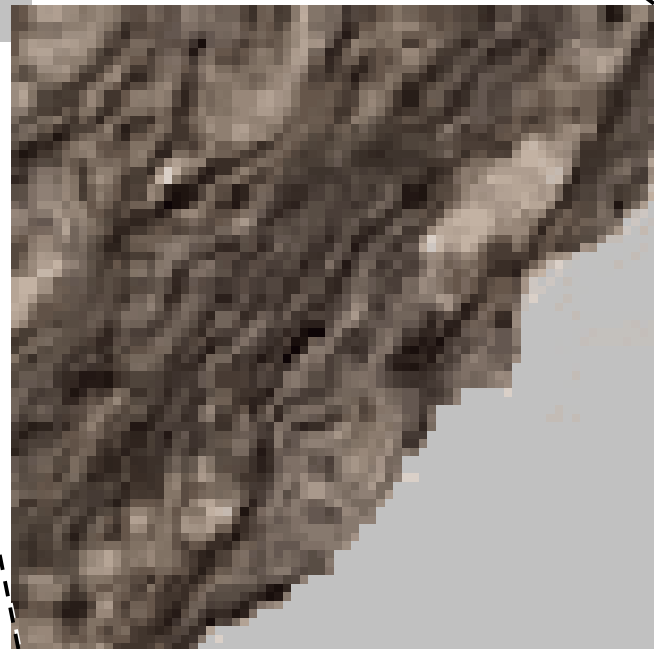
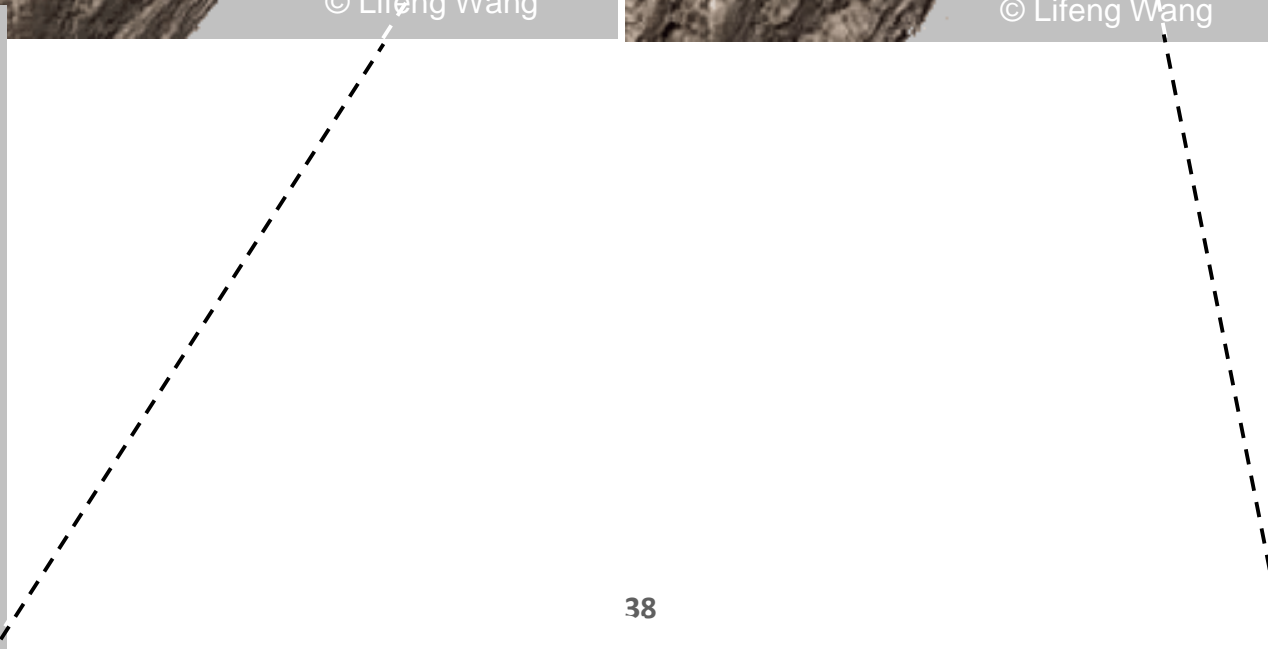
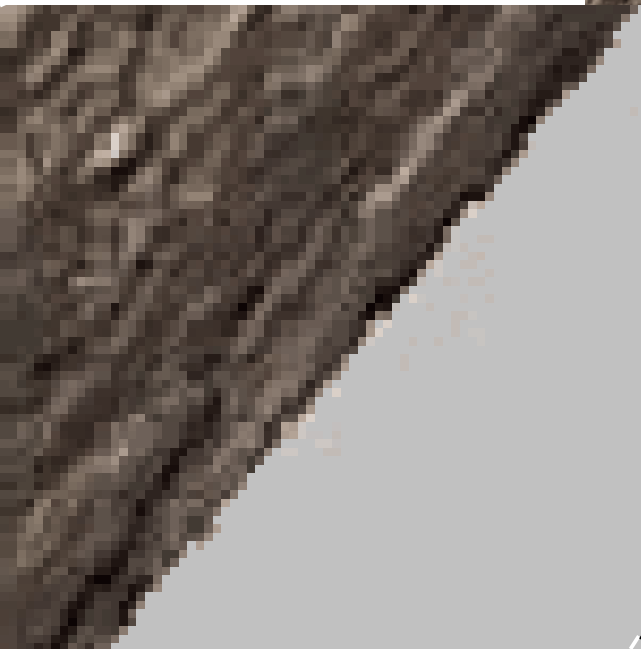
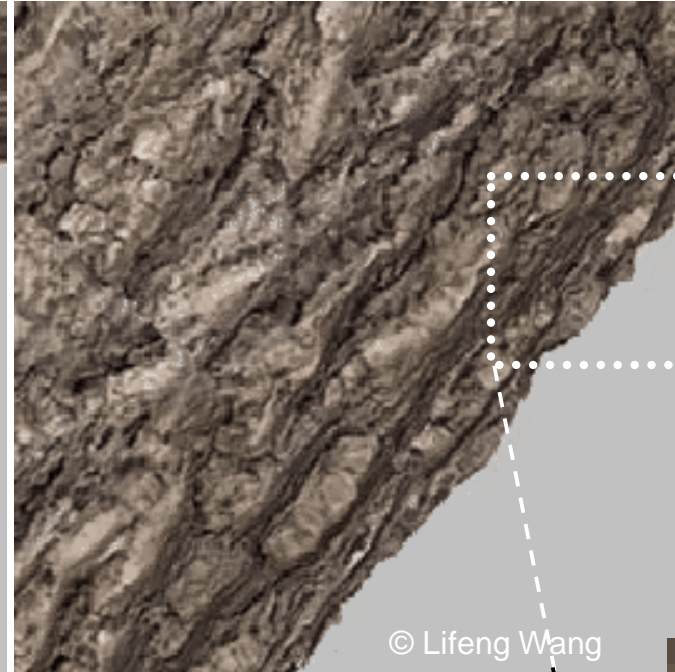


# Bump Mapping: Wrong Silhouette

bump mapping



correct  
geometry



## sources of error

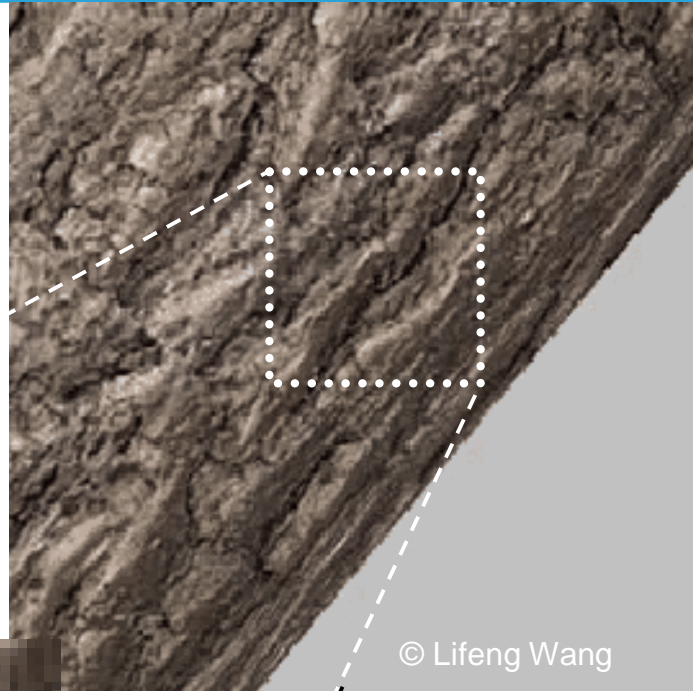
- distortions at grazing angles
- wrong silhouette (geometry is not changed!)
- **wrong shadows**
- **missing bump shadows**
- light effects on back side



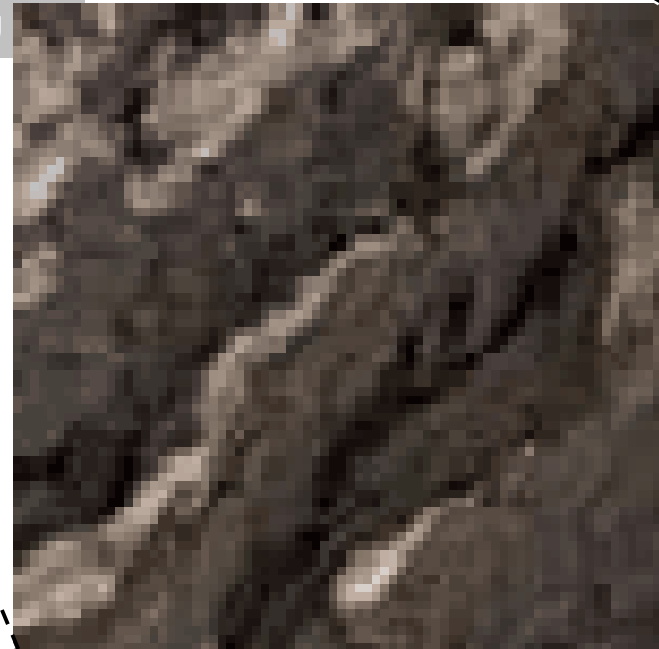
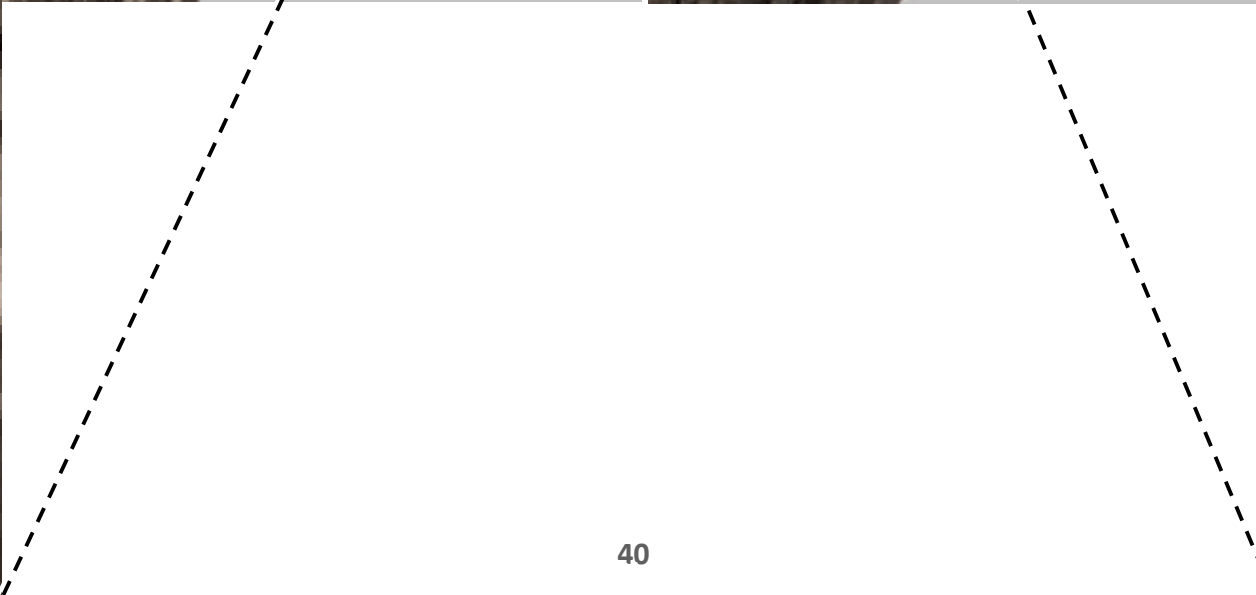
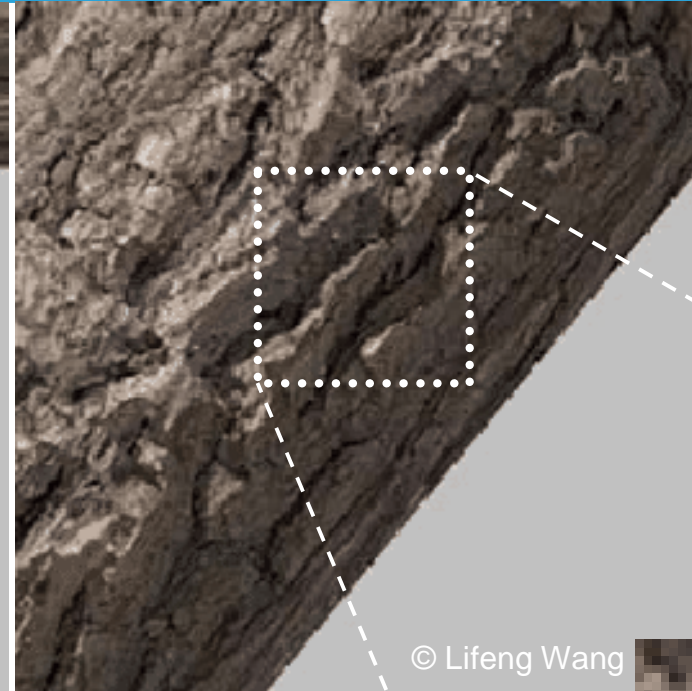


# Bump Mapping: Missing Bump Shadows

bump mapping



correct  
shadows

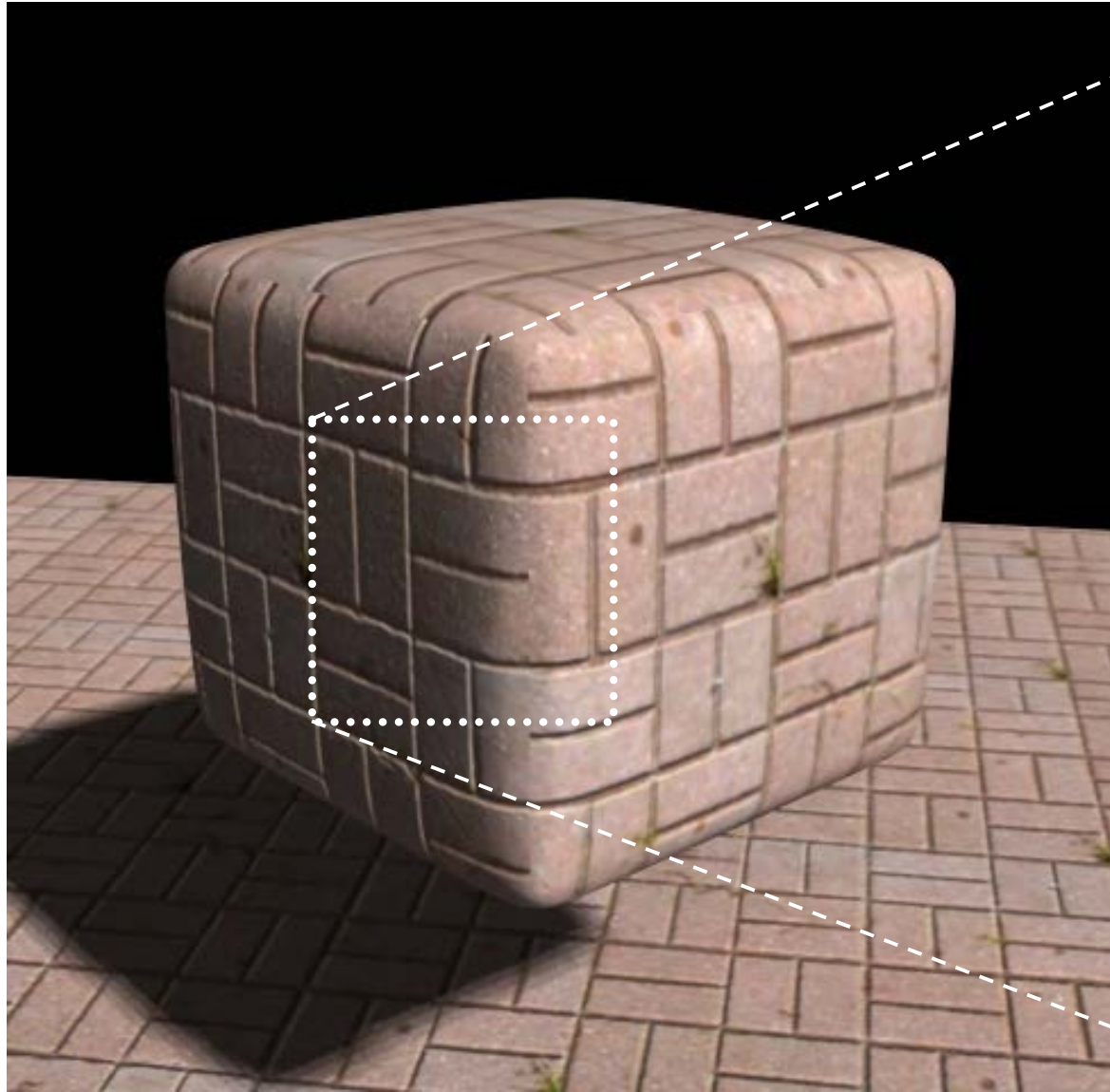




## sources of error

- distortions at grazing angles
- wrong silhouette (geometry is not changed!)
- wrong shadows
- missing bump shadows
- **light effects on back side**





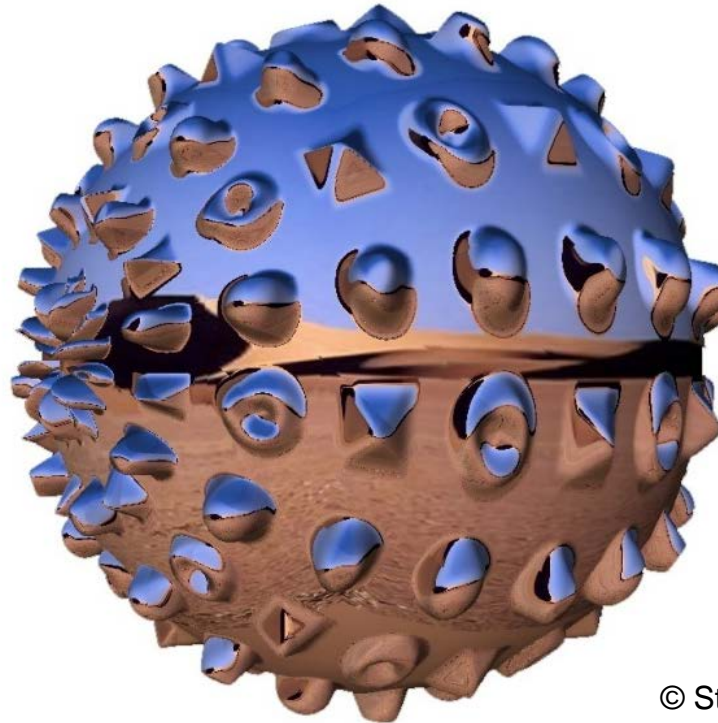
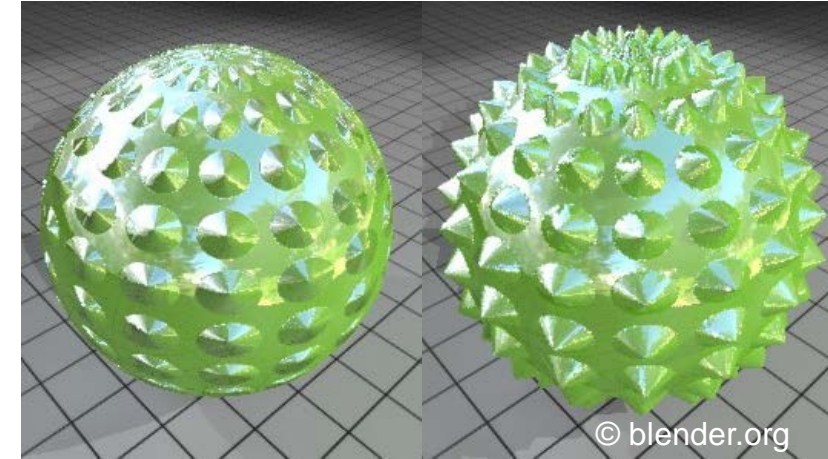
## sources of error

- distortions at grazing angles
- wrong silhouette (geometry is not changed!)
- wrong shadows
- missing bump shadows
- light effects on back side

→ there exist special algorithms to repair each error



- “correct version of bump mapping”
- surface points are moved from their original position
- outline of object changes
- much harder to implement than bump mapping
  - rare in practice
- latest hardware partially supports it

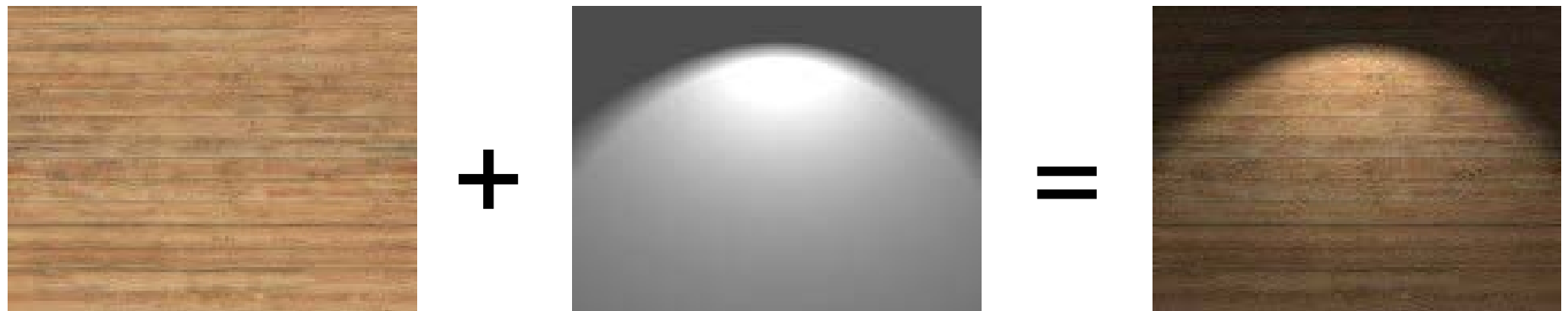


© Stefan Jeschke

= 2 or more textures applied to a surface

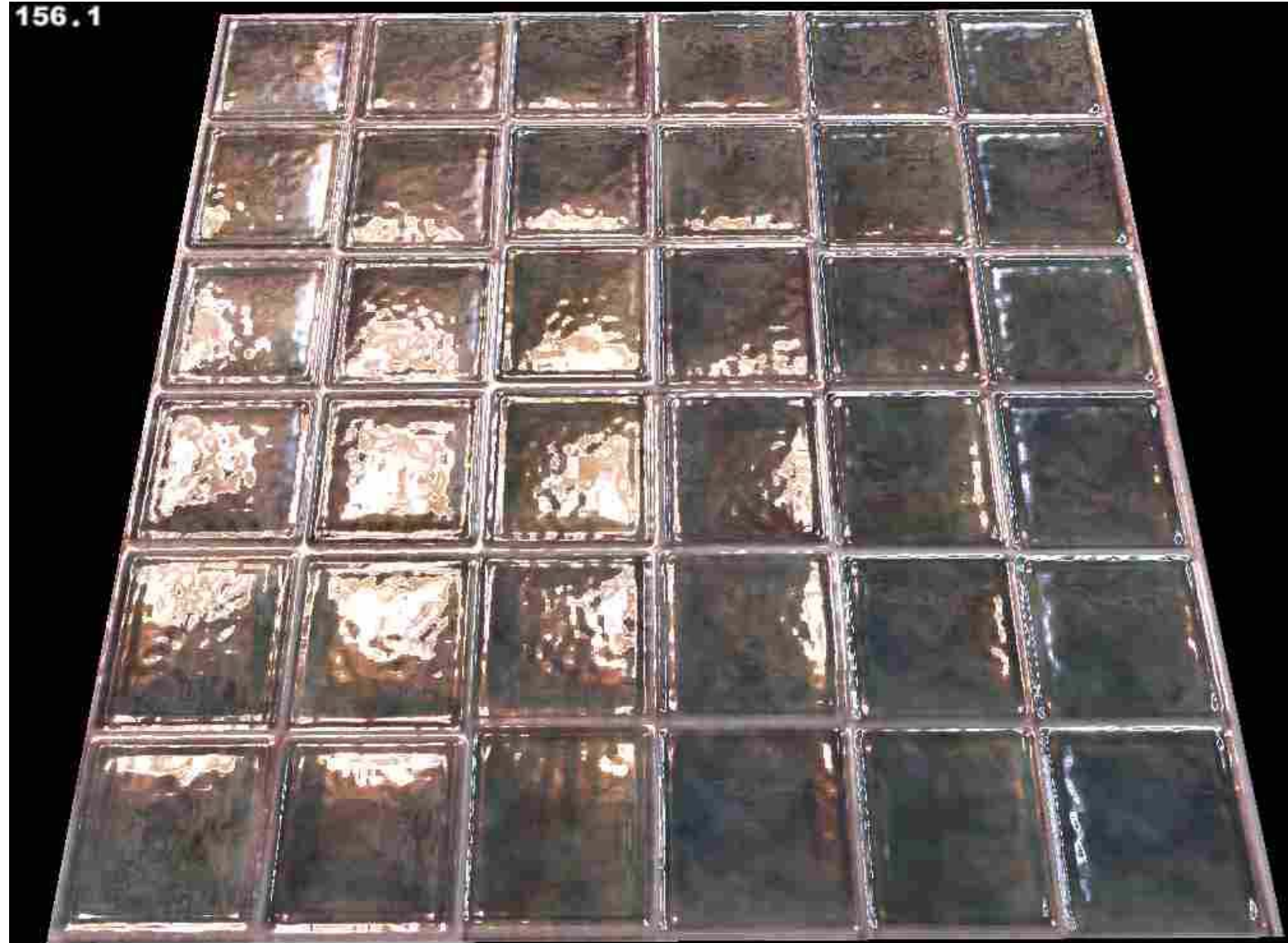
examples:

- texture & dirt
- texture & light map
- texture & bump map
- photo & annotations
- ...





bump mapping  
& environment mapping  
& texture mapping





# Einführung in Visual Computing

186.822

## Textures

## The End

