# Einführung in Visual Computing

## Global Illumination

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#### Surface-Rendering Methods



- polygon rendering methods
- ray tracing
- global illumination
- environment mapping
- texture mapping
- bump mapping



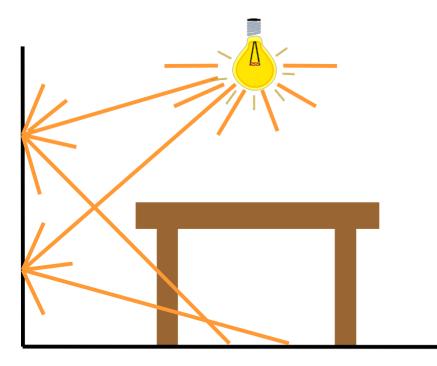
#### Global Illumination in the Rendering Pipeline object capture/creation scene objects in object space modeling vertex stage viewing ("vertex shader") projection transformed vertices in clip space clipping + homogenization scene in normalized device coordinates viewport transformation rasterization pixel stage shading ("fragment shader")

raster image in pixel coordinates

#### Radiosity Method



describes the physical process of light distribution in a diffuse reflecting environment



areas that are not illuminated directly are also not completely dark

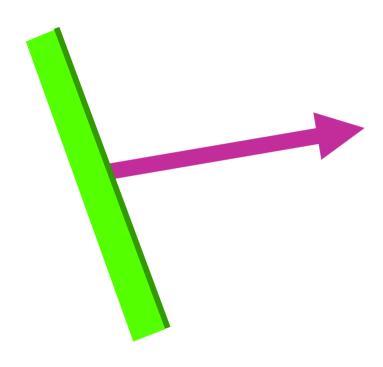
every object acts as a secondary light source



## Radiosity



Radiosity B is the "radiant flux per unit area" that is leaving a surface



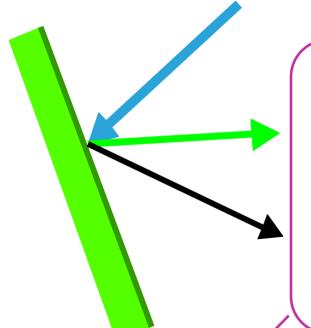




incoming light from the environment

$$\int I(x) dx = \int dB$$
hemi
hemi

E



self emission (only for light sources)

reflected light from environment

$$\rho \cdot \int dB$$

radiosity of the point

$$B = E + \rho \cdot \int_{\text{hemi}} dB$$





to calculate the light influence between surfaces

Radiosity = total light leaving a surface point

$$B = E + \rho \cdot \int_{\text{hemi}} dB$$

 $egin{array}{lll} B & ... & radiosity & hemi & ... & half space over possible E & ... & self emission & <math>
ho & ... & reflection coefficient & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... & ... &$ hemi ... half space over point

"radiosity = self emission + reflection property · sum of all incoming light"

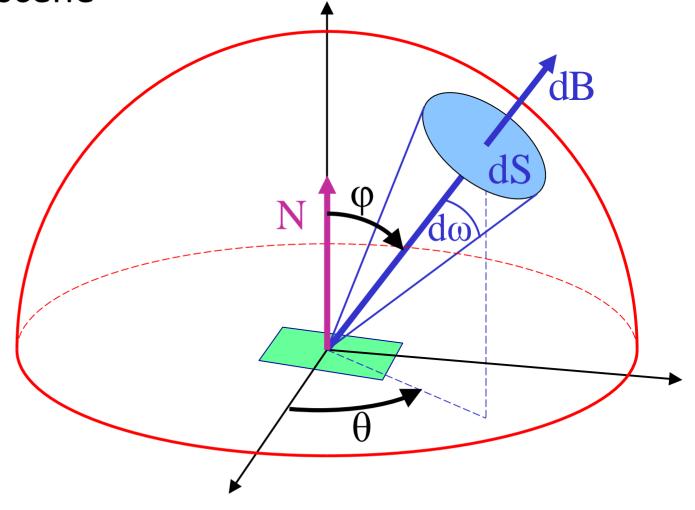


### **Radiosity Properties**



- diffuse interreflections in a scene
- radiant energy transfers
- conservation of energy, closed environments
- subdivision of scene into patches with constant radiosity B<sub>i</sub>

$$B = E + \rho \cdot \int_{\text{hemi}} dB$$





#### Radiosity: Subdivision into Patches



the scene is discretized into n "patches" (plane polygons)  $P_i$  , for each of these patches a constant radiosity  $B_i$  is assumed:

$$B = E + \rho \cdot \int_{\text{hemi}} dB \qquad \Longrightarrow \qquad B_{i} = E_{i} + \rho_{i} \cdot \sum_{j=1}^{n} B_{j} \cdot F_{ij}$$

 $ho_i$  diffuse reflection coefficient of patch i "form factor": describes what % of the influence on patch i comes from patch j; = geometric size!



#### Radiosity Model



$$B_{i} = E_{i} + \rho_{i} \cdot \sum_{j=1}^{n} B_{j} \cdot F_{ij}$$

B<sub>i</sub> ... radiosity of patch i

E<sub>i</sub> ... self-emission of patch i

 $\Sigma B_i F_{ii}$  ... contribution of other patches

 $F_{ij}$  ... form factor, defines

- $\blacksquare$  contribution of  $B_i$  on patch j which is equal to
- contribution of patch j to B<sub>i</sub>

ρ<sub>i</sub> ... reflectivity coefficient of patch i ("albedo")



#### Solving the Radiosity Equation



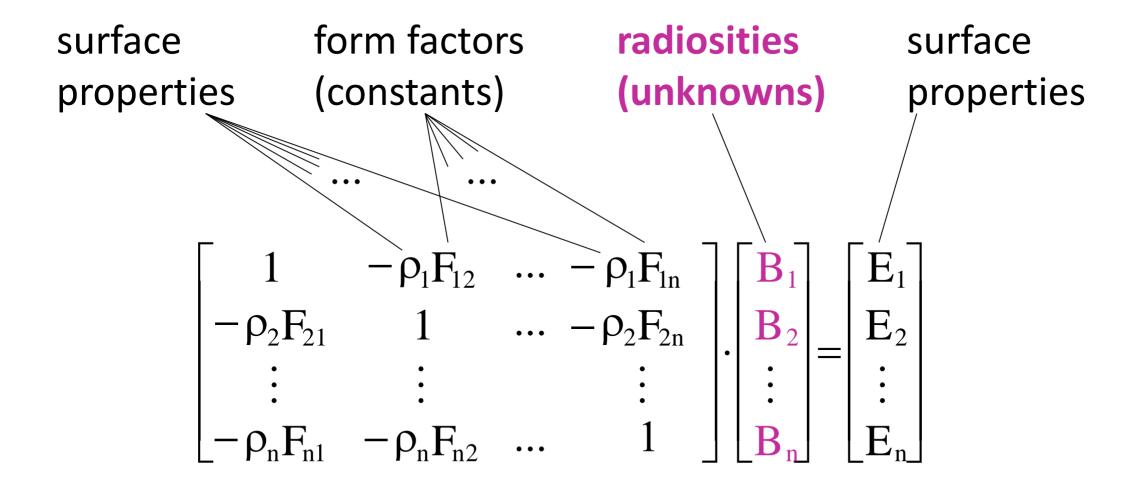
$$\mathbf{B}_{i} = \mathbf{E}_{i} + \mathbf{\rho}_{i} \sum_{j \neq i} \mathbf{B}_{j} \mathbf{F}_{ij}$$

$$B_i - \rho_i \sum_{j \neq i} B_j F_{ij} = E_i$$

$$\begin{bmatrix} 1 & -\rho_{1}F_{12} & \dots & -\rho_{1}F_{1n} \\ -\rho_{2}F_{21} & 1 & \dots & -\rho_{2}F_{2n} \\ \vdots & \vdots & & \vdots \\ -\rho_{n}F_{n1} & -\rho_{n}F_{n2} & \dots & 1 \end{bmatrix} \cdot \begin{bmatrix} B_{1} \\ B_{2} \\ \vdots \\ B_{n} \end{bmatrix} = \begin{bmatrix} E_{1} \\ E_{2} \\ \vdots \\ E_{n} \end{bmatrix}$$



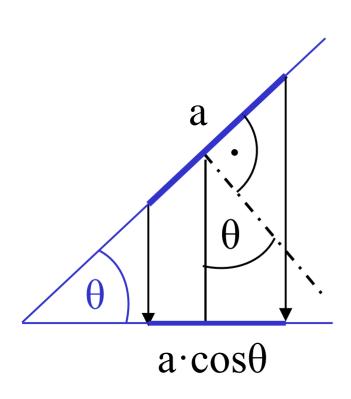


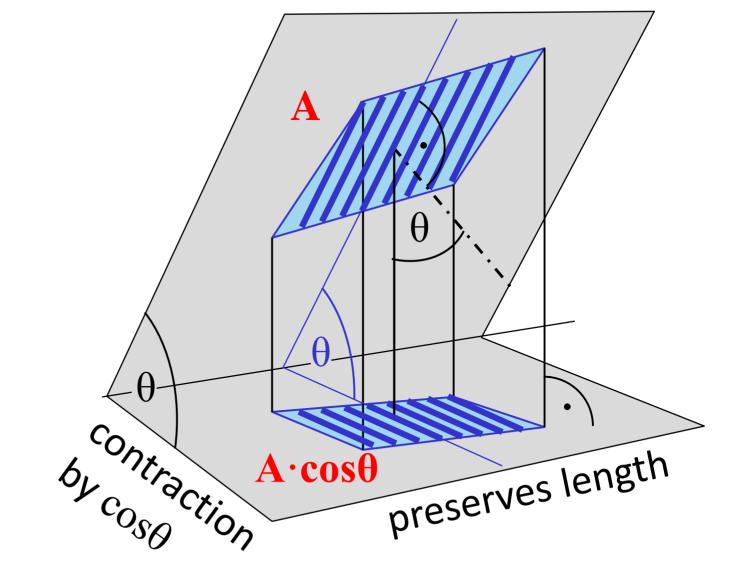




## Reminder: Projection of a Polygon





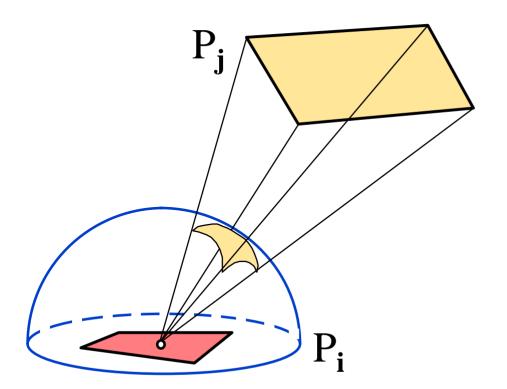




## Radiosity: Form Factors $F_{ij}$



form factor  $F_{ij}$ : contribution of patch  $P_j$  to  $B_i$ = contribution of  $B_i$  to patch  $P_j$ 

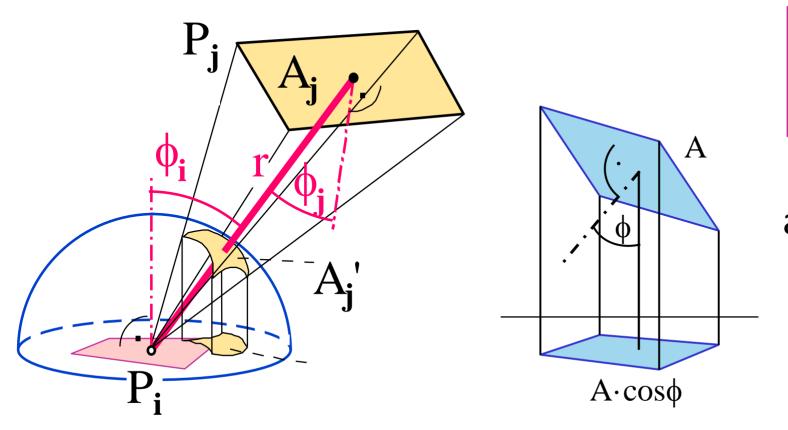


energy reaching patch j from patch i total energy leaving patch i





form factor  $F_{ij}$ : contribution of patch  $P_j$  to  $B_i$ = contribution of  $B_i$  to patch  $P_i$ 



$$F_{ij} = \frac{\cos\phi_i \cos\phi_j A_j}{\pi r^2}$$

and because 
$$\sum_{j=1}^{n} F_{ij} = 1$$

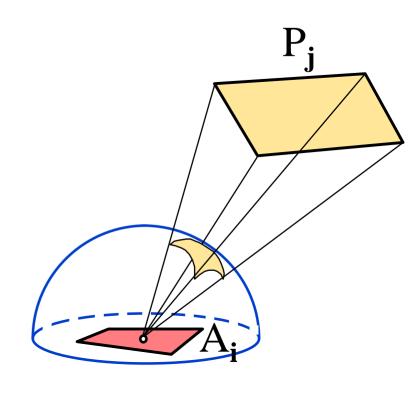




form factor  $F_{ij}$ : contribution of patch  $P_j$  to  $B_i$ = contribution of  $B_i$  to patch  $P_j$ 

$$F_{ij} = \frac{\cos\phi_i \cos\phi_j A_j}{\pi r^2}$$

more precisely: form factor is sum over contributions from  $P_{\mathbf{i}}$  averaged over area  $A_{\mathbf{i}}$ 



$$F_{ij} = \frac{1}{A_i} \int_{A_i} \int_{A_j} \frac{\cos \phi_i \cos \phi_j}{\pi r^2} dA_j dA_i$$





#### form factor properties

conservation of energy

$$\sum_{i=1}^{n} F_{ij} = 1$$

uniform light reflection

$$A_{i}F_{ij} = A_{j}F_{ji}$$

no self-incidence

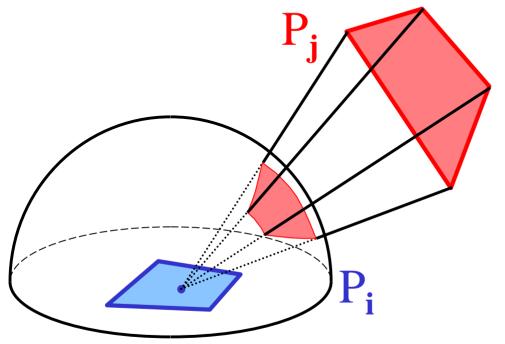
$$F_{ii} = 0$$

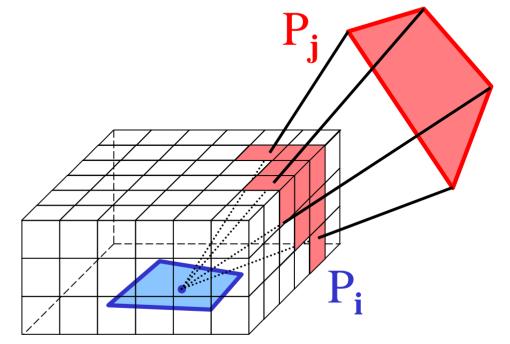




#### form factor calculation

- most expensive step in radiosity calculation
- numerical integration (Monte Carlo methods)
- hemicube approach (replaces hemisphere)









#### solving the radiosity equation

- Gaussian elimination
- Gauss-Seidel iteration

$$\begin{bmatrix} 1 & -\rho_{1}F_{12} & \dots & -\rho_{1}F_{1n} \\ -\rho_{2}F_{21} & 1 & \dots & -\rho_{2}F_{2n} \\ \vdots & \vdots & & \vdots \\ -\rho_{n}F_{n1} & -\rho_{n}F_{n2} & \dots & 1 \end{bmatrix} \cdot \begin{bmatrix} B_{1} \\ B_{2} \\ \vdots \\ B_{n} \end{bmatrix} = \begin{bmatrix} E_{1} \\ E_{2} \\ \vdots \\ E_{n} \end{bmatrix}$$

very time and storage intensive

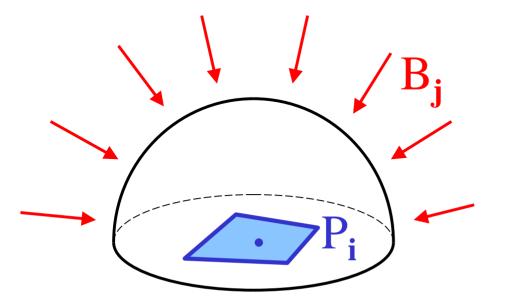




#### solving the radiosity equation

Gauss-Seidel iteration

$$B_i^{k+1} = E_i + \rho_i \sum_{j \neq i} B_j^k F_{ij}$$



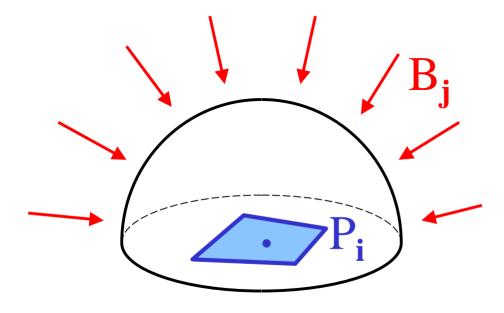
$$\begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B}
\end{pmatrix} = \begin{pmatrix}
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E}
\end{pmatrix} + \begin{pmatrix}
\mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} \\
\mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} \\
\mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} \\
\mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} \\
\mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x} & \mathbf{x}
\end{pmatrix} \cdot \begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B}
\end{pmatrix}$$

"gathering"



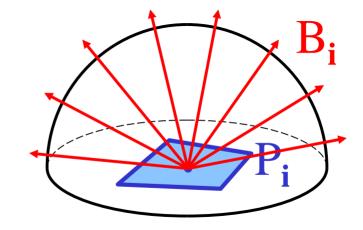


"gathering" vs. "shooting"



$$\begin{pmatrix}
\mathbf{B} \\
\mathbf{E}
\end{pmatrix} = \begin{pmatrix}
\mathbf{E} \\
\mathbf{Y}
\end{pmatrix} + \begin{pmatrix}
\mathbf{X} & \mathbf{X} & \mathbf{X} & \mathbf{X} & \mathbf{X}
\end{pmatrix} \cdot \begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B}
\end{pmatrix}$$

$$B_i^{k+1} = E_i + \rho_i \sum_{j \neq i} B_j^k F_{ij}$$



$$\begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B}
\end{pmatrix} = \begin{pmatrix}
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E}
\end{pmatrix} + \begin{pmatrix}
\mathbf{x} \\
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\mathbf{x} \\
\mathbf{x}
\end{pmatrix} \cdot \begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B}
\end{pmatrix} = \begin{pmatrix}
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E}
\end{pmatrix} + \begin{pmatrix}
\mathbf{x} \\
\mathbf{x} \\
\mathbf{x}
\end{pmatrix} \cdot \begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B} \\
\mathbf{E}
\end{pmatrix} = \begin{pmatrix}
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E}
\end{pmatrix} + \begin{pmatrix}
\mathbf{E} \\
\mathbf{E$$



#### Progressive Refinement Radiosity (1)



"shooting"  $\rightarrow$  select brightest patch  $P_i$  and distribute its radiosity  $B_i$ 

$$B_{i} = E_{i} + \rho_{i} \sum_{j \neq i} B_{j} F_{ij} \implies B_{i \text{ due to } B_{i}} = \rho_{i} B_{j} F_{ij} \implies B_{j \text{ due to } B_{i}} = \rho_{j} B_{i} F_{ji} \implies$$

$$\Rightarrow \begin{array}{c} \text{because of} \\ A_i F_{ij} = A_j F_{ji} \end{array} \Rightarrow \begin{array}{c} B_{j \text{ due to } B_i} = \rho_j B_i F_{ij} \frac{A_i}{A_j} \end{array}$$



#### Progressive Refinement Radiosity (2)



#### [one refinement step]

```
select patch i with highest A_1 * \Delta B_1
for selected patch i {
    set up hemicube
    calculate form factors Fig
for each patch j {
     \Delta rad := \rho_{i} * \Delta B_{i} * F_{ii} * A_{i} / A_{i}
     \Delta B_{i} := \Delta B_{i} + \Delta rad
     B_i := B_i + \Delta rad
```

$$\begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{B}
\end{pmatrix} = \begin{pmatrix}
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E}
\end{pmatrix} + \begin{pmatrix}
\mathbf{x} \\
\mathbf{x} \\
\mathbf{x}
\end{pmatrix} \cdot \begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{E}
\end{pmatrix} \times \begin{pmatrix}
\mathbf{E} \\
\mathbf{E} \\
\mathbf{E}
\end{pmatrix} \times \begin{pmatrix}
\mathbf{x} \\
\mathbf{x} \\
\mathbf{x}
\end{pmatrix} \cdot \begin{pmatrix}
\mathbf{B} \\
\mathbf{B} \\
\mathbf{E}
\end{pmatrix} \times \begin{pmatrix}
\mathbf{E} \\
\mathbf{E} \\
\mathbf{$$

$$B_{j \text{ due to } B_i} = \rho_j B_i F_{ij} \frac{A_i}{A_j}$$



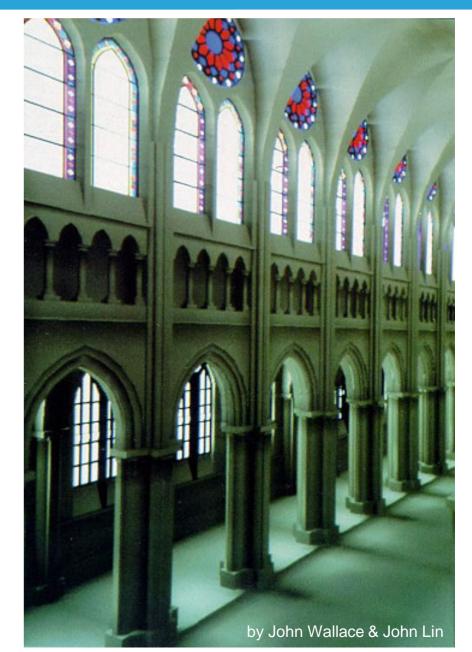
### Progressive Refinement Radiosity (3)



- initialize  $\Delta B_i = B_i = E_i$
- select patch with highest  $\Delta B_i A_i$

cathedral rendered with progressive refinement radiosity

form factors computed with ray-tracing methods





### Radiosity Example Images (1)

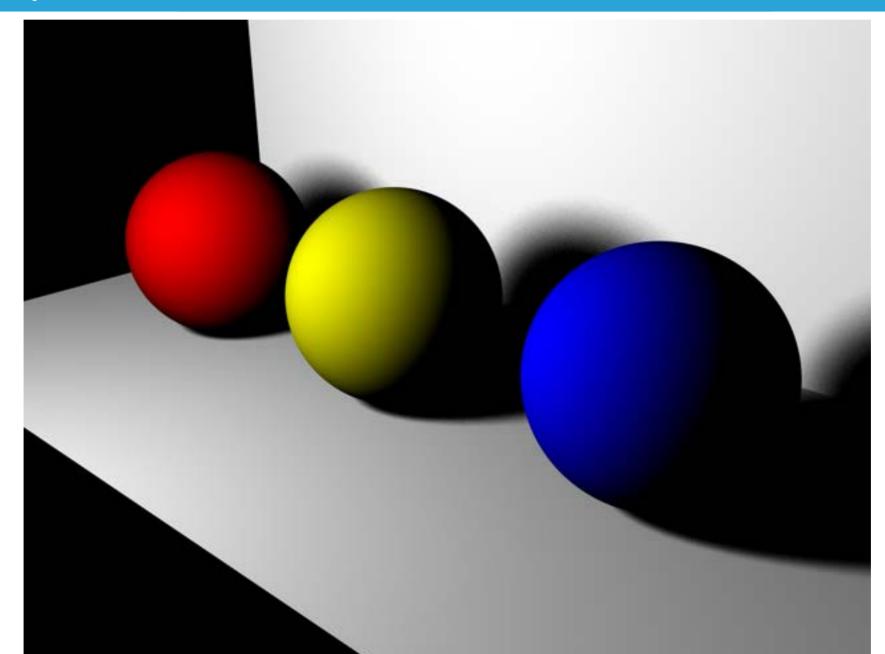




image of a constructivist museum rendered with progressive refinement radiosity

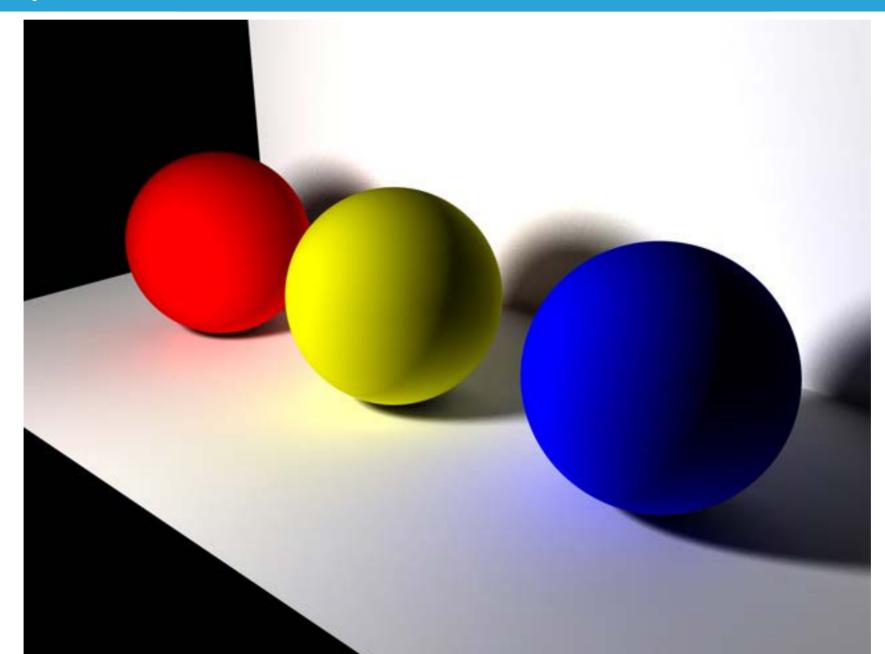




















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#### Radiosity Aspects

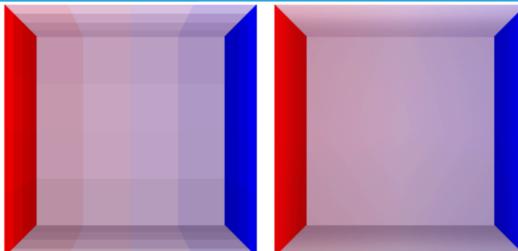


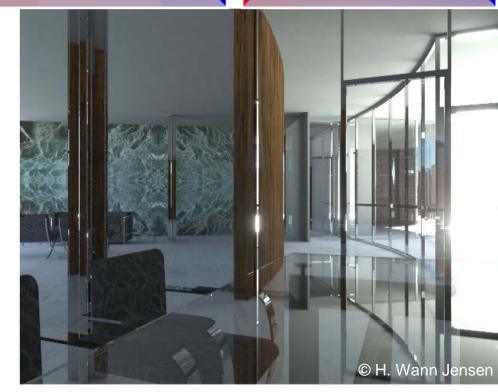
radiosity is viewpoint-independent needs a rendering step to display

- polygon rendering
- Gouraud shading
- ray-tracing
- ...

combination with ray-tracing enables

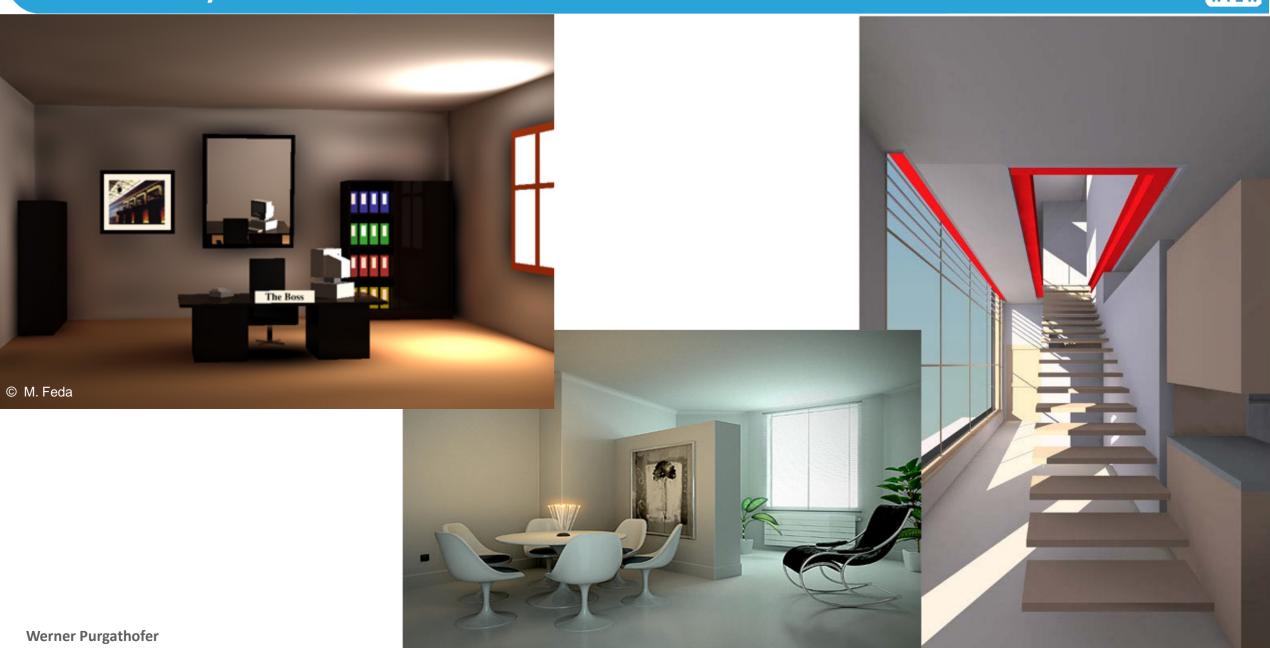
- reflections
- shadows
- •••





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#### **hierarchical radiosity** $\rightarrow$ reduces number of form factors

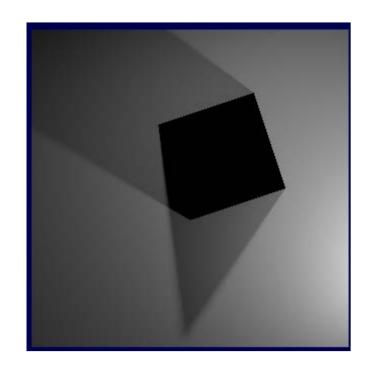


mesh density varies with importance

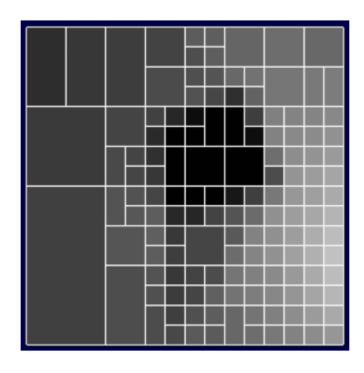




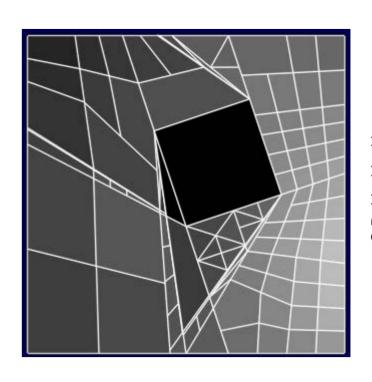
#### **discontinuity meshing** $\rightarrow$ improves shadow boundaries



sharp shadow boundaries ...



... get blurred by arbitrary meshing, ...



... stay correct with discontinuity meshing





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#### Discontinuity Meshing Example



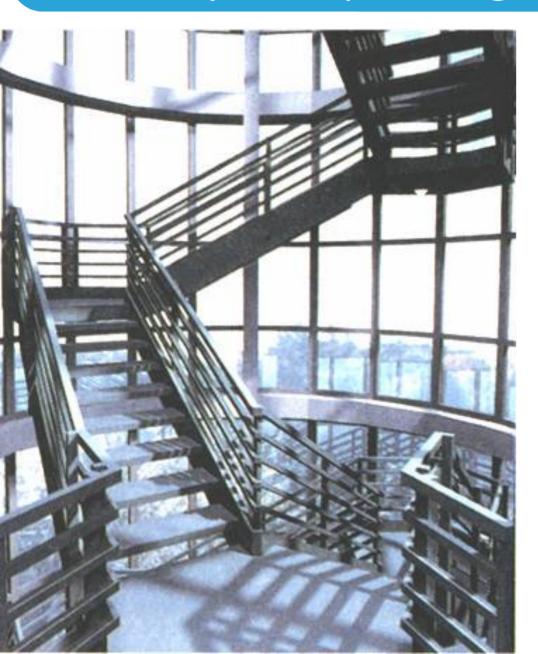


discontinuity meshing allows for sharp shadows also



#### Radiosity Example Image



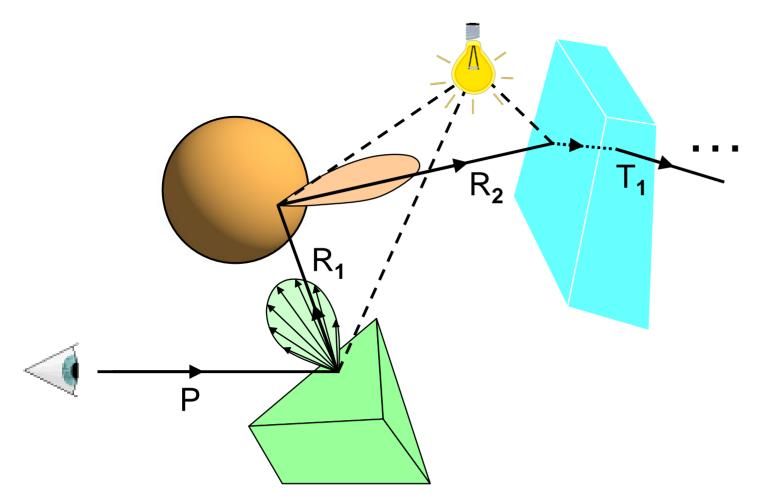


stair tower of a building at Cornell University rendered with progressive refinement radiosity

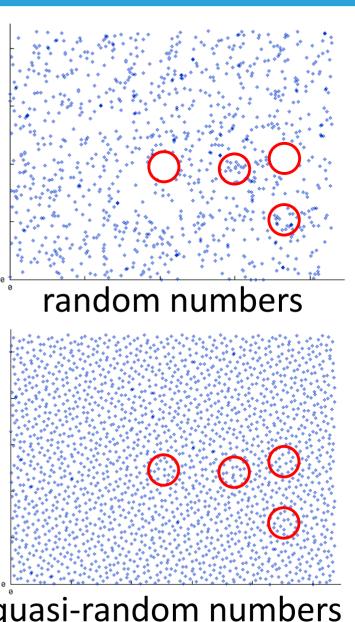




#### path tracing



35



quasi-random numbers





#### path tracing

- also called Monte Carlo ray tracing
- randomly selects ray directions

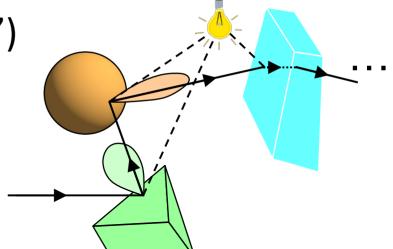
distribution functions ("importance sampling")

uses Monte Carlo integration to solve

$$B = E + \rho \cdot \int_{\text{hemi}} dB$$

hemi ... half space over point

B ... radiosity
E ... self emission p ... reflection coefficient

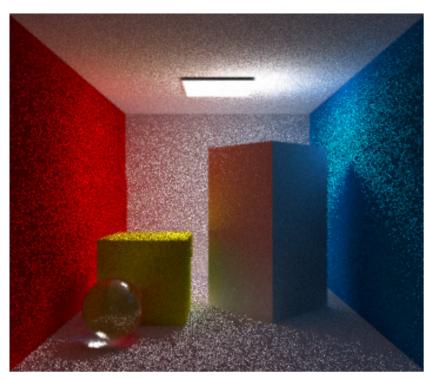




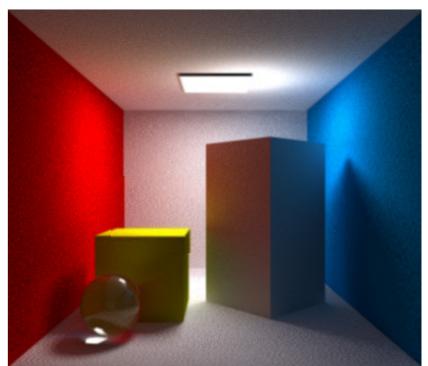


#### photon mapping

→ trace light rays from light source(s) and store illumination on objects







25 samples/pixel

125 samples/pixel

625 samples/pixel



## Photon Mapping Example





caustics from the inner surface of a ring created with photon mapping





#### path tracing + photon mapping combined enable

- all surface properties
- area light sources / penumbras
- indirect lighting
- caustics
- antialiasing
- depth of field
- motion blur
- ...

