

Solutions to Problem Set 10 FYS3140

In this PS, we follow the notation in *Boas*, including the references to the table of Laplace transforms on p. 469-471. The constraints from the third column in the table are omitted here, but do of course apply.

Chapter 8

Problem 8.4

Verify *L12*, namely

$$L[t \cos(at)] = \frac{p^2 - a^2}{(p^2 + a^2)^2} \quad (1)$$

We have *L3*:

$$L[\sin(at)] = \frac{a}{p^2 + a^2} \quad \text{Re } p > |\text{Im } a| \quad (2)$$

Differentiation with respect to a variable that is neither of the two involved in the transform (here t and p) can be taken inside the Laplace transform, according to Leibniz' rule of differentiating an integral (see *Boas* p. 236). Differentiating with respect to a gives:

$$\begin{aligned} L\left[\frac{\partial}{\partial a} \sin(at)\right] &= \frac{\partial}{\partial a} \frac{a}{p^2 + a^2} \\ L[t \cos(at)] &= \frac{(p^2 + a^2) - 2a^2}{(p^2 + a^2)^2} \\ &= \frac{p^2 - a^2}{(p^2 + a^2)^2} \end{aligned} \quad (3)$$

Problem 8.13

We have

$$F(p) = \frac{6-p}{p^2+4p+20} = \frac{6-p}{p^2+4p+4+16} = \frac{8}{(p+2)^2+16} - \frac{p+2}{(p+2)^2+16} \quad (4)$$

A good advice when doing inverse Laplace transforms is to always take care of the numerators involving p first: after this is done, the eventual constant numerators in other fractions can always be factorized to fit a given entry in the table. In this example, we took care of the factors of p by making the numerator on the right to be $p+2$. As we will now see, the other fraction with numerator of 8 is no problem. Looking at *L13* and *L14*, we see that if we rewrite $F(p)$ as

$$F(p) = 2 \frac{4}{(p+2)^2+4^2} - \frac{p+2}{(p+2)^2+4^2} \quad (5)$$

we have immediately

$$f(t) = L^{-1}[F(p)] = 2e^{-2t} \sin(4t) - e^{-2t} \cos(4t) \quad (6)$$

since the Laplace transform is linear.

Problem 8.21

We want to use $L29$ and $L11$ to calculate

$$L[te^{-at} \sin(bt)] \quad (7)$$

According to $L11$ we can write

$$L[t \sin(bt)] = \frac{2bp}{(p^2 + b^2)^2} = G(p) \quad (8)$$

with $g(t) = t \sin(bt)$. Then, $L29$ gives

$$L[e^{-at}(t \sin(bt))] = L[e^{-at}g(t)] = G(p+a) = \frac{2b(p+a)}{[(p+a)^2 + b^2]^2} \quad (9)$$

Problem 9.10

Solve

$$y'' - 4y' + 4y = 6e^{2t} \quad (10)$$

with $y_0 = y'_0 = 0$. We take the Laplace transform of the DE:

$$p^2Y - py_0 - y'_0 - 4(pY - y_0) + 4Y = 6L[e^{-(2)t}] \quad (11)$$

which according to $L2$ is

$$Y(p^2 - 4p + 4) = 6\frac{1}{p-2} \quad (12)$$

for $p > 2$. Factorizing gives:

$$\begin{aligned} Y(p-2)^2 &= 6\frac{1}{p-2} \\ Y &= 6\frac{1}{(p-2)^3} \end{aligned} \quad (13)$$

Comparing with $L6$ we see that

$$y(t) = L^{-1}[Y] = L^{-1}\left[3\frac{2!}{(p-2)^{2+1}}\right] = 3t^2e^{2t} \quad (14)$$

Problem 9.26

Solve

$$y'' + 2y' + 10y = -6e^{-t} \sin(3t) \quad (15)$$

with $y_0 = 0$, $y'_0 = 1$. Again taking the transform, we find

$$p^2Y - 1 + 2pY + 10Y = -6L[e^{-1t} \sin(3t)] = -6\frac{3}{(p+1)^2 + 3^2} \quad (16)$$

where $L13$ has been used. We find

$$\begin{aligned}
Y(p^2 + 2p + 10) &= 1 - \frac{18}{(p+1)^2 + 3^2} \\
Y(p^2 + 2p + 1 + 9) &= \frac{(p+1)^2 + 3^2}{(p+1)^2 + 3^2} - \frac{18}{(p+1)^2 + 3^2} \\
Y[(p+1)^2 + 3^2] &= \frac{(p+1)^2 + 3^2}{(p+1)^2 + 3^2} - \frac{18}{(p+1)^2 + 3^2} \\
Y &= \frac{1}{(p+1)^2 + 3^2} - \frac{18}{[(p+1)^2 + 3^2]^2}
\end{aligned} \tag{17}$$

We know that $p \rightarrow p+1$ simply correspond to a factor e^{-t} in the inverse. Overlooking this, the two entries $L13$ and $L17$ stand out as candidates for the inverse transform. We find:

$$\begin{aligned}
y(t) &= L^{-1}[Y] \\
&= L^{-1} \left[\frac{1}{3} \frac{3}{(p+1)^2 + 3^2} - \frac{1}{3} \frac{2 \cdot 3^3}{[(p+1)^2 + 3^2]^2} \right] \\
&= \frac{1}{3} [e^{-t} \sin(3t) - e^{-t} (\sin(3t) - 3t \cos(3t))] \\
&= te^{-t} \cos(3t)
\end{aligned} \tag{18}$$

Problem 10.5

Find the inverse transform of

$$Y(p) = \frac{p}{(p+a)(p+b)^2} \tag{19}$$

There are many possibilities here, but we choose to write:

$$Y = \frac{p}{(p+a)(p+b)} \cdot \frac{1}{p+b} \tag{20}$$

with the intention of using $L8$ and $L2$. Let

$$G(p) = \frac{p}{(p+a)(p+b)}, \quad H(p) = \frac{1}{p+b} \tag{21}$$

such that

$$g(t) = \frac{ae^{-at} - be^{-bt}}{a-b}, \quad h(t) = e^{-bt} \tag{22}$$

The convolution theorem then gives

$$\begin{aligned}
y(t) &= \int_0^t g(\tau)h(t-\tau) d\tau \\
&= \frac{1}{a-b} \int_0^t (ae^{-a\tau} - be^{-b\tau}) e^{-b(t-\tau)} d\tau \\
&= \frac{1}{a-b} \left[ae^{-bt} \int_0^t e^{-(a-b)\tau} d\tau - be^{-bt} \int_0^t d\tau \right] \\
&= \frac{e^{-bt}}{a-b} \left[\frac{-a}{a-b} (e^{-(a-b)t} - 1) - bt \right] \\
&= \frac{e^{-bt}}{b-a} \left[bt + \frac{a}{a-b} (e^{(b-a)t} - 1) \right]
\end{aligned} \tag{23}$$

Problem 10.14

Solve

$$y'' + 5y' + 6y = e^{-2} \quad (24)$$

with $y_0 = y'_0 = 0$. Taking the transform and using *L2*:

$$\begin{aligned} Y(p^2 + 5p + 6) &= \frac{1}{p+2} \\ Y(p+2)(p+3) &= \frac{1}{p+2} \\ Y &= \frac{1}{(p+3)(p+2)^2} \\ &= \frac{1}{p+3} \cdot \frac{1!}{(p+2)^{1+1}} \end{aligned} \quad (25)$$

Using *L2*, *L5* and convolution, with $G(p)$ and $H(p)$ corresponding to the first and second fraction respectively,

$$\begin{aligned} y(t) &= \int_0^t g(t-\tau)h(\tau) d\tau \\ &= \int_0^t e^{-3(t-\tau)}\tau e^{-2\tau} d\tau \\ &= e^{-3t} \int_0^t \tau e^{\tau} d\tau \\ &= e^{-3t} [te^t - e^t + 1] \\ &= (t-1)e^{-2t} + e^{-3t} \end{aligned} \quad (26)$$

Problem 11.8

Find the response of a unit pulse to a system described by

$$y'' + 4y' + 5y = f(t) \quad (27)$$

A unit pulse at time t_0 is equivalent to replacing $f(t)$ with $\delta(t - t_0)$, and letting the system start in the state $y_0 = y'_0 = 0$. Therefore we can take the transform of the equation:

$$\begin{aligned} Y(p^2 + 4p + 5) &= \begin{cases} e^{-pt_0} & t > t_0 \\ 0 & \text{otherwise} \end{cases} \\ Y &= e^{-pt_0} \frac{1}{(p+2)^2 + 1^2} \end{aligned} \quad (28)$$

From now on we assume $t > t_0$. Let

$$G(p+2) = \frac{1}{(p+2)^2 + 1^2} \Rightarrow g(t) = \sin(1t) \quad (29)$$

Then according to *L28* and *L29*,

$$y(t) = L^{-1}[Y] = \begin{cases} e^{-2(t-t_0)} \sin(t-t_0) & t > t_0 \\ 0 & \text{otherwise} \end{cases} \quad (30)$$

The exponential comes from *L29* and the split definition along with the replacement $t \rightarrow t - t_0$ comes from *L28*.