## Exercise 2 – Uninformed Search Strategies (DLS, IDS)

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## Aim:

To write a python program to implement the following:

- 1. Generate a random sequence for n distinct numbers by specifying the initial value and end value. Print the list.
- 2. Use a suitable data structure to keep track of the parent of every state and show the structure as a state space representation for the list created.
- 3. Print the sequence of states and actions from the initial state to the goal state using DLS with suitable data structure.
- 4. Print the sequence of states and actions from the initial state to the goal state for every level using IDS with suitable data structure.

## **Code:**

```
"Implementation of DLS and IDS"
#class and function definitions
from collections import deque as queue
class Node:
  def __init__(self, data):
     self.left = None
     self.right = None
     self.data = data
  def insert(self, data):
     if self.left is None:
       self.left = Node(data)
     elif self.right is None:
```

self.right = Node(data)elif self.left.right is None: self.left.insert(data)

self.right.insert(data)

else:

```
def printTree(self):
     print(self.data, end=" ")
     if self.left:
       self.left.printTree()
     if self.right:
       self.right.printTree()
  def dlsTree(self, root=None, goal=None, limit=None):
     if root is None:
       root = self
     print(root.data, end=" ")
     if root.data == goal:
       #print(root.data)
       print("\nGoal state found!")
       return True
     if limit \le 0:
       return False
     if root.left:
       root.left.dlsTree(goal=goal, limit=limit - 1)
     if root.right:
       root.right.dlsTree(goal=goal, limit=limit - 1)
  def idsTree(self, root=None, goal=None, limit=None):
     if root is None:
       root = self
     for i in range(limit + 1):
       print("\nlimit", i, "\b:", end=" ")
       if (root.dlsTree(root=root, goal=goal, limit=i)):
          return True
     return False
def levelOrder(root):
  print()
  if (root is None):
     return
```

```
q = queue()
  q.append(root)
  q.append(None)
  ht = 3
  h = 0
  while (len(q) > 1):
     curr = q.popleft()
     if (curr is None):
       q.append(None)
       h += 1
       print()
     else:
       if (curr.left):
          q.append(curr.left)
       if (curr.right):
          q.append(curr.right)
       print(" " * ((2**(ht - h)) + (ht - h)), curr.data, end="")
       if (h \% 2 == 1):
          print(end=" " * (4 * h))
def createSeq(start, end, n):
  seq = []
  for i in range(start, end, (end - start) // n):
     seq.append(i)
  return seq
def constrTree(nodes):
  root = Node(nodes[0])
  for i in range(1, len(nodes)):
     root.insert(nodes[i])
  return root
#main program
init = int(input("Enter initial value: "))
fin = int(input("Enter final value: "))
```

```
n = int(input("Enter no. of numbers: "))
seq = createSeq(init, fin, n)
print("\nSequence: ", seq)
tree = constrTree(seq)
print()
levelOrder(tree)
print("\n")
gl = int(input("Enter goal state: "))
lt = int(input("Enter limit value: "))
print("\nDLS: ")
tree.dlsTree(root=tree, goal=gl, limit=lt)
print("\nIDS: ")
tree.idsTree(root=tree, goal=gl, limit=lt)
```

## **Output:**

```
~/AIwork$ python3 dlsids.py
Enter initial value: 10
Enter final value: 20
Enter no. of numbers: 5
Sequence: [10, 12, 14, 16, 18]
            10
       12
                    14
    16
Enter goal state: 14
Enter limit value: 2
DLS:
10 12 16 18 14
Goal state found!
IDS:
limit 0: 10
limit 1: 10 12 14
Goal state found!
limit 2: 10 12 16 18 14
Goal state found!
```