Professional Project Report: Computer Vision for Smart Interaction

1. Introduction

This project leverages deep learning and computer vision to build a real-time object detection

system using the YOLOv8 model. The system is designed to efficiently detect multiple objects

through a web interface powered by Flask. It aims to provide an intuitive and interactive way to

recognize objects in real-time using a webcam.

2. Problem Statement

Traditional object detection models often suffer from latency and accuracy trade-offs. The goal of

this project is to implement a highly efficient, real-time object detection system that maintains a

balance between speed and precision, making it suitable for practical applications such as

surveillance, robotics, and smart assistance systems.

3. Technologies Used

- Programming Language: Python

- Deep Learning Framework: YOLOv8 (Ultralytics)

- Computer Vision Library: OpenCV

- Web Framework: Flask

- Frontend: HTML, CSS

- Model Weights: YOLOv4-tiny, YOLOv8n, YOLOv8s, YOLOv8x

4. Methodology

- The YOLO model is loaded and configured using pre-trained weights.

- A Flask web application serves as the interface for live video feed and object detection.

- OpenCV captures frames from the webcam and processes them in real-time.

- The YOLO model detects objects in each frame and overlays bounding boxes.

- The processed frames are streamed to a web page via Flask routes.

- The system supports multiple YOLO versions for different accuracy-speed trade-offs.

5. Features & Implementation

- Real-time object detection: Detects multiple objects in live webcam feed.
- Multi-model support: Users can switch between YOLOv8n, YOLOv8s, and YOLOv8x for different accuracy-speed trade-offs.
- Web-based Interface: The Flask web server allows access from a browser.
- Optimized Performance: Uses threading and OpenCV optimizations for faster frame processing.
- Predefined Object Labels: Includes COCO dataset labels for accurate identification.
- Smooth Video Streaming: Uses Flask's Response Streaming to serve real-time video.

6. Performance Analysis

- Frame Rate (FPS): 20-30 FPS (Real-time performance on mid-range GPU/CPU).
- Inference Time: ~150-250ms per frame (varies based on YOLO model used).
- Detection Accuracy: 65-85% confidence threshold for most objects.
- Latency Reduction: Uses multi-threading to improve speed and responsiveness.

7. Future Enhancements

- Custom Object Detection: Train the model on a dataset with specific objects (e.g., chargers, remote controllers).
- Mobile Deployment: Convert the application into a mobile-friendly web app.
- Cloud-Based Processing: Deploy the model on a cloud service for scalable processing.
- Integration with IoT: Use the model in smart security cameras for real-time alerts.
- Edge AI Optimization: Implement TensorRT or OpenVINO for enhanced speed on embedded devices.

8. Conclusion

This project successfully integrates YOLO-based object detection with a Flask-based web application, offering a real-time and efficient Al-powered vision system. The combination of

optimized performance, smooth frame processing, and a user-friendly i	nterface makes it a strong
candidate for practical use in Al-driven applications.	