

MATH 417

3/29/2023

Example: Is the matrix

$$A = \begin{pmatrix} 3 & 1 \\ -4 & -1 \end{pmatrix}$$

diagonalizable?

Solution:

$$\det(\lambda I - A) = \det \begin{pmatrix} \lambda - 3 & -1 \\ 4 & \lambda + 1 \end{pmatrix} =$$
$$= (\lambda - 3)(\lambda + 1) + 4 = \lambda^2 - 2\lambda + 1 = (\lambda - 1)^2$$

One eigenvalue $\lambda = 1$ with multiplicity 2.

$$A = \begin{pmatrix} 3 & 1 \\ -4 & -1 \end{pmatrix} \quad \text{Only eigenvalue } \lambda = 1 \quad \underline{\text{algebraic}} \\ \underline{\text{multiplicity}} = 2$$

If A were diagonalizable, we would have $D = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

$$B^{-1}AB = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$B \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} B^{-1} = A$$

$$\underbrace{\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}}_{\text{false!}}$$

A is not diagonalizable.

Find eigenvectors:

$$(1 \cdot I - A) = \begin{pmatrix} -2 & -1 \\ 4 & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & 1/2 \end{pmatrix}$$

$$\text{Eigenvector: } \begin{pmatrix} -1 \\ 2 \end{pmatrix} \\ (\text{or any multiple})$$

$$\underline{\text{Geometric multiplicity}} = \dim(\text{Eigenspace}) = 1.$$

$$A = \begin{pmatrix} 3 & 1 \\ -4 & -1 \end{pmatrix}$$

eigenvalue $\lambda = 1$ (algebraic multiplicity = 2)
 eigenvector: $\begin{pmatrix} -1 \\ 2 \end{pmatrix}$ (geometric multiplicity = 1).

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$f(v) = (\underbrace{\lambda I}_{\lambda=1} - A)v = (I - A)v = \begin{pmatrix} -2 & -1 \\ 4 & 2 \end{pmatrix} v.$$

$$\text{Im}(f) = \{f(v) \mid v \in \mathbb{R}^2\} = V$$

$$\boxed{f: V \rightarrow V = 0}$$

$$f: V \rightarrow V$$

In this example, $V = \left\langle \begin{pmatrix} -1 \\ 2 \end{pmatrix} \right\rangle$

A commutes with itself and the unit matrix.

(because
 2×2 -matrix)

$$\dim \text{Ker} (\lambda I - A) = 1 \quad \lambda = 1 \quad A = \begin{pmatrix} 3 & 1 \\ -4 & -1 \end{pmatrix} \quad \lambda I - A = \begin{pmatrix} -2 & -1 \\ 4 & 2 \end{pmatrix}$$

↑
solution space

$$\dim \text{Ker} ((\lambda I - A)^2) = 2$$

$$(\lambda I - A)^2 = \begin{pmatrix} -2 & -1 \\ 4 & 2 \end{pmatrix} \begin{pmatrix} -2 & -1 \\ 4 & 2 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\text{eigenvector } v = \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

We can look for a vector w which satisfies

$$(\lambda I - A)w = -v$$

$$w = \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\begin{pmatrix} -2 & -1 \\ 4 & 2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \end{pmatrix} \quad \left| \begin{array}{cc|c} -2 & -1 & 1 \\ 4 & 2 & -2 \end{array} \right| \quad \text{e.g.} \quad w = \begin{pmatrix} 1/2 \\ 0 \end{pmatrix}$$

$$\left| \begin{array}{cc|c} -2 & -1 & 1 \\ 4 & 2 & -2 \end{array} \right|$$

$$\left| \begin{array}{cc|c} 1 & 1/2 & 1/2 \end{array} \right|$$

↑ parameter: say, 0

$$\begin{pmatrix} -2 & -1 \\ 4 & 2 \end{pmatrix} \begin{pmatrix} -1/2 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \end{pmatrix} = -v$$

$$A = \begin{pmatrix} 3 & 1 \\ -4 & -1 \end{pmatrix}$$

Jordan block



$$A \underbrace{\begin{pmatrix} -1 & -1/2 \\ 2 & 0 \end{pmatrix}}_B$$

$$= \begin{pmatrix} -1 & -1/2 \\ 2 & 0 \end{pmatrix} \boxed{\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}}$$

$$Aw = w + v$$

$$(\lambda I - A)w = -v$$

↑
 $\lambda = 1$

$$B: v, w$$

$$\begin{pmatrix} -1 \\ 2 \end{pmatrix}, \begin{pmatrix} -1/2 \\ 0 \end{pmatrix}$$

check:

$$\begin{pmatrix} 3 & 1 \\ -4 & -1 \end{pmatrix} \begin{pmatrix} -1 & -1/2 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} -1 & -3/2 \\ 2 & 2 \end{pmatrix} \checkmark$$

$$\begin{pmatrix} -1 & -1/2 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 & -3/2 \\ 2 & 2 \end{pmatrix}$$

Putting the matrix A in Jordan form:

$$\underbrace{\begin{pmatrix} -1 & -1/2 \\ 2 & 0 \end{pmatrix}}_{B^{-1}} \underbrace{\begin{pmatrix} 3 & 1 \\ 4 & -1 \end{pmatrix}}_A \underbrace{\begin{pmatrix} -1 & -1/2 \\ 2 & 0 \end{pmatrix}}_B = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

In general, a Jordan block of size k with eigenvalue λ is:

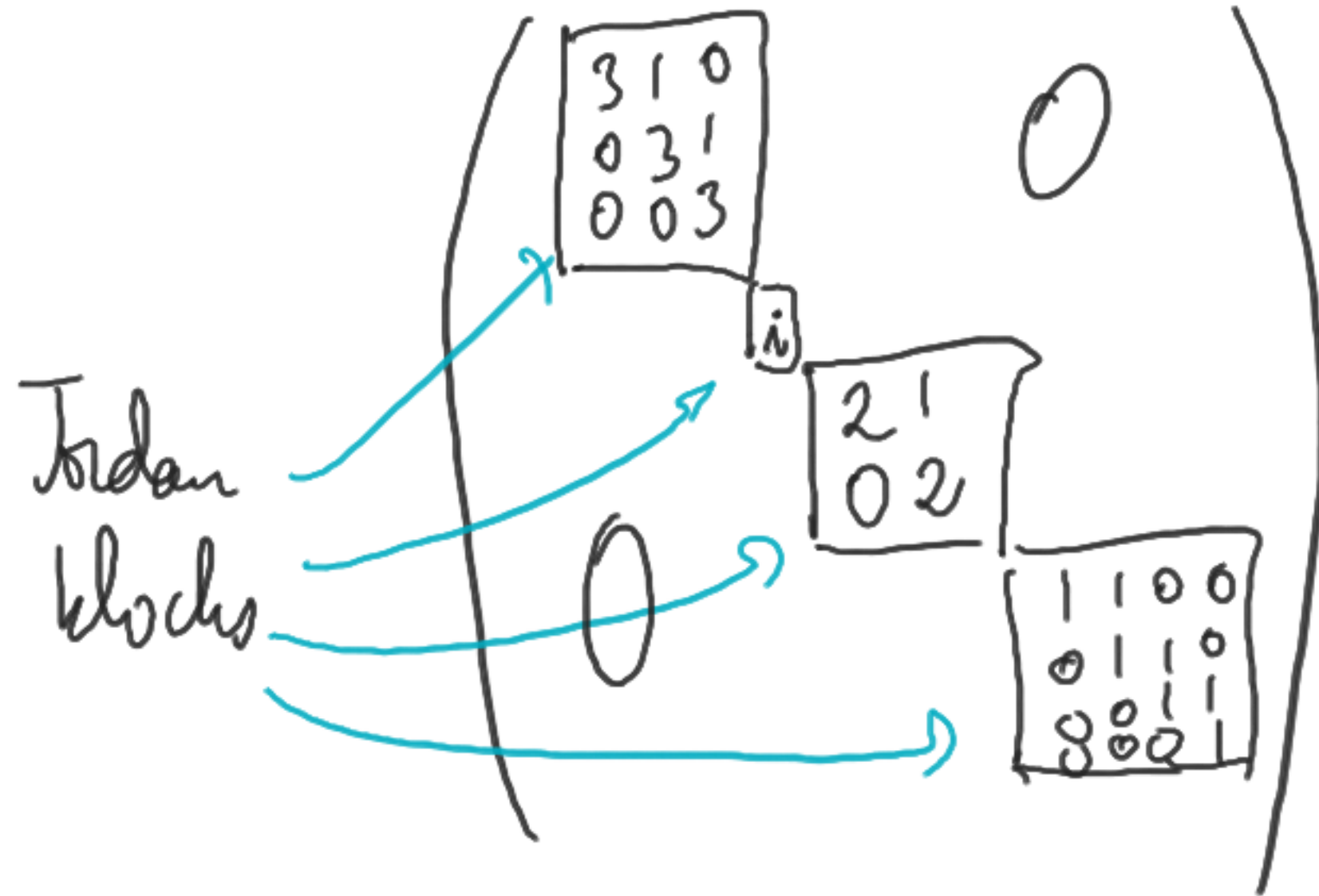
$$J_k(\lambda) = \underbrace{\begin{pmatrix} \lambda & 1 & & 0 \\ & \lambda & 1 & \\ & & \ddots & 1 \\ 0 & & & \lambda \end{pmatrix}}_k$$

(λ 's on the diagonal
1's right above the diagonal
0 elsewhere).

$$J_1(\lambda) = (\lambda)$$

1×1 matrix

A general Jordan form consists of Jordan blocks along the diagonal:



Every ^{complex} matrix A has a Jordan form
 ($B^{-1}AB$ is in Jordan form)
 The Jordan form is uniquely determined up to the order of Jordan blocks.

Example: Put the matrix

$$A = \begin{pmatrix} 3 & 1 \\ -1 & 1 \end{pmatrix}$$

into Jordan form.

Solution: $\det(\lambda I - A) = \det \begin{pmatrix} \lambda - 3 & -1 \\ 1 & \lambda - 1 \end{pmatrix} = (\lambda - 3)(\lambda - 1) + 1 = \lambda^2 - 4\lambda + 4 = (\lambda - 2)^2$

$\lambda = 2$ algebraic multiplicity 2

$$(2I - A) = \begin{pmatrix} -1 & -1 \\ 1 & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

eigenvector $v = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$

$$Aw = 2w + v$$

$$(2I - A)w = -v$$

$$\left(\begin{array}{cc|c} -1 & -1 & 1 \\ 1 & 1 & -1 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 1 & -1 \\ 0 & 0 & 0 \end{array} \right) \quad w = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$$

$$\left[\begin{pmatrix} -1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 3 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} -1 & -1 \\ 1 & 0 \end{pmatrix} \right] = \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix}$$

$$\begin{pmatrix} 3 & 1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} -1 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} -2 & -3 \\ 2 & 1 \end{pmatrix}$$

$$\begin{pmatrix} -1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 1 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} 2 & -3 \\ 2 & 1 \end{pmatrix} \checkmark$$

HW: ③ Put the matrix

$$A = \begin{pmatrix} 4 & -1 \\ 1 & 2 \end{pmatrix}$$

in Jordan form.

- ④ Write a matrix in Jordan form which has
- 2 Jordan blocks of size 3 with eigenvalue -1
 - 1 Jordan block of size 2 with eigenvalue $1+i$
 - 1 Jordan block of size 1 with eigenvalue -1
 - 1 Jordan block of size 1 with eigenvalue 5 .