

An Introduction to Robust Optimization

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Production problem

- Consider a simple production problem as follow

Parameter	DrugI	DrugII
Selling price, \$ per 1000 packs	6,200	6,900
Content of agent A, g per 1000 packs	0.500	0.600
Manpower required, hours per 1000 packs	90.0	100.0
Equipment required, hours per 1000 packs	40.0	50.0
Operational costs, \$ per 1000 packs	700	800

(a) Drug production data

Raw material	Purchasing price, \$ per kg	Content of agent A, g per kg
RawI	100.00	0.01
RawII	199.90	0.02

(b) Contents of raw materials

Budget, \$	Manpower, hours	Equipment, hours	Capacity of raw materials storage, kg
100,000	2,000	800	1,000

(c) Resources



Production problem

- The problem can be immediately posed as the following linear programming

$$\begin{aligned} \text{Opt} = \min & \left\{ \overbrace{[100 \cdot \text{RawI} + 199.90 \cdot \text{RawII} + 700 \cdot \text{DrugI} + 800 \cdot \text{DrugII}]}^{\text{purchasing and operational costs}} \right. \\ & \left. - \underbrace{[6200 \cdot \text{DrugI} + 6900 \cdot \text{DrugII}]}_{\text{income from selling the drugs}} \right\} \quad [\text{minus total profit}] \\ \text{subject to} & \\ 0.01 \cdot \text{RawI} + 0.02 \cdot \text{RawII} - 0.500 \cdot \text{DrugI} - 0.600 \cdot \text{DrugII} \geq 0 & \quad [\text{balance of active agent}] \\ \text{RawI} + \text{RawII} \leq 1000 & \quad [\text{storage constraint}] \\ 90.0 \cdot \text{DrugI} + 100.0 \cdot \text{DrugII} \leq 2000 & \quad [\text{manpower constraint}] \\ 40.0 \cdot \text{DrugI} + 50.0 \cdot \text{DrugII} \leq 800 & \quad [\text{equipment constraint}] \\ 100.0 \cdot \text{RawI} + 199.90 \cdot \text{RawII} + 700 \cdot \text{DrugI} + 800 \cdot \text{DrugII} \leq 100000 & \quad [\text{budget constraint}] \\ \text{RawI}, \text{RawII}, \text{DrugI}, \text{DrugII} \geq 0 & \end{aligned}$$

- The optimal solution of the LO problem is $\text{Opt} = -8819.658$, $\text{RawI} = 0$, $\text{RawII} = 438.789$ and $\text{DrugI} = 17.552$, $\text{DrugII} = 0$.



- **Is the data accurate?**
- Of course not, Of course, no one can guarantee the accuracy of raw material data.
- **What will be the result of inaccurate data?**
- Loss of optimality or even feasibility
- **How to tackle the problem of data uncertainty?**
- Robust optimization



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- An uncertain Linear Optimization problem is a collection as follow

$$LO_U = \{\min_x \{c^T x : Ax \leq b\}\}_{(A,b) \in U}$$

where U is a uncertainty set as follow

$$U = \left\{ [A \ b] = [A_0 \ b_0] + \sum_{\ell=1}^L \zeta_{\ell} [A_{\ell} \ b_{\ell}] : \zeta \in Z \subset \mathbf{R}^L \right\}$$

- ζ is a perturbation and Z is a perturbation set. Next, we will consider different perturbation set Z .
- PS:

Firstly, we always consider a affine uncertainty.

Secondly, if the objective is uncertain, then we can written the problem as a epigraph form. So we only consider the problem with certain objective and uncertain constraints.



- **Robust feasible:** A vector $x \in \mathbf{R}^n$ is a robust feasible solution to LO_U , if it satisfies all realizations of the constraints from the uncertainty set.

$$Ax \leq b \quad \forall (c, d, A, b) \in U$$

- **Robust counterpart model:** Based on the definition of robust feasible and value, the robust counterpart model can be written as follow.

$$\min_x \{c^T x : Ax \leq b \quad \forall (c, d, A, b) \in U\}$$



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- The outline strategy allow us to focus on the problem with single uncertainty-affected constraint as $\min_x \{c^T x : a^T x \leq b, [a, b] \in U\}$
- Review the definition of uncertainty set as follow where ζ is perturbation vector and Z is perturbation set.

$$U = \left\{ [a \ b] = [a_0 \ b_0] + \sum_{\ell=1}^L \zeta_{\ell} [a_{\ell} \ a_{\ell}] : \zeta \in Z \subset \mathbf{R}^L \right\}$$

- Consider the case of interval uncertainty, where Z in a box. W.l.o.g. we can normalize the situation by follow

$$Z = \{\zeta \in \mathbf{R}^L : \|\zeta\|_{\infty} \leq 1\}$$

- Then the robust counterpart model can be written as follow

$$\min_x \{c^T x : a^T x \leq b \ \forall (a, b) \in U\}$$



Box uncertainty

- Further, the uncertainty-affected constraint can be written as

$$\begin{aligned} & [a_0 + \sum_{\ell=1}^L \zeta_{\ell} a_{\ell}]^T x \leq b_0 + \sum_{\ell=1}^L \zeta_{\ell} b_{\ell} \\ \Leftrightarrow & a_0^T x + \sum_{\ell=1}^L \zeta_{\ell} a_{\ell}^T x \leq b_0 + \sum_{\ell=1}^L \zeta_{\ell} b_{\ell} \\ \Leftrightarrow & \sum_{\ell=1}^L \zeta_{\ell} [a_{\ell}^T x - b_{\ell}] \leq b_0 - a_0^T x \\ \Leftrightarrow & \max_{\|\zeta\|_{\infty} \leq 1} \left\{ \sum_{\ell=1}^L \zeta_{\ell} [a_{\ell}^T x - b_{\ell}] \right\} \leq b_0 - a_0^T x \\ \Leftrightarrow & \sum_{\ell=1}^L |a_{\ell}^T x - b_{\ell}| \leq b_0 - a_0^T x \end{aligned}$$



$$\Leftrightarrow \begin{cases} -u_\ell \leq a^\top x - b_\ell \leq u_\ell, & \forall \ell = 1, \dots, L \\ a_0^\top x + \sum_{\ell=1}^L u_\ell \leq b_0 \end{cases}$$

- In this way, the tractable representation of robust counterpart model can be rewritten as a tractable representation.

$$\begin{aligned} \min \quad & c^\top x \\ \text{s.t.} \quad & -u_\ell \leq a^\top x - b_\ell \quad \forall \ell = 1, \dots, L \\ & a^\top x - b_\ell \leq u_\ell \quad \forall \ell = 1, \dots, L \\ & a_0^\top x + \sum_{\ell=1}^L u_\ell \leq b_0 \end{aligned}$$



Ball uncertainty

- Similar to the box uncertainty, but we consider a new perturbation set Z as follow where Ω is the radius.

$$Z = \{\zeta \in \mathbf{R}^L : \|\zeta\|_2 \leq \Omega\}$$

Further, the uncertainty-affected constraint can be written as

$$\begin{aligned} [a_0 + \sum_{\ell=1}^L \zeta_{\ell} a_{\ell}]^T x &\leq b_0 + \sum_{\ell=1}^L \zeta_{\ell} b_{\ell} \\ \Leftrightarrow \max_{\|\zeta\|_{\infty} \leq 1} \left\{ \sum_{\ell=1}^L \zeta_{\ell} [a_{\ell}^T x - b_{\ell}] \right\} &\leq b_0 - a_0^T x \\ \Leftrightarrow \Omega \sqrt{\sum_{\ell=1}^L (a_{\ell}^T x - b_{\ell})^2} &\leq b_0 - a_0^T x \end{aligned}$$



- In this way, the tractable representation of robust counterpart model can be rewritten as a tractable representation.

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & a_0^T x + \Omega \sqrt{\sum_{\ell=1}^L (a_{\ell}^T x - b_{\ell})^2} \leq b_0 \end{aligned}$$



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General Case

- Now consider a rather general case when the perturbation set Z is given by a conic representation

$$Z = \{\zeta \in \mathbf{R}^L : \exists u \in \mathbf{R}^K : P\zeta + Qu + p \in \mathbf{K}\}$$

- the uncertainty-affected constraint can be written as

$$\begin{aligned} [a_0 + \sum_{\ell=1}^L \zeta_{\ell} a_{\ell}]^T x &\leq b_0 + \sum_{\ell=1}^L \zeta_{\ell} b_{\ell} \\ \Leftrightarrow \max_{\zeta \in Z} \left\{ \sum_{\ell=1}^L \zeta_{\ell} [a_{\ell}^T x - b_{\ell}] \right\} &\leq b_0 - a_0^T x \end{aligned}$$

- x is feasible if and only if the optimal value in the conic program is $\leq b_0 - a_0^T x$

$$\max_{\zeta, u} \left\{ \sum_{\ell=1}^L \zeta_{\ell} [a_{\ell}^T x - b_{\ell}] : P\zeta + Qu + p \in \mathbf{K} \right\}$$



General Case

- The optimal value of the conic program is $\leq b_0 - a_0^T x$ if and only if the conic dual problem as follow is attained and is $\leq b_0 - a_0^T x$

$$\begin{aligned} \min \quad & p^T y \\ \text{s.t.} \quad & Q^T y = 0 \\ & (P^T y)_\ell = -[a_\ell^T x - b_\ell] \quad \forall \ell = 1, \dots, L \\ & y \in K_* \end{aligned}$$

- Then the tractable representation of the robust counterpart model is as follow

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & p^T y + a_0^T x \leq b_0 \\ & Q^T y = 0 \\ & (P^T y)_\ell + a_\ell^T x = b_\ell \quad \forall \ell = 1, \dots, L \\ & y \in K_* \end{aligned}$$



General Case

- Further, consider the perturbation set Z is a intersection of multiple cone conic as follow.

$$Z = \{\zeta : \exists u^1, \dots, u^S : P_s \zeta + Q_s + p_s \in K^s, s = 1, \dots, S\}$$

- The tractable representation of the robust counterpart model is as follow

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & \sum_{s=1}^S p_s^T y^s + a_0^T x \leq b_0 \\ & Q_s^T y^s = 0 \quad \forall s = 1, \dots, S \\ & \sum_{s=1}^S (P_s^T y^s)_\ell + a_\ell^T x = b_\ell \quad \forall \ell = 1, \dots, L \\ & y^s \in K_*^s, \forall s = 1, \dots, S \end{aligned}$$



Example - Budgeted Uncertainty

- Consider the case where perturbation set Z is the intersection of $\|\cdot\|_\infty$ and $\|\cdot\|_1$, specifically,

$$Z = \{\zeta \in \mathbf{R}^L : \|\zeta\|_\infty \leq 1, \|\zeta\|_1 \leq \gamma\}$$

where γ is a given "uncertainty budget".

- The perturbation set Z can be rewritten as

$$Z = \{\zeta \in \mathbf{R}^L : P_1\zeta + p_1 \in K^1, P_2\zeta + p_2 \in K^2\}$$

where

$$(1) P_1\zeta = [\zeta; 0], p_1 = [0_{L \times 1}; 1], K^1 = \{[u; t] \in \mathbf{R}^L \times \mathbf{R} : \|u\|_\infty \leq t\}$$

$$(1) P_2\zeta = [\zeta; 0], p_2 = [0_{L \times 1}; \gamma], K^2 = \{[u; t] \in \mathbf{R}^L \times \mathbf{R} : \|u\|_1 \leq t\}$$

- Further, $K_*^1 = \{[u; t] \in \mathbf{R}^L \times \mathbf{R} : \|u\|_1 \leq t\} = K^2$ and $K_*^2 = \{[u; t] \in \mathbf{R}^L \times \mathbf{R} : \|u\|_\infty \leq t\} = K^1$



Example - Budgeted Uncertainty

- Define the dual variable as $y^1 = [u; \tau_1]$ and $y^2 = [v; \tau_2]$ where $u, v \in \mathbf{R}^L$ and $\tau_1, \tau_2 \in \mathbf{R}$.
- From the conclusion of general case, we can write the tractable representation of the robust counterpart model as follow

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & \tau_1 + \gamma \tau_2 + a_0^T x \leq b_0 \\ & (u + v)_\ell = b_\ell - a_\ell^T x, \quad \forall \ell = 1, \dots, L \\ & \|u\|_1 \leq \tau_1 \\ & \|v\|_\infty \leq \tau_2 \end{aligned}$$



Example - Budgeted Uncertainty

- Further, the above model can be simplified by eliminating τ_1 and τ_2 .

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & \|u\|_1 + \gamma \|v\|_\infty + a_0^T x \leq b_0 \\ & (u + v)_\ell = b_\ell - a_\ell^T x, \quad \forall \ell = 1, \dots, L \end{aligned}$$



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Scalar Chance Constraints

- We consider a scalar chance constraints as follow

$$Prob_{\zeta \sim P} \left\{ \zeta : a_0^T x + \sum_{\ell=1}^L \zeta_{\ell} a_{\ell}^T x > b_0 + \sum_{\ell=1}^L \zeta_{\ell} b_{\ell} \right\} \leq \epsilon$$

- There is two assumption of the distribution of ζ as follow

- 1. $\zeta_{\ell}, \ell = 1, \dots, L$ are independent random variables;
- 2. The distribution P_{ℓ} of the components ζ_{ℓ} are such that

$$\int \exp\{t\zeta_{\ell}\} dP_{\ell}(\zeta_{\ell}) \leq \exp\{|\mu_{\ell}t| + \frac{1}{2}\sigma_{\ell}^2 t^2\} \quad \forall t \in R$$

with known constant $\mu_{\ell}^{-} \leq \mu_{\ell}^{+}$ and $\sigma_{\ell} \geq 0$

- For convenience, let z_0 denote $z_0 = a_0^T x - b_0$ and z_{ℓ} denote $a_{\ell}^T x - b_{\ell}$ for $\ell = 1, \dots, L$. Then, the chance constraints can be written as

$$p(z) = Prob_{\zeta \sim P} \left\{ \zeta : z_0 + \sum_{\ell=1}^L z_{\ell} \zeta_{\ell} > 0 \right\} \leq \epsilon$$



Scalar Chance Constraints

$$z_0 + \sum_{\ell=1}^L z_{\ell} \zeta_{\ell} > 0$$

$$\Leftrightarrow \exp\{\alpha[z_0 + \sum_{\ell=1}^L z_{\ell} \zeta_{\ell}]\} > 1 \quad \forall \alpha > 0$$

$$\Rightarrow \mathbf{E} \left\{ \exp\{\alpha[z_0 + \sum_{\ell=1}^L z_{\ell} \zeta_{\ell}]\} \right\} \geq p(z) \quad \forall \alpha > 0$$

$$\Rightarrow \exp\{\alpha z_0 + \sum_{\ell=1}^L [\alpha |\mu_{\ell} z_{\ell}| + \frac{\alpha^2}{2} \sigma_{\ell}^2 z_{\ell}^2]\} \geq p(z) \quad \forall \alpha > 0$$

$$\Leftrightarrow \alpha z_0 + \sum_{\ell=1}^L [\alpha |\mu_{\ell} z_{\ell}| + \frac{\alpha^2}{2} \sigma_{\ell}^2 z_{\ell}^2] \geq \ln(p(z)) \quad \forall \alpha > 0$$



Scalar Chance Constraints

- Therefore, we can say $p(z) \leq \epsilon$ if the following inequality holds

$$\exists \alpha : \alpha z_0 + \sum_{\ell=1}^L [\alpha |\mu_{\ell} z_{\ell}| + \frac{\alpha^2}{2} \sigma_{\ell}^2 z_{\ell}^2] \leq \ln(\epsilon)$$

- The left side of above is a quadratic function of α . Then the above inequality holds if and only if

$$z_0 + \sum_{\ell=1}^L |\mu_{\ell} z_{\ell}| + \sqrt{2 \ln(1/\epsilon)} \sqrt{\sum_{\ell=1}^L \sigma_{\ell}^2 z_{\ell}^2} \leq 0$$

- In this way, we get a robust counterpart approximations of the chance constraints as above.



Scalar Chance Constraints - The interpretation

- Now, we consider a simple distribution as follow

$$\begin{aligned}\mathbf{E}\{\zeta_\ell\} &= 0 \\ |\zeta_\ell| &\leq 1 \quad \forall \ell = 1, \dots, L \\ \{\zeta_\ell\} &\text{ are independent.}\end{aligned}$$

- Then, the robust counterpart approximations can be written as follow which is equivalent to the ball uncertainty.

$$z_0 + \sqrt{2 \ln(1/\epsilon)} \sqrt{\sum_{\ell=1}^L \sigma_\ell^2 z_\ell^2} \leq 0$$

- Further, we can have the follow inequality

$$\text{Std}\left(\sum_{\ell=1}^L z_\ell \zeta_\ell\right) = \sqrt{\sum_{\ell=1}^L \sigma_\ell^2 z_\ell^2}$$

- The above approximation holds since

$$\text{Prob}\left\{\zeta : \sum_{\ell=1}^L z_\ell \zeta_\ell > \sqrt{2 \ln(1/\epsilon)} \sqrt{\sum_{\ell=1}^L \sigma_\ell^2 z_\ell^2}\right\} \leq \epsilon$$



Another Approximation - Budgeted Uncertainty

- In the “General case”, we get a robust corresponding constraints for budgetary uncertainty as follow.

$$\|u\|_1 + \gamma\|v\|_\infty + a_0^T x \leq b_0 \quad (1)$$

$$(u + v)_\ell = b_\ell - a_\ell^T x, \quad \forall \ell = 1, \dots, L \quad (2)$$

- Then, we can prove the above satisfy $p(z) \leq \exp(\frac{-\gamma^2}{2L})$.
- Firstly, we should have $\|v\|_2 \leq \sqrt{L}\|v\|_\infty$ from the follow inequality

$$\|v\|_2^2 = \sum_{\ell=1}^L v_\ell^2 \leq \sum_{\ell=1}^L |v_\ell| \|v\|_\infty \leq \sqrt{L} \|v\|_2 \|v\|_\infty$$



Another Approximation - Budgeted Uncertainty

Proof:

$$\sum_{\ell=1}^L \zeta_{\ell} [a_{\ell}^T x - b_{\ell}] > b_0 - a_0^T x$$

$$\Rightarrow - \sum_{\ell=1}^L u_{\ell} \zeta_{\ell} - \sum_{\ell=1}^L v_{\ell} \zeta_{\ell} > b_0 - a_0^T x \quad (\text{from (2)})$$

$$\Rightarrow \|u\|_1 - \sum_{\ell=1}^L v_{\ell} \zeta_{\ell} > b_0 - a_0^T x$$

$$\Rightarrow - \sum_{\ell=1}^L v_{\ell} \zeta_{\ell} > b_0 - a_0^T x - \|u\|_1 \geq \gamma \|v\|_{\infty} \quad (\text{from (1)})$$

$$\Rightarrow - \sum_{\ell=1}^L v_{\ell} \zeta_{\ell} > \frac{\gamma}{\sqrt{L}} \|v\|_2 \Rightarrow \text{Prob}\{z_0 + \sum_{\ell=1}^L z_{\ell} \zeta_{\ell} > 0\} \leq \exp\left(\frac{-\gamma^2}{2L}\right)$$



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A Single-Period Portfolio Selection

- There are 200 assets. The 200th Asset has yearly return $r_{200} = 1.05$ and zero variability.
- The yearly returns r_ℓ , $i = 1, \dots, 199$ of the remaining assets are independent random variables taking values in $[\mu_\ell - \sigma_\ell, \mu_\ell + \sigma_\ell]$ where

$$\mu_\ell = 1.05 + 0.3 \frac{(200-i)}{199} \quad \text{and} \quad \sigma_\ell = 0.05 + 0.06 \frac{(200-i)}{199}$$

- We want to solve the uncertain LO problem as follow.

$$\begin{aligned} \max_{\mathbf{x}, R} \quad & R \\ \text{s.t.} \quad & \sum_{\ell=1}^{199} r_\ell x_\ell + r_{200} x_{200} \geq R \\ & \sum_{\ell=1}^{200} x_\ell = 1 \\ & \mathbf{x} \succeq 0 \end{aligned}$$

- The uncertain data are $r_\ell = \mu_\ell + \sigma_\ell \zeta_\ell$, $\forall \ell = 1, \dots, 199$



Robust Counterpart Model

- The box RC is as follow:

$$\max_{x,R} \left\{ R : \begin{array}{l} \sum_{\ell=1}^{199} (\mu_{\ell} - \sigma_{\ell}) x_{\ell} + r_{200} x_{200} \geq R \\ \sum_{\ell=1}^{200} x_{\ell} = 1 \\ \sum_{\ell=1}^{200} x_{\ell} = 1 \quad \mathbf{x} \succeq 0 \end{array} \right\}$$

- The ball RC is as follow:

$$\max_{x,R,z,w} \left\{ R : \begin{array}{l} \sum_{\ell=1}^{199} \mu_{\ell} x_{\ell} + r_{200} x_{200} - \|z\|_1 - \Omega \sqrt{\sum_{\ell=1}^L w_{\ell}^2} \geq R \\ z_{\ell} + w_{\ell} = \sigma_{\ell} x_{\ell} \quad \forall \ell = 1, \dots, 199 \\ \sum_{\ell=1}^{200} x_{\ell} = 1 \quad \mathbf{x} \succeq 0 \end{array} \right\}$$

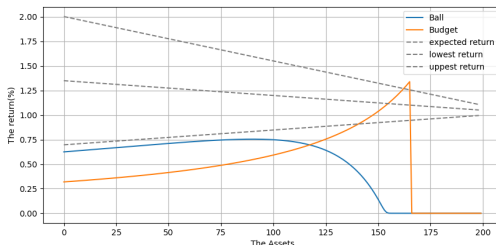
- The budgeted RC is as follow:

$$\max_{x,R,z,w} \left\{ R : \begin{array}{l} \sum_{\ell=1}^{199} \mu_{\ell} x_{\ell} + r_{200} x_{200} - \|z\|_1 - \gamma \|w\|_{\infty} \geq R \\ z_{\ell} + w_{\ell} = \sigma_{\ell} x_{\ell} \quad \forall \ell = 1, \dots, 199 \\ \sum_{\ell=1}^{200} x_{\ell} = 1 \quad \mathbf{x} \succeq 0 \end{array} \right\}$$



Performance

- Take $\epsilon = 0.005$, then the corresponding $\Omega = 3.255$ and $\gamma = 45.921$.
- The solution of box is $x_{200} = 1$ and $x_\ell = 0$ for all $\ell = 1, \dots, 199$. The solution of "ball RC" and "budget RC" is shown as follow. And $R_{box} = 1.05$, $R_{ball} = 1.12$ and $R_{budget} = 1.10$
- The solutions are robust since the failure times of three model in 10^6 simulations are 0.



Conservatism	$Box > Budget > Ball$
Risk	$Ball = Budget > Box$
Return	$Ball > Budget > Box$



Thanks!

