# assignment

## February 26, 2023

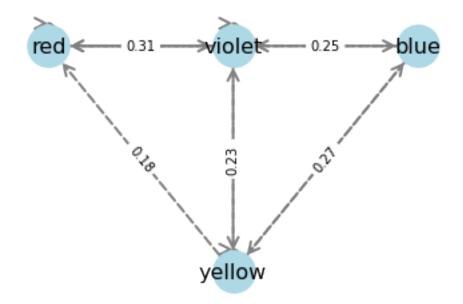
## Question 1

```
[15]: # 7-digit student ID
      student_id = 3076654
      # random digit to append
      random_digit = 8
      # Concatenate the student ID and the random digit to form an 8-digit number
      number = str(student_id) + str(random_digit)
      print ("The number is :" + str(number))
      # Calculate the probabilities
      p1 = int(number[:2]) / 100
      print(number[:2])
      p2 = int(number[2:4]) / 100
      print(number[2:4])
      p3 = int(number[4:6]) / 100
      print(number[4:6])
      p4 = int(number[6:]) / 100
      print(number[6:])
      # Print the probabilities
      print(f"p1 = {p1:.2f}")
      print(f"p2 = \{p2:.2f\}")
      print(f"p3 = {p3:.2f}")
      print(f"p4 = {p4:.2f}")
```

```
The number is :30766548
30
76
65
48
p1 = 0.30
p2 = 0.76
p3 = 0.65
p4 = 0.48
```

#### 2 A

```
[16]: import networkx as nx
      import matplotlib.pyplot as plt
      # Create a directed graph to represent the state space
      G = nx.DiGraph()
      # Add nodes to the graph
      G.add_nodes_from(['red', 'violet', 'blue', 'yellow'])
      # Add edges to the graph with their transition probabilities
      G.add edge('red', 'red', weight=0.24)
      G.add_edge('red', 'violet', weight=0.32)
      G.add edge('red', 'blue', weight=0.26)
      G.add_edge('violet', 'red', weight=0.31)
      G.add_edge('violet', 'violet', weight=0.26)
      G.add_edge('violet', 'yellow', weight=0.24)
      G.add_edge('blue', 'violet', weight=0.25)
      G.add_edge('blue', 'red', weight=0.20)
      G.add_edge('blue', 'yellow', weight=0.25)
      G.add_edge('yellow', 'red', weight=0.18)
      G.add_edge('yellow', 'violet', weight=0.23)
      G.add_edge('yellow', 'blue', weight=0.27)
      G.add_edge('yellow', 'yellow', weight=0.32)
      # Set the positions of the nodes for plotting
      pos = {'red': (0, 1), 'violet': (1, 1), 'blue': (2, 1), 'yellow': (1, 0)}
      # Draw the graph with labels and edge weights
      nx.draw_networkx(G, pos, with_labels=True, node_color='lightblue',
                       node_size=1000, font_size=16, width=2, arrowstyle='->',
                       arrowsize=20, edge_color='grey', style='dashed')
      nx.draw_networkx_edge_labels(G, pos, edge_labels=nx.get_edge_attributes(G,__
       # Show the plot
      plt.axis('off')
      plt.show()
```



## 2 B

```
[17]: import numpy as np
      # Create the 4x4 transition matrix
      transition_matrix = np.array([[0.24, 0.32, 0.26, 0],
                                    [0.31, 0.26, 0, 0.24],
                                    [0.2, 0.25, 0, 0.25],
                                    [0.18, 0.23, 0.27, 0.32]])
      \# Calculate the 2-step transition matrix
      two_step_matrix = np.linalg.matrix_power(transition_matrix, 2)
      \# Calculate the 4-step transition matrix
      four_step_matrix = np.linalg.matrix_power(transition_matrix, 4)
      # Print the transition matrices
      print("2-step transition matrix:")
      print(two_step_matrix)
      print("4-step transition matrix:")
      print(four_step_matrix)
     2-step transition matrix:
     [[0.2088 0.225 0.0624 0.1418]
      [0.1982 0.222 0.1454 0.1392]
      [0.1705 0.1865 0.1195 0.14 ]
```

[0.2261 0.2585 0.1332 0.2251]]

```
4-step transition matrix:

[[0.13089262 0.1452229 0.07208868 0.10158302]

[0.14164838 0.1569793 0.08056322 0.11069708]

[0.12459345 0.13824225 0.07068455 0.0983817 ]

[0.17205009 0.19128965 0.09759526 0.13736219]]
```

2 C

Final distribution of colors after 5 generations: [0.10105873 0.11008555 0.09708716 0.13454425]

2 D

```
# Print the stationary distribution
      print("Stationary distribution of colors:")
      print(stationary_distribution)
     Stationary distribution of colors:
     [0.2891061 0.32083113 0.16287137 0.22719141]
     3 A
[33]: import numpy as np
      # Define the transition probability matrix
      P = np.array([[0.2, 0.1, 0.15, 0, 0.55],
                    [0, 1, 0, 0, 0],
                    [0.35, 0.2, 0.2, 0.1, 0.15],
                    [0, 0, 0, 1, 0],
                    [0.25, 0.2, 0.15, 0.25, 0.15])
      # Identify the absorbing and transient states
      absorbing_states = []
      transient_states = []
      for i in range(len(P)):
          if P[i,i] == 1:
              absorbing_states.append(i)
          else:
              transient_states.append(i)
      \# Separate the matrix into Q and R
      Q = P[np.ix_(transient_states, transient_states)]
      R = P[np.ix (transient states, absorbing states)]
      \# Print the matrices Q and R
      print("Q = \n", Q)
      print("R = \n", R)
     Q =
      [[0.2 0.15 0.55]
      [0.35 0.2 0.15]
      [0.25 0.15 0.15]]
     R. =
      [[0.1 0.]
      [0.2 0.1]
      [0.2 0.25]]
     3 B
[34]: import numpy as np
```

```
# Define the transition probability matrix
P = np.array([[0.2, 0.1, 0.15, 0.0, 0.55],
               [0.0, 1.0, 0.0, 0.0, 0.0],
               [0.35, 0.2, 0.2, 0.1, 0.15],
               [0.0, 0.0, 0.0, 1.0, 0.0],
               [0.25, 0.2, 0.15, 0.25, 0.15])
# Identify the transient states
transient_states = [0, 2, 4]
# Compute the fundamental matrix
N = np.linalg.inv(np.eye(len(transient_states)) - P[np.ix_(transient_states,_
 →transient states)])
# Compute the mean number of times in each transient state, given starting in
 ⇔each state
for i in range(len(transient_states)):
    mean_num_transitions = np.zeros(len(transient_states))
    for j in range(len(transient_states)):
        if N[j].sum() == 0:
            mean_num_transitions[j] = 0
        else:
            mean_num_transitions[j] = N[j][i] / N[j].sum()
    print(f'State {transient_states[i]+1}: {mean_num_transitions}')
State 1: [0.4943609 0.28151261 0.25313283]
State 3: [0.15789474 0.45588235 0.15789474]
State 5: [0.34774436 0.26260504 0.58897243]
3C
```

```
# Compute the mean number of transitions from each transient state to and absorbing state

for i in range(len(transient_states)):
    mean_num_transitions = np.zeros(len(absorbing_states))
    for j in range(len(absorbing_states)):
        mean_num_transitions[j] = N[i][j + len(transient_states)] / N[i].sum()
    print(f'State {transient_states[i]}: {mean_num_transitions.mean()}')
```

3D

```
[]: import numpy as np
     # Define the transition probability matrix
     P = np.array([[0.4, 0.3, 0.3, 0.0],
                   [0.0, 0.2, 0.5, 0.3],
                   [0.2, 0.0, 0.3, 0.5],
                   [0.0, 0.0, 0.0, 1.0]
     # Find the indices of the transient and absorbing states
     transient_states = np.where(np.diag(P) == 0)[0]
     absorbing_states = np.where(np.diag(P) == 1)[0]
     # Compute the fundamental matrix
     N = np.linalg.inv(np.eye(len(transient_states)) - P[np.ix_(transient_states,__
      ⇔transient_states)])
     # Find the probability of ending in each absorbing state
     for i in range(len(transient_states)):
         prob_end_absorbing = N[i, np.ix_(absorbing_states)]
         print(f'State {transient_states[i]}: {prob_end_absorbing}')
```

### 4 A

```
[]: import numpy as np
import matplotlib.pyplot as plt

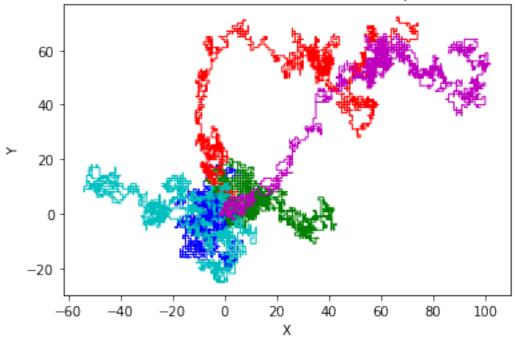
# Set the parameters of the random walk
p1, p2, p3, p4 = 0.25, 0.25, 0.25, 0.25
num_steps = 2500
num_walks = 5

# Create an array to store the positions of each random walk
positions = np.zeros((num_walks, num_steps, 2))

# Simulate the random walks
for i in range(num_walks):
    position = np.array([0, 0])
    for j in range(num_steps):
```

```
# Generate a random number to determine the direction of the next step
        rand = np.random.rand()
        if rand < p1:</pre>
            position += np.array([0, 1])
        elif rand < p1 + p2:
            position += np.array([0, -1])
        elif rand < p1 + p2 + p3:
            position += np.array([1, 0])
        else:
            position += np.array([-1, 0])
        positions[i, j] = position
# Plot the random walks
colors = ['b', 'g', 'r', 'c', 'm']
for i in range(num_walks):
    plt.plot(positions[i,:,0], positions[i,:,1], color=colors[i], linewidth=1)
plt.title(f'{num_walks} Random Walks with {num_steps} Steps')
plt.xlabel('X')
plt.ylabel('Y')
plt.show()
```

## 5 Random Walks with 2500 Steps



```
[]: import numpy as np
     # Get the input from the user
     num_steps = int(input("Enter the number of steps: "))
     p1, p2, p3, p4 = map(float, input("Enter the probabilities of moving in each ⊔

→direction (separated by spaces): ").split())
     num_walks = int(input("Enter the number of walks: "))
     # Create an array to store the positions of each random walk
     positions = np.zeros((num_walks, num_steps, 2))
     # Simulate the random walks
     for i in range(num_walks):
         position = np.array([0, 0])
         for j in range(num_steps):
             # Generate a random number to determine the direction of the next step
             rand = np.random.rand()
             if rand < p1:</pre>
                 position += np.array([0, 1])
             elif rand < p1 + p2:
                 position += np.array([0, -1])
             elif rand < p1 + p2 + p3:
                 position += np.array([1, 0])
             else:
                 position += np.array([-1, 0])
             positions[i, j] = position
     # Compute the distances of each random walk from the starting point
     distances = np.sqrt(np.sum(positions**2, axis=2))
     # Compute the average distance over all random walks
     expected_length = np.mean(distances[:, -1])
     print(f"Expected length of the walk after {num_steps} steps: {expected_length:.
      Enter the number of steps: 2500
    Enter the probabilities of moving in each direction (separated by spaces): 0.25
    0.25 0.25 0.25
    Enter the number of walks: 10000
    Expected length of the walk after 2500 steps: 44.36
[]: import numpy as np
     # Define parameters
     a = 0.5
```

```
b = 1.0
T = 1.0
N = 2500
dt = T/N
# Generate Wiener process
dW = np.sqrt(dt) * np.random.normal(size=N)
# Initialise arrays for S and t
S = np.zeros(N+1)
t = np.linspace(0, T, N+1)
# Set initial condition
S[0] = 0
# Simulate the random walk
for i in range(N):
    S[i+1] = S[i] + a*dt + b*dW[i]
# Estimate expected value
mean_S = np.mean(S)
print("Expected value of S after 2500 steps: ", mean_S)
```

Expected value of S after 2500 steps: 0.04056246901183116

6

```
[]: import random import math

# Define the radius of the circle r = 1.0

# Define the number of points to generate in each chain num_points = 10**6

# Define the burn-in period for each chain burn_in = 1000

# Define a function to calculate the distance between two points def distance(x1, y1, x2, y2): return math.sqrt((x1 - x2)**2 + (y1 - y2)**2)

# Generate 5 Markov Chains for chain in range(5):

# Initialize counters for the number of points within the circle and totalunumber of points
```

```
count_in_circle = 0
  count_total = 0
  # Run the chain for a large number of steps
  for step in range(num_points + burn_in):
       # Randomly select a point within the square
      x = random.uniform(-1, 1)
      y = random.uniform(-1, 1)
       # Calculate the distance between the selected point and the center of \Box
⇔the circle
      d = distance(x, y, 0, 0)
       # Check if the point is within the circle
      if d <= r:</pre>
           count_in_circle += 1
       # Increment the total number of points
      count total += 1
       # Calculate the estimate of pi/4 after the burn-in period
      if step == burn_in + num_points - 1:
           pi_estimate = 4 * count_in_circle / count_total
           print(f"Chain {chain + 1}: {pi_estimate}")
```

Chain 1: 3.1415704295704296 Chain 2: 3.141842157842158 Chain 3: 3.1452987012987013 Chain 4: 3.141838161838162 Chain 5: 3.1433886113886116

```
[]: import random
import math
import numpy as np

# Define the radius of the circle
r = 1.0

# Define the number of points to generate in each chain
num_points = 10**6

# Define the burn-in period for each chain
burn_in = 1000

# Define a function to calculate the distance between two points
def distance(x1, y1, x2, y2):
    return math.sqrt((x1 - x2)**2 + (y1 - y2)**2)
```

```
# Initialize a list to store the estimates of pi for each chain
pi_estimates = []
# Generate 5 Markov Chains
for chain in range(5):
    # Initialize counters for the number of points within the circle and total \Box
 ⇔number of points
    count_in_circle = 0
    count_total = 0
    # Initialize a list to store the estimates of pi for each step after the
 ⇔burn-in period
    pi_steps = []
    # Run the chain for a large number of steps
    for step in range(num_points + burn_in):
        # Randomly select a point within the square
        x = random.uniform(-1, 1)
        y = random.uniform(-1, 1)
        # Calculate the distance between the selected point and the center of \Box
 ⇔the circle
        d = distance(x, y, 0, 0)
        # Check if the point is within the circle
        if d <= r:
            count_in_circle += 1
        # Increment the total number of points
        count_total += 1
        # Calculate the estimate of pi/4 after the burn-in period
        if step >= burn_in:
            pi_estimate = 4 * count_in_circle / count_total
            pi_steps.append(pi_estimate)
    # Save the list of estimates of pi for this chain
    pi_estimates.append(pi_steps)
# Calculate the within-chain variance and correlation for each chain
for chain in range(5):
    var_within = np.var(pi_estimates[chain])
    corr_within = np.corrcoef(pi_estimates[chain][:-1], pi_estimates[chain][1:
 →])[0, 1]
    print(f"Chain {chain + 1}: within-chain variance = {var_within:.4f}, ___
 ⇔within-chain correlation = {corr_within:.4f}")
```

```
Chain 1: within-chain variance = 0.0000, within-chain correlation = 0.9998 Chain 2: within-chain variance = 0.0000, within-chain correlation = 0.9999 Chain 3: within-chain variance = 0.0000, within-chain correlation = 0.9999 Chain 4: within-chain variance = 0.0000, within-chain correlation = 0.9998 Chain 5: within-chain variance = 0.0000, within-chain correlation = 0.9997 Between-chain variance = 0.0000, between-chain correlation = -0.1352
```