

Almost Event-Rate Independent Monitoring of Metric Dynamic Logic

David Basin



Srđan Krstić



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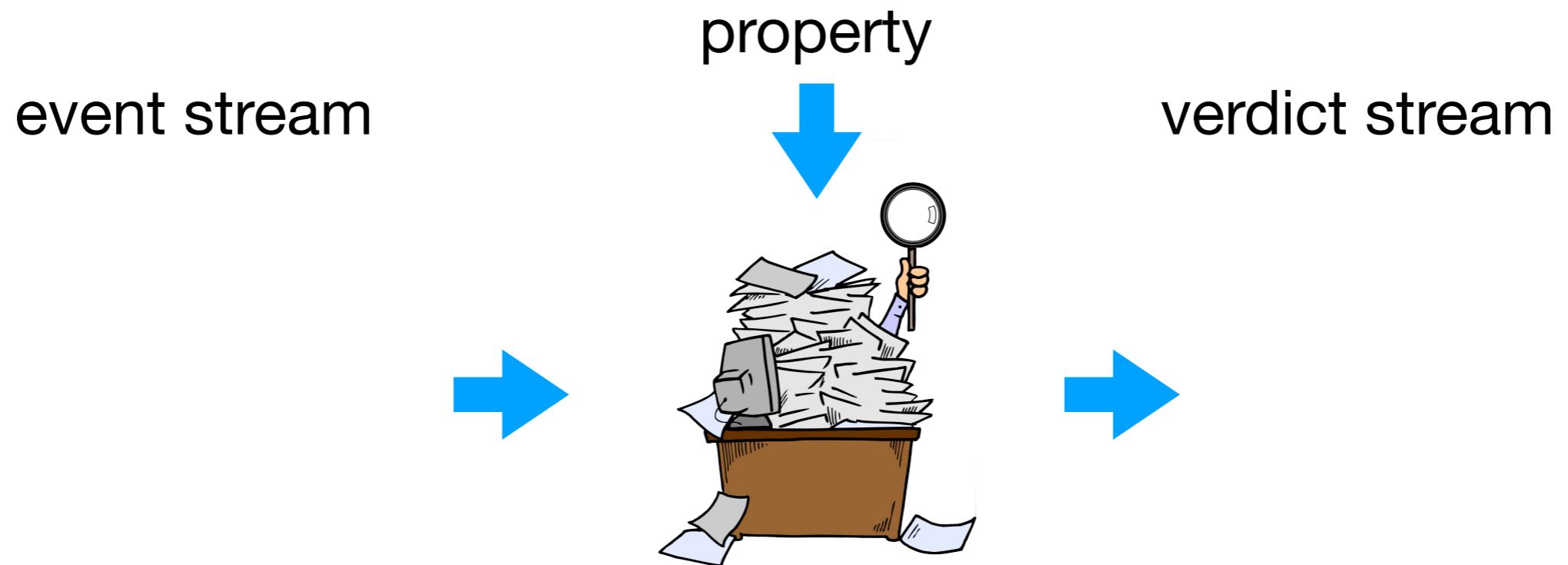
ETH zürich



Big Data
National Research Programme

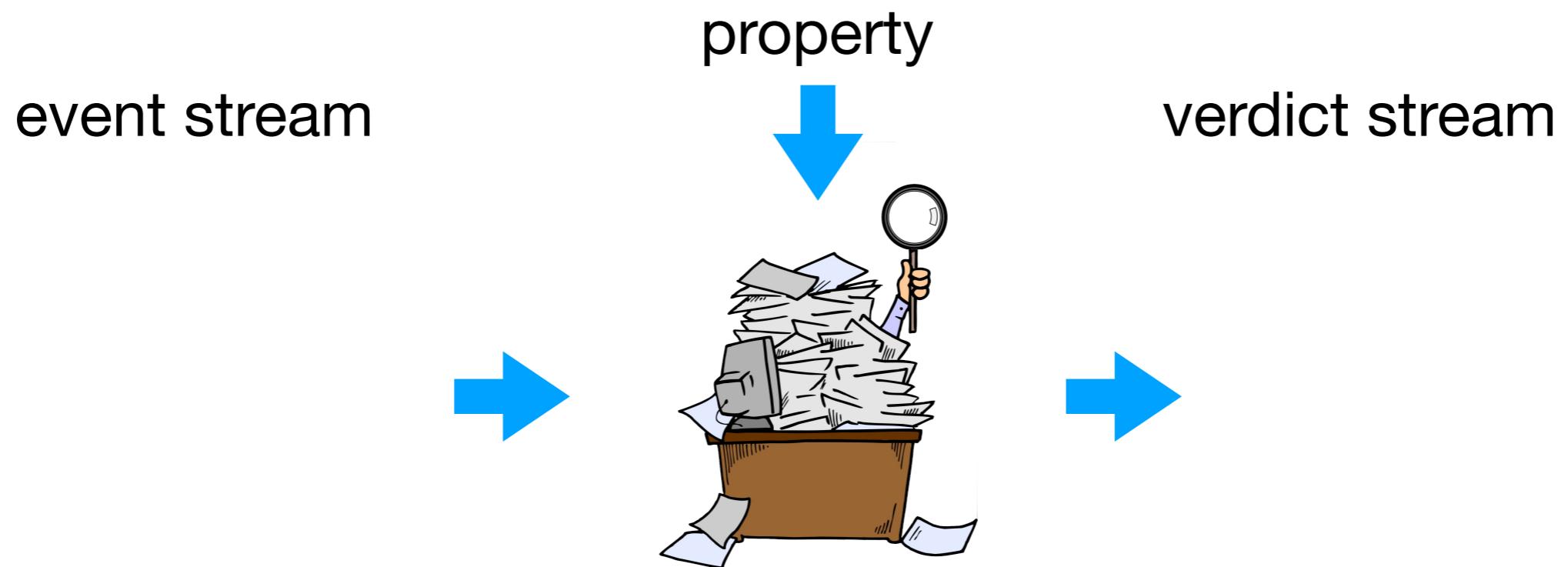
Setting

Online Monitoring Problem



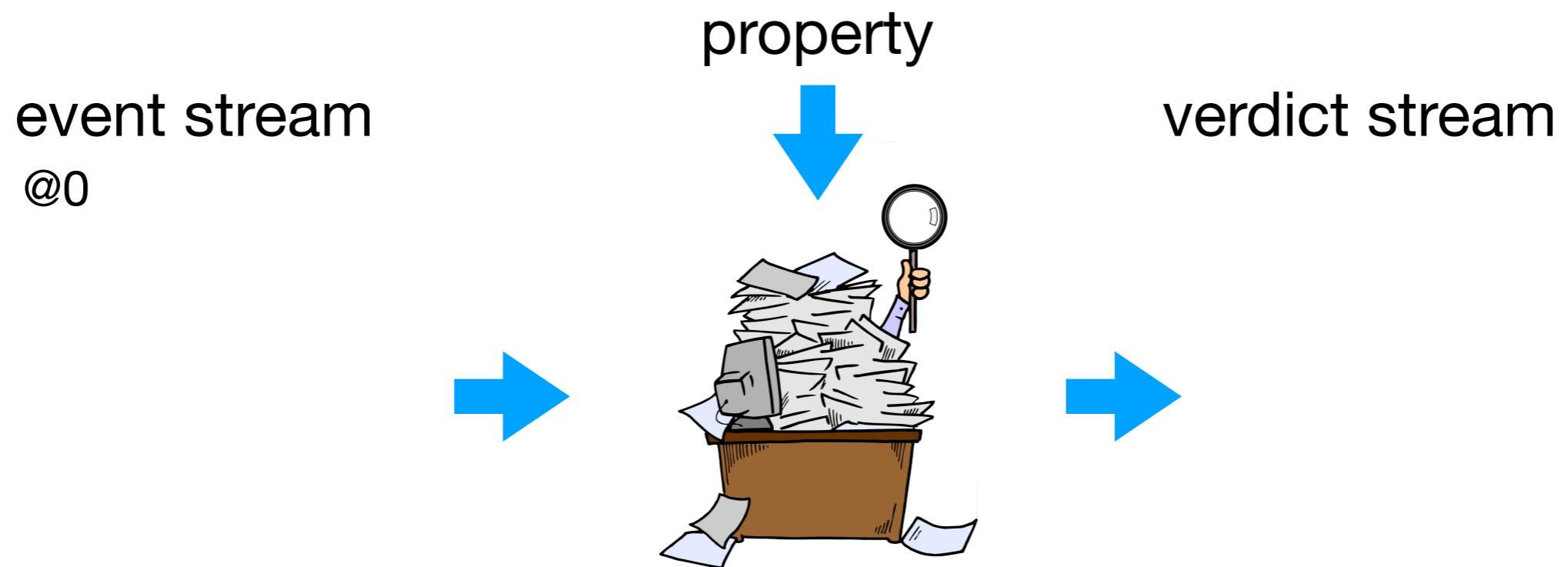
Online Monitoring Problem

within the next 2 time-units both
“enter” and “exit” must happen and
“enter” must happen before “exit”.



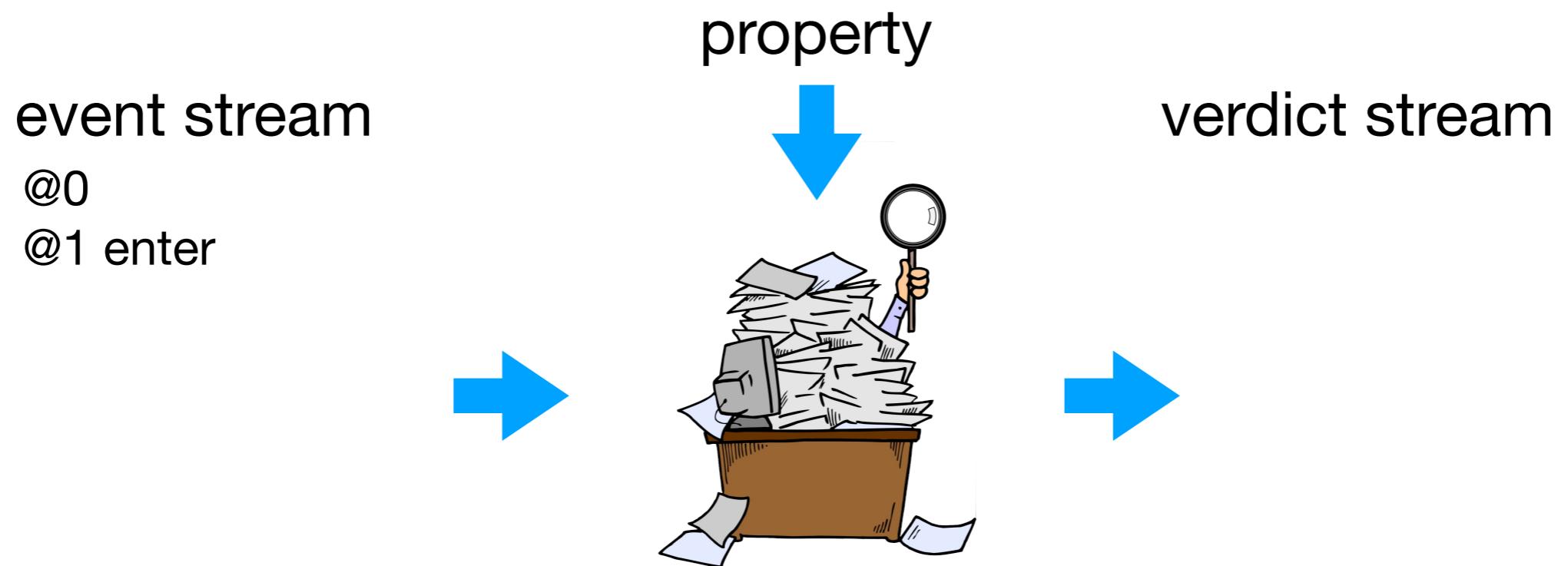
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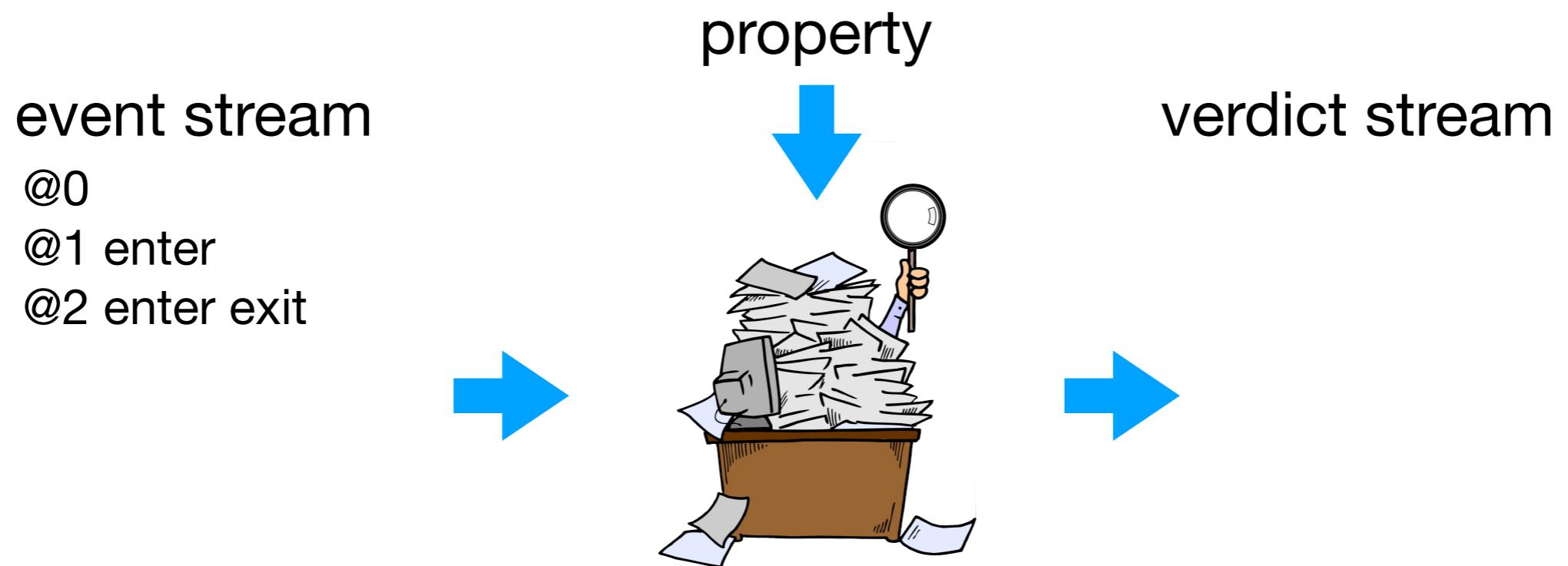
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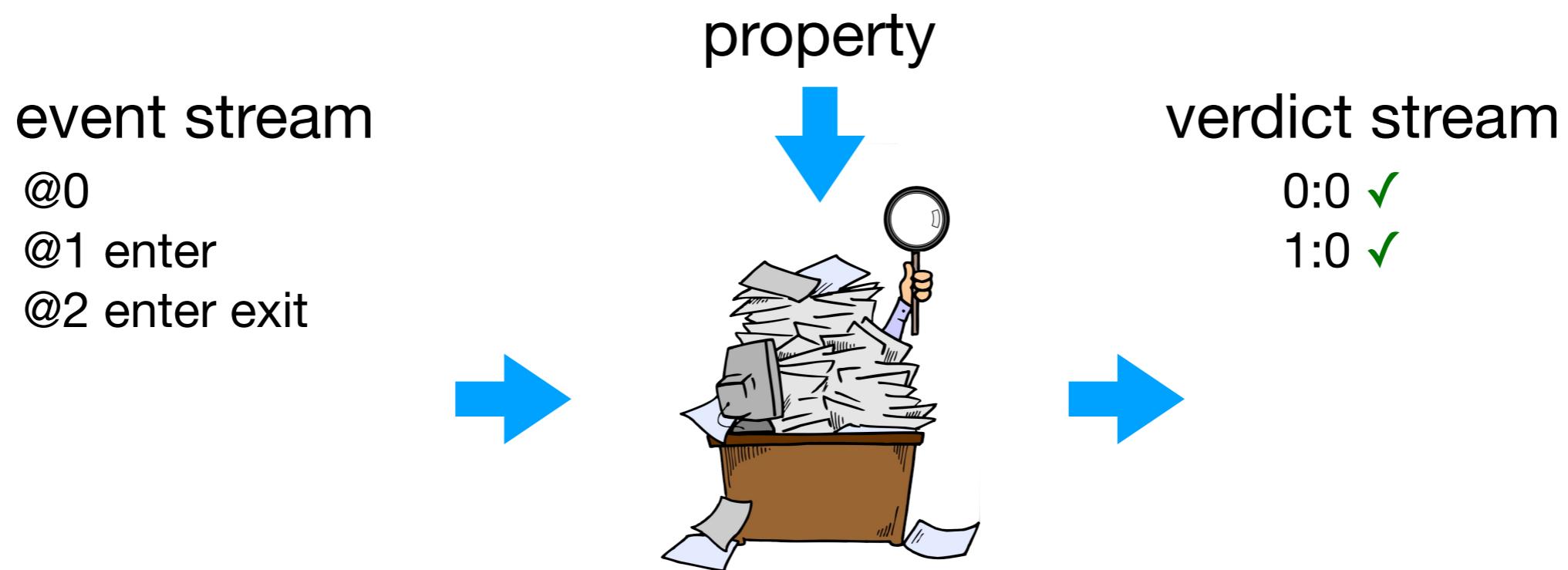
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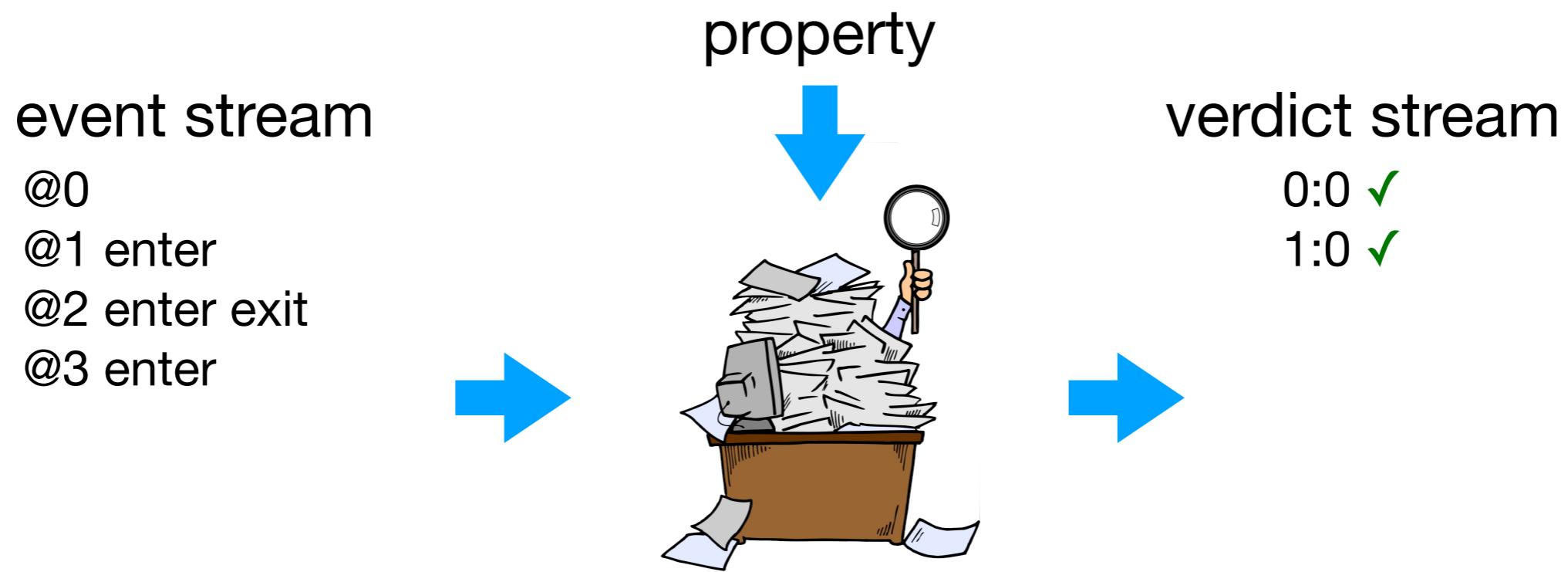
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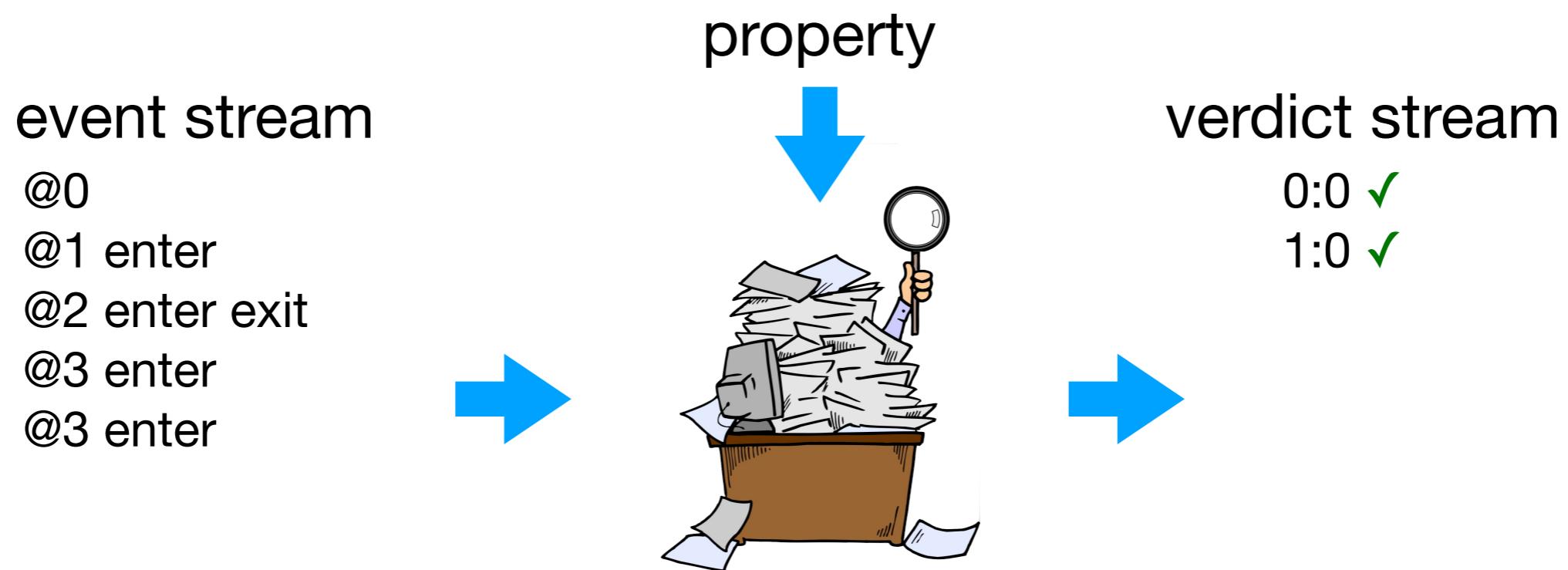
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Online Monitoring Problem

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event stream

@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter

property



verdict stream

0:0 ✓
1:0 ✓

Online Monitoring Problem

within the next 2 time-units both
“enter” and “exit” must happen and
“enter” must happen before “exit”.

event stream

@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

property

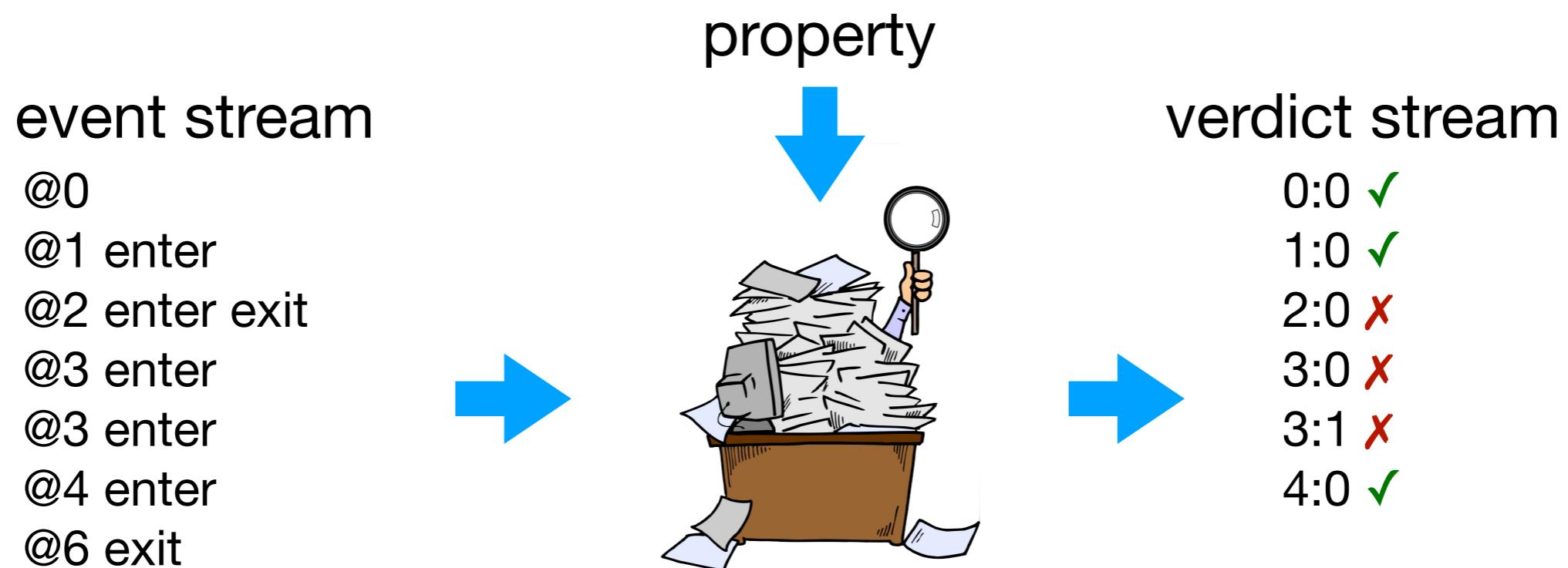


verdict stream

0:0 ✓
1:0 ✓

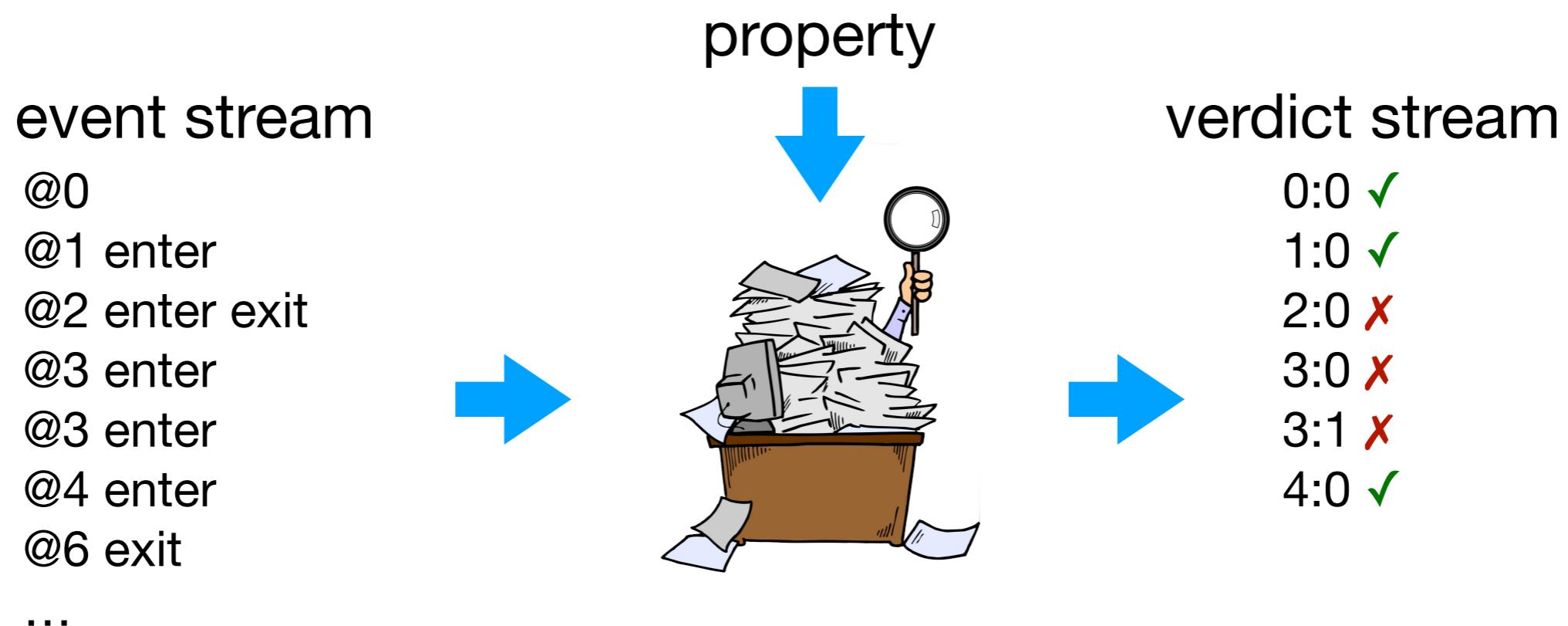
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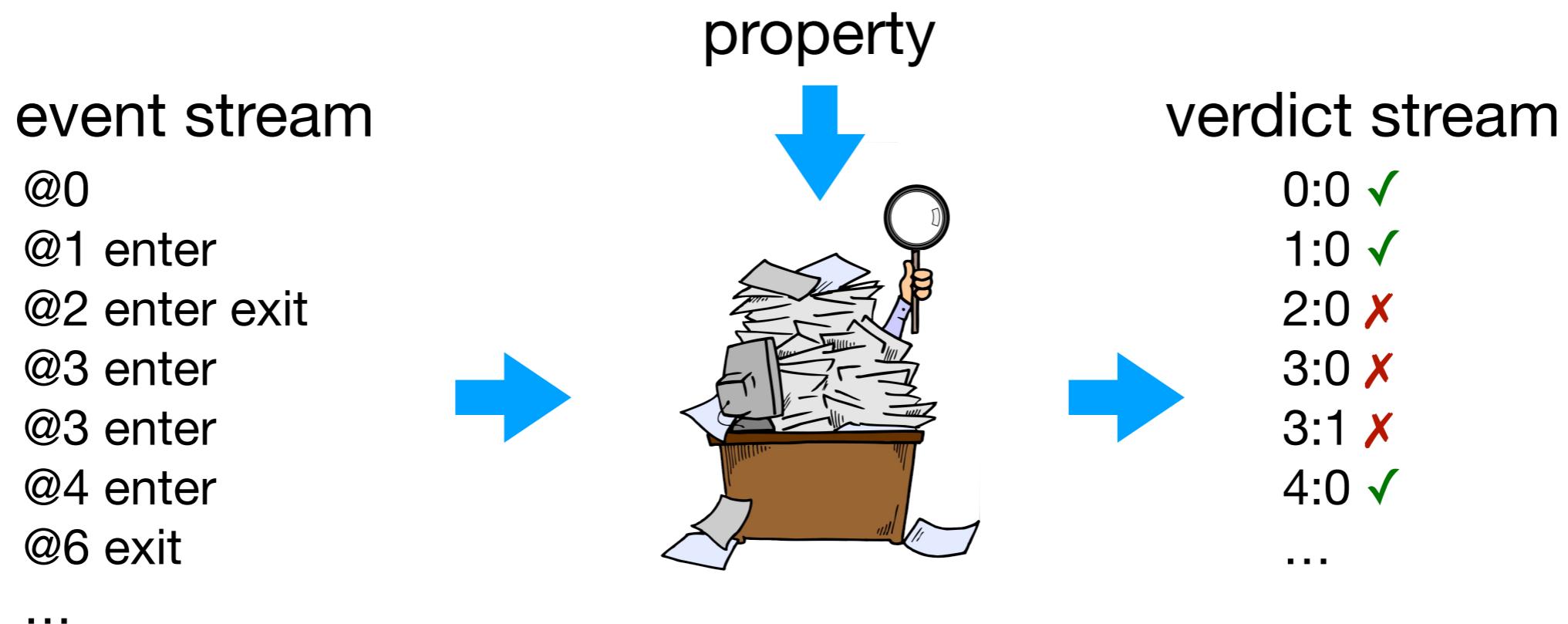
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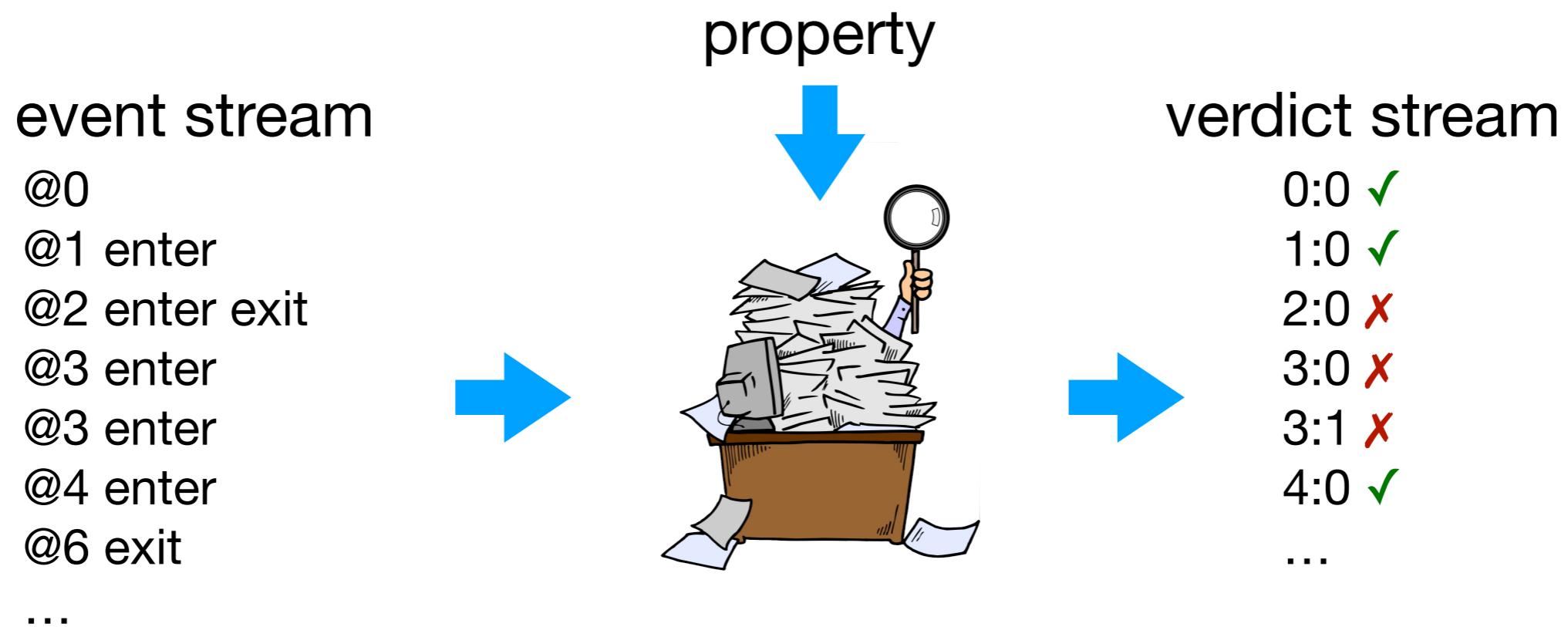
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Online Monitoring Problem

within the next 2 time-units both
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“enter” must happen before “exit”.



unlike in CRV: online \neq instrumentation

Monitoring Output

Monitoring Output

within the next 2 time-units both
“enter” and “exit” must happen and
“enter” must happen before “exit”.

@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit
...



0:0 ✓
1:0 ✓
2:0 ✗
3:0 ✗
3:1 ✗
4:0 ✓
...

Monitoring Output

ALWAYS

within the next 2 time-units both
“enter” and “exit” must happen and
“enter” must happen before “exit”.

@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...



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@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...



0:0 ✓
1:0 ✓
2:0 ✗
3:0 ✗
3:1 ✗
4:0 ✓

...

Monitoring Output

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within the next 2 time-units both
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@0
@1 enter
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@3 enter
@3 enter
@4 enter
@6 exit

...

MARQ 



within the next 2 time-units both
“enter” and “exit” must happen and
“enter” must happen before “exit”.

@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...

 MONPOLY

0:0 ✓
1:0 ✓
2:0 ✗
3:0 ✗
3:1 ✗
4:0 ✓

...

Monitoring Output

ALWAYS

within the next 2 time-units both
“enter” and “exit” must happen and
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@0
@1 enter
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@3 enter
@3 enter
@4 enter
@6 exit

...

MARQ 





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@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...

 MONPOLY

0:0 ✓
1:0 ✓
2:0 ✗
3:0 ✗
3:1 ✗
4:0 ✓

...

Monitoring Output

ALWAYS

within the next 2 time-units both
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@0
@1 enter
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@3 enter
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...

MARQ 





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@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...



 MONPOLY

0:0 ✓
1:0 ✓
2:0 ✗
3:0 ✗
3:1 ✗
4:0 ✓

...

Monitoring Output

ALWAYS

within the next 2 time-units both
“enter” and “exit” must happen and
“enter” must happen before “exit”.

@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...

MARQ 





within the next 2 time-units both

“e
“e

number unbounded
potentially equal to event-rate

@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...



 MONPOLY

0:0 ✓
1:0 ✓
2:0 ✗
3:0 ✗
3:1 ✗
4:0 ✓

...

Monitoring Output

ALWAYS

within the next 2 time-units both
“enter” and “exit” must happen and
“enter” must happen before “exit”.

@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...



within the next 2 time-units both
“enter” and “exit” must happen and
“enter” must happen before “exit”.

number unbounded
potentially equal to event-rate

@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit

...



0:0 ✓	0:0 ✓
1:0 ✓	1:0 ✓
3:1 = 3:0	2:0 ✗
2:0 ✗	3:0 ✗
3:0 ✗	3:1 ✗
4:0 ✓	4:0 ✓
...	...

Monitoring Output

ALWAYS

within the next 2 time-units both
“enter” and “exit” must happen
“enter” must happen

number bounded
independent from event-rate

@0
@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit
...

MARQ 



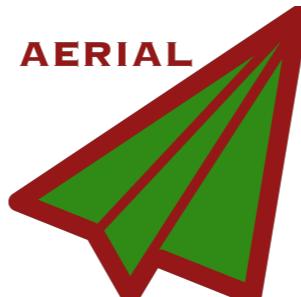




within the next 2 time-units both
“enter” and “exit” must happen
“enter” must happen

number unbounded
potentially equal to event-rate

@1 enter
@2 enter exit
@3 enter
@3 enter
@4 enter
@6 exit
...



 MONPOLY

0:0	✓	0:0	✓
1:0	✓	1:0	✓
3:1 = 3:0		2:0	✗
2:0	✗	3:0	✗
3:0	✗	3:1	✗
4:0	✓	4:0	✓
...		...	

Monitoring Output

ALWAYS

within the next 2 time-units both
“enter” and “exit” must happen
“enter” must happen

number bounded
independent from event-rate

@0
@1 enter
@2 enter exit
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@6 exit

...

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@1 enter
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@3 enter
@3 enter
@4 enter
@6 exit

...



MARQ



X



AERIAL

index depends
logarithmically
on event-rate

0:0 ✓	0:0 ✓
1:0 ✓	1:0 ✓
3:1 = 3:0	2:0 X
2:0 X	3:0 X
3:0 X	3:1 X
4:0 ✓	4:0 ✓
...	...

MONPOLY

Monitoring Output

ALWAYS

within the next 2 time-units both
“enter” and “exit” must happen
“enter” must happen

number bounded
independent from event-rate

@0
@1 enter
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@3 enter
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number unbounded
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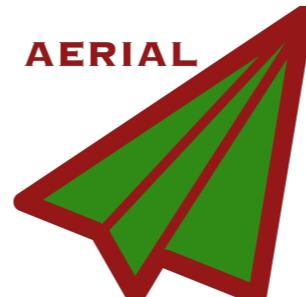
MARQ



X



AERIAL



MONPOLY

0:0	✓
1:0	✓
3:1 = 3:0	
2:0	✗
3:0	✗
3:1	✗
4:0	✓

almost event-rate independence
[Basin, Bhatt, Traytel, TACAS 2017]

index depends
logarithmically
on event-rate

Logic

History

LTL
Pnueli
1977

History

LTL
Pnueli
1977



MTL
Koymans
1990



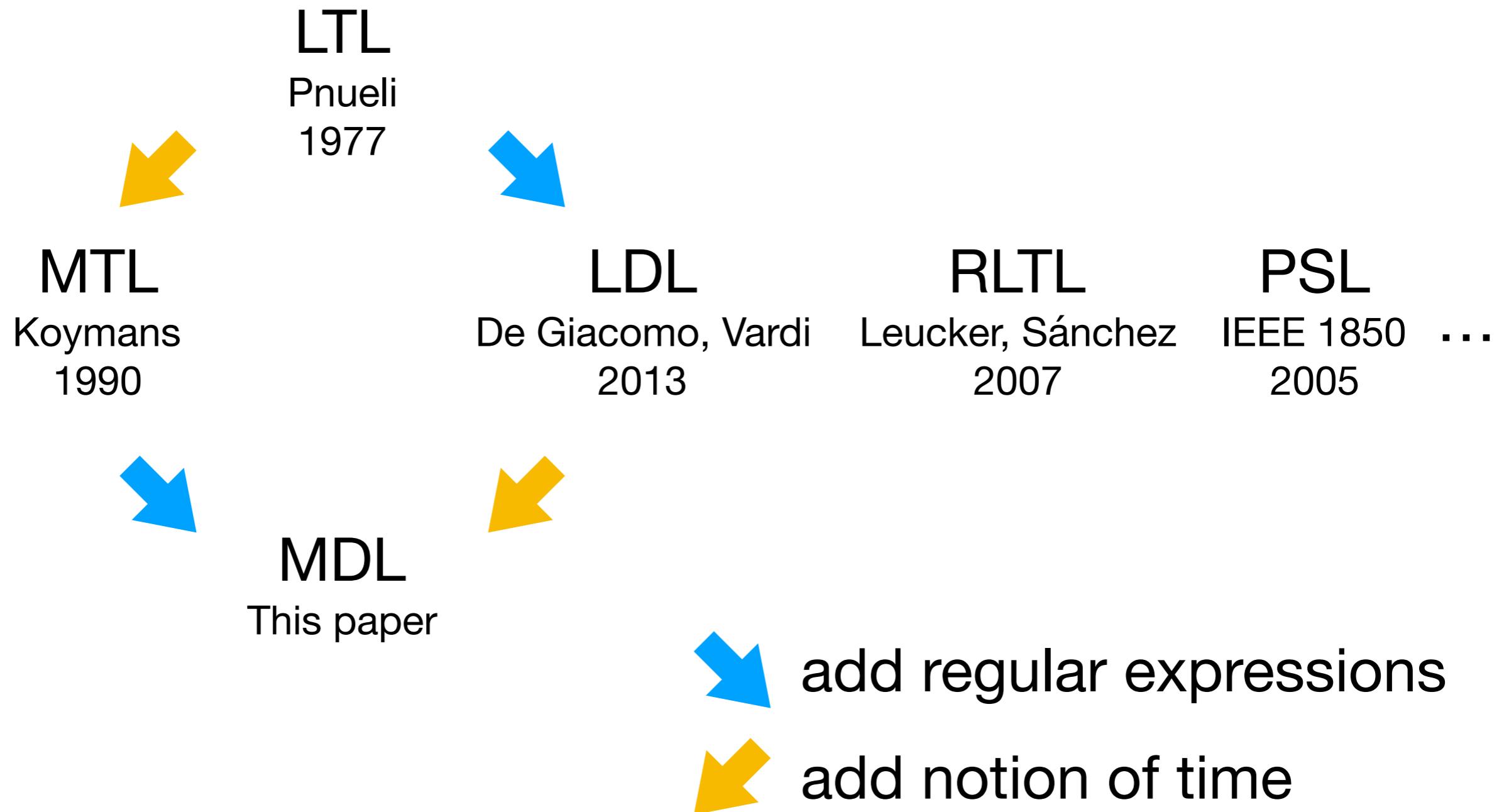
add notion of time

History



- add regular expressions
- add notion of time

History



Syntax

$$\begin{array}{c} \varphi, \psi = p \\ | \quad \neg\varphi \quad | \quad \varphi \vee \psi \\ | \quad X_I \varphi \quad | \quad \varphi U_I \psi \\ | \quad Y_I \varphi \quad | \quad \varphi S_I \psi \end{array}$$

Syntax

		atomic			Boolean		
		$\neg\varphi$	$\varphi \vee \psi$		$X_I \varphi$	$\varphi \cup_I \psi$	
e		$Y_I \varphi$	$\varphi \wedge_I \psi$		$S_I \psi$		

future

atomic

Boolean

past

Syntax

$$\varphi, \psi = p \quad \text{atomic}$$
$$\quad \quad \quad \mid \neg\varphi \quad \mid \varphi \vee \psi \quad \text{Boolean}$$
$$\quad \quad \quad \mid \langle r \rangle_I \varphi$$
$$\quad \quad \quad \mid \varphi \ I\langle r \rangle \quad \text{past}$$

future

Syntax

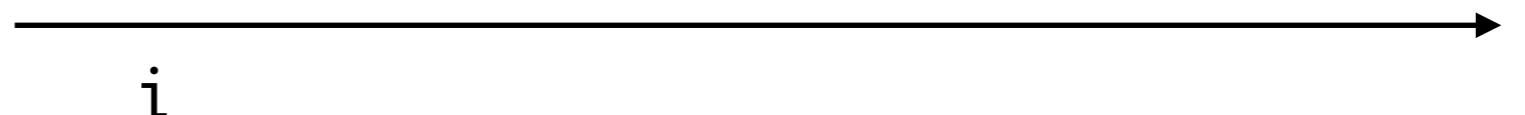
$$\varphi, \psi = p \quad \text{atomic}$$
$$\quad \quad \quad | \neg\varphi \quad | \varphi \vee \psi \quad \text{Boolean}$$
$$\quad \quad \quad | \langle r \rangle_I \varphi$$
$$\quad \quad \quad | \varphi \ I \langle r \rangle \quad \text{past}$$

future

$$r, s = \star \quad | \quad \varphi? \quad | \quad r + s \quad | \quad rs \quad | \quad r^*$$

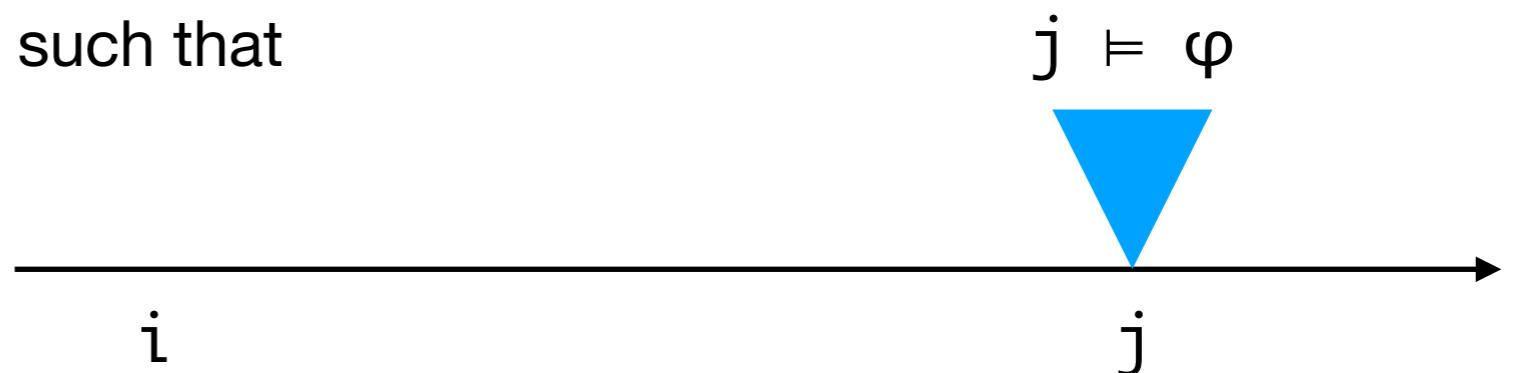
Semantics

$i \models \langle r \rangle_{[a,b]} \varphi$



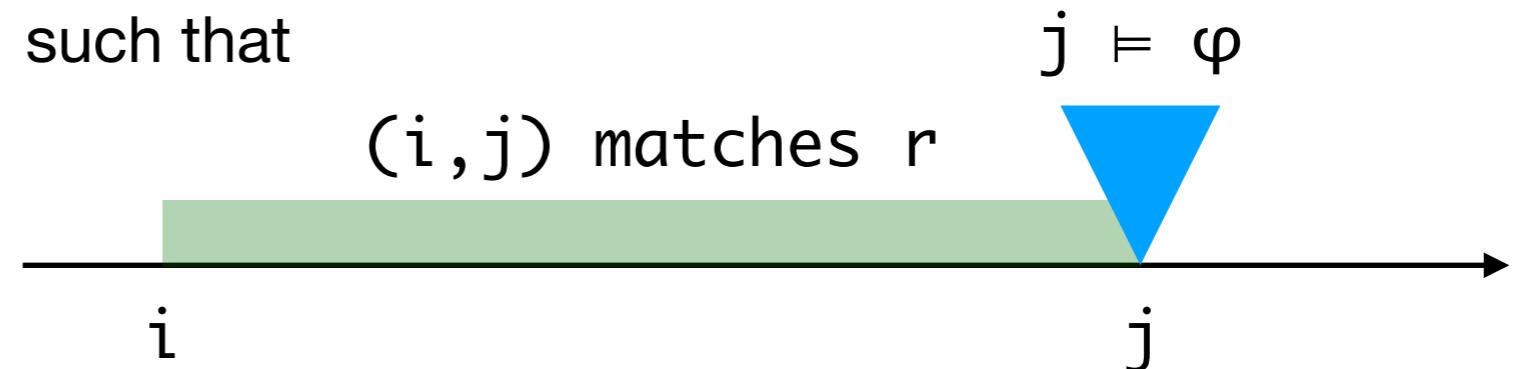
Semantics

$i \models \langle r \rangle_{[a,b]} \varphi$ iff there is a j such that



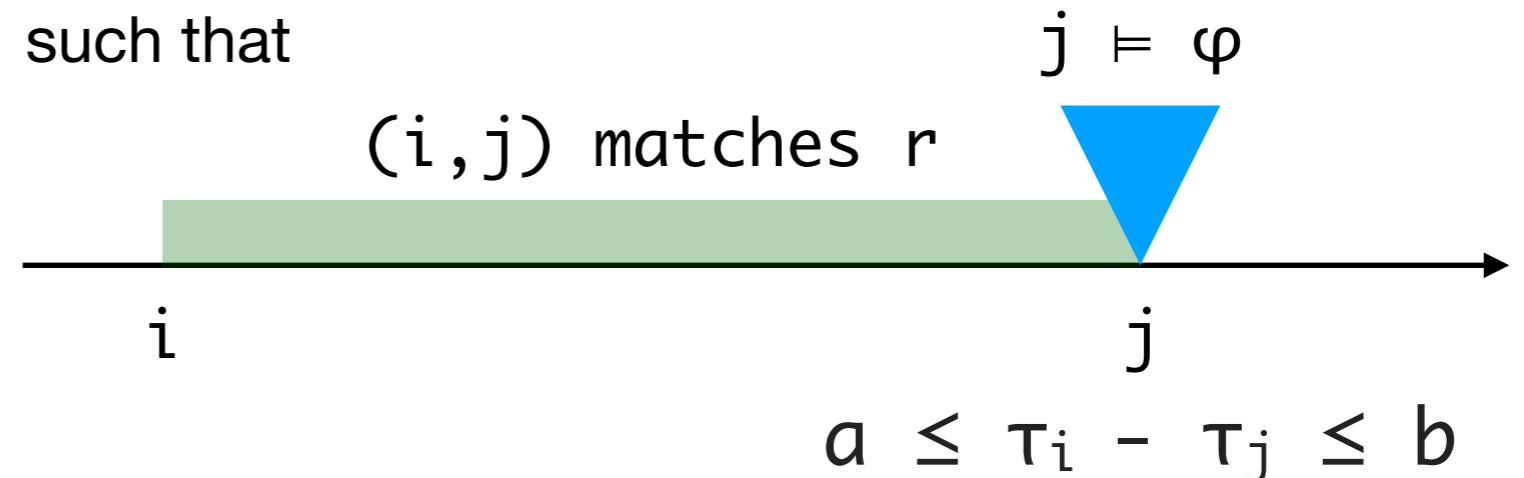
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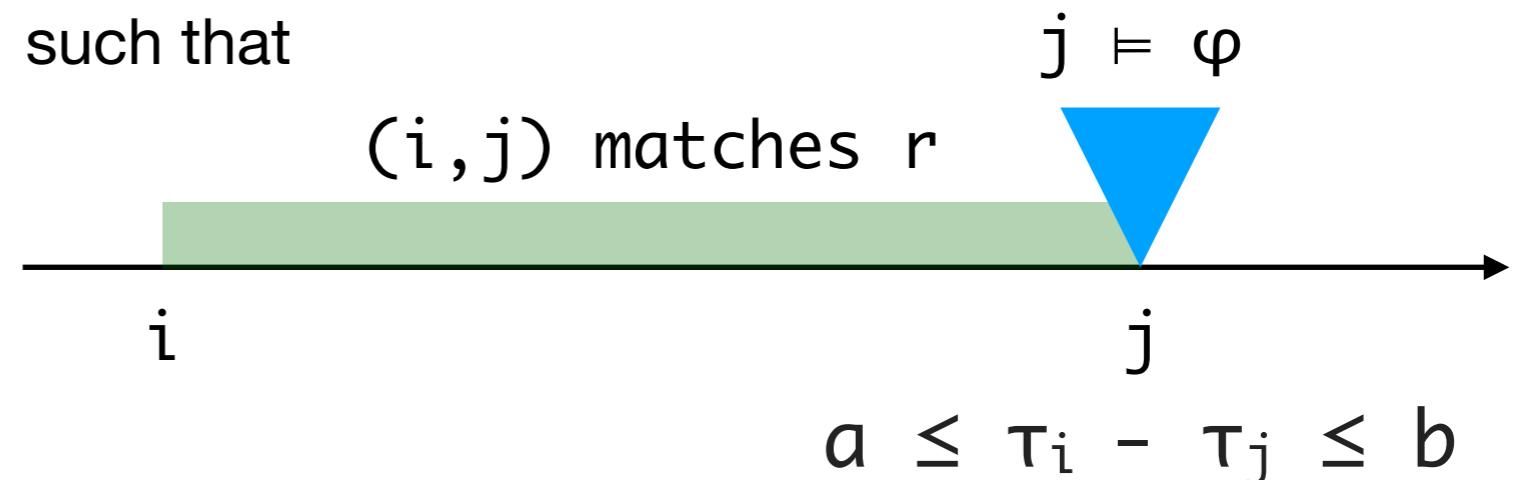
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Semantics

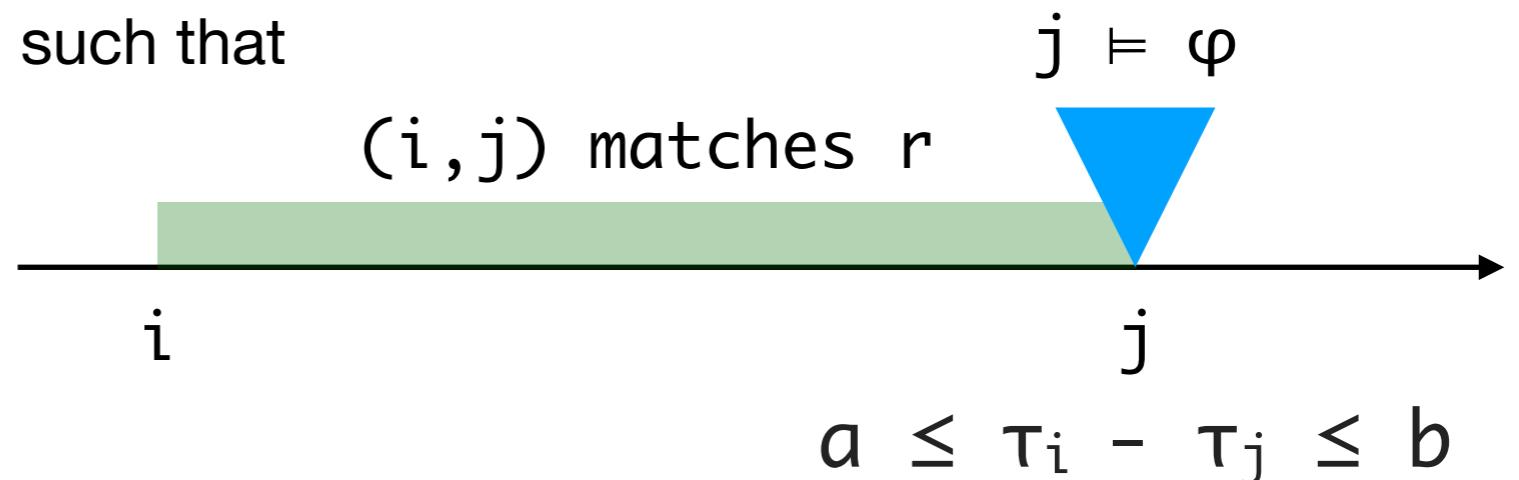
$i \models \langle r \rangle_{[a,b]} \varphi$ iff there is a j such that



$(i, i+1)$ matches \star

Semantics

$i \models \langle r \rangle_{[a,b]} \varphi$ iff there is a j such that

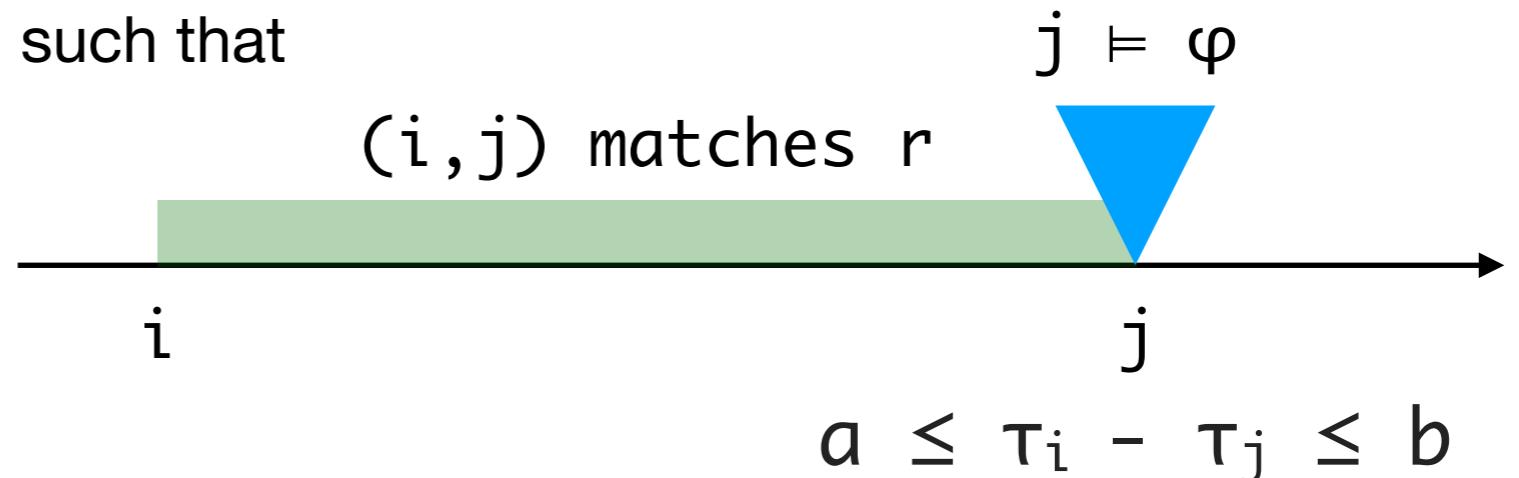


$(i, i+1)$ matches \star

(i, i) matches $\varphi?$ iff $i \models \varphi$

Semantics

$i \models \langle r \rangle_{[a,b]} \varphi$ iff there is a j such that



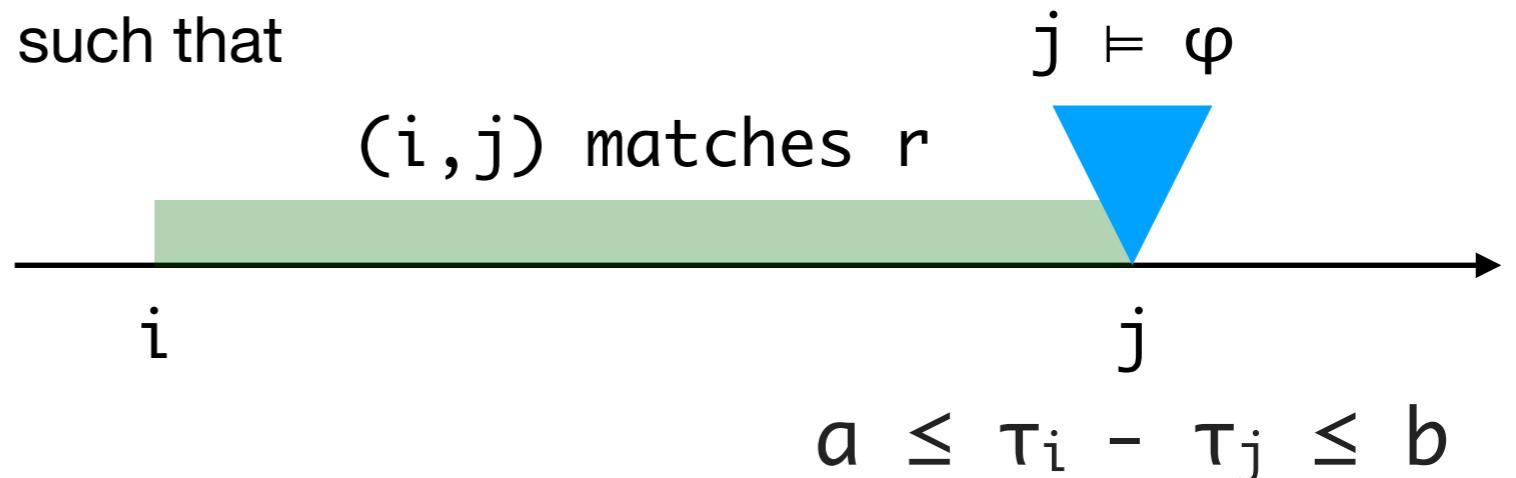
$(i, i+1)$ matches \star

(i, i) matches φ ? iff $i \models \varphi$

(i, j) matches $r+s$ iff (i, j) matches r or (i, j) matches s

Semantics

$i \models \langle r \rangle_{[a,b]} \varphi$ iff there is a j such that



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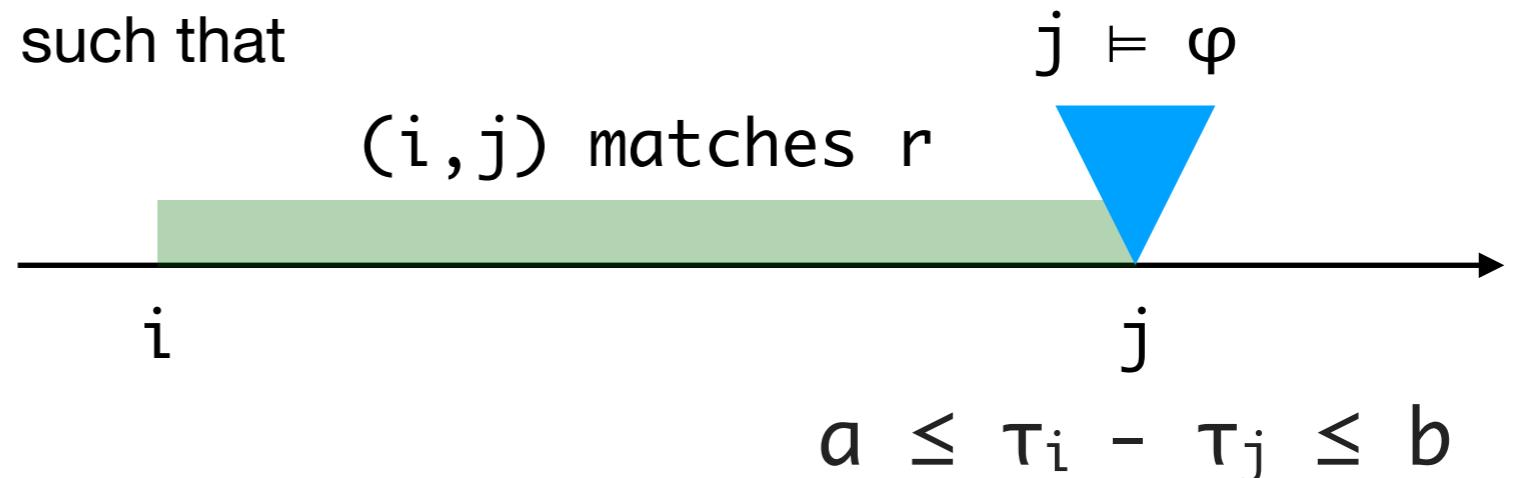
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(i, j) matches rs iff there is a k s.t. (i, k) matches r and (k, j) matches s

Semantics

$i \models \langle r \rangle_{[a,b]} \varphi$ iff there is a j such that



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(i, j) matches rs iff there is a k s.t. (i, k) matches r and (k, j) matches s

(i, j) matches r^* iff ...

MTL \subset MDL

$\varphi, \psi = p \mid \neg\varphi \mid \varphi \vee \psi \mid \langle r \rangle_I \varphi \mid \varphi \ I \langle r \rangle$
 $r, s = \star \mid \varphi? \mid r + s \mid rs \mid r^*$

$X_I \varphi$

MTL \subset MDL

$$\begin{aligned}\varphi, \psi &= p \mid \neg\varphi \mid \varphi \vee \psi \mid \langle r \rangle_I \varphi \mid \varphi \ I \langle r \rangle \\ r, s &= \star \mid \varphi? \mid r + s \mid rs \mid r^*\end{aligned}$$

$$X_I \varphi = \langle \star \rangle_I \varphi$$

MTL \subset MDL

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$$X_I \varphi = \langle \star \rangle_I \varphi$$

$$\varphi \cup_I \psi$$

MTL ⊂ MDL

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$$X_I \varphi = \langle \star \rangle_I \varphi$$

$$\varphi \cup_I \psi = \langle \varphi^* \rangle_I \psi$$

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$$X_I \varphi = \langle \star \rangle_I \varphi$$

$$\varphi \cup_I \psi = \langle \varphi^* \rangle_I \psi = \langle (\varphi? \star)^* \rangle_I \psi$$

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$$X_I \varphi = \langle \star \rangle_I \varphi$$

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$$Y_I \varphi$$

MTL ⊂ MDL

$$\begin{aligned}\varphi, \psi &= p \mid \neg\varphi \mid \varphi \vee \psi \mid \langle r \rangle_I \varphi \mid \varphi \ I \langle r \rangle \\r, s &= \star \mid \varphi? \mid r + s \mid rs \mid r^*\end{aligned}$$

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$$Y_I \varphi = \varphi \ I \langle \star \rangle$$

MTL ⊂ MDL

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$$Y_I \varphi = \varphi \ I \langle \star \rangle$$

$$\varphi \ S_I \psi$$

MTL \subset MDL

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$$\varphi \cdot_S_I \psi = \psi \ I \langle \varphi^* \rangle$$

MTL \subset MDL

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$$\varphi \cdot_S_I \psi = \psi \ I \langle \varphi^* \rangle = \psi \ I \langle (\star \varphi?)^* \rangle$$

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“enter” must happen before “exit”.

MTL \subset MDL

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$$Y_I \varphi = \varphi \ I \langle \star \rangle$$

$$\varphi \ S_I \psi = \psi \ I \langle \varphi^* \rangle = \psi \ I \langle (\star \varphi?)^* \rangle$$

within the next 2 time-units both
 “enter” and “exit” must happen and
 “enter” must happen before “exit”.

$\langle \star^* \text{ enter } \star^* \rangle [0,2] \text{ exit}$

Algorithm

Dynamic Programming for Past-time LTL

Dynamic Programming for Past-time LTL

[Havelund & Roşu, TACAS 2002]

Dynamic Programming for Past-time LTL

...

α

β

$\alpha S \beta$

[Havelund & Roşu, TACAS 2002]

Dynamic Programming for Past-time LTL

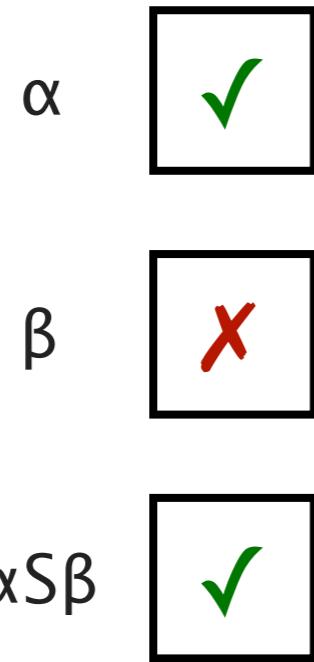
... ...



[Havelund & Roşu, TACAS 2002]

Dynamic Programming for Past-time LTL

... ...



[Havelund & Roşu, TACAS 2002]

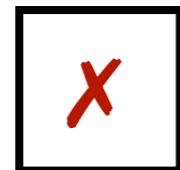
Dynamic Programming for Past-time LTL

... ...

α



β



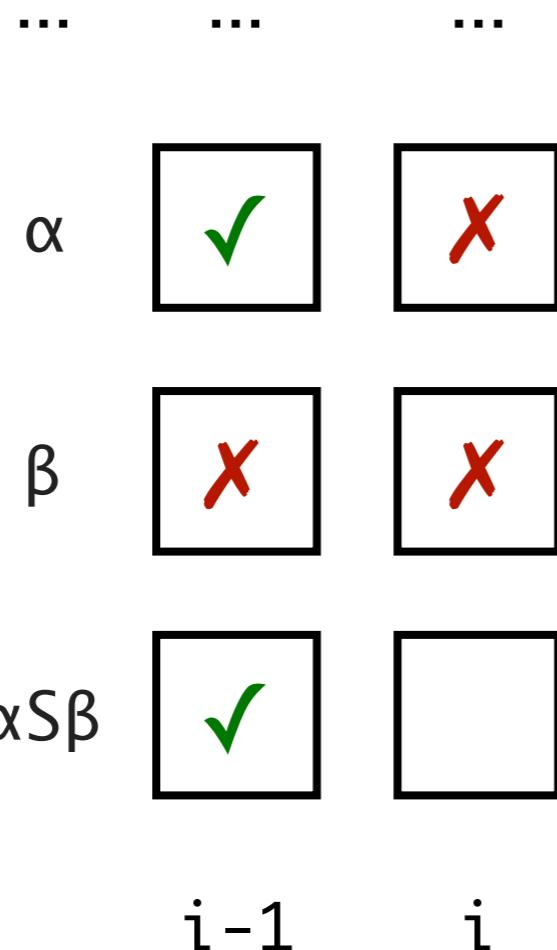
$\alpha S \beta$



$i-1$

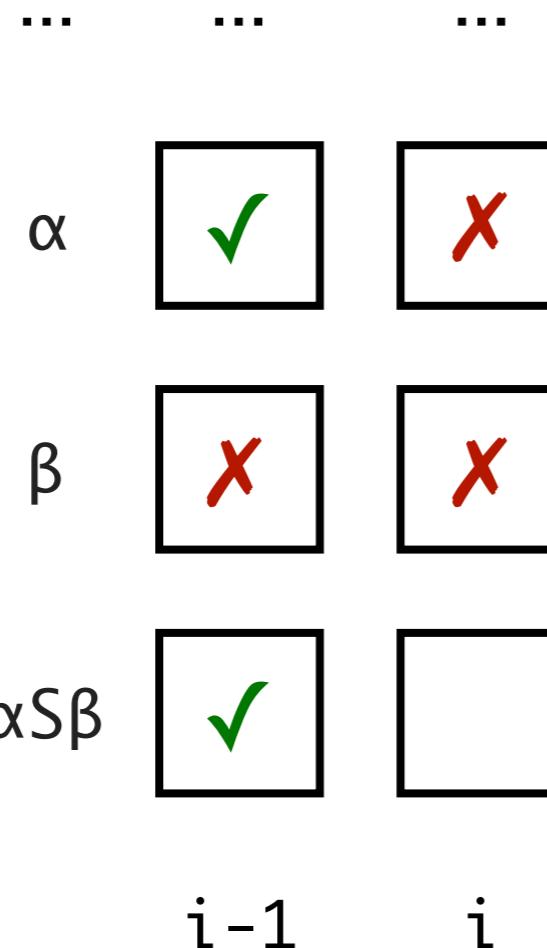
[Havelund & Roşu, TACAS 2002]

Dynamic Programming for Past-time LTL



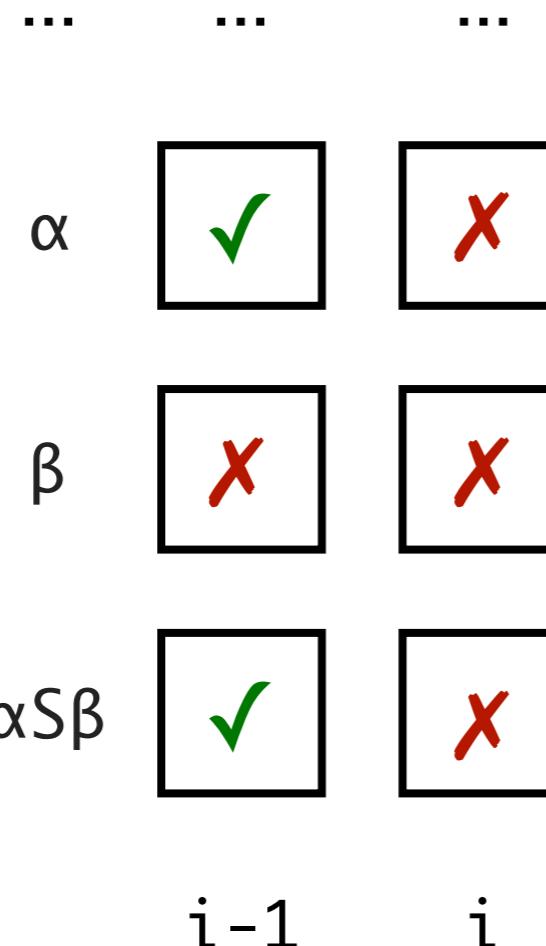
[Havelund & Roşu, TACAS 2002]

Dynamic Programming for Past-time LTL



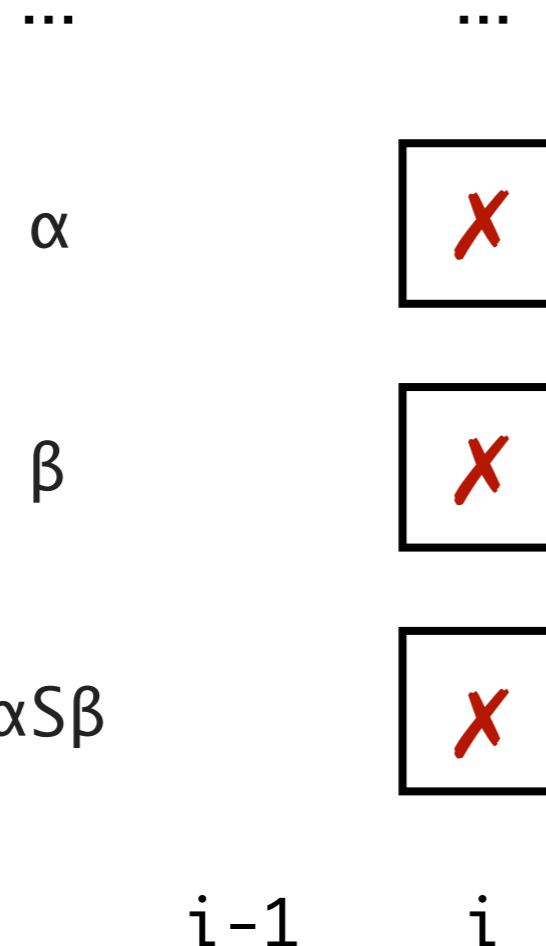
[Havelund & Roşu, TACAS 2002]

Dynamic Programming for Past-time LTL



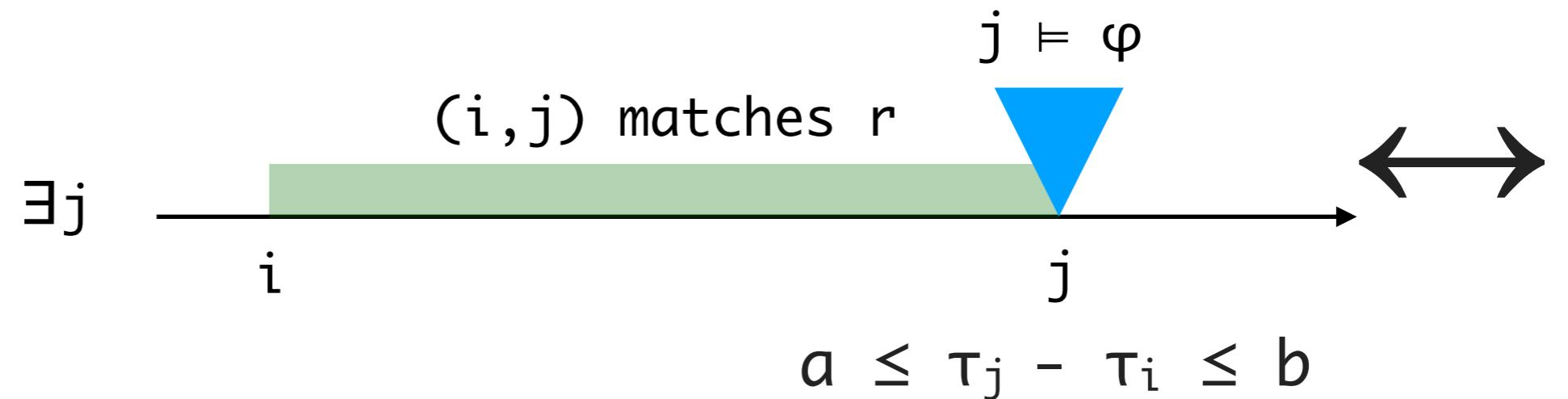
$i \models \alpha S \beta \leftrightarrow$
 $i \models \beta \vee i \models \alpha \wedge i-1 \models \alpha S \beta$

Dynamic Programming for Past-time LTL

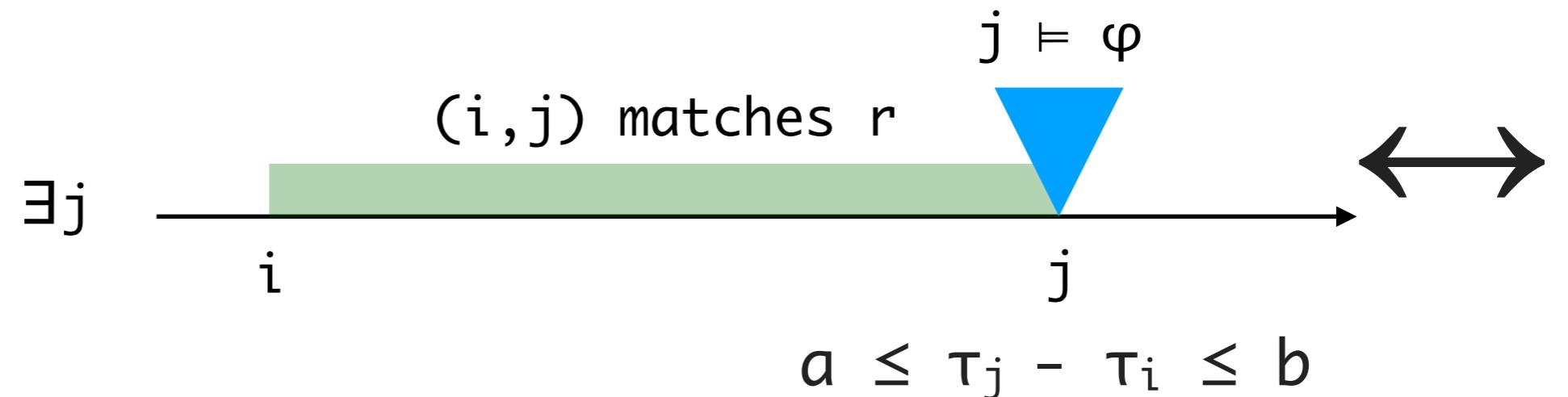


[Havelund & Roşu, TACAS 2002]

Incremental MDL Semantics

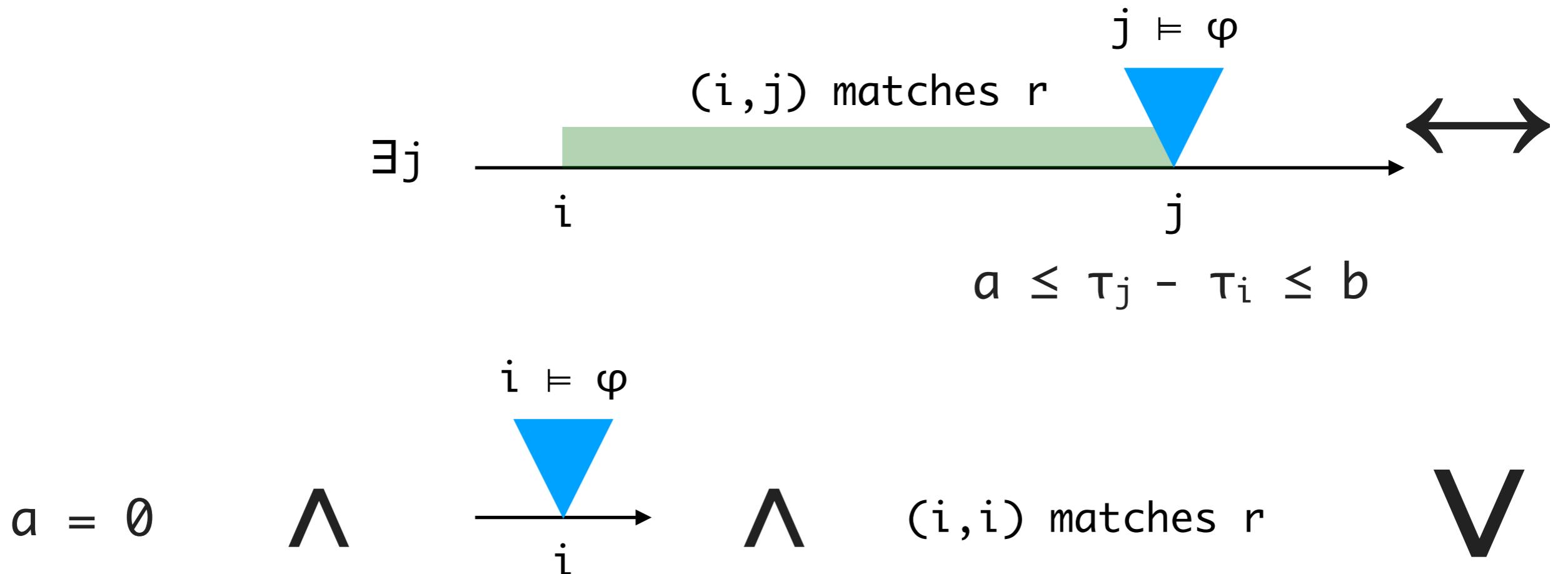


Incremental MDL Semantics

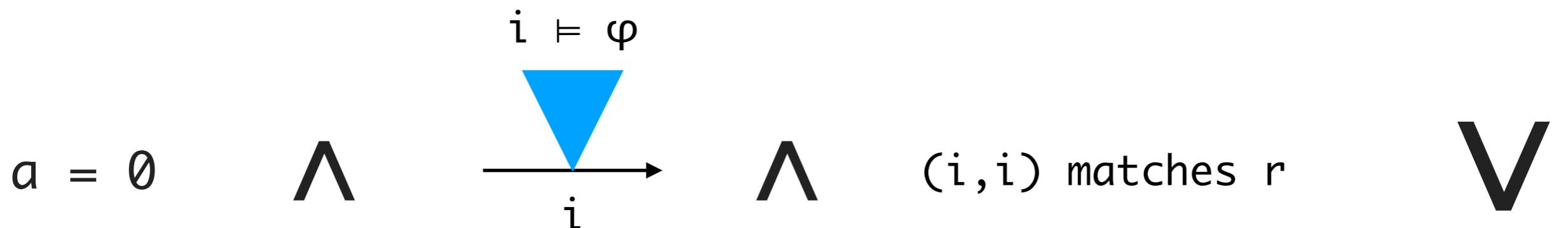
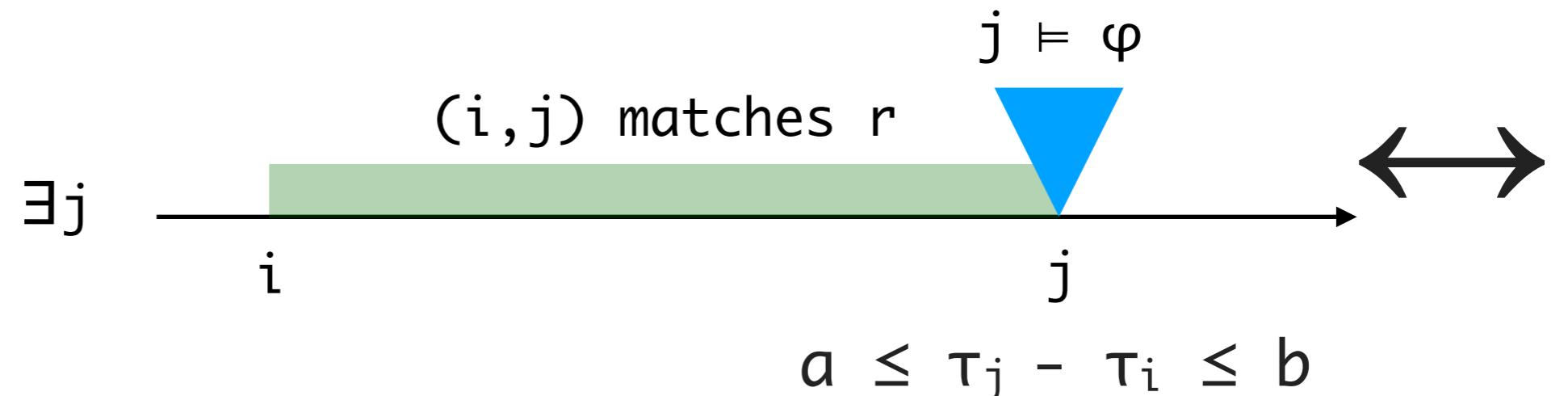


V

Incremental MDL Semantics

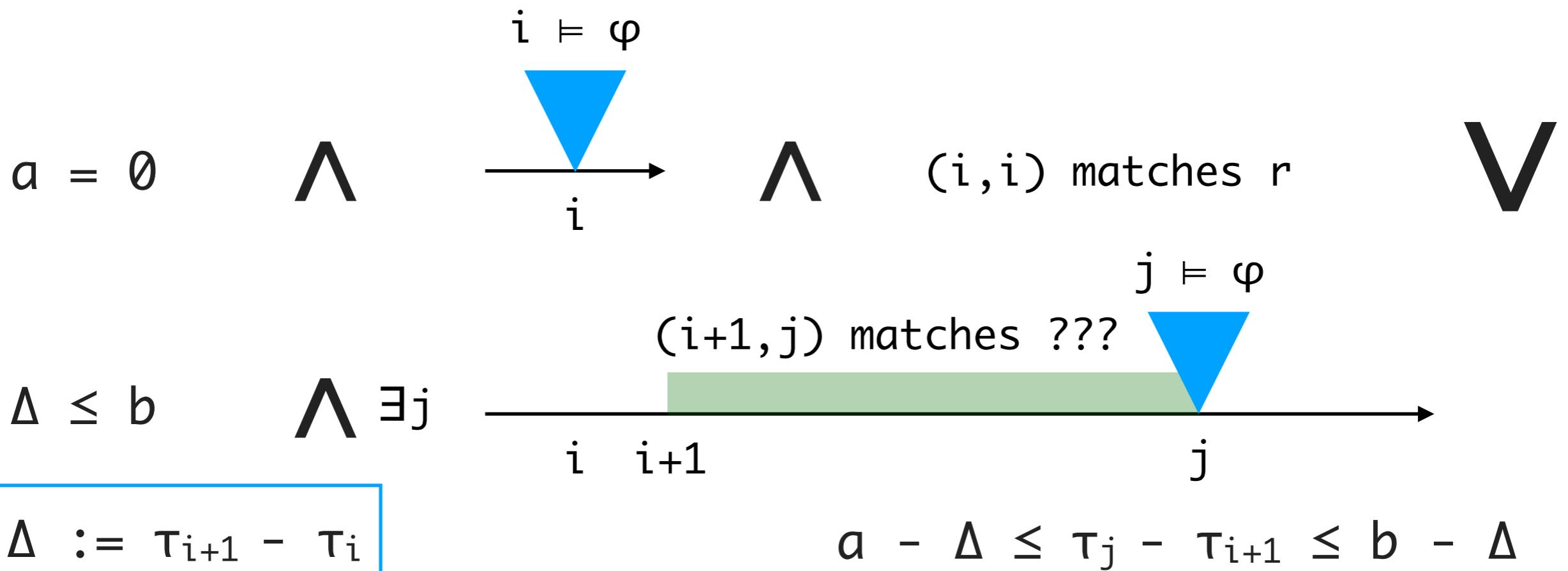
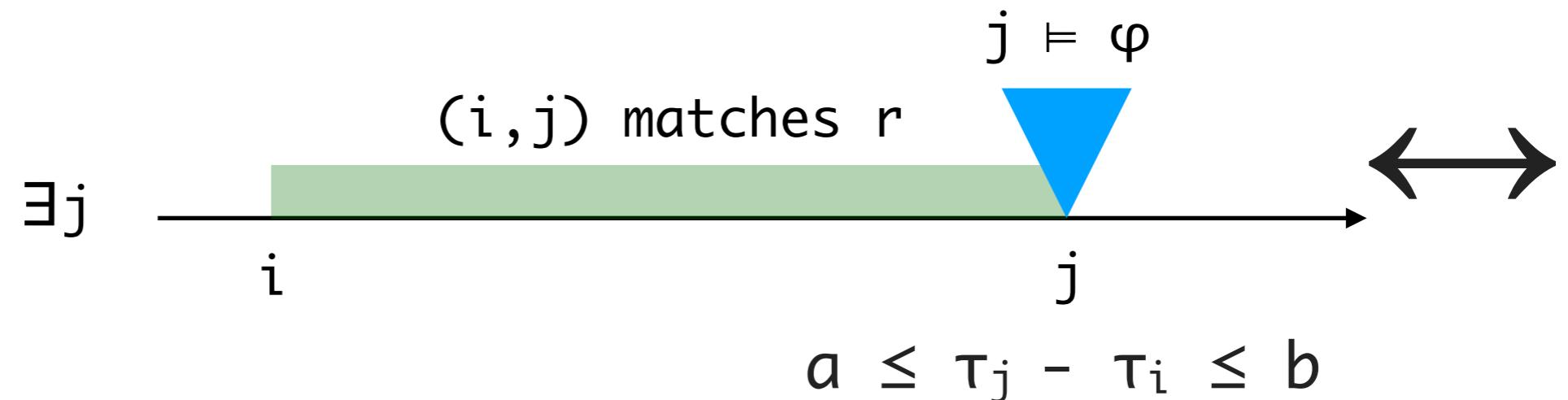


Incremental MDL Semantics



$$\Delta := \tau_{i+1} - \tau_i$$

Incremental MDL Semantics



Incremental MDL Semantics

$$i \models \langle r \rangle_{[a,b]} \varphi$$



$$a = 0$$

\wedge

$$i \models \varphi$$

\wedge

(i,i) matches r

\vee

$$\Delta \leq b$$

\wedge

$$i+1 \models \langle ??? \rangle_{[a-\Delta, b-\Delta]} \varphi$$

$$\Delta := \tau_{i+1} - \tau_i$$

Incremental MDL Semantics

$$i \models \langle r \rangle_{[a,b]} \varphi$$



$$a = 0$$

 \wedge

$$i \models \varphi$$

 \wedge $(i,i) \text{ matches } r$ \vee

$$\Delta \leq b$$

 \wedge

$$i+1 \models \langle \delta_i(r) \rangle_{[a-\Delta, b-\Delta]} \varphi$$

$$\Delta := \tau_{i+1} - \tau_i$$

Incremental MDL Semantics

$$i \models \langle r \rangle_{[a, b]} \varphi$$



$$a = 0$$

\wedge

$$i \models \varphi$$

\wedge

$$\varepsilon_i(r)$$

\vee

$$\Delta \leq b$$

\wedge

$$i+1 \models \langle \delta_i(r) \rangle_{[a-\Delta, b-\Delta]} \varphi$$

$$\Delta := \tau_{i+1} - \tau_i$$

Brzozowski Derivative

$$\varepsilon_i(\star) = \perp$$

$$\delta_i(\star) = \top?$$

$$\varepsilon_i(\varphi?) = i \models \varphi$$

$$\delta_i(\varphi?) = \perp?$$

$$\varepsilon_i(r + s) = \varepsilon_i(r) \vee \varepsilon_i(s)$$

$$\delta_i(r + s) = \delta_i(r) + \delta_i(s)$$

$$\varepsilon_i(r \cdot s) = \varepsilon_i(r) \wedge \varepsilon_i(s)$$

$$\delta_i(r \cdot s) = \delta_i(r) \cdot s + \\ \varepsilon_i(r)? \cdot \delta_i(s)$$

$$\varepsilon_i(r^*) = \top$$

$$\delta_i(r^*) = \delta_i(r) \cdot r^*$$

Brzozowski Derivative

$$\varepsilon_i(\star) = \perp$$

$$\delta_i(\star) = \top?$$

$$\varepsilon_i(\varphi?) = i \models \varphi$$

$$\delta_i(\varphi?) = \perp?$$

$$\varepsilon_i(r + s) = \varepsilon_i(r) \vee \varepsilon_i(s)$$

$$\delta_i(r + s) = \delta_i(r) + \delta_i(s)$$

$$\varepsilon_i(r \cdot s) = \varepsilon_i(r) \wedge \varepsilon_i(s)$$

$$\delta_i(r \cdot s) = \delta_i(r) \cdot s + \\ \varepsilon_i(r)? \cdot \delta_i(s)$$

$$\varepsilon_i(r^*) = \top$$

$$\delta_i(r^*) = \delta_i(r) \cdot r^*$$

not the whole story; see paper

MDL Monitor by Example

MDL Monitor by Example

enter

exit

<★*> [0,0] exit

<★*> [0,1] exit

<★*> [0,2] exit

<★* enter ★*> [0,0] exit

<★* enter ★*> [0,1] exit

<★* enter ★*> [0,2] exit

MDL Monitor by Example

enter 0

exit 1

<★*> [0,0] exit 2

<★*> [0,1] exit 3

<★*> [0,2] exit 4

<★* enter ★*> [0,0] exit 5

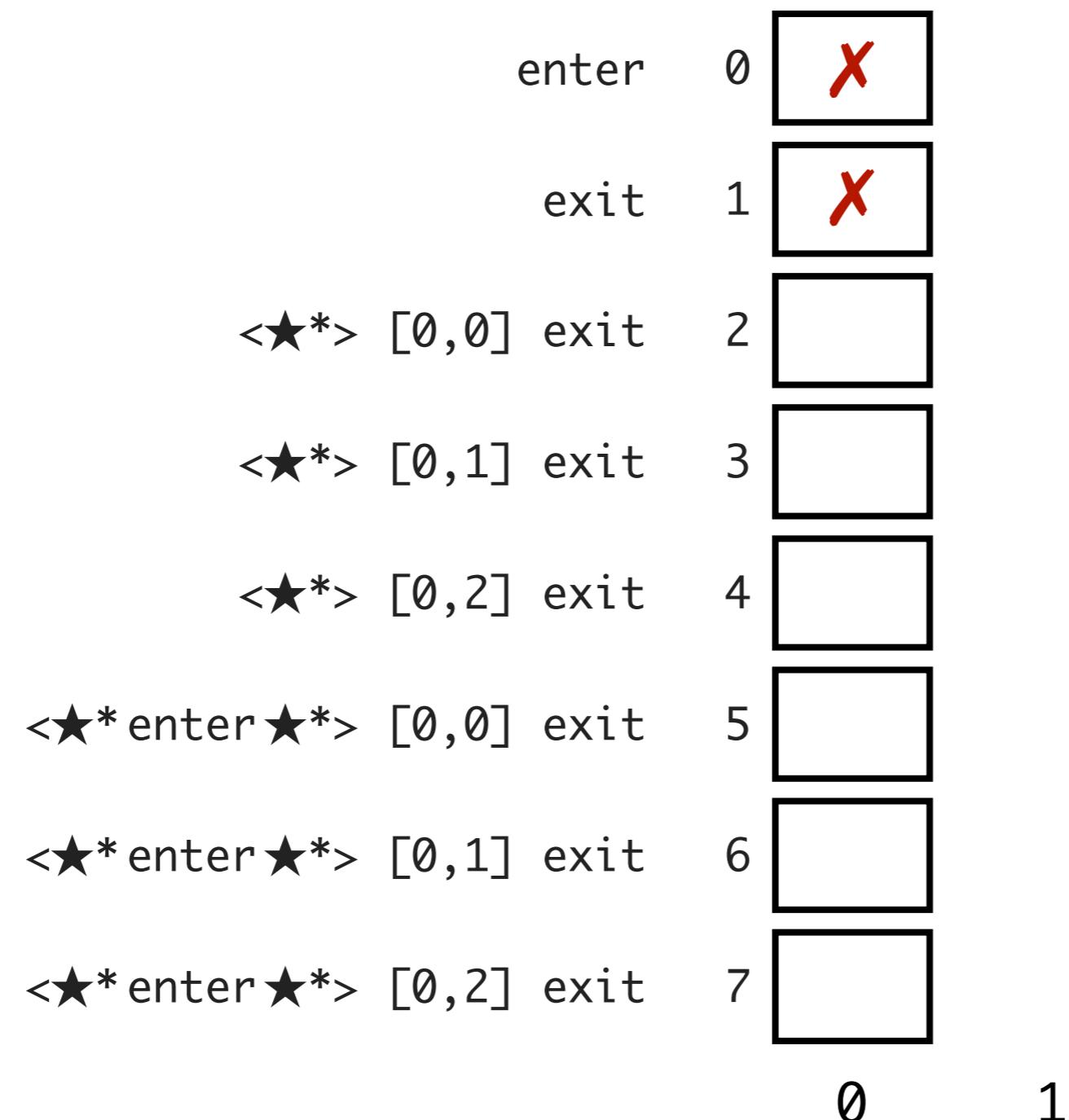
<★* enter ★*> [0,1] exit 6

<★* enter ★*> [0,2] exit 7

MDL Monitor by Example

enter	0	
exit	1	
<★*> [0,0] exit	2	
<★*> [0,1] exit	3	
<★*> [0,2] exit	4	
<★* enter ★*> [0,0] exit	5	
<★* enter ★*> [0,1] exit	6	
<★* enter ★*> [0,2] exit	7	
	0	

MDL Monitor by Example



MDL Monitor by Example

	enter	0	
	exit	1	
<★*>	[0,0] exit	2	
<★*>	[0,1] exit	3	
<★*>	[0,2] exit	4	
<★* enter ★*>	[0,0] exit	5	
<★* enter ★*>	[0,1] exit	6	
<★* enter ★*>	[0,2] exit	7	

0 1

MDL Monitor by Example

	enter	0	
	exit	1	
<★*>	[0,0] exit	2	
<★*>	[0,1] exit	3	
<★*>	[0,2] exit	4	
<★* enter ★*>	[0,0] exit	5	
<★* enter ★*>	[0,1] exit	6	
<★* enter ★*>	[0,2] exit	7	

0 1

MDL Monitor by Example

	enter	0	
	exit	1	
<★*>	[0,0] exit	2	
<★*>	[0,1] exit	3	
<★*>	[0,2] exit	4	
<★* enter ★*>	[0,0] exit	5	
<★* enter ★*>	[0,1] exit	6	
<★* enter ★*>	[0,2] exit	7	

0 1

MDL Monitor by Example

	enter	0	
	exit	1	
<★*>	[0,0] exit	2	
<★*>	[0,1] exit	3	
<★*>	[0,2] exit	4	
<★* enter ★*>	[0,0] exit	5	
<★* enter ★*>	[0,1] exit	6	
<★* enter ★*>	[0,2] exit	7	

0 1

MDL Monitor by Example

	enter	0	
	exit	1	
<★*>	[0,0] exit	2	
<★*>	[0,1] exit	3	
<★*>	[0,2] exit	4	
<★* enter ★*>	[0,0] exit	5	
<★* enter ★*>	[0,1] exit	6	
<★* enter ★*>	[0,2] exit	7	

0 1

MDL Monitor by Example

	enter	0	
	exit	1	
<★*>	[0,0] exit	2	
<★*>	[0,1] exit	3	
<★*>	[0,2] exit	4	
<★* enter ★*>	[0,0] exit	5	
<★* enter ★*>	[0,1] exit	6	
<★* enter ★*>	[0,2] exit	7	
		0	
		1	

MDL Monitor by Example

	enter	0	X	
	exit	1	X	
<★*>	[0,0] exit	2	X	
<★*>	[0,1] exit	3	2	
<★*>	[0,2] exit	4	3	
<★* enter ★*>	[0,0] exit	5	X	
<★* enter ★*>	[0,1] exit	6	5	
<★* enter ★*>	[0,2] exit	7	6	
		0		1

MDL Monitor by Example

	enter	0		
	exit	1		
<★*> [0,0] exit		2		
<★*> [0,1] exit		3	2	
<★*> [0,2] exit		4	3	
<★* enter ★*> [0,0] exit		5		
<★* enter ★*> [0,1] exit		6	5	
<★* enter ★*> [0,2] exit		7	6	
		0	1	2

MDL Monitor by Example

	enter	0		
	exit	1		
<★*> [0,0] exit		2		
<★*> [0,1] exit		3	2	
<★*> [0,2] exit		4	3	
<★* enter ★*> [0,0] exit		5		
<★* enter ★*> [0,1] exit		6	5	
<★* enter ★*> [0,2] exit		7	6	
		0	1	2

MDL Monitor by Example

	enter	0		
	exit	1		
<★*> [0,0] exit		2		
<★*> [0,1] exit		3	2	2
<★*> [0,2] exit		4	3	
<★* enter ★*> [0,0] exit		5		
<★* enter ★*> [0,1] exit		6	5	
<★* enter ★*> [0,2] exit		7	6	
		0	1	2

MDL Monitor by Example

	enter	0		
	exit	1		
<★*> [0,0] exit		2		
<★*> [0,1] exit		3	2	2
<★*> [0,2] exit		4	3	3
<★* enter ★*> [0,0] exit		5		
<★* enter ★*> [0,1] exit		6	5	
<★* enter ★*> [0,2] exit		7	6	
		0	1	2

MDL Monitor by Example

	enter	0		
	exit	1		
<★*> [0,0] exit		2		
<★*> [0,1] exit		3	2 2	
<★*> [0,2] exit		4	3 3	
<★* enter ★*> [0,0] exit		5		
<★* enter ★*> [0,1] exit		6	5	
<★* enter ★*> [0,2] exit		7	6	
			0 1 2	

MDL Monitor by Example

	enter	0		
	exit	1		
<★*> [0,0] exit		2		
<★*> [0,1] exit		3	2	2
<★*> [0,2] exit		4	3	3
<★* enter ★*> [0,0] exit		5		
<★* enter ★*> [0,1] exit		6	5	2 v 5
<★* enter ★*> [0,2] exit		7	6	
		0	1	2

MDL Monitor by Example

	enter	0		
	exit	1		
<★*> [0,0] exit		2		
<★*> [0,1] exit		3	2	2
<★*> [0,2] exit		4	3	3
<★* enter ★*> [0,0] exit		5		
<★* enter ★*> [0,1] exit		6	5	2 v 5
<★* enter ★*> [0,2] exit		7	6	3 v 6
		0	1	2

MDL Monitor by Example

	enter	0	
	exit	1	
<★*>	[0,0]	exit 2	
<★*>	[0,1]	exit 3	
<★*>	[0,2]	exit 4	
<★* enter ★*>	[0,0]	exit 5	
<★* enter ★*>	[0,1]	exit 6	
<★* enter ★*>	[0,2]	exit 7	 
		0 1 2	

MDL Monitor by Example

	enter	0	
	exit	1	
<★*>	[0,0]	exit	
<★*>	[0,1]	exit	
<★*>	[0,2]	exit	
<★* enter ★*>	[0,0]	exit	
<★* enter ★*>	[0,1]	exit	
<★* enter ★*>	[0,2]	exit	 
		0 1 2	

MDL Monitor by Example

	enter	0		
	exit	1		
<★*> [0,0]	exit	2		
<★*> [0,1]	exit	3	2	
<★*> [0,2]	exit	4	3	
<★* enter ★*> [0,0]	exit	5		
<★* enter ★*> [0,1]	exit	6	2 v 5	
<★* enter ★*> [0,2]	exit	7	2 v 5 3 v 6	
			0 1 2 3	

MDL Monitor by Example

	enter	0		
	exit	1		
<★*>	[0,0]	exit 2		
<★*>	[0,1]	exit 3	2	
<★*>	[0,2]	exit 4	3	
<★* enter ★*>	[0,0]	exit 5		
<★* enter ★*>	[0,1]	exit 6	2 v 5	2 v 5
<★* enter ★*>	[0,2]	exit 7	2 v 5	3 v 6
			0	1
			2	3

MDL Monitor by Example

	enter	0		
	exit	1		
<★*>	[0,0]	exit	2	
<★*>	[0,1]	exit	3	
<★*>	[0,2]	exit	4	
<★* enter ★*>	[0,0]	exit	5	
<★* enter ★*>	[0,1]	exit	6	2 v 5
<★* enter ★*>	[0,2]	exit	7	2 v 5 3 v 6 3 v 6
		0		
		1		
		2		
		3		

MDL Monitor by Example

enter	0				
exit	1				
<★*> [0,0]	exit	2			
<★*> [0,1]	exit	3			
<★*> [0,2]	exit	4			
<★* enter ★*>	[0,0]	exit	5		
<★* enter ★*>	[0,1]	exit	6		
<★* enter ★*>	[0,2]	exit	7		
		0			
		1			
		2			
		3			

MDL Monitor by Example

enter	0	
exit	1	
<★*> [0,0]	exit 2	
<★*> [0,1]	exit 3	
<★*> [0,2]	exit 4	
<★* enter ★*>	[0,0] exit 5	
<★* enter ★*>	[0,1] exit 6	2 v 5
<★* enter ★*>	[0,2] exit 7	3 v 6
	0	
	1	
	2	
	3	

MDL Monitor by Example

enter	0	
exit	1	
<★*> [0,0]	exit 2	
<★*> [0,1]	exit 3	
<★*> [0,2]	exit 4	
<★* enter ★*>	[0,0] exit 5	
<★* enter ★*>	[0,1] exit 6	2 v 5
<★* enter ★*>	[0,2] exit 7	3 v 6

0 1 2 3

Evaluation

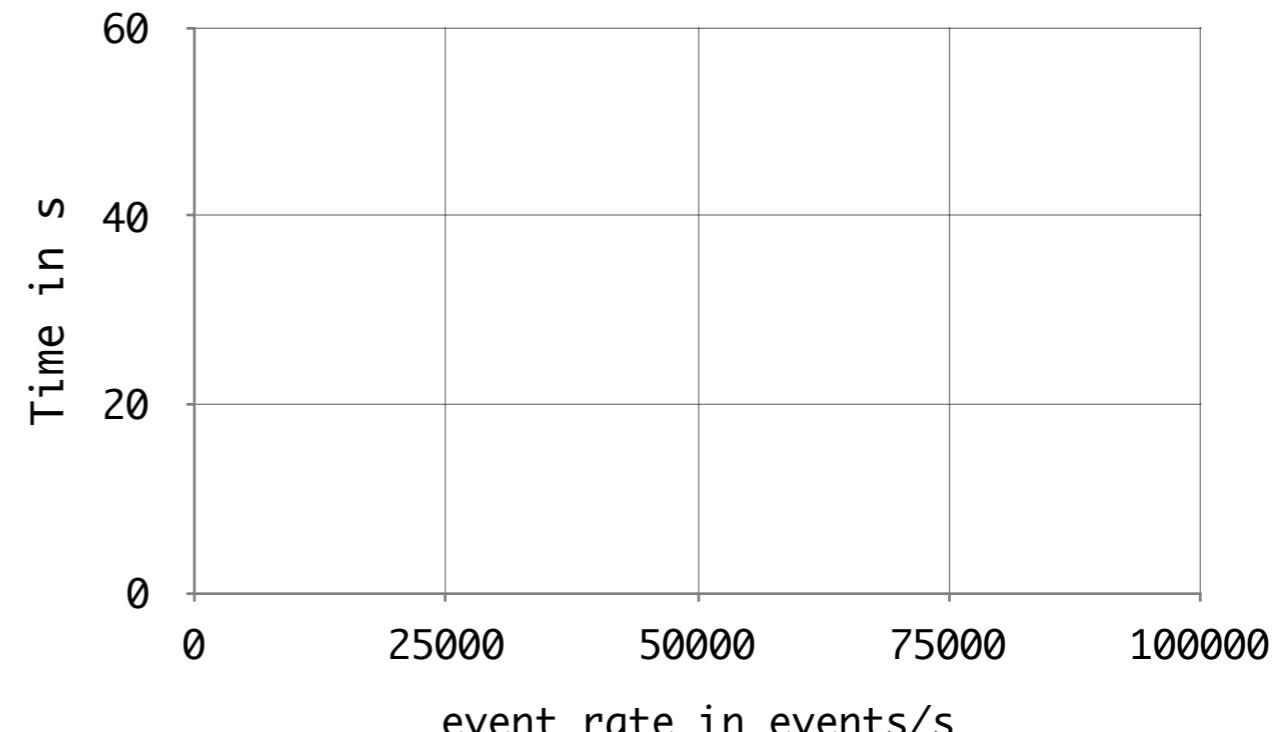
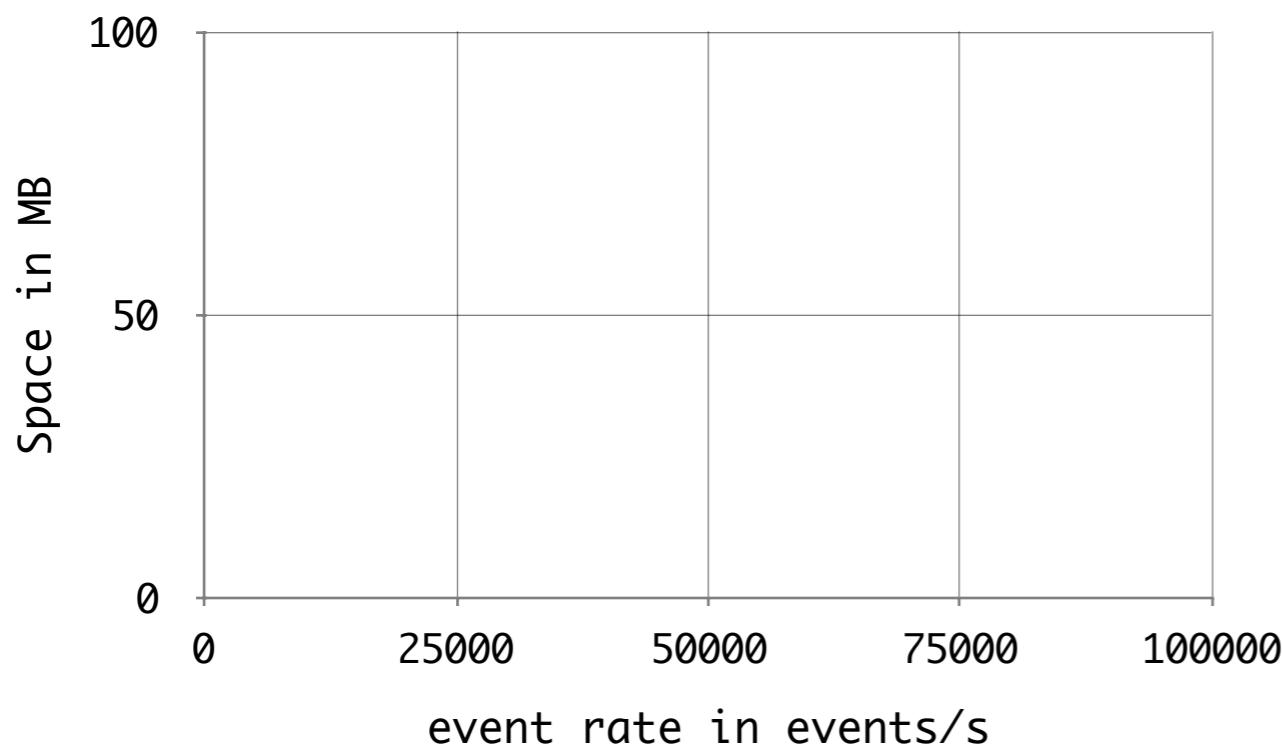
Event-Rate

$p \sim U[0, 5]$ ($q \sim U[2, 6]$ r)
100s of random data

Event-Rate

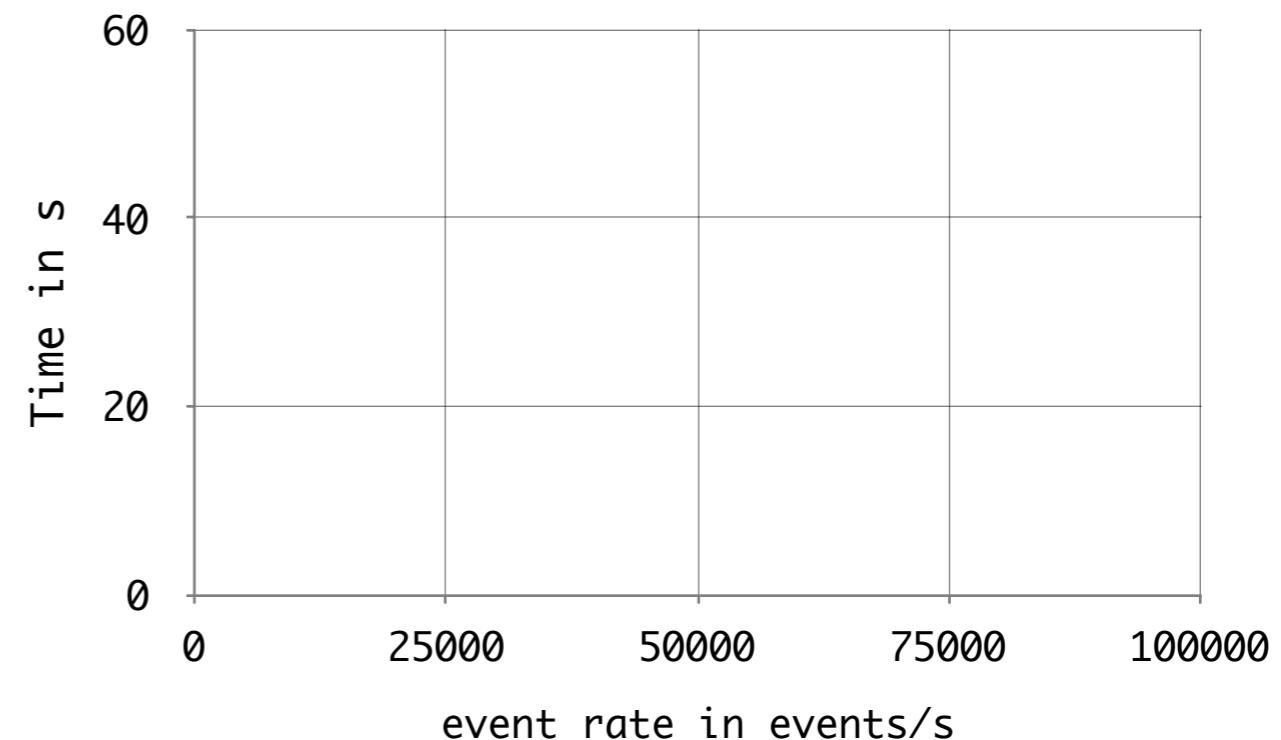
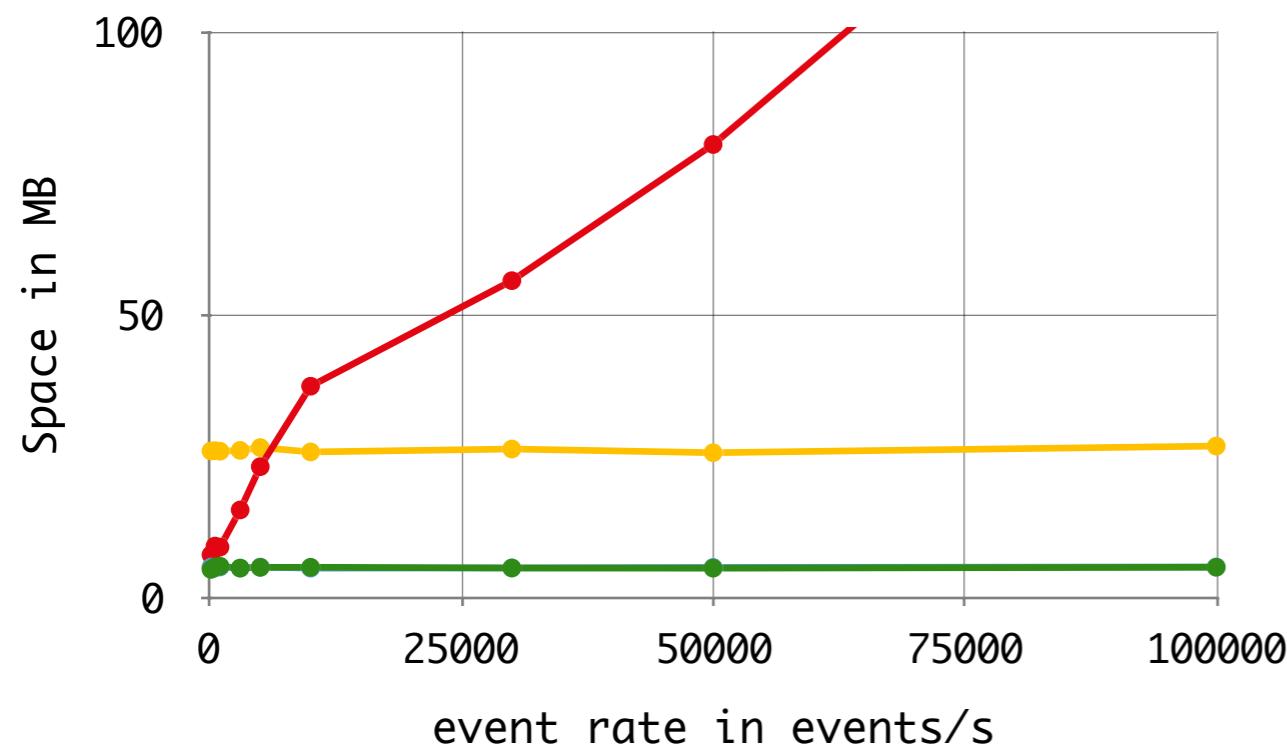
- Aerial MDL
- Aerial MTL
- Monpoly
- Montre

$p \sim U[0, 5]$ ($q \sim U[2, 6]$ r)
100s of random data



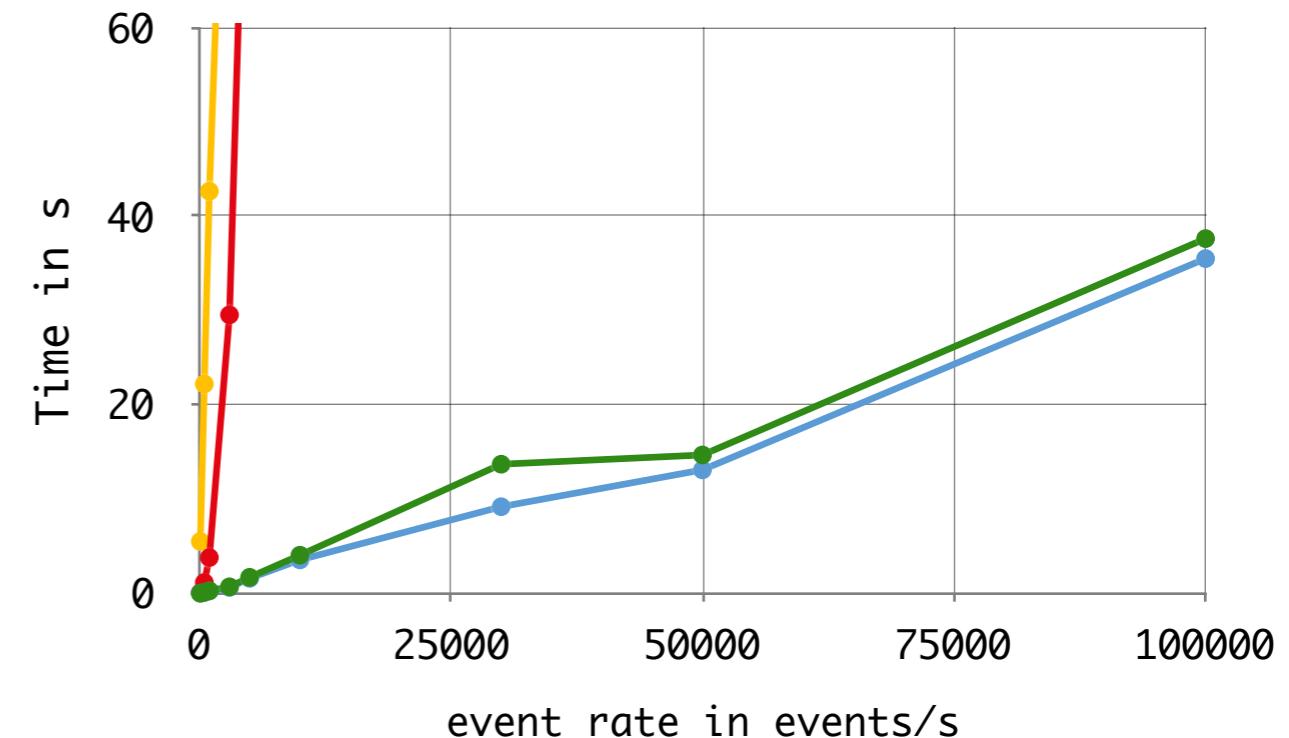
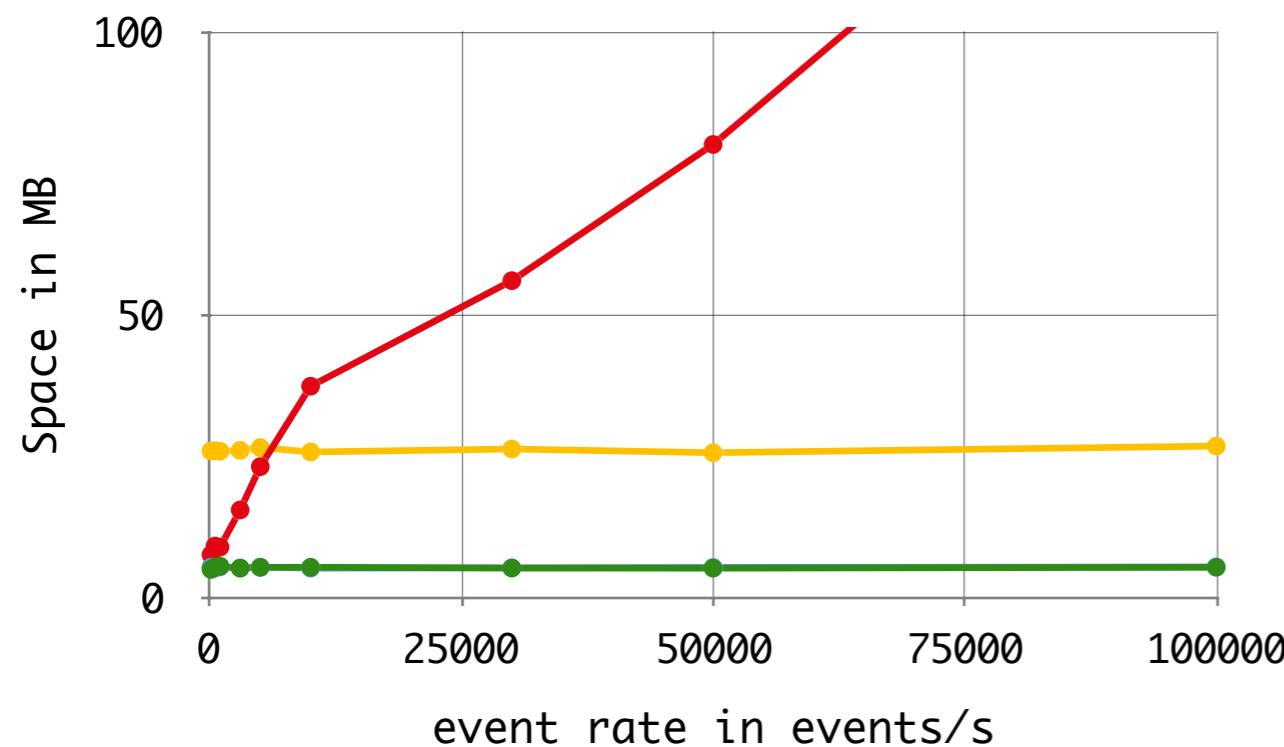
Event-Rate

$p \sim U[0,5]$ ($q \sim U[2,6]$ r)
100s of random data



Event-Rate

$p \sim U[0,5]$ ($q \sim U[2,6]$ r)
100s of random data



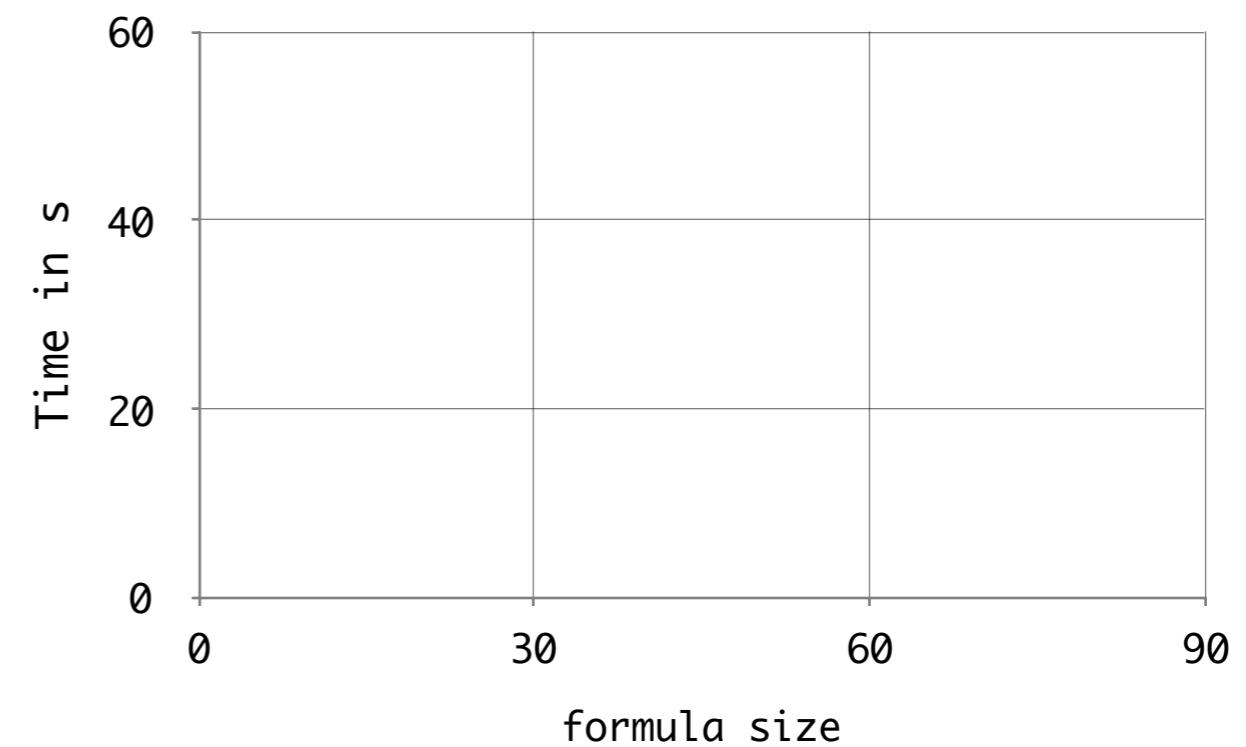
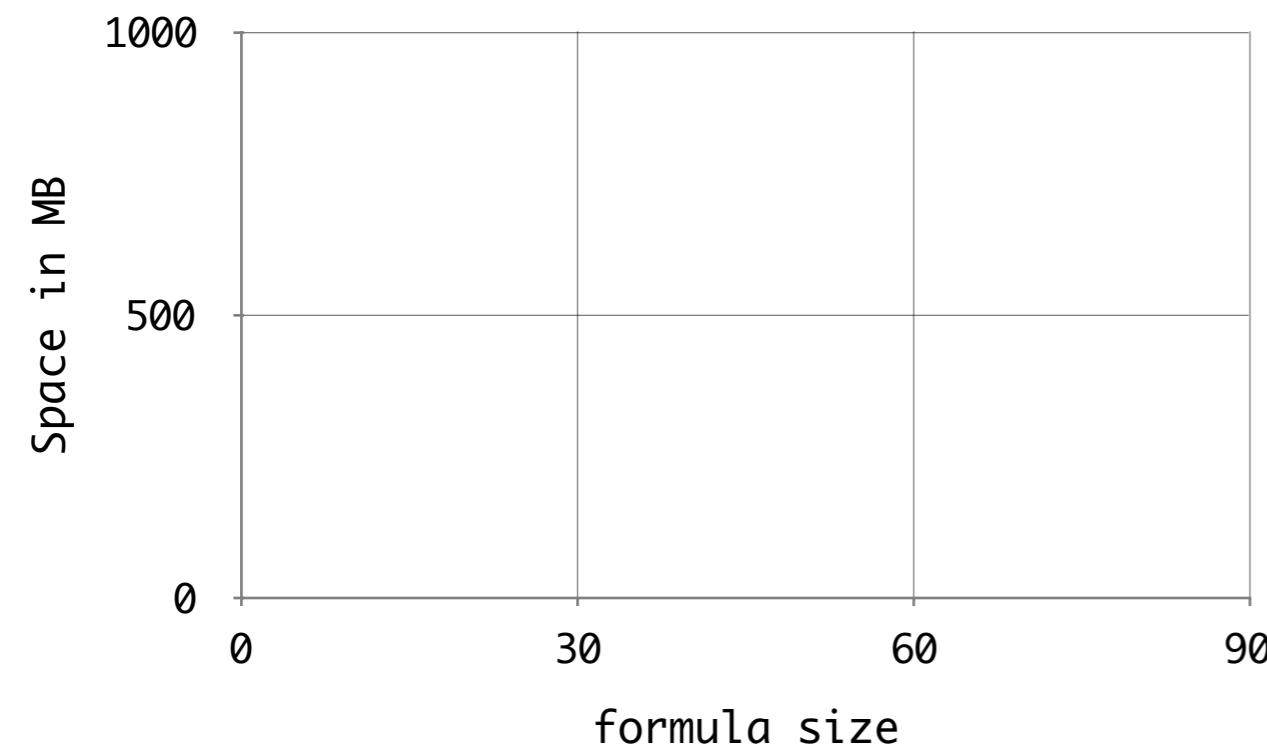
Formula Size

average of 10 random formulas
100s of random data
1000 events/s

Formula Size

- Aerial MDL
- Aerial MTL
- Monpoly

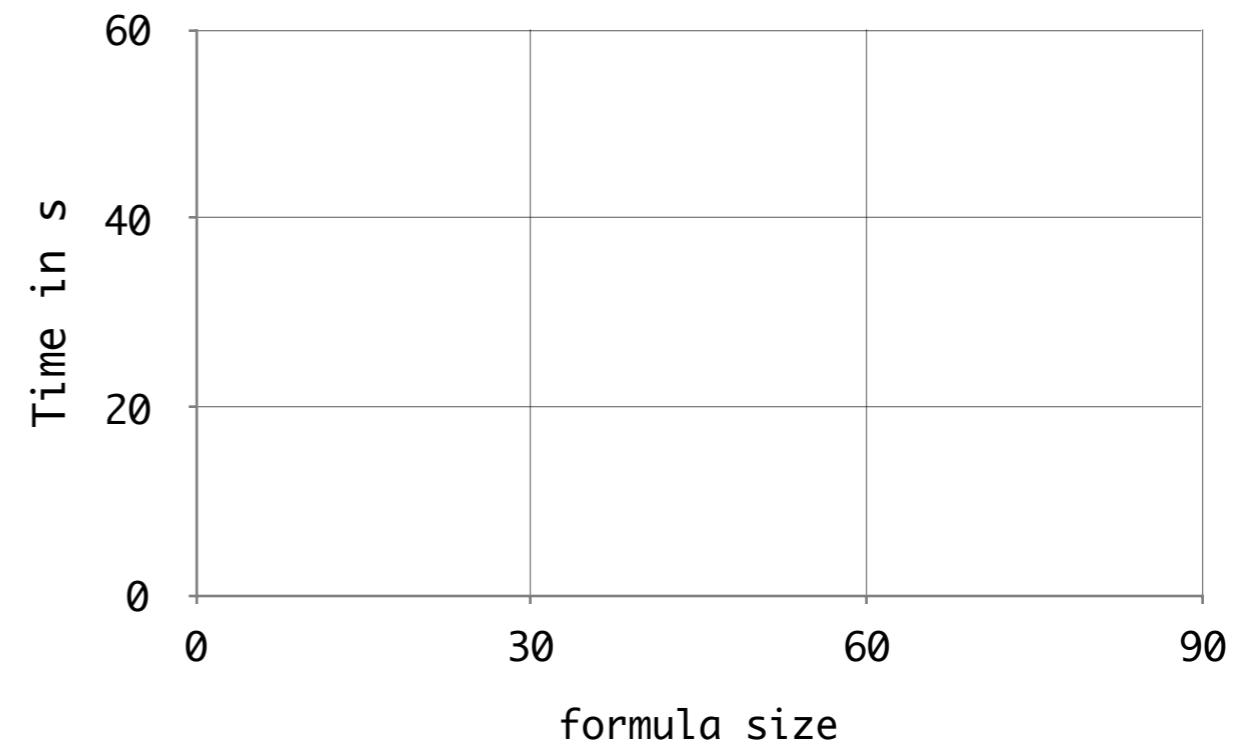
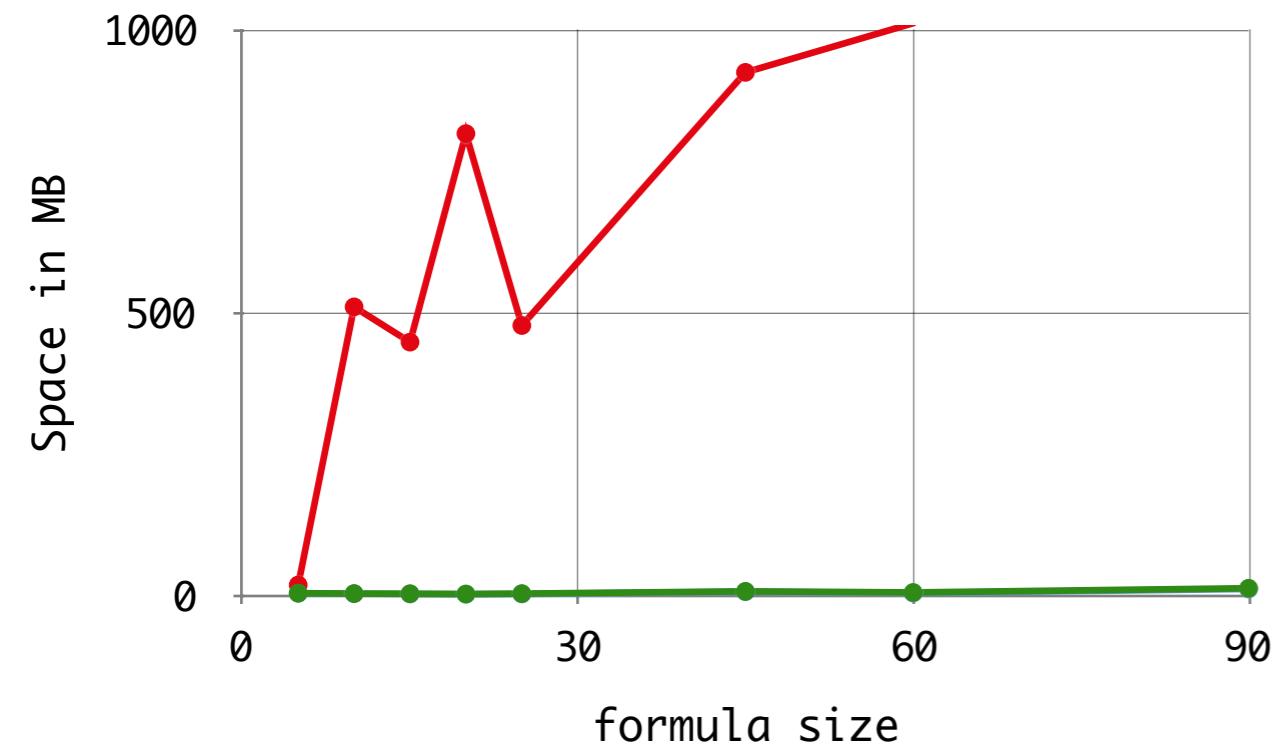
average of 10 random formulas
100s of random data
1000 events/s



Formula Size

- Aerial MDL
- Aerial MTL
- Monopoly

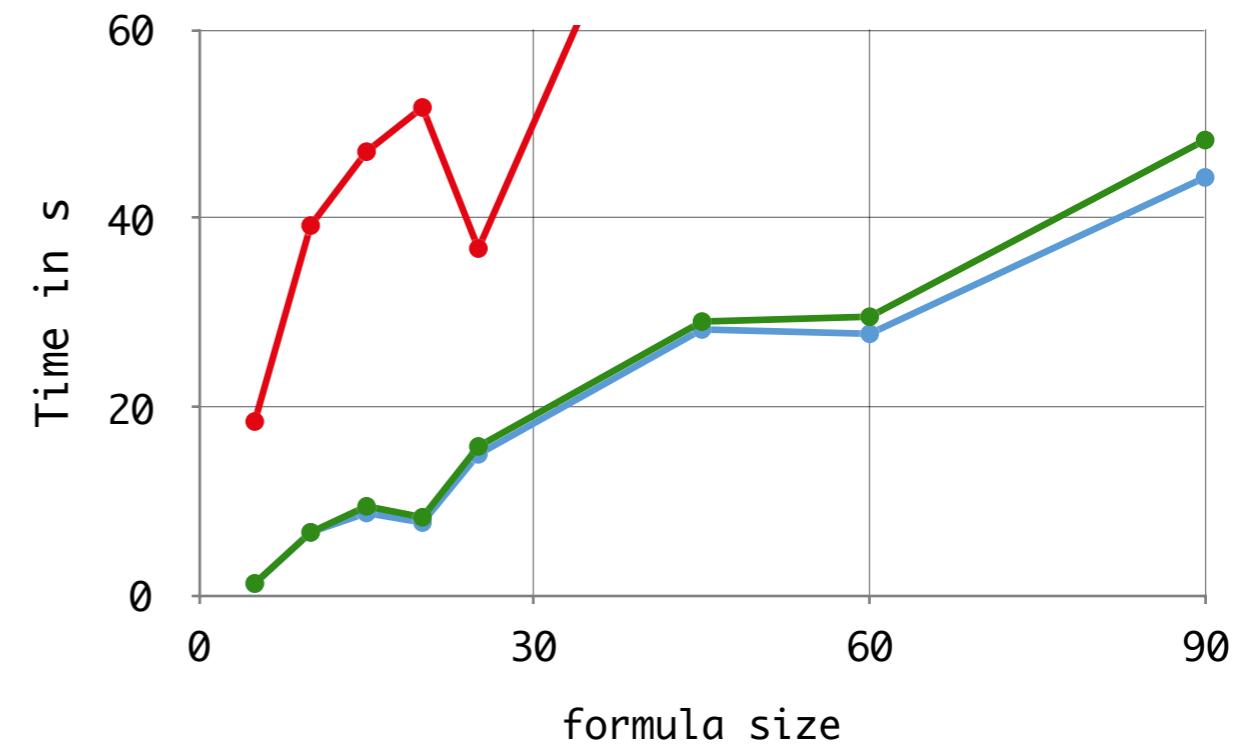
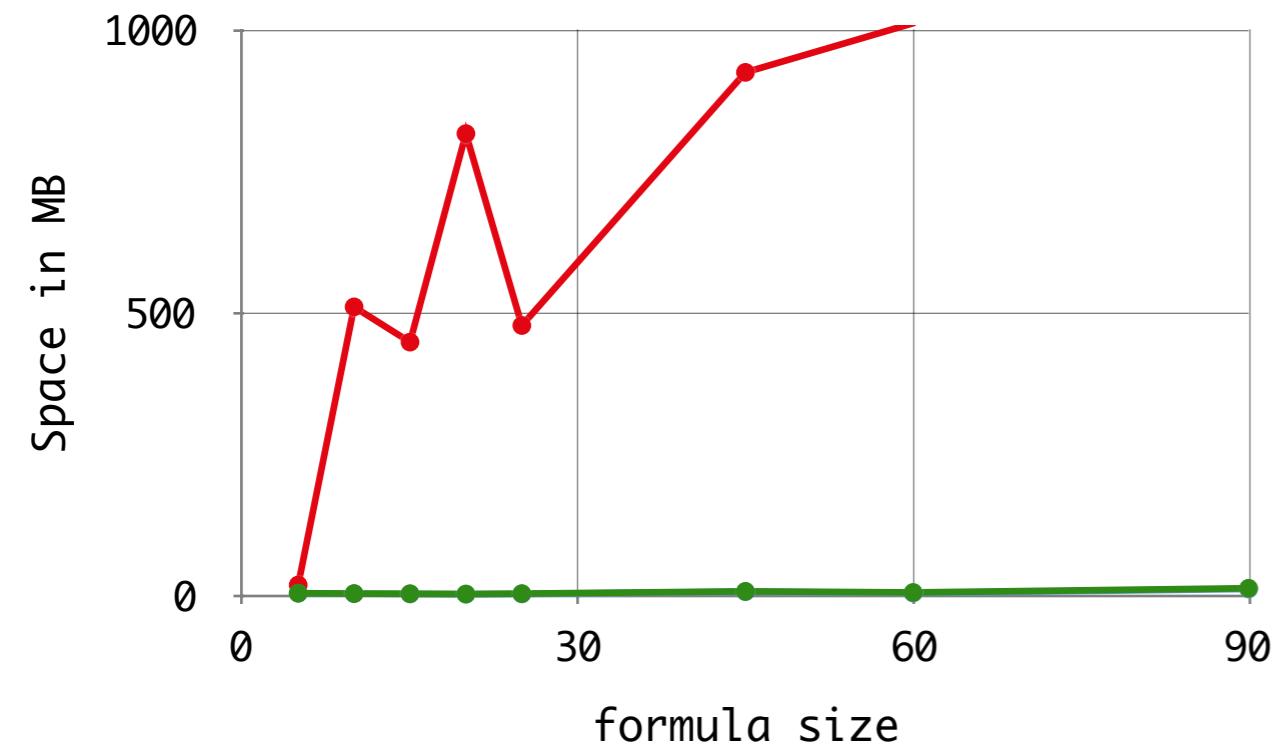
average of 10 random formulas
100s of random data
1000 events/s



Formula Size

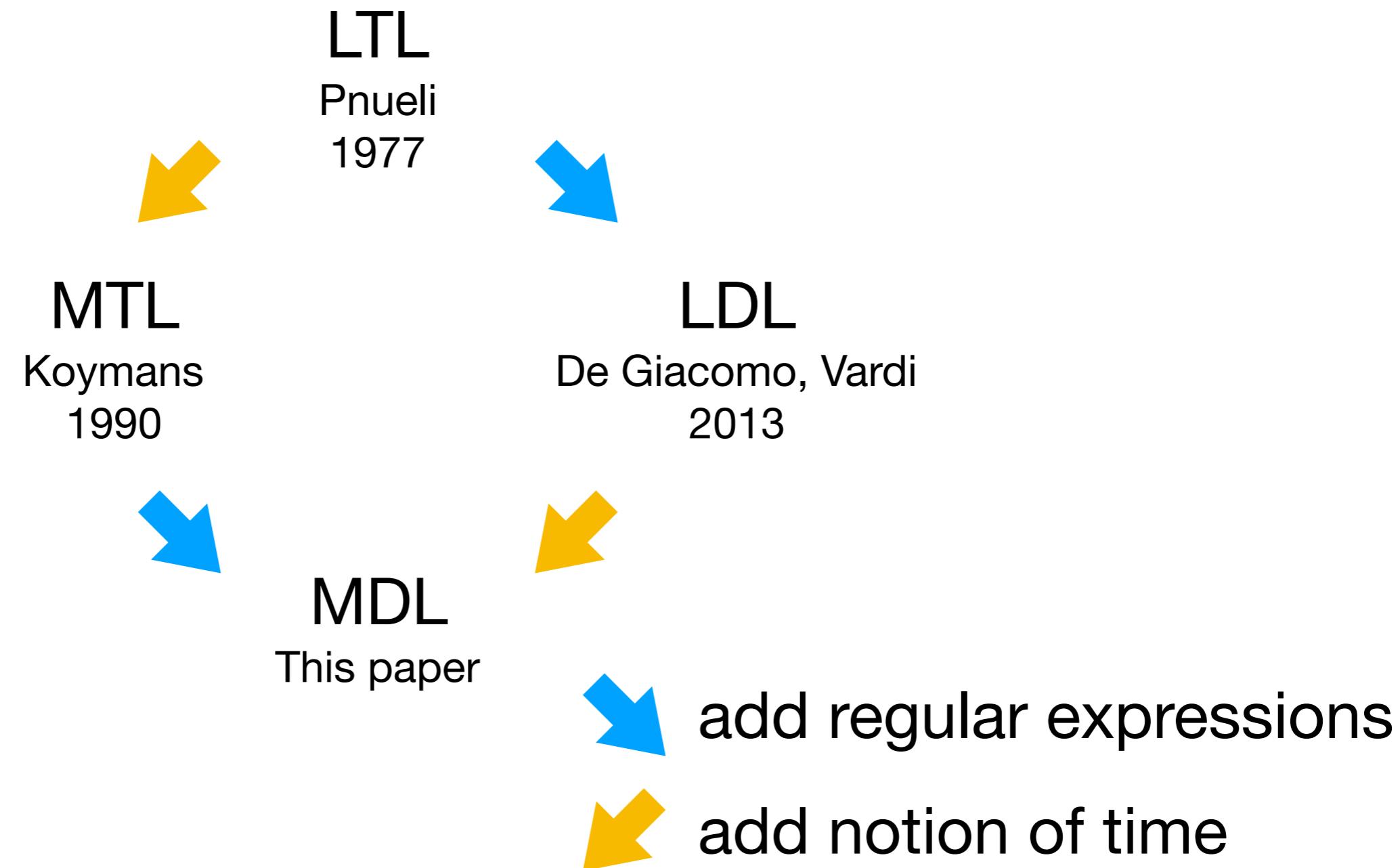
- Aerial MDL
- Aerial MTL
- Monopoly

average of 10 random formulas
100s of random data
1000 events/s

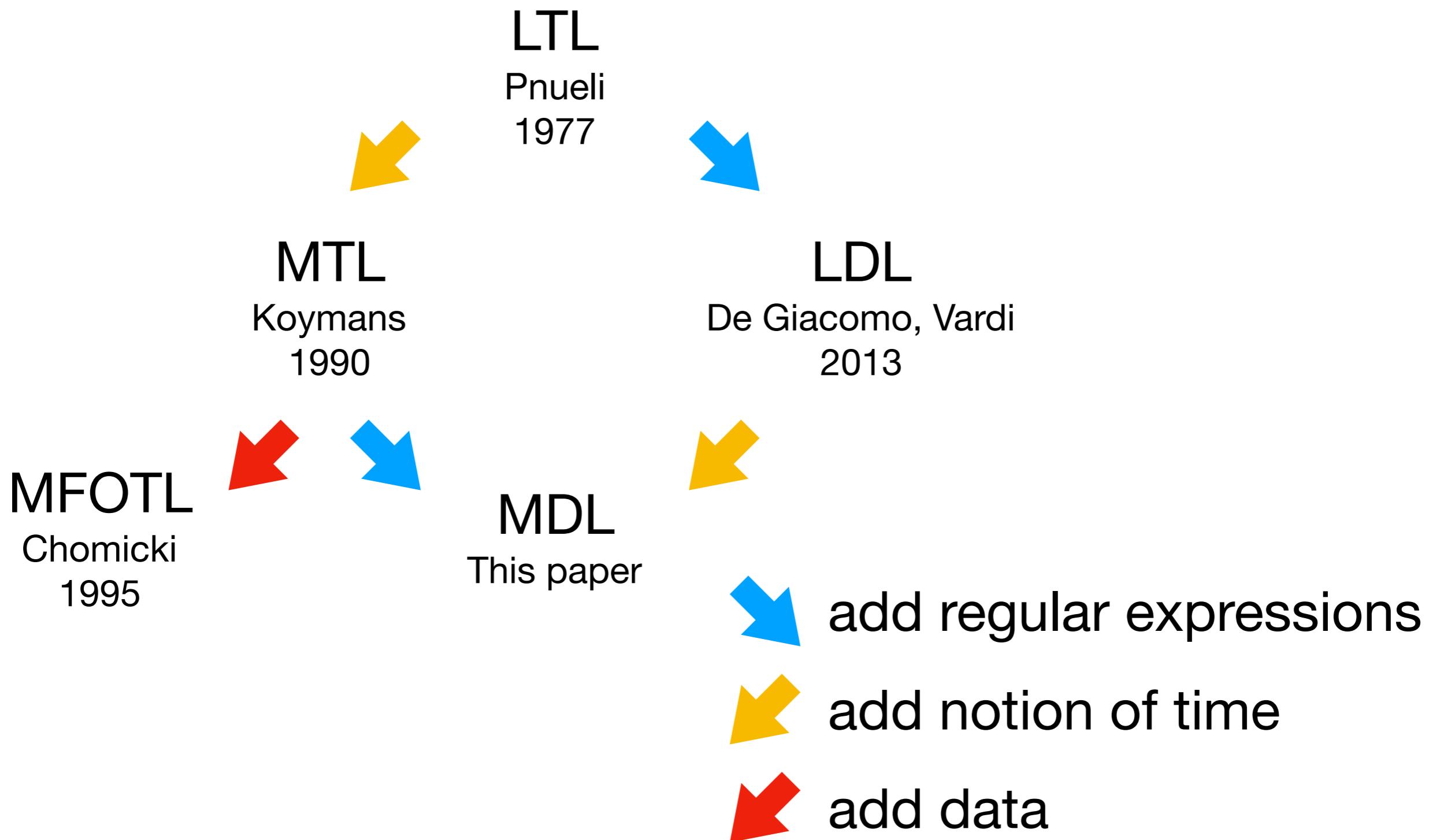


Future Work

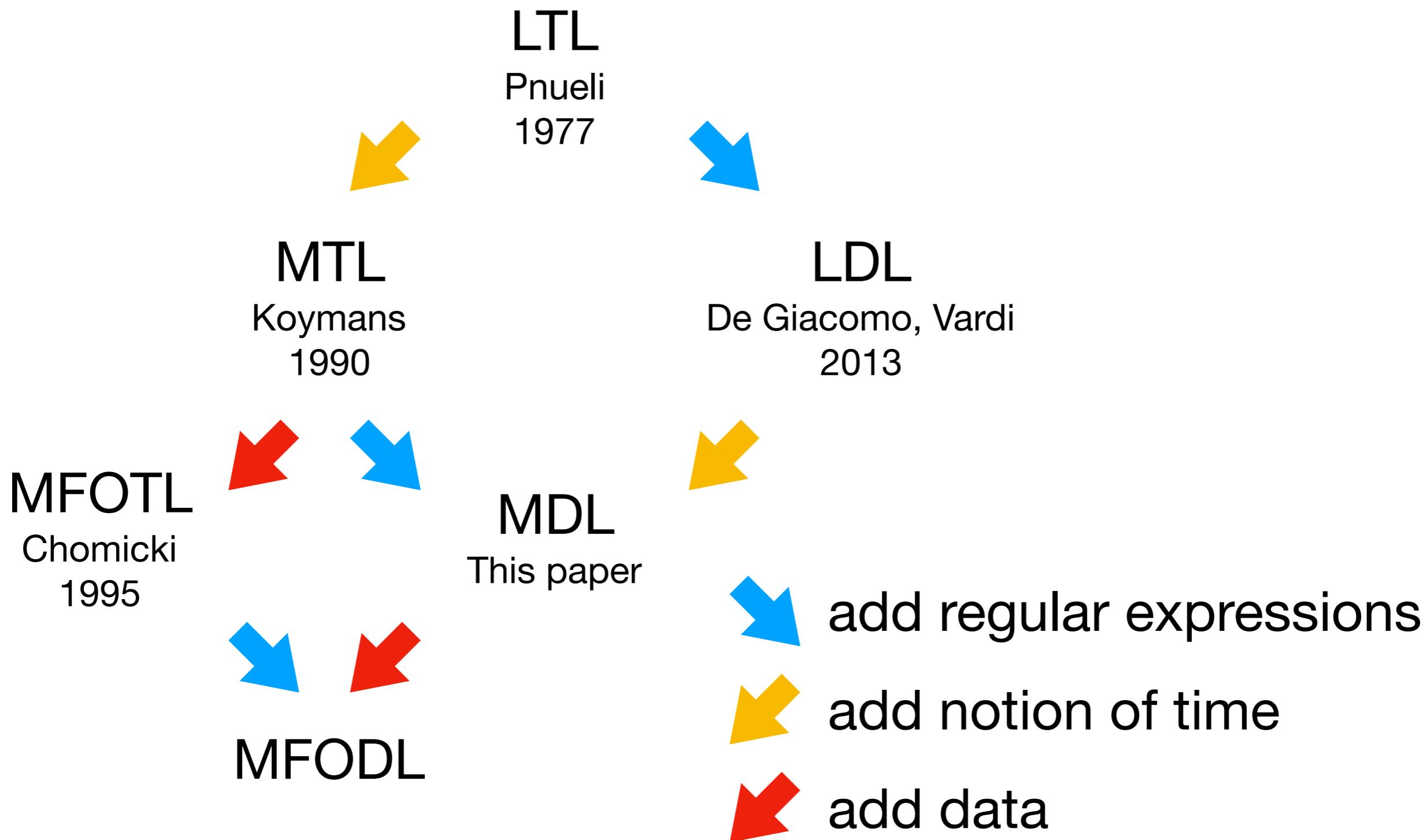
Expressiveness



Expressiveness



Expressiveness



Almost Event-Rate Independent Monitoring of Metric Dynamic Logic

David Basin



Srđan Krstić



Dmitriy Traytel



ETH zürich

75
NRP

Big Data
National Research Programme