Solution of the heat equation in 1D

Check orthogonality

out[5]:
$$J[m_{n}] = IP[v_{m}[x], v_{n}[x]]$$

$$n \sin(\pi m) \cos(\pi n) - m \cos(\pi m) \sin(\pi n)$$

$$\pi m^{2} - \pi n^{2}$$

A simple example

$$In[6]:= U_0[x_] = v_1[x] + 1 / 3 v_4[x]$$

$$Out[6]:= sin(\pi x) + \frac{1}{3} sin(4 \pi x)$$

• Find the coefficients

$$\begin{split} & & \text{In[7]:=} \quad B_{n_-} = \text{IP[v_n[x], U_0[x]] / IP[v_n[x], v_n[x]]} \\ & & & \frac{\left(n^2 + 44\right) \sin(\pi \, n)}{3 \, \pi \left(n^2 - 16\right) \left(n^2 - 1\right) \left(\frac{1}{2} - \frac{\sin(2 \, \pi \, n)}{4 \, \pi \, n}\right)} \\ & & \text{This is messy!} \\ & & \text{In[8]:=} \quad B_{n_-} = \text{Assuming[n } \in \text{Integers \&\& n } > 0 \text{, IP[v_n[x], U_0[x]] / IP[v_n[x], v_n[x]]]} \\ & \text{Out[8]=} \quad 0 \\ & & \text{This misses the special cases!} \\ & & \text{In[9]:=} \quad B_{n_-} := \text{IP[v_n[x], U_0[x]] / IP[v_n[x], v_n[x]]} \end{split}$$

• Form M-th partial sum of the solution

0.2

0.4

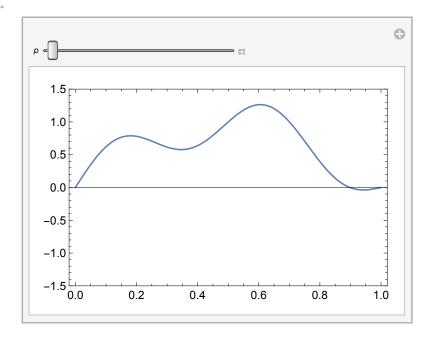
0.6

8.0

1.0

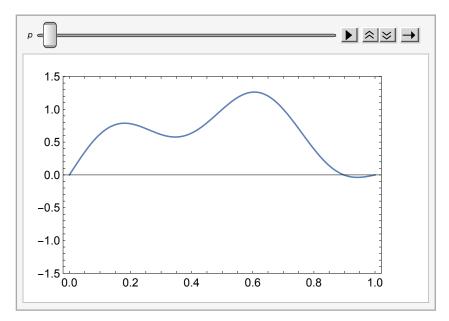
Manipulate[showU[10^p], {p, -4, 0}] In[15]:=

Out[15]=



Animate[showU[10^p], {p, -4, 0}, AnimationRunning \rightarrow False]

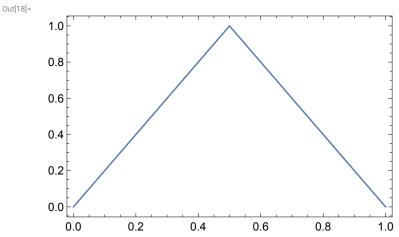
Out[16]=



A not-so-simple example

In[17]:=
$$U_0[x_] = Piecewise[{{2 x, x \le 1/2}, {2 (1-x), x > 1/2}}]$$
Out[17]:=
$$\begin{cases} 2x & x \le \frac{1}{2} \\ 2(1-x) & x > \frac{1}{2} \end{cases}$$

In[18]:=
$$Plot[U_0[x], \{x, 0, 1\}]$$



• Find the coefficients

$$In[19]:= B_{n_{-}} = IP[v_{n}[x], U_{0}[x]] / IP[v_{n}[x], v_{n}[x]]$$

Out[19]=

$$\frac{2\left(2\sin\left(\frac{\pi n}{2}\right) - \sin(\pi n)\right)}{\pi^2 n^2 \left(\frac{1}{2} - \frac{\sin(2\pi n)}{4\pi n}\right)}$$

This is messy!

$$In[20]:=$$
 $B_{n_{-}} = Assuming[n \in Integers && n > 0, IP[v_{n}[x], U_{0}[x]] / IP[v_{n}[x], v_{n}[x]]]$

Out[20]=

$$\frac{8\sin(\frac{\pi n}{2})}{\pi^2 n^2}$$

This misses the special cases!

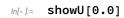
$$\ln[21] := B_{n_{-}} := IP[v_{n}[x], U_{0}[x]] / IP[v_{n}[x], v_{n}[x]]$$

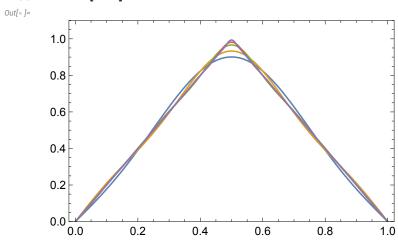
In[22]:= Table[{n, B_n}, {n, 1, 10}]

Out[22]=
$$\begin{pmatrix}
1 & \frac{8}{\pi^2} \\
2 & 0 \\
3 & -\frac{8}{9\pi^2} \\
4 & 0 \\
5 & \frac{8}{25\pi^2} \\
6 & 0 \\
7 & -\frac{8}{49\pi^2} \\
8 & 0 \\
9 & \frac{8}{81\pi^2} \\
10 & 0
\end{pmatrix}$$

• Form M-th partial sum of the solution

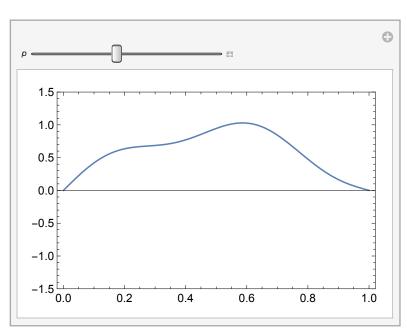
$$\begin{aligned} & \text{In}[23] = & \text{uSum}[M_-, \mathbf{x}_-, \mathbf{t}_-] := \text{Sum}[B_n \, \mathbf{v}_n[\mathbf{x}] \, \text{Exp}[-k_n^2 \, \mathbf{t}_-], \, \{n, 1, M\}] \\ & \text{In}[24] = & \text{u3}[\mathbf{x}_-, \mathbf{t}_-] = \text{uSum}[\mathbf{3}, \mathbf{x}, \mathbf{t}_-] \\ & & \frac{8 \, e^{-\pi^2 \, t} \sin(\pi x)}{\pi^2} - \frac{8 \, e^{-9 \, \pi^2 \, t} \sin(3 \, \pi \, x)}{9 \, \pi^2} \\ & \text{In}[25] = & \text{u5}[\mathbf{x}_-, \mathbf{t}_-] = \text{uSum}[\mathbf{5}, \mathbf{x}, \mathbf{t}_-] \\ & \frac{8 \, e^{-\pi^2 \, t} \sin(\pi \, x)}{\pi^2} - \frac{8 \, e^{-9 \, \pi^2 \, t} \sin(3 \, \pi \, x)}{9 \, \pi^2} + \frac{8 \, e^{-25 \, \pi^2 \, t} \sin(5 \, \pi \, x)}{25 \, \pi^2} \\ & \text{In}[26] = & \text{u11}[\mathbf{x}_-, \mathbf{t}_-] = \text{uSum}[\mathbf{11}, \mathbf{x}, \mathbf{t}_-] \\ & \frac{8 \, e^{-\pi^2 \, t} \sin(\pi \, x)}{\pi^2} - \frac{8 \, e^{-9 \, \pi^2 \, t} \sin(3 \, \pi \, x)}{9 \, \pi^2} + \frac{8 \, e^{-25 \, \pi^2 \, t} \sin(5 \, \pi \, x)}{25 \, \pi^2} - \frac{8 \, e^{-49 \, \pi^2 \, t} \sin(7 \, \pi \, x)}{49 \, \pi^2} + \frac{8 \, e^{-81 \, \pi^2 \, t} \sin(9 \, \pi \, x)}{81 \, \pi^2} - \frac{8 \, e^{-121 \, \pi^2 \, t} \sin(11 \, \pi \, x)}{121 \, \pi^2} \\ & \text{In}[27] = & \text{u21}[\mathbf{x}_-, \mathbf{t}_-] = \text{uSum}[21, \mathbf{x}, \mathbf{t}_-]; \\ & \text{In}[28] = & \text{u61}[\mathbf{x}_-, \mathbf{t}_-] = \text{uSum}[61, \mathbf{x}, \mathbf{t}_-]; \\ & \text{u61}[\mathbf{x}_-, \mathbf{t}_-] = \text{uSum}[61, \mathbf{x}, \mathbf{t}_-]; \\ & \text{showU}[\mathbf{t}_-] := \text{Plot}[\{u3[\mathbf{x}_+, \mathbf{t}_-], u5[\mathbf{x}_+, \mathbf{t}_-], u11[\mathbf{x}_+, \mathbf{t}_-], u21[\mathbf{x}_+, \mathbf{t}_-], u61[\mathbf{x}_+, \mathbf{t}_-], \\ & \text{showU}[\mathbf{t}_-] := \text{Plot}[\{u3[\mathbf{x}_+, \mathbf{t}_-], u5[\mathbf{x}_+, \mathbf{t}_-], u11[\mathbf{x}_+, \mathbf{t}_-], u21[\mathbf{x}_+, \mathbf{t}_-], u61[\mathbf{x}_+, \mathbf{t}_-], \\ & \text{u61}[\mathbf{x}_-, \mathbf{t}_-] = \text{u5m}[61, \mathbf{x}_+, \mathbf{t}_-], u5[\mathbf{x}_+, \mathbf{t}_-], u5[\mathbf{x}_+, \mathbf{t}_-], u61[\mathbf{x}_+, \mathbf{t}_-], u61[\mathbf{x}_+$$



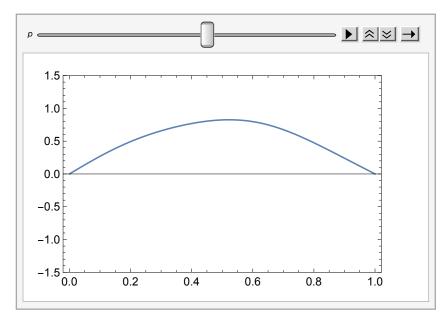


Manipulate[showU[10^p], {p, -4, 0}]





Animate[showU[10^p], $\{p, -4, 0\}$, AnimationRunning \rightarrow False] In[o]:= Out[•]=



Animate[showU[t], $\{t, 0, 1\}$, AnimationRunning \rightarrow False] Out[•]=

