

Math 521 HW3

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1 Theory

1.1 Problem 1

To prove $\nabla_v(v, v) = 2v$

Let $v = [v_1, v_2, v_3 \dots v_n]$

$$\text{L.H.S} = \nabla_v(v, v) = \frac{d}{dv}(v^T v)$$

$$\text{Let } \alpha = v^T v = \sum_{i=1}^n \sum_{j=1}^n v_i v_j$$

Differentiating w.r.t to the kth element of v we have:

$$\frac{d\alpha}{dv_k} = \sum_{i=1}^n v_j + \sum_{i=1}^n v_i$$

for all $k = 1, 2, 3, \dots, n$, we have

$$\frac{d\alpha}{dv_k} = v^T + v^T = 2v^T = 2v = \text{R.H.S}$$

To prove $\nabla_v(v, Cv) = 2Cv$

$$\text{L.H.S} = \nabla_v(v, Cv) = \nabla_v v^T C v$$

$$\text{Let } \alpha = v^T C v = \sum_{i=1}^n \sum_{j=1}^n c_{ij} v_i v_j$$

Differentiating w.r.t to the kth element of v we have:

$$\frac{d\alpha}{dv_k} = \sum_{i=1}^n c_{kj} v_j + \sum_{i=1}^n c_{ik} v_i$$

for all $k = 1, 2, 3, \dots, n$, we have

$$\frac{d\alpha}{dv_k} = v^T C^T + v^T C = v^T 2C = 2Cv = \text{R.H.S} \text{ (Since } C = C^T \text{)}$$

1.2 Problem 2

To prove $(\phi^{(1)}, C\phi^{(2)}) = (C\phi^{(1)}, \phi^{(2)})$

$$\text{R.H.S} = (C\phi^{(1)}, \phi^{(2)}) = C\phi^{(1)} \cdot \phi^{(2)} = \phi^{(1)T} C^T \phi^{(2)}$$

$$= \phi^{(1)T} C \phi^{(2)} \text{ (Since } C = C^T \text{ as } C \text{ is symmetric)}$$

$$= (\phi^{(1)}, C\phi^{(2)}) = \text{L.H.S}$$

1.3 Problem 4

Determine the eigenvalues and eigenvectors of $X^T X$ and XX^T given

$$X = \begin{pmatrix} -2 & -1 & 1 \\ 0 & -1 & 0 \\ -1 & 1 & -2 \\ 1 & -1 & 1 \end{pmatrix}$$

$$X^T X = \begin{pmatrix} 6 & 0 & -3 \\ 0 & 4 & 0 \\ -3 & 0 & 6 \end{pmatrix}$$

To get the eigenvalue we set: $\det(X^T X - \lambda I) = 0$

$$\Rightarrow \det\left(\begin{pmatrix} 6 & 0 & -3 \\ 0 & 4 & 0 \\ -3 & 0 & 6 \end{pmatrix} - \begin{pmatrix} \lambda & 0 & 0 \\ 0 & \lambda & 0 \\ 0 & 0 & \lambda \end{pmatrix}\right) = 0$$

$$\Rightarrow (6 - \lambda)((4 - \lambda)(6 - \lambda) - 0) - 0 + (-3)(3(4 - \lambda)) = 0$$

$$\Rightarrow ((6 - \lambda)^2 - 9)(4 - \lambda) = 0$$

$$\Rightarrow \lambda = 9, 4 \text{ or } 3$$

For $\lambda = 9$

$$X^T X - \lambda I = \begin{pmatrix} -3 & 0 & -3 \\ 0 & -5 & 0 \\ -3 & 0 & -3 \end{pmatrix}$$

$$\text{The rref of the above matrix} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

To find the null space of the above matrix we do the following:

$$\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$\Rightarrow x_1 = -x_3$$

$$\Rightarrow x_2 = 0$$

$$\text{Therefore the null space of } X^T X - \lambda I = \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{So } v_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \text{ since we have to normalize the null space, as the } v_i \text{ vectors}$$

are orthonormal.

Similarly for $\lambda_2 = 4$ we have:

$$X^T X - \lambda_2 I = \begin{pmatrix} 2 & 0 & -3 \\ 0 & 0 & 0 \\ -3 & 0 & 2 \end{pmatrix}$$

$$\text{The rref of the above matrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

To find the null space of the above matrix we do the following:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$\Rightarrow x_1 = 0$$

$$\Rightarrow x_3 = 0$$

$$\text{Therefore the null space of } X^T X - \lambda_2 I = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\text{So } v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

And finally for $\lambda_3 = 3$

$$X^T X - \lambda_3 I = \begin{pmatrix} 3 & 0 & -3 \\ 0 & 1 & 0 \\ -3 & 0 & -3 \end{pmatrix}$$

$$\text{The rref of the above matrix} = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

To find the null space of the above matrix we do the following:

$$\begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = 0$$

$$\Rightarrow x_1 = x_3$$

$$\Rightarrow x_2 = 0$$

Therefore the null space of $X^T X - \lambda_3 I = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$

$$\text{So } v_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ -1 \end{pmatrix}$$

The S matrix is constructed by taking the square root of the eigenvalues λ s and putting them in a diagonal matrix as follows:

$$S = \begin{pmatrix} \sigma_1 & 0 & 0 \\ 0 & \sigma_2 & 0 \\ 0 & 0 & \sigma_3 \end{pmatrix} = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & \sqrt{3} \end{pmatrix}$$

The eigenvalues of XX^T are same as $X^T X$

For $\lambda = 9$

$$XX^T - \lambda I = \begin{pmatrix} -3 & 1 & 3 & 0 \\ 1 & -8 & -1 & 1 \\ 3 & -1 & -3 & 0 \\ 0 & 1 & 0 & -6 \end{pmatrix}$$

$$\text{The rref of the above matrix} = \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\text{Therefore the null space of } XX^T - \lambda_1 I = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\text{So } u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ -1 \\ 0 \end{pmatrix}$$

For $\lambda_2 = 4$

$$XX^T - \lambda_2 I = \begin{pmatrix} 2 & 1 & 3 & 0 \\ 1 & -3 & -1 & 1 \\ 3 & -1 & 2 & 0 \\ 0 & 1 & 0 & -1 \end{pmatrix}$$

The rref of the above matrix =
$$\begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Therefore the null space of $XX^T - \lambda_2 I = \begin{pmatrix} 1 \\ 1 \\ -1 \\ 1 \end{pmatrix}$

So $u_2 = \frac{1}{2} \begin{pmatrix} -1 \\ -1 \\ 1 \\ -1 \end{pmatrix}$

For $\lambda_3 = 3$

$$XX^T - \lambda_3 I = \begin{pmatrix} 3 & 1 & 3 & 0 \\ 1 & -2 & -1 & 1 \\ 3 & -1 & 3 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

The rref of the above matrix =
$$\begin{pmatrix} 1 & 0 & 0 & 0.5 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -0.5 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Therefore the null space of $XX^T - \lambda_3 I = \begin{pmatrix} -0.5 \\ 0 \\ 0.5 \\ 1 \end{pmatrix}$

So $u_3 = \sqrt{\frac{2}{3}} \begin{pmatrix} 0.5 \\ 0 \\ -0.5 \\ 1 \end{pmatrix}$

To get the U matrix we do the following:

$$u_1 = \frac{1}{\sigma_1} X v_1 = \frac{1}{3} \begin{pmatrix} -2 & -1 & 1 \\ 0 & -1 & 0 \\ -1 & 1 & -2 \\ 1 & -1 & 1 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ -1 \\ 0 \end{pmatrix}$$

$$u_2 = \frac{1}{\sigma_2} X v_2 = \frac{1}{2} \begin{pmatrix} -2 & -1 & 1 \\ 0 & -1 & 0 \\ -1 & 1 & -2 \\ 1 & -1 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -1 \\ -1 \\ 1 \\ -1 \end{pmatrix}$$

$$u_3 = \frac{1}{\sigma_3} X v_3 = \frac{1}{\sqrt{3}} \begin{pmatrix} -2 & -1 & 1 \\ 0 & -1 & 0 \\ -1 & 1 & -2 \\ 1 & -1 & 1 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ -1 \end{pmatrix} = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ 0 \\ -1 \\ -2 \end{pmatrix}$$

$$u_4 = \frac{NS(X^T)}{\det(NS(X^T))}$$

$$rref(X^T) = \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 1 \end{pmatrix}$$

$$\text{Therefore, } \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = 0$$

$$\begin{aligned} &=> x_1 = x_4 \\ x_2 &= -3x_4 \\ x_3 &= -x_4 \end{aligned}$$

$$\text{Therefore the null space of } A^T = \begin{pmatrix} 1 \\ -3 \\ -1 \\ 1 \end{pmatrix}$$

$$u_4 = \frac{1}{2\sqrt{3}} \begin{pmatrix} 1 \\ -3 \\ -1 \\ 1 \end{pmatrix}$$

$$\begin{aligned} \text{Finally SVD of } X &= U \Sigma V^T = \begin{pmatrix} -0.7071 & -0.5 & 0.4082 & 0.2887 \\ 0 & -0.5 & 0 & -0.8660 \\ -0.7071 & 0.5 & -0.4082 & -0.2887 \\ 0 & -0.5 & -0.8165 & 0.2887 \end{pmatrix} \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & \sqrt{3} \\ 0 & 0 & 0 \end{pmatrix} \\ &\begin{pmatrix} 0.7071 & 0 & -0.7071 \\ 0 & 1 & 0 \\ -0.7071 & 0 & -0.7071 \end{pmatrix} \end{aligned}$$

1.4 Problem 5

If we take thin SVD

$$A = \Sigma V^T$$

$$= \begin{pmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & \sqrt{3} \end{pmatrix} \begin{pmatrix} 0.7071 & 0 & -0.7071 \\ 0 & 1 & 0 \\ -0.7071 & 0 & -0.7071 \end{pmatrix}$$

This requires 9 multiplications and 0 additions

$$A = U^T \Sigma$$

$$\begin{pmatrix} -0.7071 & 0 & -0.7071 & 0 \\ -0.5 & -0.5 & 0.5 & -0.5 \\ 0.4082 & 0 & -0.4082 & -0.8165 \end{pmatrix} \begin{pmatrix} -2 & -1 & 1 \\ 0 & -1 & 0 \\ -1 & 1 & -2 \\ 1 & -1 & 1 \end{pmatrix}$$

This requires 36 multiplications and 27 additions.

$A = \Sigma V^T$ is better. This is because we are dealing with a diagonal matrix Σ which reduces computations.