

Math 521 HW1

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1 Theory

1. Change of basis

Given standard vectors defining \mathcal{B}_1 are $e^{(1)} = (1 \ 0)^T$ and $e^{(2)} = (0 \ 1)^T$

or $E = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

Basis vectors defining \mathcal{B}_2 are $v^{(1)} = (1 \ 1)^T$ and $v^{(2)} = (-1 \ 1)^T$ or

$V = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}$

Given $u_{\mathcal{B}_1} = (1 \ 1)^T$

Since both \mathcal{B}_1 and \mathcal{B}_2 span R^2 , any vector in R^2 can be represented as

$u = x_1 e^{(1)} + x_2 e^{(2)}$ and

$u = y_1 v^{(1)} + y_2 v^{(2)}$ or

$$Eu_{\mathcal{B}_1} = Vu_{\mathcal{B}_2}$$

$$\Rightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix} u_{\mathcal{B}_2}$$

$$u_{\mathcal{B}_2} = \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0.5 & 0.5 \\ -0.5 & 0.5 \end{pmatrix}$$