

# Deep Learning

## 15 Encoder-Decoder Models

Dr. Konda Reddy Mopuri  
Dept. of AI, IIT Hyderabad  
Jan-May 2023

# Encoder-Decoder Model

- ① Revisit the 'language modeling' problem

# Encoder-Decoder Model

- ① Revisit the 'language modeling' problem
- ②  $y^* = \operatorname{argmax} P(y_t / y_1, y_2 \dots y_{t-1})$

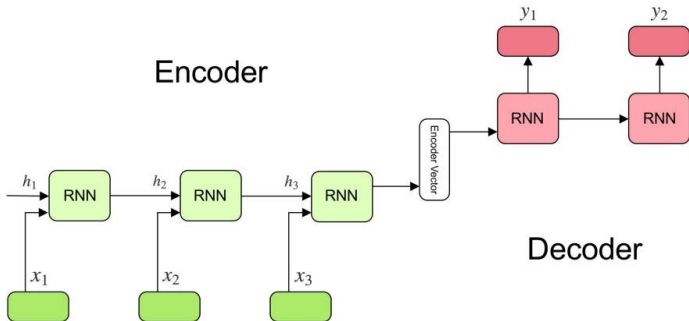
# Encoder-Decoder Model

- ① Revisit the 'language modeling' problem
- ②  $y^* = \operatorname{argmax} P(y_t / y_1, y_2 \dots y_{t-1})$
- ③ We have an RNN consuming the i/p sequence  $(y_1^{t-1}) \rightarrow$  **Encoder**

# Encoder-Decoder Model

- ① Revisit the 'language modeling' problem
- ②  $y^* = \operatorname{argmax} P(y_t/y_1, y_2 \dots y_{t-1})$
- ③ We have an RNN consuming the i/p sequence  $(y_1^{t-1}) \rightarrow$  **Encoder**
- ④ We have another RNN predicting the o/p (sequence of words after the i/p)  $\rightarrow$  **Decoder**

# Encoder-Decoder Model



Credits: Simeon Kostadinov

# Encoder-Decoder Model

- 1 Both encoder and decoder use Neural networks

# Encoder-Decoder Model

- ① Both encoder and decoder use Neural networks
- ② Based on the application need minor adjustments



# Encoder-Decoder Model

- ① Both encoder and decoder use Neural networks
- ② Based on the application need minor adjustments
- ③ Basis for a lot of applications

# Encoder-Decoder Model

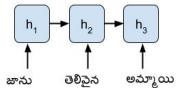
- ① Both encoder and decoder use Neural networks
- ② Based on the application need minor adjustments
- ③ Basis for a lot of applications
- ④ Let's consider machine translation...

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

Output sequence:  $y_1, y_2, \dots, y_T$

Encoder:  $h_t = E(x_t, h_{t-1})$



---

Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

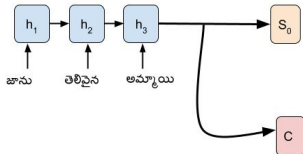
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Encoder:  $h_t = E(x_t, h_{t-1})$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

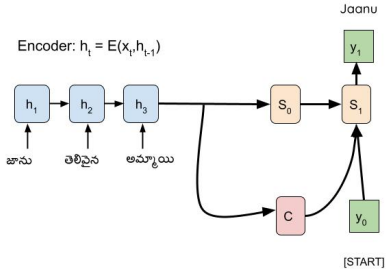
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Decoder:  $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

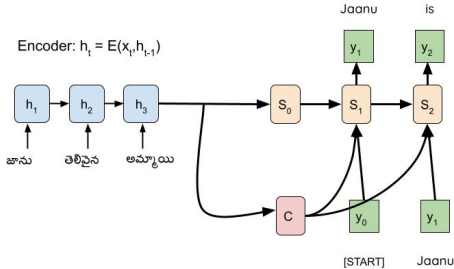
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Decoder:  $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

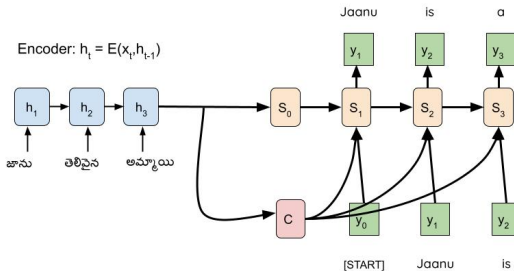
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Decoder:  $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

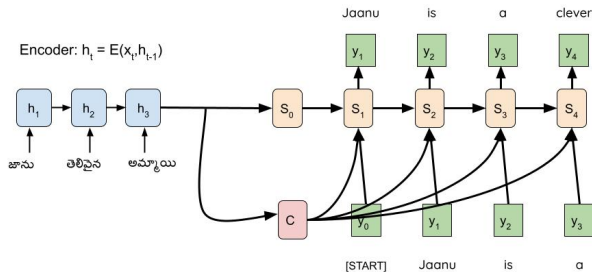
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Decoder:  $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014



# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

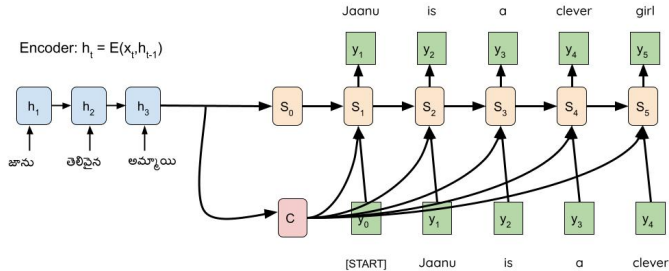
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Decoder:  $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

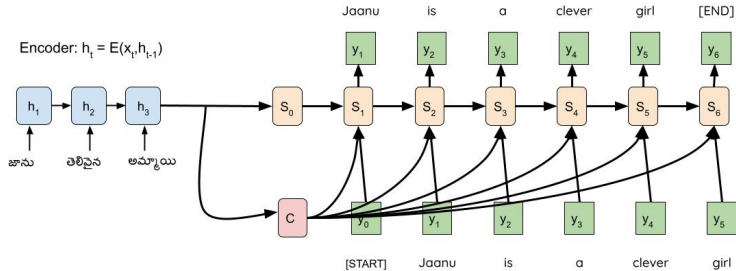
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Decoder:  $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

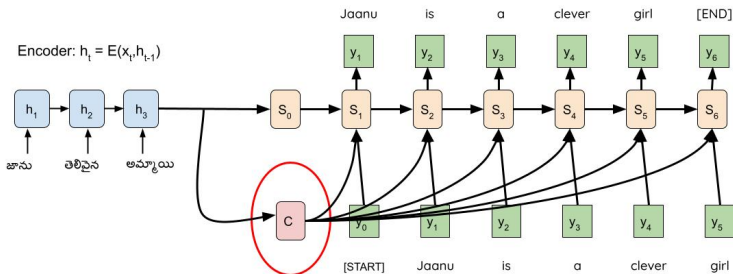
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Decoder:  $s_t = D(y_{t-1}, s_{t-1}, C)$



Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation

Input sequence:  $x_1, x_2, \dots, x_T$

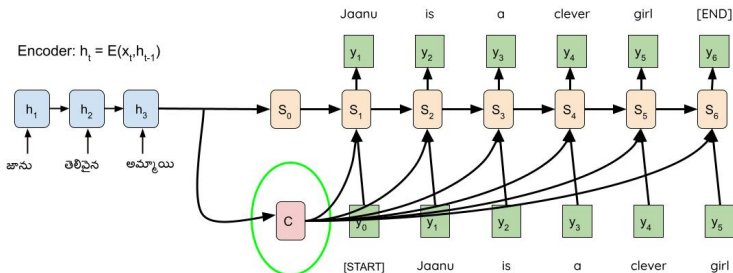
Output sequence:  $y_1, y_2, \dots, y_T$

Last hidden state  $h_T \rightarrow$  Initial state of the Decoder

$S_0$  and the context information  $C$

E.g.  $S_0 \leftarrow h_T + \text{dense layers}$ , and  $C \leftarrow h_T$

Decoder:  $s_t = D(y_{t-1}, s_{t-1}, C)$



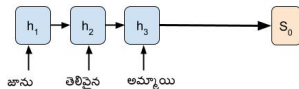
Sequence to sequence learning by Sutskever et al. NeurIPS 2014

# Encoder-Decoder for Machine Translation with Attention

Input sequence:  $x_1, x_2, \dots, x_T$

Input sequence:  $y_1, y_2, \dots, y_T$

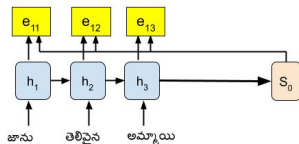
Encoder:  $h_t = E(x_t, h_{t-1})$



# Encoder-Decoder for Machine Translation with Attention

Compute the alignment scores

$$e_{t,i} = f_{\text{att}}(s_{t-1}, h_i) \quad f_{\text{att}} - \text{couple of dense layers}$$

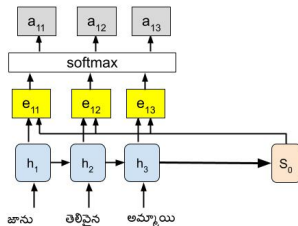


Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention

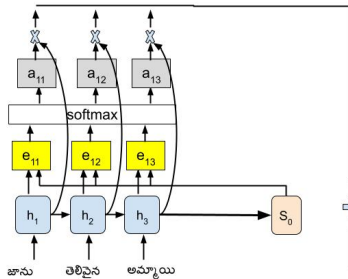
Compute the alignment scores

$$e_{t,i} = f_{\text{att}}(s_{t-1}, h_i) \quad f_{\text{att}} - \text{couple of dense layers}$$



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention



Compute the alignment scores

$$e_{t,i} = f_{\text{att}}(s_{t-1}, h_i) \quad f_{\text{att}} - \text{couple of dense layers}$$

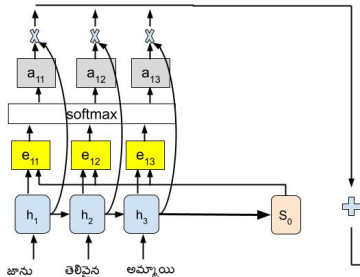
Compute the context as a linear combination of intermediate hidden states

$$c_t = \sum_i a_{i,t} \cdot h_i$$

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015



# Encoder-Decoder for Machine Translation with Attention

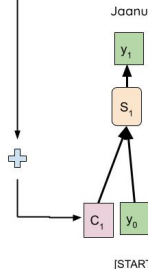


Compute the alignment scores

$$e_{t,i} = f_{\text{att}}(s_{t-1}, h_i) \quad f_{\text{att}} - \text{couple of dense layers}$$

Compute the context as a linear combination of intermediate hidden states

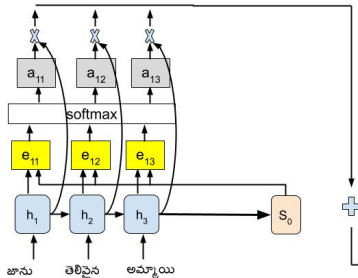
$$c_t = \sum_i a_{i,t} \cdot h_i$$



$$\text{Decoder: } s_t = D(y_{t-1}, C_t)$$

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention



Compute the alignment scores

$$e_{t,i} = f_{\text{att}}(s_{t-1}, h_i) \quad f_{\text{att}} - \text{couple of dense layers}$$

Compute the context as a linear combination of intermediate hidden states

$$c_t = \sum_i a_{i,t} \cdot h_i$$

Jaanu



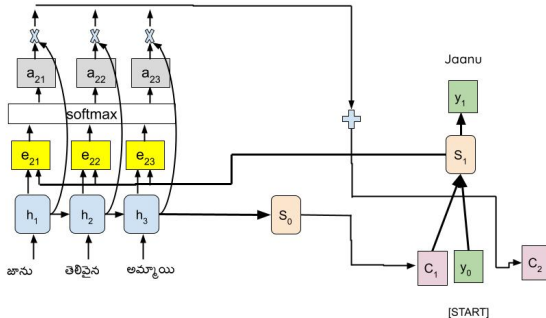
$$\text{Decoder: } s_t = D(y_{t-1}, C_t)$$

All these operations are differentiable!  
 Attention is learned using backprop!!

[START]

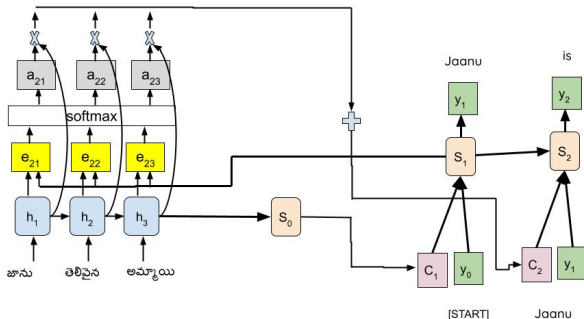
Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention



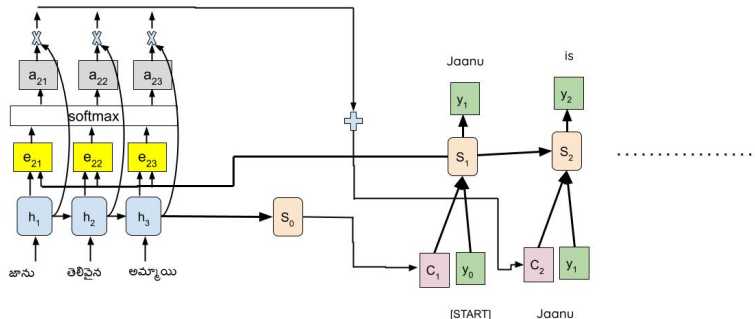
Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention



Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

- Employs a different context at each time step of decoding

---

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention

- Employs a different context at each time step of decoding
- No more bottleneck-ing of the input

---

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention

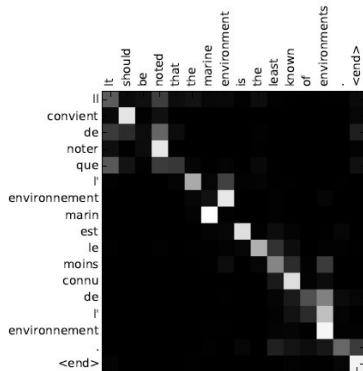
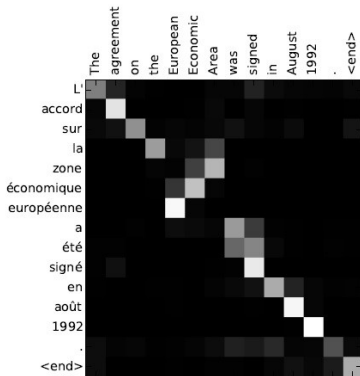
- Employs a different context at each time step of decoding
- No more bottleneck-ing of the input
- Decoder can 'attend' to different portions of the input at each time step

---

Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

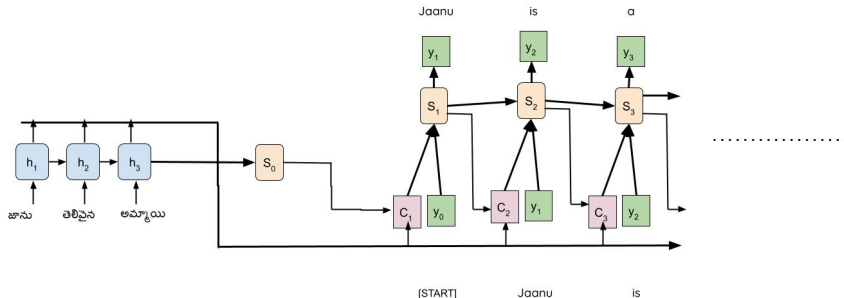


# Encoder-Decoder for Machine Translation with Attention



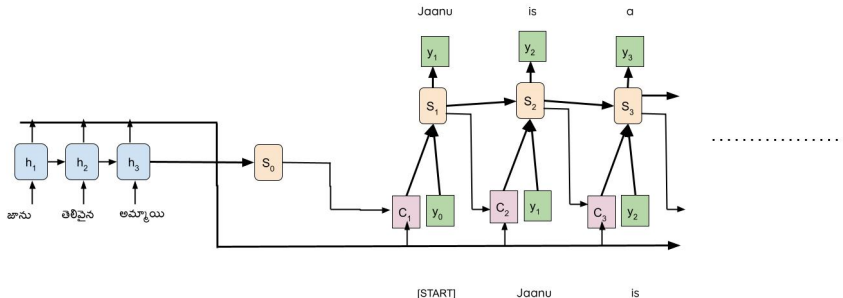
Neural Machine Translation with aligning by Bahdanau et al. ICLR 2015

# Encoder-Decoder for Machine Translation with Attention



- Decoder doesn't consider the  $h_i$  to be an ordered set

# Encoder-Decoder for Machine Translation with Attention



- Decoder doesn't consider the  $h_i$  to be an ordered set
- This architecture can be exploited to process a set of inputs  $h_i$

# Image captioning using RNNs with Attention

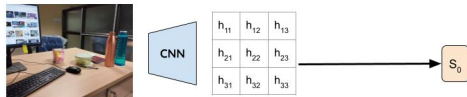


$h_{11}$	$h_{12}$	$h_{13}$
$h_{21}$	$h_{22}$	$h_{23}$
$h_{31}$	$h_{32}$	$h_{33}$

---

Show Attend and Tell by Xu et al. 2015

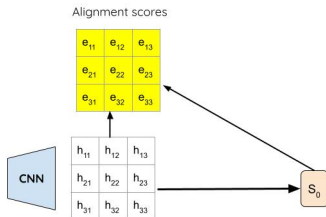
# Image captioning using RNNs with Attention



---

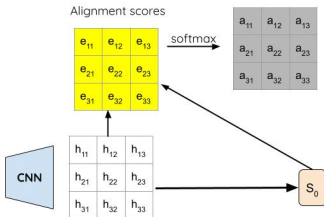
Show Attend and Tell by Xu et al. 2015

# Image captioning using RNNs with Attention



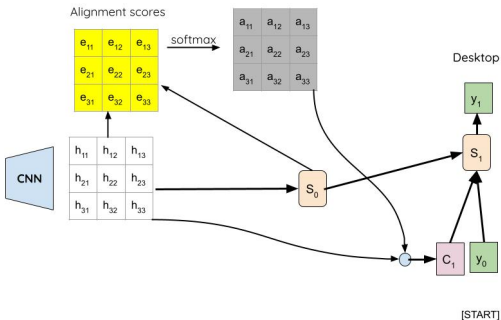
Show Attend and Tell by Xu et al. 2015

# Image captioning using RNNs with Attention



Show Attend and Tell by Xu et al. 2015

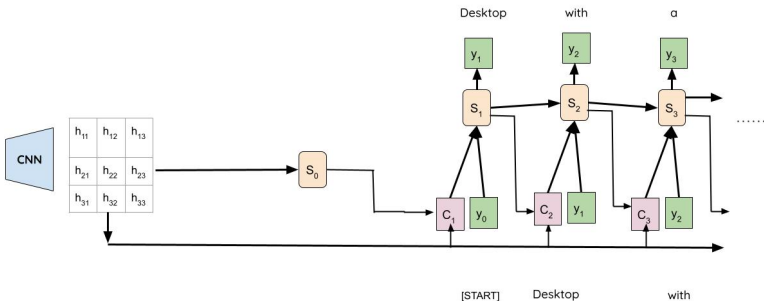
# Image captioning using RNNs with Attention



Show Attend and Tell by Xu et al. 2015



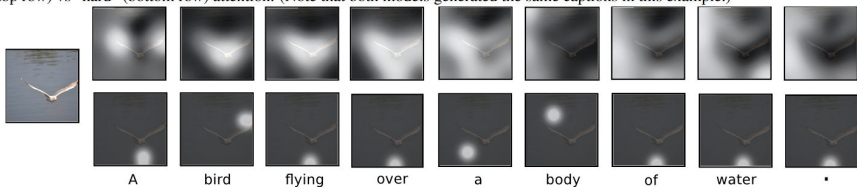
# Image captioning using RNNs with Attention



Show Attend and Tell by Xu et al. 2015

# Image captioning using RNNs with Attention

Figure 2. Attention over time. As the model generates each word, its attention changes to reflect the relevant parts of the image. “soft” (top row) vs “hard” (bottom row) attention. (Note that both models generated the same captions in this example.)

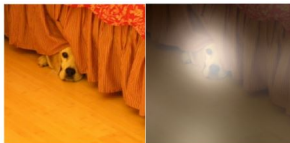


Show Attend and Tell by Xu et al. 2015

# Image captioning using RNNs with Attention



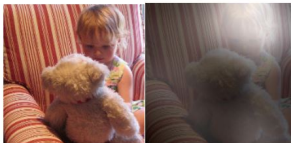
A woman is throwing a frisbee in a park.



A dog is standing on a hardwood floor.



A stop sign is on a road with a mountain in the background.



A little girl sitting on a bed with a teddy bear.



A group of people sitting on a boat in the water.



A giraffe standing in a forest with trees in the background.

---

Show Attend and Tell by Xu et al. 2015



1

2

1

2

3

1

2

3

4

1

2

3

4

5





1

2

1

2

3

1

2

3

4

1

2

3

4

5