Foundations of Machine Learning Al2000 and Al5000

FoML-06 Linear Regression

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So far in FoML

- What is ML and the learning paradigms
- Probability refresher
- MLE, MAP, and fully Bayesian treatment





Linear Regression





Linear Regression

Dataset D = ? (2, 6) (2 52) ... (2)

x; ERD

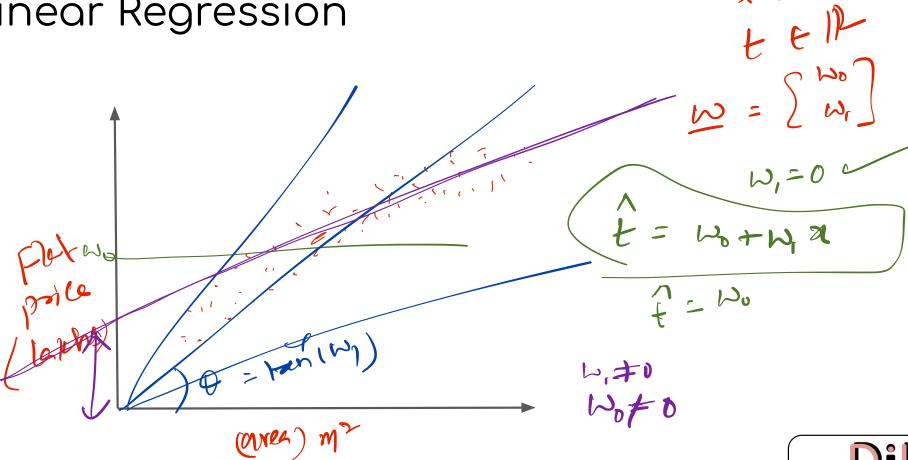


- Input variable
- tieR Output variable
- Simplest linear model











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Linear Basis function Models WOER, W= [WM-] ER

- Fix the number of parameters M s.t.
- Choose M-1 basis functions x:
- Mapping/Approximation:

$$\phi_{i}(\underline{x}) \in \mathbb{R} \quad i = 1, 2, \dots m-1$$

$$\phi_{i}(\underline{x}) : \mathbb{R}^{0} \longrightarrow \mathbb{R}$$

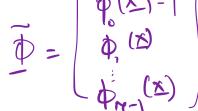
9/Approximation:

$$y(\mathbf{x}, \mathbf{w}) = \omega_0 + \omega_1 \phi_1(\underline{x}) + \omega_2 \phi_2(\underline{x}) + \cdots + \omega_{\mathsf{H}-\mathsf{H}} \phi_{\mathsf{H}-\mathsf{H}}(\underline{x})$$

$$y(\underline{x}, \mathbf{w}) = \dot{\mathbf{t}} = \omega_0 + \dot{\mathbf{t}} = \dot{\mathbf{t}} =$$



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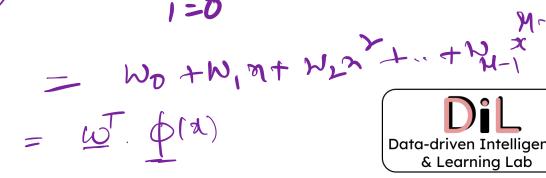
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Example Basis functions

- $\frac{1}{t}(X,\omega) = \omega_0 + \frac{m-1}{2}\omega_0 \phi_0(X) \quad \text{where} \quad \phi_1(X) = X_1$ $\frac{1}{t}(X,\omega) = \omega_0 + \frac{2}{2}\omega_0 \phi_0(X)$ x = (2, 2, 2D) Components of input
- Powers of input

$$\frac{1}{t}(x) = x$$







Example Basis Function

Gaussian basis functions

$$\frac{x \in \mathbb{R}}{2}$$

Example Basis Function

Logistic sigmoid basis functions

$$\frac{1}{t_i} = w_{0t} \underbrace{S}_{i=1} w_{i} \cdot \phi_i(x)$$

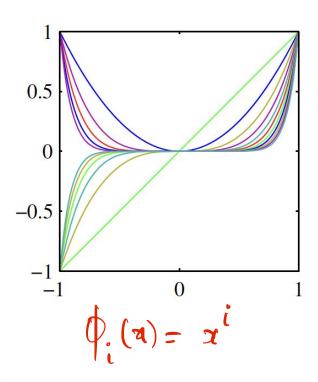
$$\frac{1}{2} \left(\frac{3 - \mu_0}{2^0} \right)$$

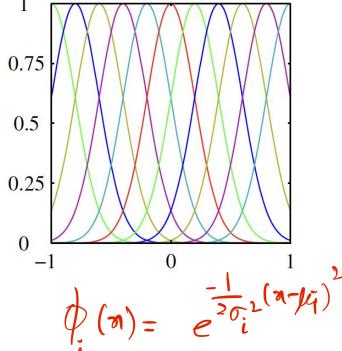


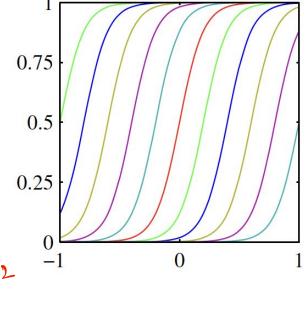


Example Basis Function

$$\oint_{i} (a) = \sigma \left(\frac{a - \mu_{i}}{\lambda_{i}} \right)$$









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Linear Regression via MLE





Linear Regression

Given data D

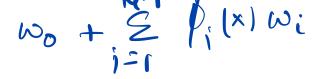
$$D = \{(x_1, t_1), (x_2, t_2), \dots (x_N, t_N)\} = \{\mathbf{x}, \mathbf{t}\}$$

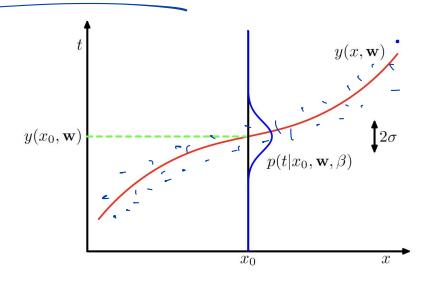
Input variables

Target variables

Linear Model with basis functions

$$y(\mathbf{x}, \mathbf{w}) =$$









Maximum Likelihood

Assume Gaussian noise around the target

$$t = y(x, \mathbf{w}) + \sigma \cdot \epsilon, \quad \epsilon \in \mathcal{N}(0, 1)$$





Maximum Likelihood

Assume Gaussian noise around the target

$$t = y(x, \mathbf{w}) + \sigma \cdot \epsilon, \quad \epsilon \in \mathcal{N}(0, 1)$$

$$p(t|x, \mathbf{w}, \beta) =$$

Data matrix

Targets vector





ML: sum of squares error

Likelihood

$$p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta) = \prod_{i=1}^{N} \mathcal{N}(t_i|\mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i), \beta^{-1})$$

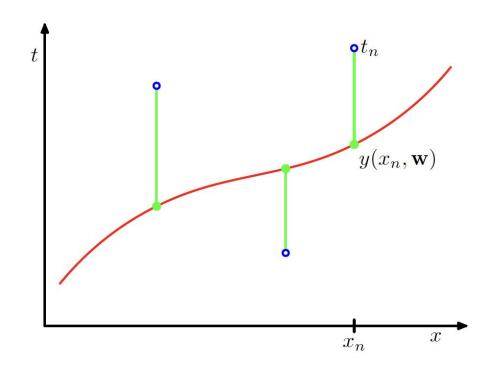
NLL =

Sum-of-squared error E_D (w) =





ML: sum of squares error







ML Estimates

• Minimize the NLL (or, the sum of squared errors)





ML Estimates

Optimal w* satisfies

$$\mathbb{E}[t'|\mathbf{x}',\mathbf{w_{ML}}] =$$





Next SGD



