Foundations of Machine Learning Al2000 and Al5000

FoML-31 Kernelized Linear Models

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So far in FoML

- Intro to ML and Probability refresher
- MLE, MAP, and fully Bayesian treatment
- Supervised learning
 - Linear Regression with basis functions
 - Bias-Variance Decomposition
 - Decision Theory & three broad classification strategies
 - Neural Networks
- Unsupervised learning
 - K-Means, Hierarchical, GMM for clustering, and PCA





For today

- Equivalent Kernel
- Kernelizing Linear models





Recap

Bayesian Regression (foml-11)





Equivalent Kernel





Equivalent Kernel formuluation

• The predictive distribution: $p(t|\mathbf{x}, \mathbf{t}, \alpha, \beta) = \mathcal{N}(t|\mathbf{m}_N^T \phi(\mathbf{x}), \sigma_N^2(\mathbf{x}))$

$$\mathbf{m}_{N} = \beta \mathbf{S}_{N} \mathbf{\Phi}^{\mathrm{T}} \mathbf{t}$$

$$\mathbf{S}_{N}^{-1} = \alpha \mathbf{I} + \beta \mathbf{\Phi}^{\mathrm{T}} \mathbf{\Phi}.$$

$$\sigma_{N}^{2}(\mathbf{x}) = \frac{1}{\beta} + \phi(\mathbf{x})^{\mathrm{T}} \mathbf{S}_{N} \phi(\mathbf{x})$$





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 $\bullet \quad \text{predictive mean:} \quad y(\mathbf{x}, \mathbf{m}_N) = \mathbf{m}_N^\mathrm{T} \boldsymbol{\phi}(\mathbf{x}) = \beta \boldsymbol{\phi}(\mathbf{x})^\mathrm{T} \mathbf{S}_N \boldsymbol{\Phi}^\mathrm{T} \mathbf{t} = \sum_{n=1} \beta \boldsymbol{\phi}(\mathbf{x})^\mathrm{T} \mathbf{S}_N \boldsymbol{\phi}(\mathbf{x}_n) t_n$

$$k(x, x_n) = y(\mathbf{x}, \mathbf{m}_N) =$$





Equivalent Kernel formuluation

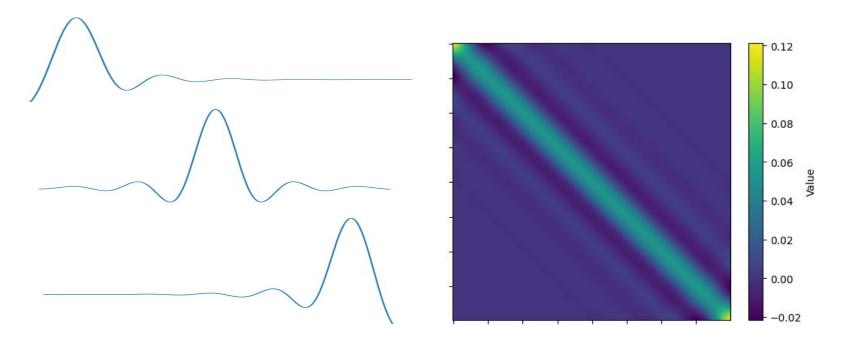
$$k(\mathbf{x}, \mathbf{x}_n) = \beta \phi(\mathbf{x})^T \mathbf{S_N} \phi(\mathbf{x_n})$$
 $y(\mathbf{x}, \mathbf{m}_N) = \sum_{n=1}^N k(\mathbf{x}, \mathbf{x}_n) t_n$

- K smoother matrix or equivalent kernel
 - o It depends on all the input samples
- Functions that make predictions by taking linear combinations of the training set target values - linear smoothers





Equivalent kernel for Gaussian Basis functions





Training samples close to x contribute more!



Covariance between two predictions

$$Cov[t_1, t_2 | \mathbf{x}_1, \mathbf{x}_2] =$$





Alternate approach to parametric modeling

- Instead of working with basis functions
- Define a localized kernel to make predictions for new points
 - Gaussian Processes





Summary - Parametric Models

- Use fixed basis function to project the data
 - Learning: regression, classification
- Learnable basis functions: neural networks
- Training
 - MLE, MAP → point estimate W
 - Full Bayesian → posterior on W
- Test time
 - Don't need the training data
 - Work with W or its distribution





Memory-based Methods

- Training data is kept and used for inference
 - KDE
 - KNN
- Fast 'training', slow 'inference'





Non-parametric Kernel Methods





Non-parametric methods

- Kernel methods
 - Use training data for test time predictions
- 'Dual representation' for the linear parametric models
 - Equivalent kernels





$$J(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left\{ \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_{n}) - t_{n} \right\}^{2} + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w}$$

Solution to w takes a form of linear combination of basis vectors





Instead of working with w, let us work with a

$$J(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left\{ \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x}_{n}) - t_{n} \right\}^{2} + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w} \qquad \mathbf{w} = \mathbf{\Phi}^{T} \mathbf{a}$$

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a} - \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{t} + \frac{1}{2} \mathbf{t}^{\mathrm{T}} \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a}$$





Instead of working with w, let us work with a

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a} - \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{t} + \frac{1}{2} \mathbf{t}^{\mathrm{T}} \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a}$$

• Introduce a gram matrix K $K_{nm} = \phi(\mathbf{x}_n)^{\mathrm{T}} \phi(\mathbf{x}_m) = k(\mathbf{x}_n, \mathbf{x}_m)$





Optimizing for a

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{K} \mathbf{a} - \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{t} + \frac{1}{2} \mathbf{t}^{\mathrm{T}} \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{a}.$$

భారతీయ సాంకేతిక విజ్ఞాన సంస్థ హైదరాబాద్ भारतीय प्रौद्योगिकी संस्थान हैदराबाद Indian Institute of Technology Hyderabad

$$\mathbf{a} = (\mathbf{K} + \lambda \mathbf{I}_N)^{-1} \, \mathbf{t}.$$



Primal and Dual perspectives

$$\mathbf{w} = \Phi^T \mathbf{a}$$

$$y(\mathbf{x}, \mathbf{w}) = \mathbf{w}^T \phi(\mathbf{x})$$

$$\mathbf{a} = (\mathbf{K} + \lambda \mathbf{I}_N)^{-1} \mathbf{t}.$$

$$y(\mathbf{x}, \mathbf{a}) = \sum_{n=1}^{N} a_n k(\mathbf{x}_n, \mathbf{x})$$

Primal and Dual perspectives

$$\mathbf{w} = \Phi^T \mathbf{a}$$

$$y(\mathbf{x}, \mathbf{w}) = \mathbf{w}^T \phi(\mathbf{x})$$

- \circ O(M³) vs. O(N³)
- Compute (inference)
 - O(M) vs. O(NM)



 $\mathbf{a} = (\mathbf{K} + \lambda \mathbf{I}_N)^{-1} \mathbf{t}.$

 $y(\mathbf{x}, \mathbf{a}) = \sum_{n=1}^{N} a_n k(\mathbf{x}_n, \mathbf{x})$



Primal and Dual perspectives





Next

• Kernel methods with 'sparsity' in solutions



