

# Foundations of Machine Learning AI2000 and AI5000

FoML-06  
Linear Regression

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July-Nov 2025



భారతీయ సాంకేతిక విజ్ఞాన సంస్థ హైదరాబాద్  
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# So far in FoML

- What is ML and the learning paradigms
- Probability refresher
- MLE, MAP, and fully Bayesian treatment



# Linear Regression



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# Linear Regression

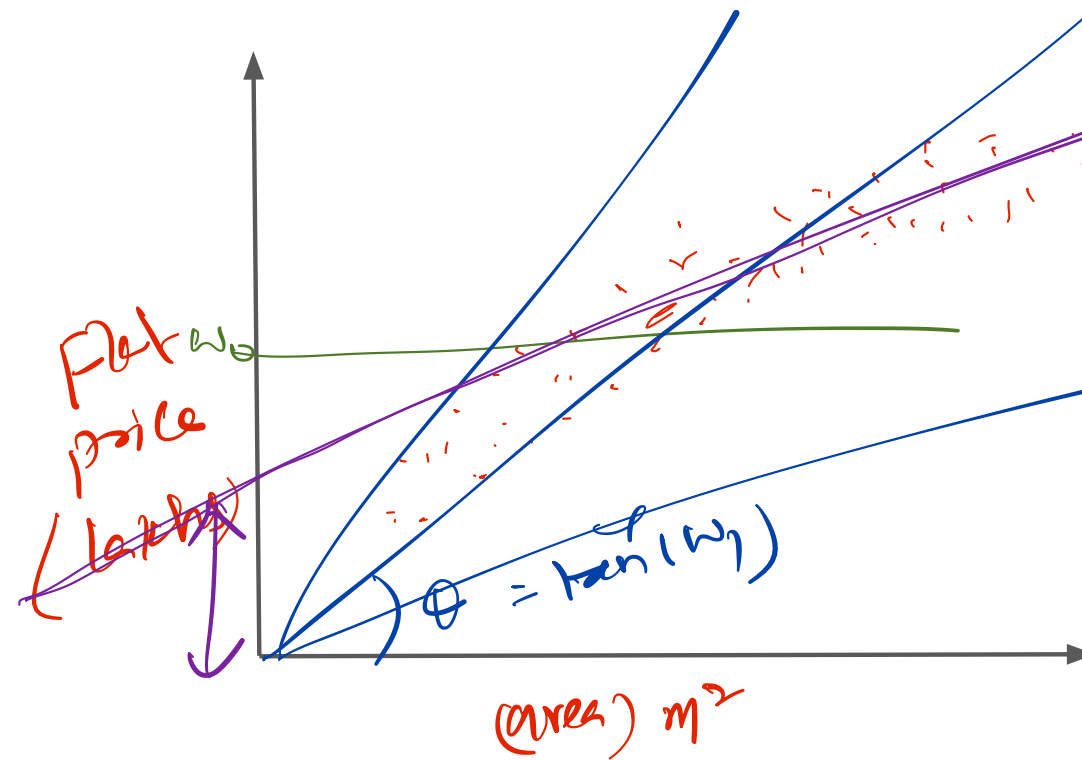
- Dataset  $D = \{(\underline{x}_1, t_1), (\underline{x}_2, t_2), \dots, (\underline{x}_N, t_N)\}$  ✓  
 $\underline{w} \in \mathbb{R}^D$

- Input variable  $\underline{x}_i \in \mathbb{R}^D$
- Output variable  $t_i \in \mathbb{R}$
- Simplest linear model

$$\begin{aligned} \hat{t}_i &= y(\underline{x}_i, \underline{w}) = w_0 + w_1 \underline{x}_{i1} + w_2 \underline{x}_{i2} + \dots + w_D \underline{x}_{iD} \\ &= w_0 + \underline{w}^T \underline{x}_i \end{aligned}$$



# Linear Regression



$$w_0 = 0$$

$$x \in \mathbb{R}$$

$$t \in \mathbb{R}$$

$$\underline{w} = \begin{bmatrix} w_0 \\ w_1 \end{bmatrix}$$

$$w_1 = 0$$

$$\hat{t} = w_0 + w_1 x$$

$$\hat{t} = w_0$$

$$w_1 \neq 0$$

$$w_0 \neq 0$$



# Linear Basis function Models

- Fix the number of parameters  $M$  s.t.

$$\omega_0 \in \mathbb{R}, \underline{\omega} = \begin{bmatrix} \omega_1 \\ \vdots \\ \omega_{m-1} \end{bmatrix} \in \mathbb{R}^{m-1}$$

- Choose  $M-1$  basis functions  $\phi_i(\underline{x})$ :

$$\phi_i(\underline{x}) \in \mathbb{R} \quad i = 1, 2, \dots, m-1$$

- Mapping/Approximation:

$$\phi_i(\underline{x}): \mathbb{R}^D \rightarrow \mathbb{R}$$

$$y(\underline{x}, \underline{w}) = \omega_0 + \omega_1 \phi_1(\underline{x}) + \omega_2 \phi_2(\underline{x}) + \dots + \omega_{m-1} \phi_{m-1}(\underline{x})$$

$$\hat{y}(\underline{x}, \underline{w}) = \omega_0 + \underline{\phi}^T \cdot \underline{\omega}$$

$$= \underline{\phi}^T \cdot \underline{z}$$

$$\underline{z} = \begin{bmatrix} \omega_0 \\ \omega_1 \\ \vdots \\ \omega_{m-1} \end{bmatrix}$$

$$\underline{\phi} = \begin{bmatrix} \phi_1(\underline{x}) \\ \vdots \\ \phi_{m-1}(\underline{x}) \end{bmatrix}$$

$$\underline{\phi} = \begin{bmatrix} \phi_0(\underline{x}) = 0 \\ \phi_1(\underline{x}) \\ \vdots \\ \phi_{m-1}(\underline{x}) \end{bmatrix}$$



# Example Basis functions

- Components of input  $\underline{x} = (x_1 \ x_2 \dots x_D)^T$   $m=D$  where  $\phi_i(\underline{x}) = x_i$   
 $\hat{t}(\underline{x}, \underline{\omega}) = \omega_0 + \sum_{i=1}^{m-1} \omega_i \phi_i(\underline{x})$

- Powers of input  $\phi_i(x) = x^i$   
 $x \in \mathbb{R}$   
 $\underline{\omega} \in \mathbb{R}^m$   
 $\hat{t}(\underline{\omega}, x) = \sum_{i=0}^{m-1} \phi_i(x) \cdot \omega_i$

$$= \omega_0 + \omega_1 x + \omega_2 x^2 + \dots + \omega_{m-1} x^{m-1}$$

$$= \underline{\omega}^T \cdot \underline{\phi}(x)$$



# Example Basis Function

- Gaussian basis functions

$$\underline{x} \in \mathbb{R}^D$$

$$\hat{f}(\underline{x}, \underline{w}) = w_0 + \sum_{i=1}^{m-1} w_i$$

$$\phi_i(\underline{x}) =$$

$$e^{-\frac{1}{2} (\underline{x} - \underline{\mu}_i)^T \underline{\Sigma}_i^{-1} (\underline{x} - \underline{\mu}_i)}$$



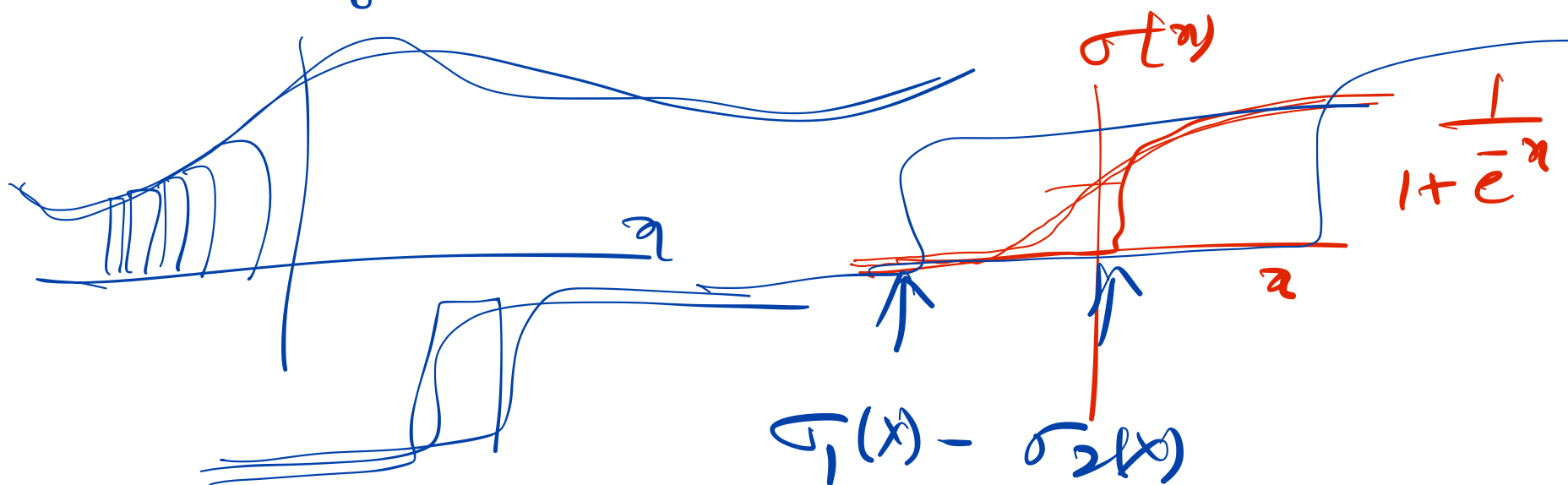


# Example Basis Function

- Logistic sigmoid basis functions

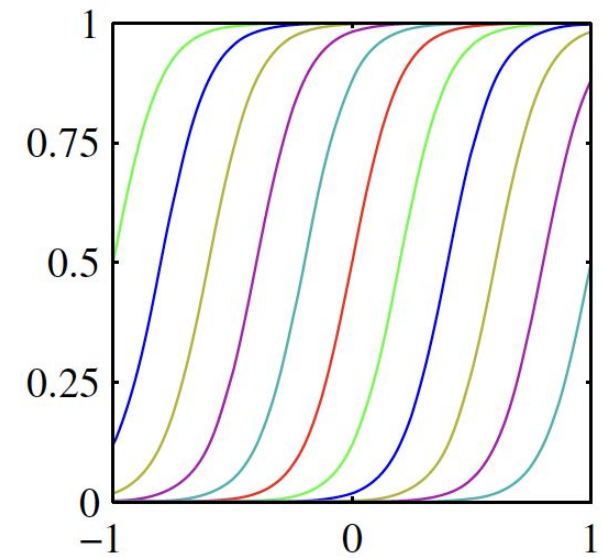
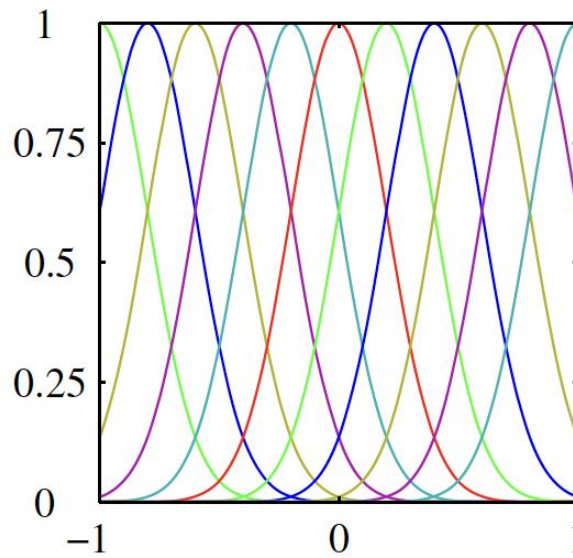
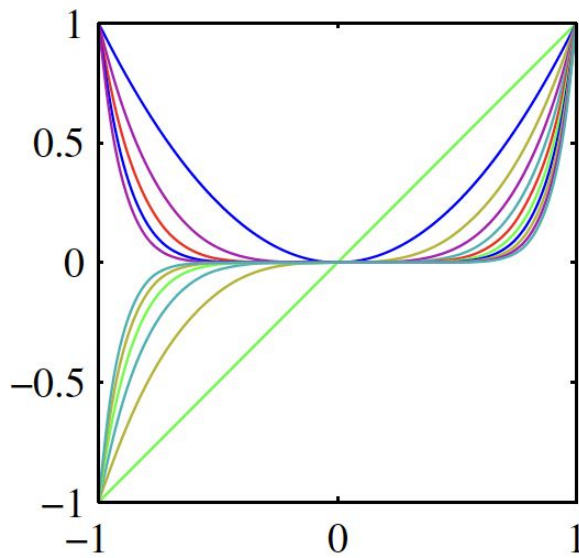
thy

$$\beta_i(\underline{x}) = \left( \sigma \left( \frac{\underline{x} - \underline{\mu}_i}{\underline{\sigma}_i} \right) \right)$$



# Example Basis Function

$$\phi_j = x_j^2$$



# Linear Regression via MLE



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# Linear Regression

- Given data  $D$

$$D = \{(x_1, t_1), (x_2, t_2), \dots, (x_N, t_N)\} = \{\mathbf{x}, \mathbf{t}\}$$

Input variables

$x$

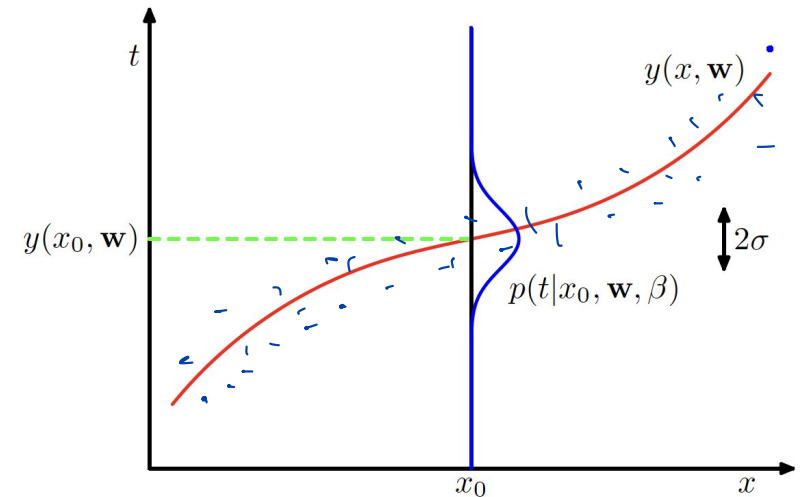
Target variables

$t$

Linear Model with basis functions

$$y(\mathbf{x}, \mathbf{w}) =$$

$$w_0 + \sum_{i=1}^{N-1} \phi_i(x) w_i$$



# Maximum Likelihood

- Assume Gaussian noise around the target

$$t = \underline{y(x, \mathbf{w}) + \sigma \cdot \epsilon}, \quad \epsilon \in \mathcal{N}(0, 1) \quad \checkmark$$

$$\frac{1}{\sigma^2} = \sigma^2$$



# Maximum Likelihood

- Assume Gaussian noise around the target

$$t = y(x, \mathbf{w}) + \sigma \cdot \epsilon, \quad \epsilon \in \mathcal{N}(0, 1)$$

$$p(t|x, \mathbf{w}, \beta) =$$

Data matrix

Targets vector

# ML: sum of squares error

- Likelihood

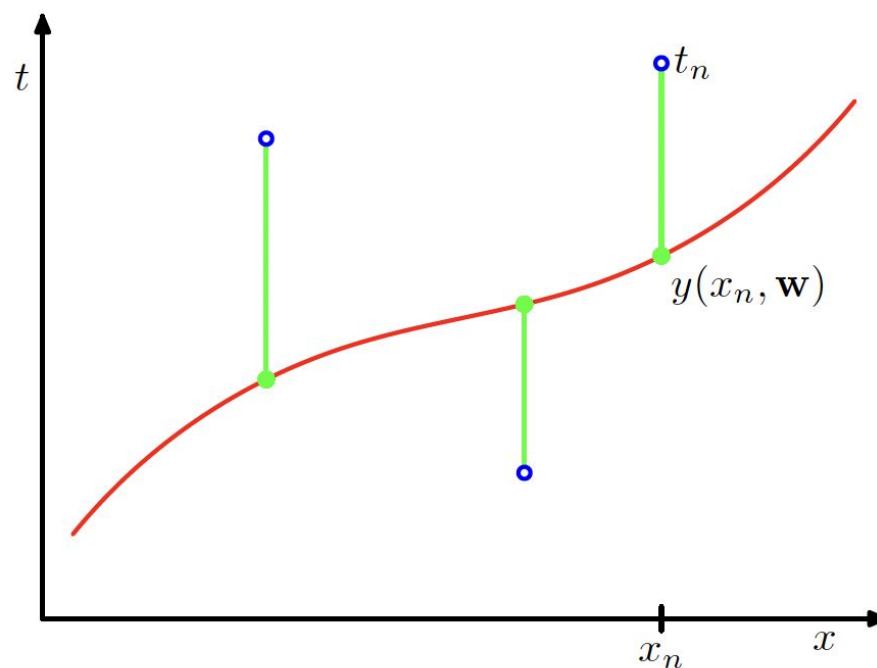
$$p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta) = \prod_{i=1}^N \mathcal{N}(t_i | \mathbf{w}^T \phi(\mathbf{x}_i), \beta^{-1})$$

NLL =

Sum-of-squared error  $E_D(\mathbf{w}) =$



# ML: sum of squares error





# ML Estimates

- Minimize the NLL (or, the sum of squared errors)



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# ML Estimates

- Optimal  $w^*$  satisfies

$$\mathbb{E}[t' | \mathbf{x}', \mathbf{w}_{\text{ML}}] =$$



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# Next SGD



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