

Foundations of Machine Learning AI2000 and AI5000

FoML-06
Linear Regression

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భారతీయ సాంకేతిక విజ్ఞాన సంస్థ హైదరాబాద్
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So far in FoML

- What is ML and the learning paradigms
- Probability refresher
- MLE, MAP, and fully Bayesian treatment



Linear Regression



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Linear Regression

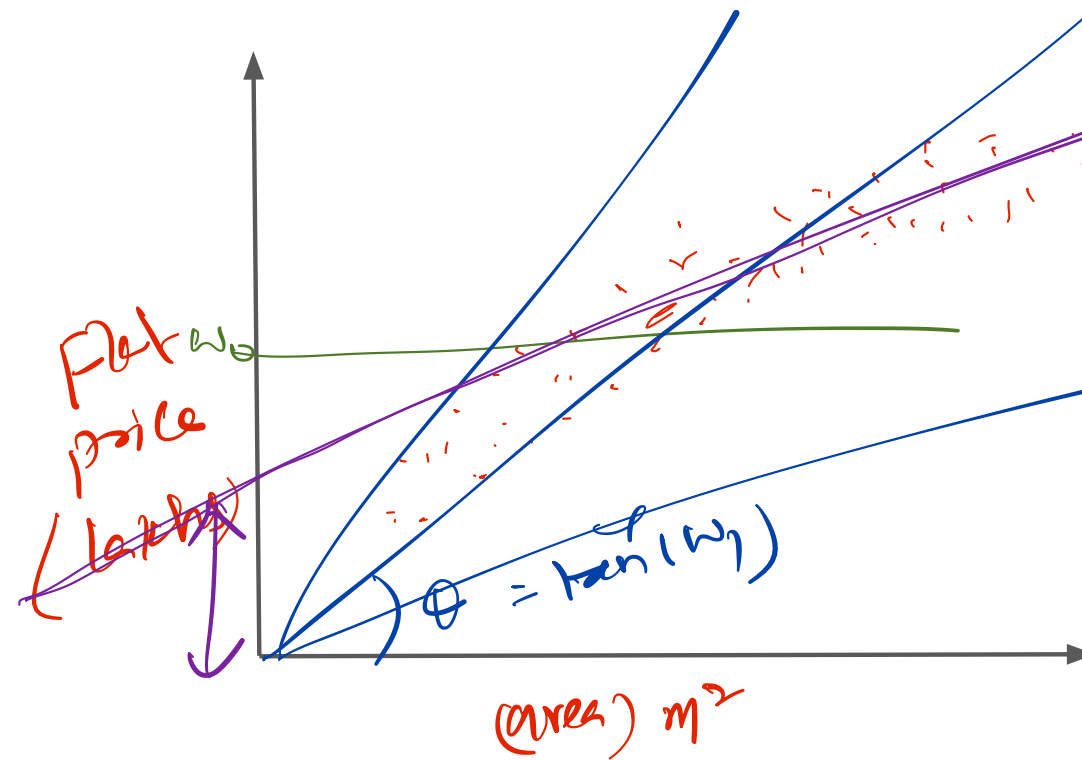
- Dataset $D = \{(\underline{x}_1, t_1), (\underline{x}_2, t_2), \dots, (\underline{x}_N, t_N)\}$ ✓
 $\underline{w} \in \mathbb{R}^D$

- Input variable $\underline{x}_i \in \mathbb{R}^D$
- Output variable $t_i \in \mathbb{R}$
- Simplest linear model

$$\begin{aligned} \hat{t}_i &= y(\underline{x}_i, \underline{w}) = w_0 + w_1 \underline{x}_{i1} + w_2 \underline{x}_{i2} + \dots + w_D \underline{x}_{iD} \\ &= w_0 + \underline{w}^T \underline{x}_i \end{aligned}$$



Linear Regression



$$w_0 = 0$$

$$x \in \mathbb{R}$$

$$t \in \mathbb{R}$$

$$\underline{w} = \begin{bmatrix} w_0 \\ w_1 \end{bmatrix}$$

$$w_1 = 0$$

$$\hat{t} = w_0 + w_1 x$$

$$\hat{t} = w_0$$

$$w_1 \neq 0$$

$$w_0 \neq 0$$



Linear Basis function Models

- Fix the number of parameters M s.t.

$$\omega_0 \in \mathbb{R}, \underline{\omega} = \begin{bmatrix} \omega_1 \\ \vdots \\ \omega_{m-1} \end{bmatrix} \in \mathbb{R}^{m-1}$$

- Choose $M-1$ basis functions x :

$$\phi_i(\underline{x}) \in \mathbb{R} \quad i = 1, 2, \dots, m-1$$

- Mapping/Approximation:

$$\phi_i(\underline{x}): \mathbb{R}^D \rightarrow \mathbb{R}$$

$$y(\underline{x}, \underline{w}) = \omega_0 + \omega_1 \phi_1(\underline{x}) + \omega_2 \phi_2(\underline{x}) + \dots + \omega_{m-1} \phi_{m-1}(\underline{x})$$

$$\hat{y}(\underline{x}, \underline{w}) = \omega_0 + \underline{\phi}^T \cdot \underline{\omega}$$

$$= \underline{\phi}^T \cdot \underline{z}$$

$$\underline{z} = \begin{bmatrix} \omega_0 \\ \omega_1 \\ \vdots \\ \omega_{m-1} \end{bmatrix}$$

$$\underline{\phi} = \begin{bmatrix} \phi_1(\underline{x}) \\ \vdots \\ \phi_{m-1}(\underline{x}) \end{bmatrix}$$

$$\underline{\phi} = \begin{bmatrix} \phi_0(\underline{x}) = 1 \\ \phi_1(\underline{x}) \\ \vdots \\ \phi_{m-1}(\underline{x}) \end{bmatrix}$$



Example Basis functions

- Components of input $\underline{x} = (x_1 \ x_2 \dots x_D)^T$ $m=D$ where $\phi_i(\underline{x}) = x_i$

$$\hat{t}(\underline{x}, \underline{w}) = w_0 + \sum_{i=1}^{m-1} w_i \phi_i(\underline{x})$$

- Powers of input $x \in \mathbb{R}$
 $\underline{w} \in \mathbb{R}^m$

$$\phi_i(x) = x^i$$

$$\hat{t}(\underline{w}, x) = \sum_{i=0}^{m-1} w_i \cdot \phi_i(x)$$

$$= w_0 + w_1 x + w_2 x^2 + \dots + w_{m-1} x^{m-1}$$

$$= \underline{w}^T \cdot \underline{\phi}(x)$$



Example Basis Function

- Gaussian basis functions

$$\underline{x} \in \mathbb{R}^D$$

$$\hat{f}(\underline{x}, \underline{\omega}) = \omega_0 + \sum_{i=1}^{m-1} \omega_i \phi_i(\underline{x})$$

$$\phi_i(\underline{x}) =$$

$$e^{-\frac{1}{2} (\underline{x} - \underline{\mu}_i)^T \underline{\Sigma}_i^{-1} (\underline{x} - \underline{\mu}_i)}$$

Hyper parameters
 $\underline{\mu}_i, \underline{\Sigma}_i, m$



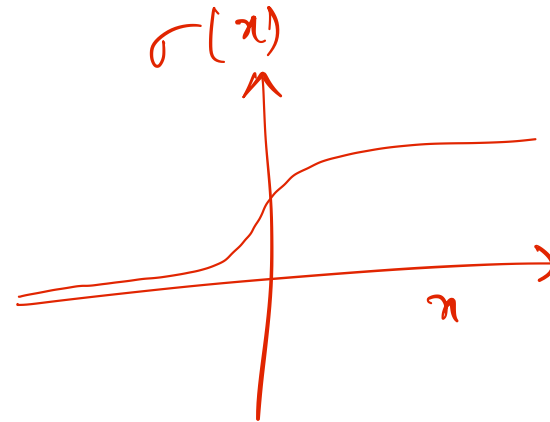
Example Basis Function

- Logistic sigmoid basis functions

$$\hat{t}_i = w_0 + \sum_{i=1}^m w_i \cdot \phi_i(x)$$

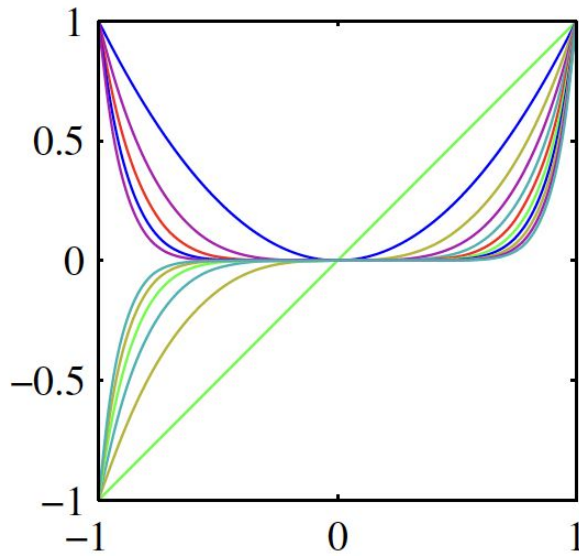
$$\phi_i(x) = \sigma\left(\frac{x - \mu_i}{\Delta_i}\right)$$

$$x, \mu_i, \Delta_i \in \mathbb{R}$$

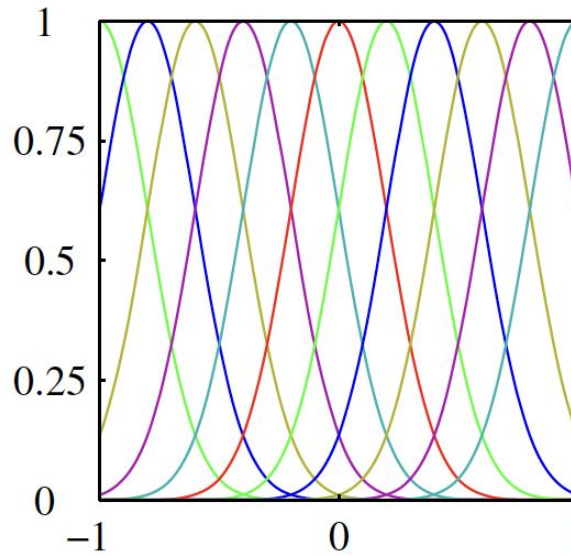


Example Basis Function

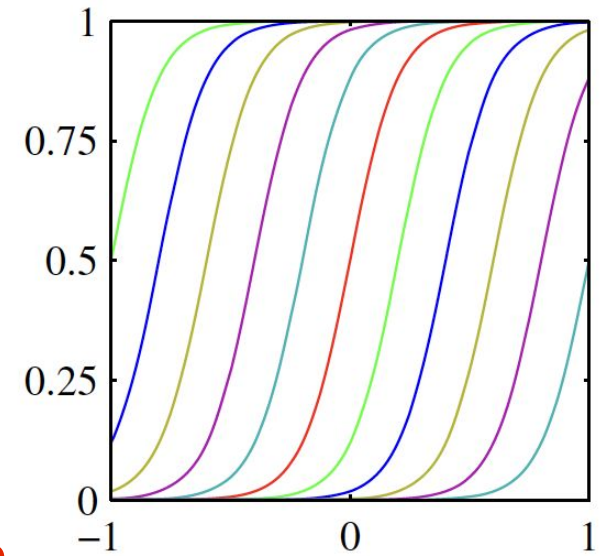
$$\phi_i(x) = \sigma\left(\frac{x - \mu_i}{\sigma_i}\right)$$



$$\phi_i(x) = x^i$$



$$\phi_i(x) = e^{-\frac{1}{2\sigma_i^2}(x - \mu_i)^2}$$



Linear Regression via MLE



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Linear Regression

- Given data D

$$D = \{(x_1, t_1), (x_2, t_2), \dots, (x_N, t_N)\} = \{\mathbf{x}, \mathbf{t}\}$$

Input variables

x

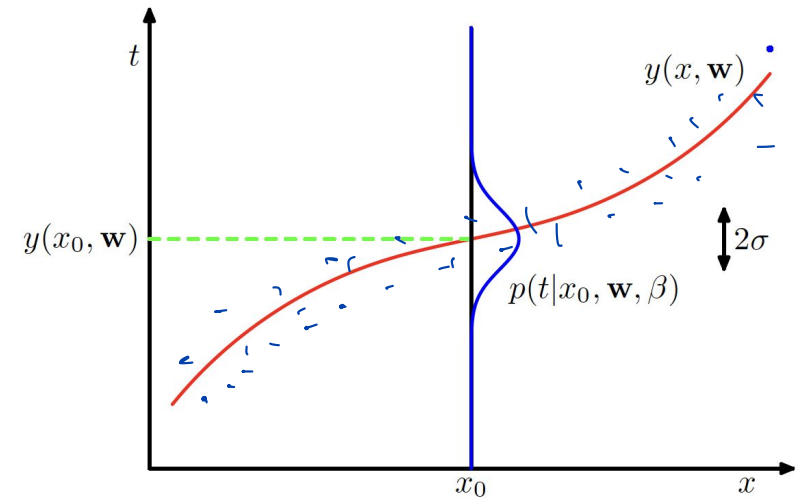
Target variables

t

Linear Model with basis functions

$$y(\mathbf{x}, \mathbf{w}) =$$

$$w_0 + \sum_{i=1}^{N-1} \phi_i(x) w_i$$



Maximum Likelihood

- Assume Gaussian noise around the target

$$t = \underline{y(x, \mathbf{w}) + \sigma \cdot \epsilon}, \quad \epsilon \in \mathcal{N}(0, 1) \quad \checkmark$$

$$\frac{1}{\sigma^2} = \sigma^2$$



Maximum Likelihood

- Assume Gaussian noise around the target

$$t = y(x, \mathbf{w}) + \sigma \cdot \epsilon, \quad \epsilon \in \mathcal{N}(0, 1)$$

$$p(t|x, \mathbf{w}, \beta) = \mathcal{N}\left(t \mid \mathbf{w}^T \phi(x), \beta\right)$$

Data matrix $\begin{bmatrix} 1 & 1 & \dots & 1 \\ x_1 & x_2 & \dots & x_N \\ 1 & 1 & \dots & 1 \end{bmatrix}$

Targets vector

$$\begin{bmatrix} t_1 \\ t_2 \\ \vdots \\ t_N \end{bmatrix}$$



ML: sum of squares error

- Likelihood

$$p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta) = \prod_{i=1}^N \mathcal{N}(t_i | \mathbf{w}^T \phi(\mathbf{x}_i), \beta^{-1})$$

NLL =

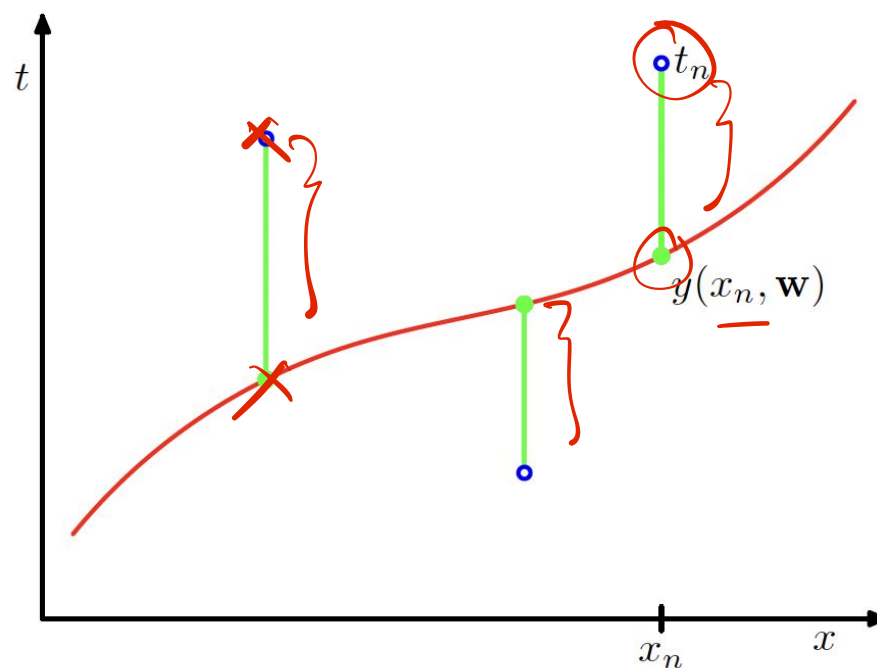
$$-\frac{N}{2} \log \beta + \frac{N}{2} \log 2\pi + \beta \sum_{i=1}^N \left[t_i - \mathbf{w}^T \phi(\mathbf{x}_i) \right]^2$$

Sum-of-squared error $E_D(\mathbf{w}) =$

$$\frac{1}{2} \sum_{i=1}^N \left[t_i - \mathbf{w}^T \phi(\mathbf{x}_i) \right]^2$$



ML: sum of squares error



ML Estimates

- Minimize the NLL (or, the sum of squared errors)

$$\frac{1}{2} \sum_{i=1}^N [t_i - \underline{\omega}^T \phi(x_i)]^2$$

$\frac{\partial}{\partial \underline{\omega}} \left(\right) = 0$

$$\sum_{i=1}^N [t_i - \underline{\omega}^T \phi(x_i)] \cdot (-1) \phi(x_i) = 0$$

$$\sum_{i=1}^N t_i \phi(x_i) = \sum_{i=1}^N \underline{\omega}^T \phi(x_i) \phi^T(x_i)$$

→ Apply transpose

$$\sum_{i=1}^N t_i \cdot \phi(x_i) = \sum_{i=1}^N \phi(x_i) \phi(x_i)^T \cdot \underline{\omega}$$



ML Estimates

- Optimal w^* satisfies

$$\left(\sum_{i=1}^N \underline{\phi}(x_i) \underline{\phi}(x_i)^T \right) \cdot \underline{w} = \sum_{i=1}^N \underline{\phi}(x_i) \cdot t_i$$

$$\Phi^T \Phi \cdot \underline{w} = \Phi^T \underline{t}$$

$$\underline{w} = [\Phi^T \Phi]^{-1} \Phi^T \underline{t}$$

$$\mathbb{E}[t' | \mathbf{x}', \mathbf{w}_{ML}] = \underline{w}_{ML}^T \underline{\phi}(x')$$

$$\underline{\phi}_0 \leftarrow \Phi = \begin{bmatrix} \phi_0(x_1) & \phi_1(x_1) & \dots & \phi_{M-1}(x_1) \\ \phi_0(x_2) & \phi_1(x_2) & \dots & \phi_{M-1}(x_2) \\ \vdots & \vdots & \ddots & \vdots \\ \phi_0(x_N) & \phi_1(x_N) & \dots & \phi_{M-1}(x_N) \end{bmatrix}$$

design matrix

↗ pseudo inverse



Next SGD



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DiL

Data-driven Intelligence
& Learning Lab