Foundations of Machine Learning Al2000 and Al5000

FoML-32 Constructing the Kernels

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So far in FoML

- Intro to ML and Probability refresher
- MLE, MAP, and fully Bayesian treatment
- Supervised learning
 - a. Linear Regression with basis functions
 - b. Bias-Variance Decomposition
 - c. Decision Theory three broad classification strategies
 - d. Neural Networks
- Unsupervised learning
 - a. K-Means, Hierarchical, and GMM for clustering
- Kernelizing linear Models
 - a. Dual representation





For today

- Kernel substitution/trick
- Constructing the Kernels





Dual formulation

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a} - \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{t} + \frac{1}{2} \mathbf{t}^{\mathrm{T}} \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^{\mathrm{T}} \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}} \mathbf{a}$$

$$\mathbf{a} = (\mathbf{K} + \lambda \mathbf{I}_N)^{-1} \mathbf{t}.$$
 $y(\mathbf{x}) = \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}) = \mathbf{a}^{\mathrm{T}} \boldsymbol{\Phi} \boldsymbol{\phi}(\mathbf{x}) = \mathbf{k}(\mathbf{x})^{\mathrm{T}} (\mathbf{K} + \lambda \mathbf{I}_N)^{-1} \mathbf{t}$

- Despite the computational demand, is useful
 - Expressed entirely in terms of the Kernel function
 - Avoids defining the basis functions explicitly
 - o Allows us to implicitly use high (even, infinite) dimensional feature spaces





Kernel substitution

If we have an algorithm formulated in such a way that the input vector x enters only in the form of scalar products



then we can replace that scalar product with a kernel



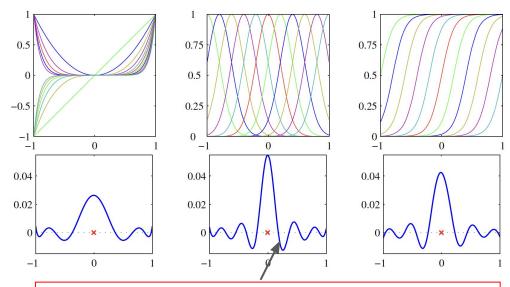


- One way choose the feature space
 - Then construct the kernel

$$k(x, x') = \boldsymbol{\phi}(x)^{\mathrm{T}} \boldsymbol{\phi}(x') = \sum_{i=1}^{M} \phi_i(x) \phi_i(x')$$







Likely to be result of using a different kernel based on the Gaussian basis, but not the one shown in the above equation, or, a scaled dot product is used.





- Alternate construct kernel directly
- We must ensure that it is valid
 - o i.e., it corresponds to scalar product in some feature space





- Example
- 2D input: x, z

$$k(\mathbf{x}, \mathbf{z}) = (\mathbf{x}^{\mathrm{T}} \mathbf{z})^{2}$$
.





- Need a simple way to test a function if it is a valid kernel
- Necessary and sufficient condition
 - Gram matrix should be PSD
 - \circ i.e., for every PSD kernel, there exists a feature projection (ϕ)



Example Kernels

Gaussian

$$k(\mathbf{x}, \mathbf{x}') = \exp\left(-\|\mathbf{x} - \mathbf{x}'\|^2 / 2\sigma^2\right)$$

• Generalized polynomial

$$k(\mathbf{x}, \mathbf{x}') = (1 + \mathbf{x}^T \mathbf{x}')^M$$

Radial basis function

$$k(\mathbf{x}, \mathbf{x}') = k(||\mathbf{x}^T \mathbf{x}'||^2)$$





• Another way - build them out of simpler kernels as building blocks

```
k(\mathbf{x}, \mathbf{x}') = ck_1(\mathbf{x}, \mathbf{x}')
k(\mathbf{x}, \mathbf{x}') = f(\mathbf{x})k_1(\mathbf{x}, \mathbf{x}')f(\mathbf{x}')
k(\mathbf{x}, \mathbf{x}') = q(k_1(\mathbf{x}, \mathbf{x}'))
k(\mathbf{x}, \mathbf{x}') = \exp(k_1(\mathbf{x}, \mathbf{x}'))
k(\mathbf{x}, \mathbf{x}') = k_1(\mathbf{x}, \mathbf{x}') + k_2(\mathbf{x}, \mathbf{x}')
k(\mathbf{x}, \mathbf{x}') = k_1(\mathbf{x}, \mathbf{x}')k_2(\mathbf{x}, \mathbf{x}')
k(\mathbf{x}, \mathbf{x}') = k_3(\phi(\mathbf{x}), \phi(\mathbf{x}'))
k(\mathbf{x}, \mathbf{x}') = \mathbf{x}^{\mathrm{T}} \mathbf{A} \mathbf{x}'
k(\mathbf{x}, \mathbf{x}') = k_a(\mathbf{x}_a, \mathbf{x}'_a) + k_b(\mathbf{x}_b, \mathbf{x}'_b)
k(\mathbf{x}, \mathbf{x}') = k_a(\mathbf{x}_a, \mathbf{x}'_a)k_b(\mathbf{x}_b, \mathbf{x}'_b)
```





Next

SVM





Rough



