Foundations of Machine Learning Al2000 and Al5000

FoML-11 Bayesian Regression

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So far in FoML

- What is ML and the learning paradigms
- Probability refresher
- MLE, MAP, and fully Bayesian treatment
- Linear Regression with basis functions and regularization
- Model selection
- Bias-Variance Decomposition/Trade-off





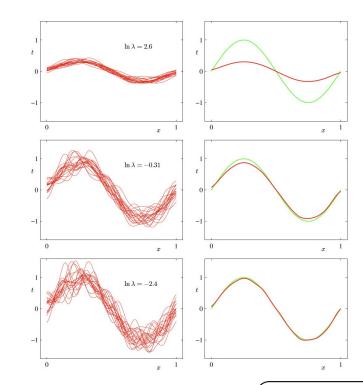
Bayesian Regression





We have seen that

- Model averaging may be a good thing to do
 - Across different datasets







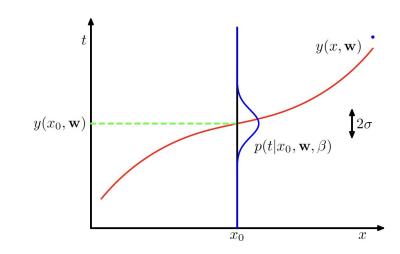
Bayesian Regression

 Instead of averaging over different datasets, we do it over different parameter sets





Data
$$\mathbf{t} = (t_1, \dots t_N)^T$$
 $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_N)^T$







Data $\mathbf{t} = (t_1, \dots, t_N)^T$ $\mathbf{X} = (\mathbf{x}_1, \dots, \mathbf{x}_N)^T$

 $y(x_0, \mathbf{w})$

Likelihood:
$$p(t'|\mathbf{x}',\mathbf{w},\beta) = \mathcal{N}(t/\omega^{\dagger}\phi(x), \vec{\beta})_{t}$$

 $\underbrace{p(\mathbf{t}|\mathbf{X},\mathbf{w},\beta) = \prod_{i=1}^{N} \mathcal{N}(t_i|y(x_i,\mathbf{w}),\beta^{-1}) =}_{\mathcal{N}\left(\underbrace{t}/\bigoplus\underline{\omega},\widecheck{\beta}^{1}\right)}$





Conjugate Prior: $p(\mathbf{w}) = \mathcal{N}(\mathbf{w}|m_0, \mathbf{S}_0)$ C) prior; before observing any data $p(\mathbf{w}|\mathbf{t}, \mathbf{X}) = \frac{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta)p(\mathbf{w})}{p(\mathbf{t}|\mathbf{X}, \beta)} = \bigwedge \left(\bigsqcup_{\mathbf{y} \in \mathcal{S}_{\mathbf{y}}} \mathcal{S}_{\mathbf{y}} \right)$

) posterior; after observing N data samples X Nxm

N(0,2) This is what we worked with during ontp dicultion (Font-05)



Conjugate Prior: $p(\mathbf{w}) = \mathcal{N}(\mathbf{w}|m_0, \mathbf{S}_0)$

Makes it possible for Avis a comportable posterior this case)

$$p(\mathbf{w}|\mathbf{t}, \mathbf{X}) = \frac{p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta)p(\mathbf{w})}{p(\mathbf{t}|\mathbf{X}, \beta)} = \mathcal{N}(\mathbf{w}|\mathbf{m}_N, \mathbf{S}_N)$$

$$\mathbf{S}_N^{-1} = \mathbf{S}_0^{-1} + \beta \Phi^T \Phi$$

$$\mathbf{m}_N = \mathbf{S}_N (\mathbf{S}_0^{-1} \mathbf{m}_0 + \beta \Phi^T \mathbf{t})$$



It we want a point estimate,

WMAP = MN

• Simple prior: $p(\mathbf{w}|\alpha) = \mathcal{N}(\underline{\mathsf{P}}/\underline{\mathsf{Q}}, \underline{\mathsf{S}})$

$$\mathbf{m}_0 = \mathbf{0}$$
 $\mathbf{S}_0 = \alpha^{-1} \mathbf{I}$





• Simple prior: $p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w}|\mathbf{0}, \alpha^{-1}\mathbf{I})$

$$\mathbf{m}_0 = \mathbf{0} \ \mathbf{S}_0 = lpha^{-1} \mathbf{I}$$

Posterior

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$$p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \alpha, \beta) = \mathcal{N}(\mathbf{w}|\mathbf{m}_N, \mathbf{S}_N)$$

$$\mathcal{S}_N^{-1} = \mathbf{S}_0^{-1} + \beta \Phi^T \Phi = (\mathcal{A} \mathcal{I} + \mathcal{F} \mathcal{O} \mathcal{O})$$

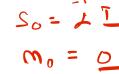
$$\mathbf{m}_N = \mathbf{S}_N(\mathbf{S}_0^{-1}\mathbf{m}_0 + \beta\Phi^T\mathbf{t}) = (\mathbf{A} \mathbf{I} + \beta\Phi^T\Phi)(\mathbf{Q} + \mathbf{F}\Phi^T\Phi)$$





Special prior: Infinitely broad prior (no restriction) on w $p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w}|\mathbf{0}, \alpha^{-1}\mathbf{I}) \quad \alpha \to 0$

Posterior





Special prior: Infinitely narrow prior on w

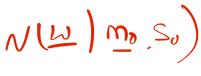
$$p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w}|\mathbf{0}, \alpha^{-1}\mathbf{I}) \quad \alpha \to \inf$$

Posterior

$$\mathbf{S}_{N}^{-1} = \mathbf{S}_{0}^{-1} + \beta \Phi^{T} \Phi = \lim_{\Delta \to \infty} \left[\Delta \mathbf{I} + \beta \mathbf{D} \right] \Rightarrow \mathbf{S}_{N} = \mathbf{O}$$

$$\mathbf{m}_{N} = \mathbf{S}_{N} (\mathbf{S}_{0}^{-1} \mathbf{m}_{0} + \beta \Phi^{T} \mathbf{t}) = \lim_{\Delta \to \infty} \left[\Delta \mathbf{I} + \beta \mathbf{D} \right] \beta \mathbf{D}^{T} \mathbf{t}$$

Yer -> 0









Next Decision Theory



